Arm® Compiler for Embedded FuSa

Version 6.22.1 LTS

Migration and Compatibility Guide

Issue 01
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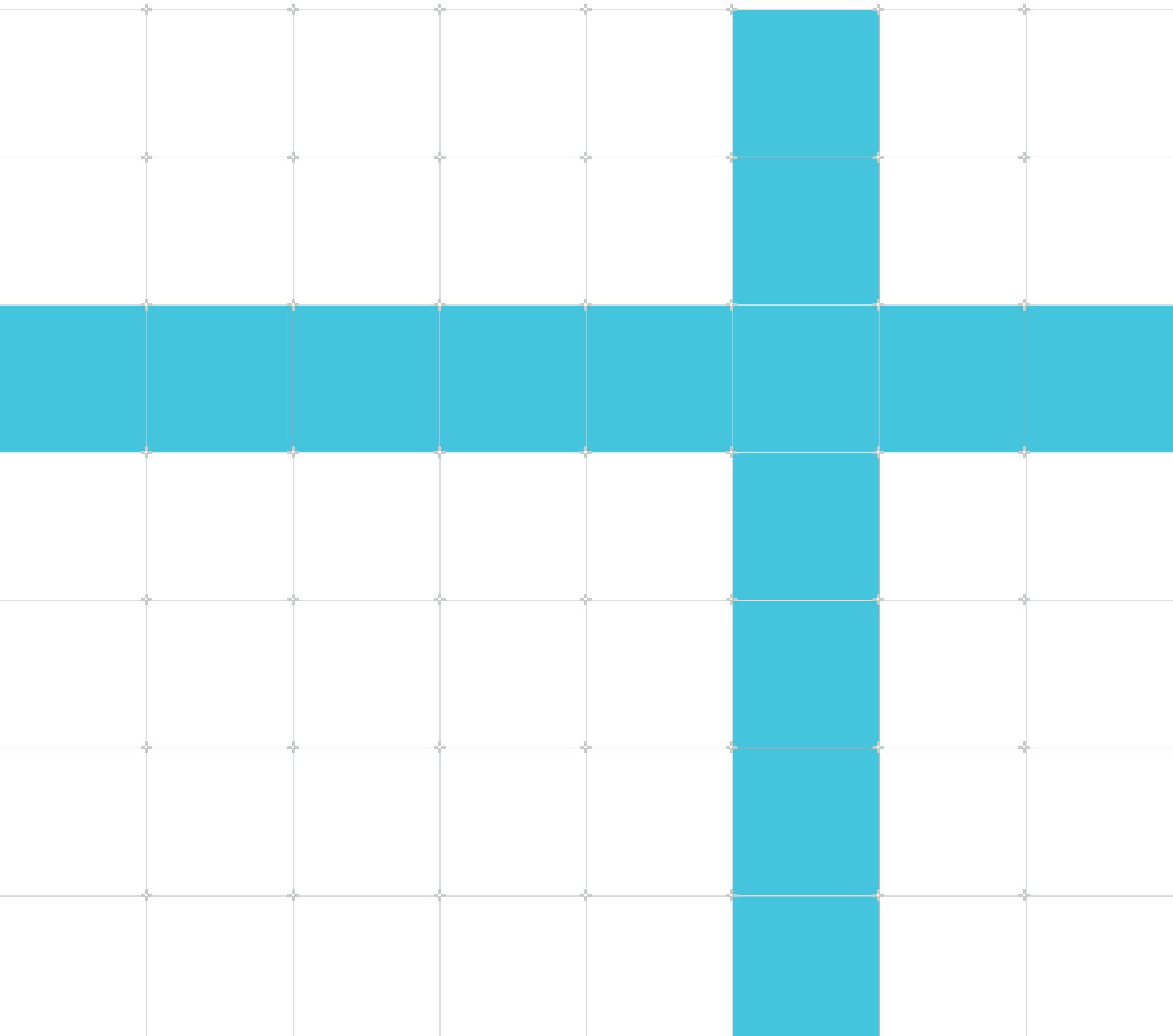

Arm® Compiler for Embedded FuSa

Migration and Compatibility Guide

Release information

Document history

Issue	Date	Confidentiality	Change
062201LTS-01	21 August 2024	Non-Confidential	Arm Compiler for Embedded FuSa 6.22.1 LTS Release.

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Inclusive language commitment

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1. Introduction

The Arm® Compiler Migration and Compatibility Guide provides migration and compatibility information for users moving from older versions of Arm Compiler 6 to Arm Compiler for Embedded FuSa 6.22.1 LTS.

1.1 Conventions

The following subsections describe conventions used in Arm documents.

Glossary

The Arm Glossary is a list of terms used in Arm documentation, together with definitions for those terms. The Arm Glossary does not contain terms that are industry standard unless the Arm meaning differs from the generally accepted meaning.

See the Arm Glossary for more information: developer.arm.com/glossary.

Typographic conventions

Arm documentation uses typographical conventions to convey specific meaning.

Convention	Use
italic	Citations.
bold	Interface elements, such as menu names. Terms in descriptive lists, where appropriate.
`monospace`	Text that you can enter at the keyboard, such as commands, file and program names, and source code.
`monospace underline`	A permitted abbreviation for a command or option. You can enter the underlined text instead of the full command or option name.
`<and>`	Encloses replaceable terms for assembler syntax where they appear in code or code fragments. For example: `MRC p15, 0, <Rd>, <CRn>, <CRm>, <Opcode_2>`
SMALL CAPITALS	Terms that have specific technical meanings as defined in the *Arm® Glossary*. For example, **IMPLEMENTATION DEFINED**, **IMPLEMENTATION SPECIFIC**, **UNKNOWN**, and **UNPREDICTABLE**.

We recommend the following. If you do not follow these recommendations your system might not work.

Your system requires the following. If you do not follow these requirements your system will not work.

You are at risk of causing permanent damage to your system or your equipment, or harming yourself.

This information is important and needs your attention.

A useful tip that might make it easier, better or faster to perform a task.

A reminder of something important that relates to the information you are reading.

1.2 Useful resources

This document contains information that is specific to this product. See the following resources for other useful information.

Access to Arm documents depends on their confidentiality:

- Non-Confidential documents are available at developer.arm.com/documentation. Each document link in the following tables goes to the online version of the document.
- Confidential documents are available to licensees only through the product package.

Arm product resources	Document ID	Confidentiality
Arm Compiler for Embedded FuSa User Guide	109442	Non-Confidential
Arm Compiler for Embedded FuSa Reference Guide	109443	Non-Confidential

Arm product resources	Document ID	Confidentiality
Arm Compiler for Embedded FuSa Arm C and C++ Libraries and Floating-Point Support User Guide	109445	Non-Confidential
Arm Compiler for Embedded FuSa Errors and Warnings Reference Guide	109446	Non-Confidential
Arm Support	-	-
Manage Arm Compiler Versions	-	Non-Confidential
User-based licensing User Guide	102516	Non-Confidential
Complex Math Functions	-	Non-Confidential
Complex Matrix Multiplication	-	Non-Confidential
Complex FFT Functions	-	Non-Confidential

Arm® architecture and specifications	Document ID	Confidentiality
Arm Architecture Reference Manual for A-profile architecture	DDI 0487	Non-Confidential
ARM Architecture Reference Manual ARMv7-A and ARMv7-R edition	DDI 0406	Non-Confidential
C++ ABI for the Arm Architecture	-	Non-Confidential
C++ Application Binary Interface Standard for the Arm 64-bit Architecture	-	Non-Confidential
Addenda to, and Errata in, the ABI for the Arm Architecture	-	Non-Confidential
Whitepaper - Armv8-M Architecture Technical Overview	-	Non-Confidential

Non-Arm resources	Document ID	Organization
GCC	-	https://gcc.gnu.org/onlinedocs/gcc
GNU Binutils	-	https://sourceware.org/binutils
Itanium C++ ABI	-	https://itanium-cxx-abi.github.io/cxx-abi
The Security Implications Of Compiler Optimizations On Cryptography - A Review	-	https://arxiv.org
Using Clang as a Compiler	-	https://clang.llvm.org/docs
Automatic variable initialization	-	https://reviews.llvm.org
How to Use Inline Assembly Language in C Code	-	https://gcc.gnu.org
Constraints for asm Operands	-	https://gcc.gnu.org
Constraint Modifier Characters	-	https://gcc.gnu.org

1.3 Other information

See the Arm website for other relevant information.

- Arm® Developer.

- Arm® Documentation.
- Technical Support.
- Arm® Glossary.

2. Configuration and Support Information

A summary of the support levels for the Arm compilation tools.

2.1 Support level definitions

Arm® Compiler for Embedded FuSa 6 is built on Clang and LLVM technology. Therefore, it has more functionality than the set of product features described in the documentation.

Arm welcomes feedback regarding the use of all Arm Compiler for Embedded FuSa 6 features, and intends to support users to a level that is appropriate for that feature. You can contact support at https://developer.arm.com/support.

The following definitions clarify the levels of support and guarantees on functionality that are expected from these features.

Identification in the documentation

All features that are documented in the Arm Compiler for Embedded FuSa 6 documentation are product features, except where explicitly stated. The limitations of non-product features are explicitly stated.

Product features

Product features are suitable for use in a production environment. The functionality is well-tested, and is expected to be stable across feature and update releases.

- Arm intends to give advance notice of significant functionality changes to product features.
- If you have a support and maintenance contract, Arm provides full support for use of all product features.
- Arm welcomes feedback on product features.
- Any issues with product features that Arm encounters or is made aware of are considered for fixing in future versions of Arm Compiler for Embedded FuSa.

In addition to fully supported product features, some product features are only alpha or beta quality.

Beta product features

Beta product features are implementation complete, but have not been sufficiently tested to be regarded as suitable for use in production environments.

Beta product features are identified with [BETA].

- Arm endeavors to document known limitations on beta product features.
- Beta product features are expected to eventually become product features in a future release of Arm Compiler for Embedded FuSa 6.
- Arm encourages the use of beta product features, and welcomes feedback on them.

- Any issues with beta product features that Arm encounters or is made aware of are considered for fixing in future versions of Arm Compiler for Embedded FuSa.

Alpha product features

Alpha product features are not implementation complete, and are subject to change in future releases, therefore the stability level is lower than in beta product features.

Alpha product features are identified with [ALPHA].

- Arm endeavors to document known limitations of alpha product features.
- Arm encourages the use of alpha product features, and welcomes feedback on them.
- Any issues with alpha product features that Arm encounters or is made aware of are considered for fixing in future versions of Arm Compiler for Embedded FuSa.

Community features

Arm Compiler for Embedded FuSa 6 is built on LLVM technology and preserves the functionality of that technology where possible. This means that there are additional features available in Arm Compiler for Embedded FuSa that are not listed in the documentation. These additional features are known as community features. For information on these community features, see the Clang Compiler User's Manual.

Where community features are referenced in the documentation, they are identified with [COMMUNITY].

- Arm makes no claims about the quality level or the degree of functionality of these features, except when explicitly stated in this documentation.
- Functionality might change significantly between feature releases.
- Arm makes no guarantees that community features are going to remain functional across update releases, although changes are expected to be unlikely.

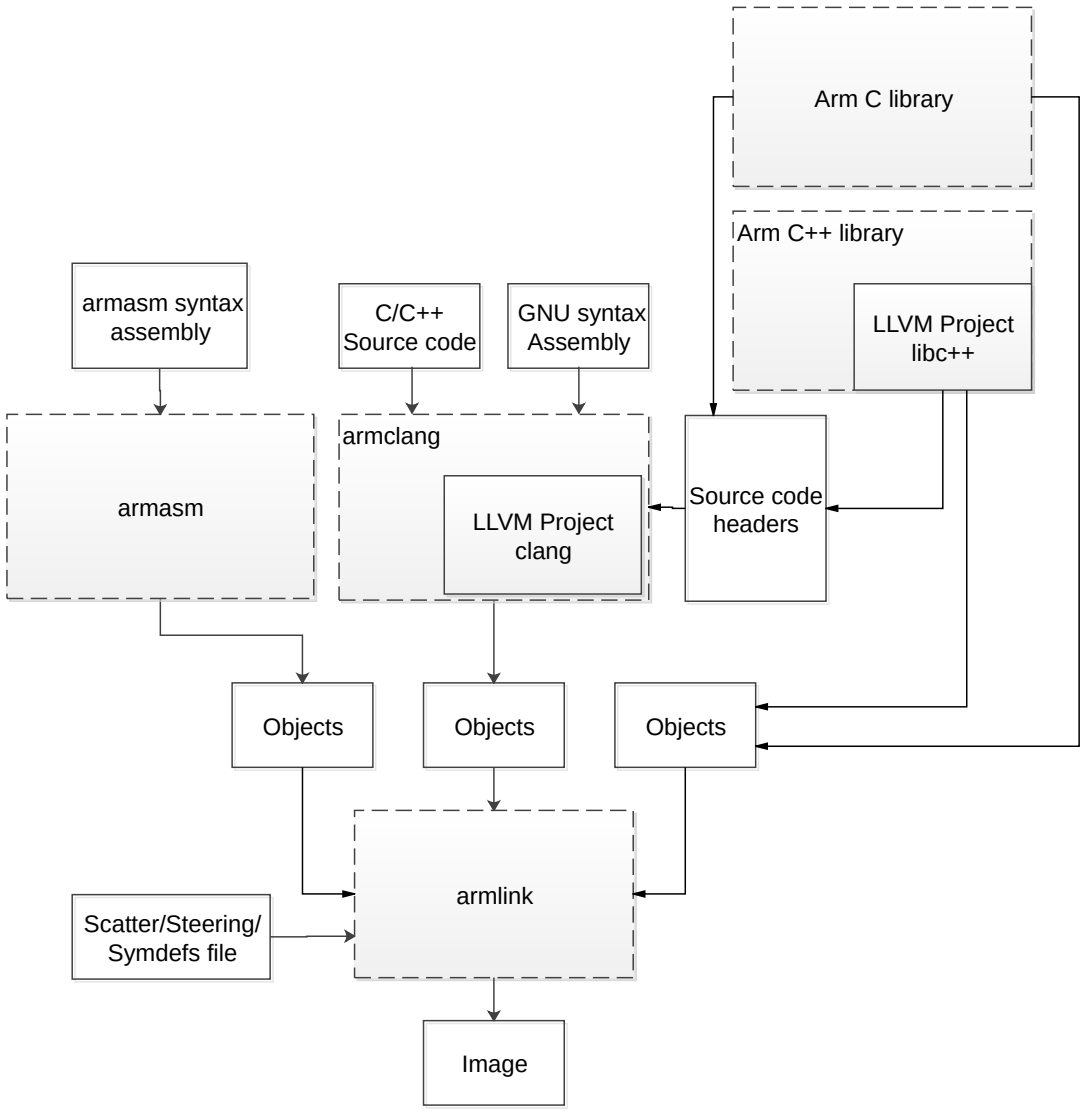
Some community features might become product features in the future, but Arm provides no roadmap for this. Arm is interested in understanding your use of these features, and welcomes feedback on them. Arm supports customers using these features on a best-effort basis, unless the features are unsupported. Arm accepts defect reports on these features, but does not guarantee that these issues are going to be fixed in future releases.

Guidance on use of community features

There are several factors to consider when assessing the likelihood of a community feature being functional:

- The following figure shows the structure of the Arm Compiler for Embedded FuSa 6 toolchain:

Figure 2-1: Integration boundaries in Arm Compiler for Embedded 6.



The dashed boxes are toolchain components, and any interaction between these components is an integration boundary. Community features that span an integration boundary might have significant limitations in functionality. The exception to this is if the interaction is codified in one of the standards supported by Arm Compiler for Embedded FuSa 6. See Application Binary Interface (ABI). Community features that do not span integration boundaries are more likely to work as expected.

- Features primarily used when targeting hosted environments such as Linux or BSD might have significant limitations, or might not be applicable, when targeting bare-metal environments.

- The Clang implementations of compiler features, particularly those that have been present for a long time in other toolchains, are likely to be mature. The functionality of new features, such as support for new language features, is likely to be less mature and therefore more likely to have limited functionality.

Deprecated features

A deprecated feature is one that Arm plans to remove from a future release of Arm Compiler for Embedded FuSa. Arm does not make any guarantee regarding the testing or maintenance of deprecated features. Therefore, Arm does not recommend using a feature after it is deprecated.

For information on replacing deprecated features with supported features, see the Arm Compiler for Embedded FuSa documentation and Release Notes. Where appropriate, each Arm Compiler document includes notes for features that are deprecated, and also provides entries in the changes appendix of that document.

Unsupported features

With both the product and community feature categories, specific features and use cases are known not to function correctly, or are not intended for use with Arm Compiler for Embedded FuSa 6.

Limitations of product features are stated in the documentation. Arm cannot provide an exhaustive list of unsupported features or use cases for community features. The known limitations on community features are listed in Community features.

List of known unsupported features

The following is an incomplete list of unsupported features, and might change over time:

- The Clang option `-stdlib=libstdc++` is not supported.
- `-mabi=aapcs-soft` is not supported for A-profile targets in AArch64 state. The `aapcs-soft` ABI is defined only for Armv8-R AArch64 targets. For more information, see the *Soft-float* section of the Procedure Call Standard for the Arm 64-bit Architecture.
- `-mabi=aapcs-soft` is not supported for C++ source language modes.
- C++ static initialization of local variables is not thread-safe when linked against the standard C++ libraries. For thread-safety, you must provide your own implementation of thread-safe functions as described in Standard C++ library implementation definition.

This restriction does not apply to the [ALPHA]-supported multithreaded C++ libraries.

- Use of C11 library features is unsupported.
- Any community feature that is exclusively related to non-Arm architectures is not supported.
- Except for Armv6-M, compilation for targets that implement architectures lower than Armv7 is not supported.

- The `long double` data type is not supported for AArch64 state because of limitations in the current Arm C library.
- C complex arithmetic is not supported, because of limitations in the current Arm C library.
- Complex numbers are defined in C++ as a template, `std::complex`. Arm Compiler for Embedded FuSa supports `std::complex` with the `float` and `double` types, but not the `long double` type because of limitations in the current Arm C library.

For C code that uses complex numbers, it is not sufficient to recompile with the C++ compiler to make that code work. How you can use complex numbers depends on whether or not you are building for Armv8-M targets.

- You must take care when mixing translation units that are compiled with and without the [COMMUNITY] `-fsigned-char` option, and that share interfaces or data structures.

The Arm ABI defines `char` as an unsigned byte, and this is the interpretation used by the C libraries supplied with the Arm compilation tools.

- There are limitations with the *Control Flow Integrity* (CFI) sanitizer implementation, `-fsanitize=cfi`, which requires *Link-Time Optimization* (LTO), `-flto`. The following are likely to occur:
  - When using features such as C++ I/O streams, the linker might report errors for a rejected local symbol, `L6654E`, or that a symbol is not preserved by the LTO code generation, `L6137E`.
  - The linker might report a diagnostic that a symbol has a size that extends outside of its containing section, `L6783E` or `L6784E`.

    Use the linker option `--diag_suppress 6783` or `--diag_suppress 6784` to suppress the diagnostic.

Alternatives to C complex numbers not being supported

If you are building for Armv8-M targets, consider using the free and open-source CMSIS-DSP library that includes a data type and library functions for complex number support in C. For more information about CMSIS-DSP and complex number support see the following sections of the CMSIS documentation:

- Complex Math Functions
- Complex Matrix Multiplication
- Complex FFT Functions

If you are not building for Armv8-M targets, consider modifying the affected part of your project to use the C++ standard library type `std::complex` instead.

3. Migrating from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6

Provides an overview of the differences between Arm® Compiler 5 and Arm Compiler for Embedded FuSa 6.

3.1 Migration overview

Migrating from Arm® Compiler 5 to Arm Compiler for Embedded FuSa 6 requires the use of new command-line options and might also require changes to existing source files.

Arm Compiler for Embedded FuSa 6 is based on the modern LLVM compiler framework. Arm Compiler 5 is not based on the LLVM compiler framework. Therefore migrating your project and source files from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6 requires you to be aware of:

- Differences in the command-line options when invoking the compiler.
- Differences in the adherence to language standards.
- Differences in compiler specific keywords, attributes, and pragmas.
- Differences in optimization and diagnostic behavior of the compiler.

Even though these differences exist between Arm Compiler 5 and Arm Compiler for Embedded FuSa 6, it is possible to migrate your projects from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6 by modifying your command-line arguments and by changing your source code if required.

Arm Compiler 5 does not support processors based on Armv8 and later architectures. Migrating to Arm Compiler for Embedded FuSa 6 enables you to generate highly efficient code for processors based on Armv8 and later architectures.

Related information

Optimization differences on page 26
Diagnostic messages on page 28
Migration of compiler command-line options from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6 on page 34
Compiler Source Code Compatibility on page 55
Migrating projects from Arm Compiler 5 to Arm Compiler for Embedded 6

3.2 Toolchain differences

Arm® Compiler 5 and Arm Compiler for Embedded FuSa 6 share many of the same compilation tools. However, the main difference between the two toolchains is the compiler tool `armclang`, which is based on Clang and LLVM.

The table lists the individual compilation tools and the toolchain they apply to.

Table 3-1: List of compilation tools

Arm Compiler 5	Arm Compiler for Embedded FuSa 6	Function
`armcc`	`armclang`	Compiles C and C++ language source files, including inline assembly.
`armcc`	`armclang`	Preprocessor.
`armasm`	`armasm`	Legacy assembler for assembly language source files written in `armasm` syntax. Use the `armclang` integrated assembler for all new assembly files.
Not available	`armclang`. This is also called the `armclang` integrated assembler.	Assembles assembly language source files written in GNU assembly syntax.
`fromelf`	`fromelf`	Converts Arm ELF images to binary formats and can also generate textual information about the input image, such as its disassembly and its code and data size.
`armlink`	`armlink`	Combines the contents of one or more object files with selected parts of one or more object libraries to produce an executable program.
`armar`	`armar`	Enables sets of ELF object files to be collected together and maintained in archives or libraries.

Arm Compiler for Embedded FuSa 6 uses the compiler tool `armclang` instead of `armcc`. The command-line options for `armclang` are different to the command-line options for `armcc`. These differences are described in Migration of compiler command-line options from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6.

Arm Compiler for Embedded FuSa 6 includes the legacy assembler `armasm`, which you can use to assemble your older assembly language source files if they are written in `armasm` syntax. Arm recommends that you write new assembly code using the GNU assembly syntax, which you can assemble using the `armclang` integrated assembler. You can also migrate existing assembly language source files from `armasm` syntax to GNU syntax, and then assemble them using the `armclang` integrated assembler. For more information see Migrating from armasm to the armclang Integrated Assembler.

Related information

Migrating projects from Arm Compiler 5 to Arm Compiler for Embedded 6

3.3 Default differences

Some compiler and assembler options are different between Arm® Compiler 5 and Arm Compiler for Embedded FuSa 6, or have different default values.


Note

This topic includes descriptions of [COMMUNITY] features. See Support level definitions.

The following table lists these differences.

Table 3-2: Differences in defaults

Feature	Arm Compiler 5	Arm Compiler for Embedded FuSa 6	Notes	Further information
Symbol visibility	`--hide_all`	`-fvisibility=hidden`	These defaults are similar but `-fvisibility=hidden` does not affect extern declarations or symbol references. In Arm Compiler for Embedded FuSa 6, symbols in the final image are hidden if the reference or the definition is hidden. Therefore the visibility of the reference alone does not determine the visibility of the symbol, as it does in Arm Compiler 5.	--hide_all for Arm Compiler 5 -fvisibility for Arm Compiler for Embedded 6

Feature	Arm Compiler 5	Arm Compiler for Embedded FuSa 6	Notes	Further information
Floating-point linkage	`--apcs=/hardfp` or `--apcs=/softfp`	`-mfloat-abi=softfp`	The default floating-point linkage in Arm Compiler 5 depends on the specified processor. If the processor has floating-point hardware, then Arm Compiler 5 uses hardware floating-point linkage. If the processor does not have floating-point hardware, then Arm Compiler 5 uses software floating-point linkage. In Arm Compiler for Embedded FuSa 6, the default is always software floating-point linkage for AArch32 state. For AArch64 state, Arm Compiler for Embedded FuSa 6 always uses hardware linkage. For AArch32 state, the `-mfloat-abi` option also controls the type of floating-point instructions that the compiler uses: • `-mfloat-abi=softfp` uses hardware floating-point instructions and software floating-point linkage. • `-mfloat-abi=soft` to use software floating-point linkage and software library functions for floating-point operations. • `-mfloat-abi=hard` uses hardware floating-point instructions and hardware floating-point linkage.	--apcs (armcc) for Arm Compiler 5 -mfloat-abi for Arm Compiler for Embedded 6
Default output file	`__image.axf`	`a.out`	Default name for the executable image if none of `-o`, `-c`, `-E`, or `-S` are specified on the command-line.	-o for Arm Compiler 5 -o for Arm Compiler for Embedded 6

Feature	Arm Compiler 5	Arm Compiler for Embedded FuSa 6	Notes	Further information
Enumerator size	`--enum_is_int` is disabled by default	`-fno-short-enums`	`--enum_is_int` is disabled by default in Arm Compiler 5, so the smallest data type that can hold the enumerator values is used. `-fno-short-enums` is the default in Arm Compiler for Embedded FuSa 6, so the size of the enumeration type is at least 32 bits.	--enum_is_int for Arm Compiler 5 -fno-short-enums for Arm Compiler for Embedded 6
Optimization level	`-O2`	`-O0`	Arm Compiler 5 uses high optimization (`-O2`) and optimizes for reduced code size (`-Ospace`) by default, rather than optimizing for performance (`-Otime`). Arm Compiler for Embedded FuSa 6 uses minimum optimization (`-O0`) by default, and the choice of code size versus performance is controlled by the optimization level.	-Onum for Arm Compiler 5 -Ospace for Arm Compiler 5 -Otime for Arm Compiler 5 -Olevel for Arm Compiler for Embedded 6 Optimization differences.
A32/T32 interwork	`--apcs=/nointerwork`	`--apcs=/interwork`	In Arm Compiler 5, `armasm` does not specify by default that code in the input file can safely interwork between A32 and T32. In Arm Compiler for Embedded FuSa 6, `armasm` specifies interworking by default for AArch32 targets that support A32 and T32 instruction sets.	--apcs (armasm) for Arm Compiler 5 --apcs for Arm Compiler for Embedded 6
Default C++ source language mode	C++03	C++17	In Arm Compiler 5, the default C++ source language mode is C++03. In Arm Compiler for Embedded FuSa 6, the default C++ source language mode is C++17. You can override the default source language with `-std` in Arm Compiler for Embedded FuSa 6.	--cpp for Arm Compiler 5 -std for Arm Compiler for Embedded 6

Feature	Arm Compiler 5	Arm Compiler for Embedded FuSa 6	Notes	Further information
Default C source language mode	C90	C11 [COMMUNITY]	In Arm Compiler 5, the default C source language mode is C90. In Arm Compiler for Embedded FuSa 6, the default C source language mode is C11 [COMMUNITY]. You can override the default source language with `-std` in Arm Compiler for Embedded FuSa 6.	--c90 for Arm Compiler 5 -std for Arm Compiler for Embedded 6
Exception handling	`--no_exceptions`	`-fexceptions` or `-fno-exceptions`	In Arm Compiler 5, C++ exceptions are disabled by default (`--no_exceptions`). In Arm Compiler for Embedded FuSa 6, C++ exceptions are enabled by default (`-fexceptions`) for C++ sources, or disabled by default (`-fno-exceptions`) for C sources.	--no_exceptions for Arm Compiler 5 -fexceptions, -fno-exceptions for Arm Compiler for Embedded 6
Wide chars	`--wchar16`	`-fno-short-wchar`	In Arm Compiler 5, the size of `wchar_t` is 2 bytes by default (`--wchar16`). In Arm Compiler for Embedded FuSa 6, the size of `wchar_t` is 4 bytes by default (`-fno-short-wchar`).	--wchar16 for Arm Compiler 5 --fno-short-wchar for Arm Compiler for Embedded 6

Feature	Arm Compiler 5	Arm Compiler for Embedded FuSa 6	Notes	Further information
Section placement	`--split_sections` (is disabled by default)	`-ffunction-sections` (is enabled by default)	In Arm Compiler 5, functions are not put into separate ELF sections by default (`--split_sections` is disabled). In Arm Compiler for Embedded FuSa 6, each function is put into a separate ELF section by default (`-ffunction-sections` is enabled). Although each function is located in a separate section its associated debug information is not. As a result, when functions are optimized out, the debug information is still part of the executable and might show incorrect debug information. To resolve this situation, use the `armlink` option `--dangling-debug-address`.	--split_sections for Arm Compiler 5 --ffunction-sections for Arm Compiler for Embedded 6 -dangling-debug-address=address for Arm Compiler 6 Dealing with leftover debug data for code and data removed by armlink for Arm Compiler 6

3.4 Optimization differences

Arm® Compiler for Embedded FuSa 6 provides more performance optimization settings than are present in Arm Compiler 5. However, the optimizations that are performed at each optimization level might differ between the two toolchains.

The table compares the optimization settings and functions in Arm Compiler 5 and Arm Compiler for Embedded FuSa 6.

Table 3-3: Optimization settings

Description	Arm Compiler 5	Arm Compiler for Embedded FuSa 6	Notes
Optimization levels for performance.	• `-Otime -O0` • `-Otime -O1` • `-Otime -O2` • `-Otime -O3`	• `-O0` • `-O1` • `-O2` • `-O3` • `-Ofast` • `-Omax`	The Arm Compiler 5 `-O0` option is more similar to the Arm Compiler for Embedded FuSa 6 `-O1` option than the Arm Compiler for Embedded FuSa 6 `-O0` option. The Arm Compiler for Embedded FuSa 6 `-Omax` option refers to maximum performance, with Link-Time Optimization (LTO) enabled.
Optimization levels for code size.	• `-Ospace -O0` • `-Ospace -O1` • `-Ospace -O2` • `-Ospace -O3`	• `-Os` • `-Oz` • `-Omin`	The Arm Compiler 5 `-O0` option is more similar to the Arm Compiler for Embedded FuSa 6 `-O1` option than the Arm Compiler for Embedded FuSa 6 `-O0` option. The Arm Compiler for Embedded FuSa 6 `-Omin` option refers to minimum code size, with Link-Time Optimization (LTO) enabled..
Default.	`-Ospace -O2`	`-O0`	-
Best trade-off between image size, performance, and debug.	`-Ospace -O2`	`-O1`	-
Highest optimization for performance.	`-Otime -O3`	• `-Omax` • `-Ofast`	The `-Omax` option uses Link-Time Optimization (LTO). If LTO is not appropriate for you, use `-Ofast`.
Highest optimization for code size.	`-Ospace -O3`	• `-Omin` • `-Oz`	The `-Omin` option uses Link-Time Optimization (LTO). If LTO is not appropriate for you, use `-Oz`.

Arm Compiler for Embedded FuSa 6 provides an aggressive performance optimization option, `-Omax`, which automatically enables a feature called Link-Time Optimization. For more information, see -flto.

At the opposite end of the spectrum, the `-Omin` option in Arm Compiler for Embedded FuSa 6 is an aggressive code size optimization setting. This also enables Link-Time Optimization and aggressively removes unused code and data.

When using `-Omax` or `-Omin` , `armclang` can perform link-time optimizations that were not possible in Arm Compiler 5. In some cases these link-time optimizations can expose latent bugs in a program, which manifest as an image with different or unanticapted behavior. Therefore, an image built with Arm Compiler 5 might have a different behavior to the image built with Arm Compiler for Embedded FuSa 6.

For example, unused variables without the `volatile` keyword might be removed when using `-Omax` or `-Omin` in Arm Compiler for Embedded FuSa 6. If the unused variable is actually a `volatile` variable that requires the `volatile` keyword, then the removal of the variable can cause the generated image to behave unexpectedly. Since Arm Compiler 5 does not have these aggressive optimization settings, it might not have removed the unused variable, and the resulting image might behave as expected, and therefore the error in the code would be more difficult to detect.

Related information

-flto armclang option
-O armclang option
Effect of the volatile keyword on compiler optimization
Optimizing across modules with Link-Time Optimization

3.5 Backwards compatibility issues

Some Arm® Compiler 5 options produce objects that are not compatible with Arm Compiler for Embedded FuSa 6.

SHF_COMDEF ELF sections

Linking with legacy objects that contain ELF sections with the legacy `SHF_COMDEF` ELF section flag is deprecated. Use the `GRP_COMDAT` ELF section group instead of the legacy `SHF_COMDEF` ELF section flag by:

- Replacing the `COMDEF` section attribute of the legacy armasm syntax `AREA` directive with the `COMGROUP=<symbol_name>` section attribute.
- Rebuilding incompatible legacy objects using one of the following:
  - Arm Compiler 5 but with the `--dwarf3` option. Other incompatibilities might still exist.
  - Arm Compiler for Embedded FuSa 6.

Related information

AREA directive
--dwarf3

3.6 Diagnostic messages

In general, `armclang` provides more precise and detailed diagnostic messages compared to `armcc`. Therefore you can expect to see more information about your code when using Arm® Compiler for Embedded FuSa 6, which can help you understand and fix your source more quickly.

`armclang` and `armcc` differ in the quality of diagnostic information they provide about your code. The following sections demonstrate some of the differences.

Assignment in condition

The following code is an example of `armclang` providing more precise information about your code. The error in this example is that the assignment operator, `=`, must be changed to the equality operator, `==`.

```
//main.cpp:

#include <stdio.h>

int main()
{
  int a = 0, b = 0;
  if (a = b)
  {
    printf("Right\n");
  }
  else
  {
    printf("Wrong\n");
  }
  return 0;
}
```

Compiling this example with Arm Compiler 5 gives the message:

```
"main.cpp", line 6: Warning: #1293-D: assignment in condition

if (a = b)
    ^
```

Compiling this example with Arm Compiler for Embedded FuSa 6 gives the message:

```
main.cpp:6:7: warning: using the result of an assignment as a condition without
 parentheses[-Wparentheses]

 if (a = b)
      ~^~

main.cpp:6:7: note: place parentheses around the assignment to silence this warning
 if (a = b)
       ^
      (   )

main.cpp:6:7: note: use '==' to turn this assignment into an equality comparison
 if (a = b)
       ^
       ==
```

`armclang` highlights the error in the code, and also suggests two different ways to resolve the error. The warning messages highlight the specific part which requires attention from the user.


Note

When using `armclang`, it is possible to enable or disable specific warning messages. In the example above, you can enable this warning message using the `-Wparentheses` option, or disable it using the `-Wno-parentheses` option.

Automatic macro expansion

Another very useful feature of diagnostic messages in Arm Compiler for Embedded FuSa 6, is the inclusion of notes about macro expansion. These notes provide useful context to help you understand diagnostic messages resulting from automatic macro expansion.

Consider the following code:

```
//main.cpp:

#include <stdio.h>

#define LOG(PREFIX, MESSAGE) fprintf(stderr, "%s: %s", PREFIX, MESSAGE)
#define LOG_WARNING(MESSAGE) LOG("Warning", MESSAGE)

int main(void)
{
    LOG_WARNING(123);
}
```

The macro `LOG_WARNING` has been called with an integer argument. However, expanding the two macros, you can see that the `fprintf` function expects a string. When the macros are close together in the code it is easy to spot these errors. These errors are not easy to spot if they are defined in different part of the source code, or in other external libraries.

Compiling this example with Arm Compiler 5 `armcc main.cpp` reports the message:

```
main.cpp", line 8: Warning:  #181-D: argument is incompatible with corresponding
 format string conversion

      LOG_WARNING(123);
      ^
```

Compiling this example with Arm Compiler for Embedded FuSa 6 `armclang --target=arm-arm-none-eabi -march=armv8-a` reports the message:

```
main.cpp:8:14: warning: format specifies type 'char *' but the argument has type
 'int' [-Wformat]

 LOG_WARNING(123);
 ~~~~~~~~~~~~^~~

main.cpp:4:45: note: expanded from macro 'LOG_WARNING'
#define LOG_WARNING(MESSAGE) LOG("Warning", MESSAGE)
                             ~~~~~~~~~~~~~~~^~~~~~~

main.cpp:3:64: note: expanded from macro 'LOG'
#define LOG(PREFIX, MESSAGE) fprintf(stderr, "%s: %s", PREFIX, MESSAGE)
                                                       ~~           ^~~~~~~
```

For more information, see Diagnostics for pragma compatibility.


Note

When starting the migration from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6, you can expect additional diagnostic messages because `armclang` does not recognize some of the pragmas, keywords, and attributes that were specific to `armcc`. When you replace the pragmas, keywords, and attributes from Arm Compiler 5 with their Arm Compiler for Embedded FuSa 6 equivalents, the majority of these diagnostic messages disappear. You might require additional code changes if there is no direct equivalent for Arm Compiler for Embedded FuSa 6. For more information see Compiler Source Code Compatibility.

3.7 Migration example

This topic shows you the process of migrating an example code from Arm® Compiler 5 to Arm Compiler for Embedded FuSa 6.


Note

This topic includes descriptions of [COMMUNITY] features. See Support level definitions.

Compiling with Arm Compiler 5

For an example startup code that builds with Arm Compiler 5, see Example startup code for Arm Compiler 5 project.

To compile this example with Arm Compiler 5, enter:

```
armcc startup_ac5.c --cpu=7-A -c
```

This command generates a compiled object file for the Armv7-A architecture.

Compiling with Arm Compiler for Embedded FuSa 6

Try to compile the `startup_ac5.c` example with Arm Compiler for Embedded FuSa 6. The first step in the migration is to use the new compiler tool, `armclang` , and use the correct command-line options for `armclang`.

To compile this example with Arm Compiler for Embedded FuSa 6, enter:

```
armclang --target=arm-arm-none-eabi startup_ac5.c -march=armv7-a -c -O1 -std=c90
```

The following table shows the differences in the command-line options between Arm Compiler 5 and Arm Compiler for Embedded FuSa 6:

Table 3-4: Command-line changes

Description	Arm Compiler 5	Arm Compiler for Embedded FuSa 6
Tool	`armcc`	`armclang`
Specifying an architecture	`--cpu=7-A`	• `-march=armv7-a` • `--target` is a mandatory option for `armclang`. To generate A64 instructions for AArch64 state, specify `--target=aarch64-arm-none-eabi`. To generate A32 / T32 instructions for AArch32 state, specify `--target=arm-arm-none-eabi` (you must also specify `-mthumb` for T32 instructions). Specify either an architecture (`-march`) or processor (`-mcpu`), but not both.
Optimization	The default optimization is `-O2`.	The default optimization is `-O0`. To get similar optimizations as the Arm Compiler 5 default, use `-O1`.
Source language mode	The default source language mode for `.c` files is `c90`.	The default source language mode for `.c` files is `gnu11` [COMMUNITY]. To compile for `c90` in Arm Compiler for Embedded FuSa 6, use `-std=c90`.

Arm Compiler for Embedded FuSa 6 generates the following errors and warnings when trying to compile the example `startup_ac5.c` file in `c90` mode:

```
startup_ac5.c:39:22: error: 'main' must return 'int'

__declspec(noreturn) void main (void)
                     ^~~~
                     int
startup_ac5.c:45:9: error: '#pragma import' is an ARM Compiler 5 extension, and is
 not supported by ARM Compiler 6 [-Warmcc-pragma-import]
#pragma import (__use_no_semihosting)
        ^
startup_ac5.c:60:7: error: expected '(' after 'asm'
__asm void Vectors(void) {
      ^
startup_ac5.c:60:6: error: expected ';' after top-level asm block
__asm void Vectors(void) {
     ^
      ;
startup_ac5.c:61:3: error: use of undeclared identifier 'IMPORT'
  IMPORT Undef_Handler
  ^
startup_ac5.c:80:7: error: expected '(' after 'asm'
__asm void Reset_Handler(void) {
      ^
startup_ac5.c:80:6: error: expected ';' after top-level asm block
__asm void Reset_Handler(void) {
     ^
      ;
startup_ac5.c:83:3: error: use of undeclared identifier 'CPSID'
  CPSID   if
  ^
8 errors generated.
```

The following section describes how to modify the source file to fix these errors and warnings.

Modifying the source code for Arm Compiler for Embedded FuSa 6

You must make the following changes to the source code to compile with `armclang`.

- The return type of function `main` function cannot be void in standard C. Replace the following line:

  ```
  __declspec(noreturn) void main(void)
  ```

  With:

  ```
  __declspec(noreturn) int main(void)
  ```

- The intrinsic `__enable_irq()` is not supported in Arm Compiler for Embedded FuSa 6. You must replace the intrinsic with an inline assembler equivalent. Replace the following line:

  ```
  __enable_irq();
  ```

  With:

  ```
  __asm("CPSIE i");
  ```

- The `#pragma import` is not supported in Arm Compiler for Embedded FuSa 6. You must replace the pragma with an equivalent directive using inline assembler. Replace the following line:

  ```
  #pragma import(__use_no_semihosting)
  ```

  With:

  ```
  __asm(".global __use_no_semihosting");
  ```

- In certain situations, `armclang` might remove infinite loops that do not have side-effects. You must use the `volatile` keyword to tell `armclang` not to remove such code. Replace the following line:

  ```
  while(1);
  ```

  With:

  ```
  while(1) __asm volatile("");
  ```

4. Migrating from armcc to armclang

Compares Arm® Compiler for Embedded FuSa 6 command-line options to older versions of Arm Compiler.

4.1 Migration of compiler command-line options from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6

Arm® Compiler for Embedded FuSa 6 provides many command-line options, including most Clang command-line options and several Arm-specific options.

This topic includes descriptions of [COMMUNITY] features. See Support level definitions.

The following table describes the most common Arm Compiler 5 command-line options, and shows the equivalent options for Arm Compiler for Embedded FuSa 6.

More information about command-line options is available:

- The *Arm Compiler for Embedded FuSa Reference Guide* provides more information about the supported command-line options. The options described are fully supported, unless the level of support is indicated.
- For a full list of Clang command-line options, see the Clang and LLVM documentation.

Table 4-1: Comparison of compiler command-line options in Arm Compiler 5 and Arm Compiler for Embedded FuSa 6

Arm Compiler 5 option	Arm Compiler for Embedded FuSa 6 option	Description
`--allow_fpreg_for_nonfpdata`, `--no_allow_fpreg_for_nonfpdata`	`-mimplicit-float`, `-mno-implicit-float` [COMMUNITY]	Enables or disables the use of VFP and SIMD registers and data transfer instructions for non-VFP and non-SIMD data.
`--apcs=/nointerwork`	No equivalent.	Disables interworking between A32 and T32 code. Interworking is always enabled in Arm Compiler for Embedded FuSa 6.

`--apcs=/ropi`
 	
`--apcs=/noropi`
	`-fropi`
	
	`-fno-ropi`
		Enables or disables the generation of *Read-Only Position Independent* (ROPI) code.

`--apcs=/rwpi`
 	
`--apcs=/norwpi`
	`-frwpi`
	
	`-fno-rwpi`
		Enables or disables the generation of *Read/Write Position Independent* (RWPI) code.

`--arm`	`-marm`	Targets the A32 instruction set. The compiler is permitted to generate both A32 and T32 code, but recognizes that A32 code is preferred.

Arm Compiler 5 option	Arm Compiler for Embedded FuSa 6 option	Description
`--arm_only`	`No equivalent.`	Enforces A32 instructions only. The compiler does not generate T32 instructions.
`--asm`	`-save-temps`	Instructs the compiler to generate intermediate assembly files as well as object files.
`--bigend`	`-mbig-endian`	Generates code for big-endian data.
`--branch_tables`, `--no_branch_tables`	No equivalent.	`-fno-jump-tables` is the closest option [COMMUNITY]
`-c`	`-c`	Performs the compilation step, but not the link step.
`--c90`	`-xc -std=c90`	Enables the compilation of C90 source code. `-xc` is a positional argument and only affects subsequent input files on the command-line. It is also only required if the input files do not have the appropriate file extension.
`--c90 --gnu`	`-xc -std=gnu90`	Enables the compilation of C90 source code with additional GNU extensions. `-xc` is a positional argument and only affects subsequent input files on the command-line. It is also only required if the input files do not have the appropriate file extension.
`--c99`	`-xc -std=c99`	Enables the compilation of C99 source code. `-xc` is a positional argument and only affects subsequent input files on the command-line. It is also only required if the input files do not have the appropriate file extension.
`--c99 --gnu`	`-xc -std=gnu99`	Enables the compilation of C99 source code with additional GNU extensions. `-xc` is a positional argument and only affects subsequent input files on the command-line. It is also only required if the input files do not have the appropriate file extension.
`--cpp`	`-xc++ -std=c++03`	Enables the compilation of C++03 source code. `-xc++` is a positional argument and only affects subsequent input files on the command-line. It is also only required if the input files do not have the appropriate file extension. The default C++ language standard is different between Arm Compiler 5 and Arm Compiler for Embedded FuSa 6.

Arm Compiler 5 option	Arm Compiler for Embedded FuSa 6 option	Description
`--cpp --gnu`	`-xc++ -std=gnu++03`	Enables the compilation of C++03 source code with additional GNU extensions. `-xc++` is a positional argument and only affects subsequent input files on the command-line. It is also only required if the input files do not have the appropriate file extension. The default C++ language standard is different between Arm Compiler 5 and Arm Compiler for Embedded FuSa 6.
`--cpp11`	`-xc++ -std=c++11`	Enables the compilation of C++11 source code. `-xc++` is a positional argument and only affects subsequent input files on the command-line. It is also only required if the input files do not have the appropriate file extension. The default C++ language standard is different between Arm Compiler 5 and Arm Compiler for Embedded FuSa 6.
`--cpp11 --gnu`	`-xc++ -std=gnu++11`	Enables the compilation of C++11 source code with additional GNU extensions. `-xc++` is a positional argument and only affects subsequent input files on the command-line. It is also only required if the input files do not have the appropriate file extension. The default C++ language standard is different between Arm Compiler 5 and Arm Compiler for Embedded FuSa 6.
`--cpp_compat`	No equivalent.	Compiles C++ code to maximize binary compatibility.
`--cpu=8-A.32`	`--target=arm-arm-none-eabi -march=armv8-a`	Targets Armv8-A and AArch32 state.
`--cpu 8-A.64`	`--target=aarch64-arm-none-eabi`	Targets Armv8-A and AArch64 state. (Implies `-march=armv8-a` if `-mcpu` is not specified.)
`--cpu=7-A`	`--target=arm-arm-none-eabi -march=armv7-a`	Targets the Armv7-A architecture.
`--cpu=Cortex-M4`	`--target=arm-arm-none-eabi -mcpu=cortex-m4`	Targets the Cortex® -M4 processor.
`--cpu=Cortex-A15`	`--target=arm-arm-none-eabi -mcpu=cortex-a15`	Targets the Cortex -A15 processor.
`-D`	`-D`	Defines a preprocessing macro.
`--depend`	`-MF`	Specifies a filename for the makefile dependency rules.
`--depend_dir`	No equivalent. Use `-MF` to specify each dependency file individually.	Specifies the directory for dependency output files.

Arm Compiler 5 option	Arm Compiler for Embedded FuSa 6 option	Description
`--depend_format=unix_escaped`	-	Dependency file entries use UNIX-style path separators and escapes spaces with `\\`. This is the default in Arm Compiler for Embedded FuSa 6.
`--depend_system_headers`, `--no_depend_system_headers`	No direct equivalent to the standalone command-line option. However, see the Arm Compiler 5 entries in this table for `--md`, `--md --no_depend_system_headers`, and `--mm`.	Enables and disables the output of system include dependency lines when generating makefile dependency information using either the `-M` option or the `--md` option.
`--depend_target`	`-MT`	Changes the target name for the makefile dependency rule.
`--diag_error`	`-Werror`	Turn compiler warnings into errors.
`--diag_style=<string>`	No equivalent.	`armclang` produces diagnostic messages in the following format: `<source-file>:<line-number>:<char-number>: <description> [<diagnostic-flag>]`
`--diag_suppress=<code>`	`-Wno-<flag>`	Suppress warning message `<flag>`. The error or warning codes might be different between Arm Compiler 5 and Arm Compiler for Embedded FuSa 6.

`--dollar`
 	
`--no_dollar`
	`-Wno-dollar-in-identifier-extension`
	
	`-Werror=dollar-in-identifier-extension`
		Disable or enable error messages if the dollar character `$` is used in identifiers. By default Arm Compiler for Embedded FuSa 6 does not give an error if `$` is used. However, if you are using the `-pedantic-errors` option, this generates an error if `$` is used. In this case, use both the `-pedantic-errors` and `-Wno-dollar-in-identifier-extension` options to suppress the error. If you are not using the `-pedantic-errors` option, use `-Werror=dollar-in-identifier-extension` to generate errors.

`-E`	`-E`	Executes only the preprocessor step.
`--enum_is_int`	`-fno-short-enums`, `-fshort-enums`	Sets the minimum size of an enumeration type. By default Arm Compiler 5 does not set a minimum size. By default Arm Compiler for Embedded FuSa 6 uses `-fno-short-enums` to set the minimum size to 32-bit.
`--float_literal_pools`, `--no_float_literal_pools`	No equivalent.	The way that literals are merged is handled differently in Arm Compiler for Embedded FuSa 6 compared to Arm Compiler 5. For more information, see Literal pool options in armclang.
`--forceline`	No equivalent.	Forces aggressive inlining of functions. Arm Compiler for Embedded FuSa 6 automatically decides whether to inline functions depending on the optimization level.
`--fpmode=std`	`-ffp-mode=std`	Provides IEEE-compliant code with no IEEE exceptions, NaNs, and Infinities. Denormals are sign preserving. This is the default.

Arm Compiler 5 option	Arm Compiler for Embedded FuSa 6 option	Description
`--fpmode=fast`	`-ffp-mode=fast`	Similar to the default behavior, but also performs aggressive floating-point optimizations and therefore it is not IEEE-compliant.
`--fpmode=ieee_full`	`-ffp-mode=full`	Provides full IEEE support, including exceptions.

`--fpmode=ieee_fixed`
 	
`--fpmode=ieee_no_fenv`
	There are no supported equivalent options.	There might be community features that provide these IEEE floating-point modes.

`--fpu` For example, `--fpu=fpv5_d16`	`-mfpu` For example, `-mfpu=fpv5-d16`	Specifies the target FPU architecture. **Note:** `--fpu=none` checks the source code for floating-point operations, and if any are found it produces an error. `-mfpu=none` prevents the compiler from using hardware-based floating-point functions. If the compiler encounters floating-point types in the source code, it uses software-based floating-point library functions. The option values might be different. For example `fpv5_d16` in Arm Compiler 5 is equivalent to `fpv5-d16` in Arm Compiler for Embedded FuSa 6, and targets the FPv5-D16 floating-point extension.
`--global_reg=<reg_name>`	`-ffixed-r<N>`	Prevents the compiler from using the specified core register, unless the use is required for Arm ABI compliance. In Arm Compiler 5, `<reg_name>` is an integer starting from `1` to `8` , which maps to registers R4 to R11. In Arm Compiler for Embedded FuSa 6, `<N>` is an integer starting from `6` to `11`, which maps to registers R6 to R11.
`--gnu_instrument`, `--no_gnu_instrument`	`-finstrument-functions` [COMMUNITY]	Inserts instrumentation calls for profiling entry and exit to functions.
`-I`	`-I`	Adds the specified directories to the list of places that are searched to find included files.
`--ignore_missing_headers`	`-MG`	Prints dependency lines for header files even if the header files are missing.
`--inline`	Default at all optimization levels except `-O0`.	There is no equivalent of the `--inline` option. Arm Compiler for Embedded FuSa 6 automatically decides whether to inline functions at all optimization levels except at `-O0`. However, the threshold at which the compiler decides to inline depends on the level.
`--integer_literal_pools`, `--no_integer_literal_pools`	No equivalent.	The way that literals are merged is handled differently in Arm Compiler for Embedded FuSa 6 compared to Arm Compiler 5. For more information, see Literal pool options in armclang.
`-J`	`-isystem`	Adds the specified directories to the list of places that are searched to find included system header files.

Arm Compiler 5 option	Arm Compiler for Embedded FuSa 6 option	Description
`-L`	`-Xlinker`	Specifies command-line options to pass to the linker when a link step is being performed after compilation.
`--library_interface=armcc`	This is the default.	Arm Compiler for Embedded FuSa 6 by default uses the Arm standard C library.
`--library_interface=<lib>` Where `<lib>` is one of: • `aeabi_clib` • `aeabi_clib90` • `aeabi_clib99`	`-nostdlib -nostdlibinc -fno-builtin`	Specifies that the compiler output works with any ISO C library compliant with the Arm Embedded Application Binary Interface (AEABI).
`--library_interface=<lib>` Where `<lib>` is not one of: • `aeabi_clib` • `aeabi_clib90` • `aeabi_clib99` • `armcc`	No equivalent.	Arm Compiler for Embedded FuSa 6 assumes the use of an AEABI compliant library.
`--licretry`	No equivalent.	There is no equivalent of the `--licretry` option. The Arm Compiler for Embedded FuSa 6 tools automatically retry failed attempts to obtain a license.
`--list_macros`	`-E -dM`	List all the macros that are defined at the end of the translation unit, including the predefined macros.
`--littleend`	`-mlittle-endian`	Generates code for little-endian data.
`--lower_ropi`, `--no_lower_ropi`	`-fropi-lowering`, `-fno-ropi-lowering`	Enables or disables less restrictive C when generating *Read-Only Position Independent* (ROPI) code. **Note:** In Arm Compiler 5, when `--acps=/ropi` is specified, `--lower_ropi` is not switched on by default. In Arm Compiler for Embedded FuSa 6, when `-fropi` is specified, `-fropi-lowering` is switched on by default.
`--lower_rwpi`, `--no_lower_rwpi`	`-frwpi-lowering`, `-fno-rwpi-lowering`	Enables or disables less restrictive C when generating *Read/Write Position Independent* (RWPI) code.
`-M`	`-M`	Instructs the compiler to produce a list of makefile dependency lines suitable for use by a make utility.
`--md`	`-MD`	Creates makefile dependency files, including the system header files. In Arm Compiler 5, this is equivalent to `--md --depend_system_headers`.
`--md --no_depend_system_headers`	`-MMD`	Creates makefile dependency files, without the system header files.
`--mm`	`-MM`	Creates a single makefile dependency file, without the system header files. In Arm Compiler 5, this is equivalent to `-M --no_depend_system_headers`.

Arm Compiler 5 option	Arm Compiler for Embedded FuSa 6 option	Description
`--multifile`, `--no_multifile`	No direct equivalent. However, see Optimizing across modules with Link-Time Optimization in the *Arm Compiler for Embedded FuSa User Guide*.	Enables and disables optimizations between multiple source files.
`--no_comment_section`	`-fno-ident`	Removes the `.comment` section from object files.
`--no_exceptions`	`-fno-exceptions`	Disables the generation of code needed to support C ++ exceptions. **Note:** For C++ code, Arm Compiler for Embedded FuSa 6 defaults to `-fexceptions`. As a result, there might be a large increase in the code size. If you use `-fno_exceptions`, then the code size is in the range of that created with Arm Compiler 5.
`--no_hide_all`	`-fvisibility=default`	Sets the default visibility of ELF symbols to the specified option, unless overridden in the source with the `__attribute__ ((visibility("<visibility_type>")))` attribute. The default is `-fvisibility=hidden`. **Note:** The behavior of the `armclang` option `-fvisibility=hidden` is different from that of the `armcc` option `--hide-all`. With the `armclang` option `-fvisibility=hidden`, `extern` declarations are visible, and all other symbols are hidden. With the `armcc` option `--hide-all`, all symbols are hidden.
`--no_protect_stack`	`-fno-stack-protector`	Explicitly disables stack protection. For more information, see Arm Compiler 5 and Arm Compiler for Embedded FuSa 6 stack protection behavior.
`-rtti`	`-frtti`	C++ only. `-frtti` enables the generation of code that is needed to support *Run-Time Type Information* (RTTI) features. This option is the default when compiling for C++. See -frtti, -fno-rtti
`-no_rtti`	`-fno-rtti`	C++ only. `-fno-rtti` disables the generation of code that is needed to support RTTI features. See -frtti, -fno-rtti
`-o`	`-o`	Specifies the name of the output file.

Arm Compiler 5 option	Arm Compiler for Embedded FuSa 6 option	Description
`-O<num>`	`-O<num>`	Specifies the level of optimization to be used when compiling source files. The default for Arm Compiler 5 is `-O2`. The default for Arm Compiler for Embedded FuSa 6 is `-O0`. For Arm Compiler for Embedded FuSa 6, Arm recommends `-O1` rather than `-O0` for best trade-off between debug view, codesize, and performance. For more information, see Optimization differences.
`-Ospace`	`-Oz /-Os`	Performs optimizations to reduce image size at the expense of a possible increase in execution time.
`-Otime`	This is the default.	Performs optimizations to reduce execution time at the expense of a possible increase in image size. There is no equivalent of the `-Otime` option. Arm Compiler for Embedded FuSa 6 optimizes for execution time by default, unless you specify the `-Os` or `-Oz` options.
`--phony_targets`	`-MP`	Emits dummy makefile rules.
`--preinclude`	`-include`	Include the source code of a specified file at the beginning of the compilation.
`--protect_stack`	`-fstack-protector`, `-fstack-protector-strong`	Enables stack protection on vulnerable functions. For more information, see Arm Compiler 5 and Arm Compiler for Embedded FuSa 6 stack protection behavior.
`--protect_stack_all`	`-fstack-protector-all`	Enables stack protection on all functions. For more information, see Arm Compiler 5 and Arm Compiler for Embedded FuSa 6 stack protection behavior.
`--relaxed_ref_def`	`-fcommon`	Places zero-initialized definitions in a common block.
`--retain`	`-O`	The optimization level to use for the best code coverage might depend on your source code. In Arm Compiler 5 the `--retain` option disables specific optimizations by name. There is no direct equivalent of this for Arm Compiler for Embedded FuSa 6. Instead you will need to select the optimization level which best suits your needs. For more information, see -O in the *Arm Compiler for Embedded FuSa Reference Guide*.
`-S`	`-S`	Outputs the disassembly of the machine code that the compiler generates. The output from this option differs between releases. Arm Compiler 5 produces output with `armasm` syntax while Arm Compiler for Embedded FuSa 6 produces output with GNU syntax.
`--show_cmdline`	`-v`	Shows how the compiler processes the command-line. The commands are shown normalized, and the contents of any via files are expanded.

Arm Compiler 5 option	Arm Compiler for Embedded FuSa 6 option	Description
`--split_ldm`	`-fno-ldm-stm`	Disables the generation of `LDM` and `STM` instructions. **Note:** While the `armcc` option `--split_ldm` limits the size of generated LDM/STM instructions, the `armclang` option `-fno-ldm-stm` disables the generation of `LDM` and `STM` instructions altogether.
`--split_sections`	`-ffunction-sections`	Generates one ELF section for each function in the source file. In Arm Compiler for Embedded FuSa 6, `-ffunction-sections` is the default. Therefore, the merging of identical constants cannot be done by `armclang`. Instead, the merging is done by `armlink`. For more information, see Merging identical constants in the *Arm Compiler for Embedded FuSa Reference Guide*.
`--strict`	`-pedantic-errors`	Generate errors if code violates strict ISO C and ISO C++.
`--strict_warnings`	`-pedantic`	Generate warnings if code violates strict ISO C and ISO C++.
`--string_literal_pools`, `--no_string_literal_pools`	No equivalent.	The way that literals are merged is handled differently in Arm Compiler for Embedded FuSa 6 compared to Arm Compiler 5. For more information, see Literal pool options in armclang.
`--thumb`	`-mthumb`	Targets the T32 instruction set.
`--no_unaligned_access`, `--unaligned_access`	`-mno-unaligned-access`, `-munaligned-access`	Enables or disables unaligned accesses to data on Arm processors.
`--use_frame_pointer`, `--no_use_frame_pointer`	`-fno-omit-frame-pointer`, `-fomit-frame-pointer`	Controls whether a register is reserved for storing the stack frame pointer.

`--vectorize`
 	
`--no_vectorize`
	`-fvectorize`
	
	`-fno-vectorize`
		Enables or disables the generation of Advanced SIMD vector instructions directly from C or C++ code.

`--via`	`@file`	Reads an additional list of compiler options from a file.
`--vla`	No equivalent.	Support for variable length arrays. Arm Compiler for Embedded FuSa 6 automatically supports variable length arrays in accordance with the language standard.
`--vsn`	`--version`	Displays version information and license details. In Arm Compiler for Embedded FuSa 6 you can also use `--vsn`.
`--wchar16`, `--wchar32`	`-fshort-wchar`, `-fno-short-wchar`	Sets the size of `wchar_t` type. The default for Arm Compiler 5 is `--wchar16`. The default for Arm Compiler for Embedded FuSa 6 is `-fno-short-wchar`.

Related information

armclang Command-line Options
Compiler-specific Function, Variable, and Type Attributes
The LLVM Compiler Infrastructure Project

4.2 Arm Compiler 5 and Arm Compiler for Embedded FuSa 6 stack protection behavior

You can see which functions are protected and compare Arm® Compiler 5 protection with Arm Compiler for Embedded FuSa 6 protection after migration.

This topic includes descriptions of [COMMUNITY] features. See Support level definitions.

The behavior of `armclang -fstack-protector` and `armclang -fstack-protector-strong` is different from the behavior of the `armcc --protect_stack` option:

- With `armcc --protect_stack`, a function is considered vulnerable if it contains a `char` or `wchar_t` array of any size.
- With `armclang -fstack-protector`, a function is considered vulnerable if it contains at least one of the following:
  - A character array larger than 8 bytes.
  - An 8-bit integer array larger than 8 bytes.
  - A call to `alloca()` with either a variable size or a constant size bigger than 8 bytes.
- With `armclang -fstack-protector-strong`, a function is considered vulnerable if it contains:
  - An array of any size and type.
  - A call to `alloca()`.
  - A local variable that has its address taken.

  Arm recommends the use of `-fstack-protector-strong`.

When using Arm Compiler 5, the value of the variable `__stack_chk_guard` could change during the life of the program. With Arm Compiler for Embedded FuSa 6, a suitable implementation might set this variable to a random value when the program is loaded, before the first protected function is entered. The value must then remain unchanged during the life of the program.

Example

1. Create the file `test.c` containing the following code:

```
// test.c

#include <stdio.h>
#include <stdlib.h>
#include <string.h>

void *__stack_chk_guard = (void *)0xdeadbeef;

void __stack_chk_fail(void) {
  printf("Stack smashing detected.\n");
  exit(1);
}

static void copy(const char *p) {
  char buf[9];
  strcpy(buf, p);
  printf("Copied: %s\n", buf);
}

int main(void) {
  const char *t = "Hello World!";
  copy(t);
  printf("%s\n", t);
  return 0;
}
```

2. For Arm Compiler 5, search for branches to the `__stack_chk_fail()` function in the output from the `fromelf -c` command. The functions containing such branches are protected.

```
armcc -c --cpu=7-A --protect_stack test.c -o test.o

fromelf -c test.o
...
    main
        0x00000010:    e92d407f    .@-.    PUSH     {r0-r6,lr}
        0x00000014:    e28f4064    d@..    ADR      r4,{pc}+0x6c ; 0x80
        0x00000018:    e59f5070    pP..    LDR      r5,[pc,#112] ;
 [__stack_chk_guard = 0x90] = 0
        0x0000001c:    e1a01004    ....    MOV      r1,r4
        0x00000020:    e5950000    ....    LDR      r0,[r5,#0]
        0x00000024:    e58d000c    ....    STR      r0,[sp,#0xc]
        0x00000028:    e1a0000d    ....    MOV      r0,sp
        0x0000002c:    ebffffe     ....    BL       strcpy
        0x00000030:    e1a0100d    ....    MOV      r1,sp
        0x00000034:    e28f0058    X...    ADR      r0,{pc}+0x60 ; 0x94
        0x00000038:    ebffffe     ....    BL       __2printf
        0x0000003c:    e59d000c    ....    LDR      r0,[sp,#0xc]
        0x00000040:    e5951000    ....    LDR      r1,[r5,#0]
        0x00000044:    e1500001    ..P.    CMP      r0,r1
        0x00000048:    1bffffe     ....    BLNE     __stack_chk_fail ; 0x0
 Section #1
        0x0000004c:    e1a01004    ....    MOV      r1,r4
...
```

3. For Arm Compiler for Embedded FuSa 6, use the `armclang` [COMMUNITY] `-Rpass` remark option.

```
> armclang -c --target=arm-arm-none-eabi -march=armv8-a -O0 -fstack-protector -
Rpass=stack-protector test.c
test.c:14:13: remark: Stack protection applied to function main due to a stack
 allocated buffer or struct containing a
```

```
      buffer [-Rpass=stack-protector]
int main(void) {
    ^
```


Note

You can also use the `fromelf -c` command and search the output for functions containing branches to the `__stack_chk_fail()` function.

Related information

-fstack-protector, -fstack-protector-all, -fstack-protector-strong, -fno-stack-protector
-Rpass

4.3 Command-line options for preprocessing assembly source code

The functionality of the `--cpreproc` and `--cpreproc_opts` command-line options in the version of `armasm` supplied with Arm® Compiler for Embedded FuSa 6 is different from the options used in earlier versions of `armasm` to preprocess assembly source code.

If you are using `armasm` to assemble source code that requires the use of the preprocessor, you must use both the `--cpreproc` and `--cpreproc_opts` options together. Also:

- As a minimum, you must include the `armclang` options `--target` and either `-mcpu` or `-march` in `--cpreproc_opts`.
- The input assembly source must have an upper-case extension `.s`.

If you have existing source files, which require preprocessing, and that have the lower-case extension `.s`, then to avoid having to rename the files:

1. Perform the preprocessing step separately using the `armclang` option `-x assembler-with-cpp`.
2. Assemble the preprocessed file without using the `--cpreproc` and `--cpreproc_opts` options.

Example using armclang -x

This example shows the use of the armclang `-x` option.

```
armclang --target=aarch64-arm-none-eabi -march=armv8-a -x assembler-with-cpp -E
 test.s -o test_preproc.s
armasm --cpu=8-A.64 test_preproc.s
```

Example using armasm --cpreproc_opts

The options to the preprocessor in this example are `--cpreproc_opts=--target=arm-arm-none-eabi,-mcpu=cortex-a9,-D,DEF1,-D,DEF2`.

```
armasm --cpu=cortex-a9 --cpreproc --cpreproc_opts=--target=arm-arm-none-eabi,-
mcpu=cortex-a9,-D,DEF1,-D,DEF2 -I /path/to/includes1 -I /path/to/includes2 input.S
```

Ensure that you specify compatible architectures in the `armclang` options `--target`, `-mcpu` or `-march`, and the `armasm` option `--cpu`.

Related information

--cpreproc assembler option
--cpreproc_opts assembler option
Mandatory armclang options
-march armclang option
-mcpu armclang option
--target armclang option
-x armclang option
Preprocessing assembly code

4.4 Inline assembly with Arm Compiler for Embedded FuSa 6

Inline assembly in Arm® Compiler for Embedded FuSa 6 must be written in GNU assembly syntax. Inline assembly in Arm Compiler 5 is written in `armasm` syntax. If you have inline assembly written in `armasm` syntax, you must modify the `armasm` syntax assembly to use GNU assembly syntax.

In Arm Compiler 5:

- You can use C variable names directly inside inline assembly statements.
- You do not have direct access to physical registers. You must use C or C++ variables names as operands, and the compiler maps them to physical register. You must set the value of these variables before you read them within an inline assembly statement.
- If you use register names in inline assembly code, they are treated as C or C++ variables. They do not necessarily relate to the physical register of the same name. If the register name is not declared as a C or C++ variable, the compiler generates a warning.

In Arm Compiler for Embedded FuSa 6:

- You cannot use C or C++ variable names directly inside inline assembly statements. You can map the physical registers to C or C++ variable names using operand mapping and constraints.

- You have direct access to physical registers. There is no need to set the value of the registers before you read them within inline assembly statements.
- If you use register names in inline assembly code, they are the physical register of the same name.

In Arm Compiler for Embedded FuSa 6 you cannot use C variable names directly within inline assembly. However, the GNU assembly syntax in Arm Compiler for Embedded FuSa 6 provides a way for mapping input and output operands to C variable names.

Arm Compiler 5 optimizes inline assembly, but Arm Compiler for Embedded FuSa 6 emits it exactly as written.


Note

While Arm Compiler for Embedded FuSa 6 does not attempt to optimize the inline assembly instructions, it can remove a block of code containing inline assembly during optimization. The compiler is unaware of the content of the assembly, so might in some cases remove the block while attempting to remove unused code.

The `volatile` qualifier disables certain compiler optimizations that might otherwise lead to the compiler removing the code block. The `volatile` qualifier is optional. However, consider using it around your assembly code blocks to ensure the compiler does not remove them when compiling at any optimization level other than `-O0`.

See the documentation of the `volatile` keyword in the *Arm Compiler for Embedded 6 User Guide* for details.

For more information on writing inline assembly using `__asm` in `armclang`, see __asm.

For more information on GNU assembly syntax, see Overview of differences between armasm and GNU syntax assembly code.

Inline assembly example in Arm Compiler 5

The following example shows inline assembly code in Arm Compiler 5:

```
//foo.c:

int add(int i, int j)
{
  int res;
  __asm
  (
    "ADD res, i, j \t\n"
    "SUB res, i, res \t\n"
  );
  return res;
}
```

The following example shows an alternative syntax for inline assembly code in Arm Compiler 5:

```
//foo.c:
```

```
int add(int i, int j)
{
  int res;
  __asm
  {
    ADD   res, i, j
    SUB   res, i, res
  }
  return res;
}
```

Compile `foo.c` using `armcc`:

```
armcc foo.c -c -S -o foo.s
```

Arm Compiler 5 converts the example inline assembly code to:

```
;foo.s:

add PROC
        ADD r1,r0,r1
        SUB r0,r0,r1
        BX  lr
        ENDP
```

Inline assembly example in Arm Compiler for Embedded FuSa 6

The example below shows the equivalent inline assembly code in Arm Compiler for Embedded FuSa 6.

```
//foo.c:

int add(int i, int j)
{
  int res = 0;
  __asm
  (
    "ADD %[result], %[input_i], %[input_j] \t\n"
    "SUB %[result], %[input_i], %[result]  \t\n"
    : [result] "=&r" (res)
    : [input_i] "r" (i), [input_j] "r" (j)
  );
  return res;
}
```

Compile `foo.c` using `armclang` with optimization level `-O1`:

```
armclang foo.c --target=arm-arm-none-eabi -march=armv8-a -O1 -c -S -o foo.s
```

Arm Compiler for Embedded FuSa 6 converts the example inline assembly code to:

```
;foo.s:

add:
        .fnstart
@ BB#0:
        @APP
```

```
        add r2,r0,r1
        sub r2,r0,r2
        @NO_APP
        mov r0,r2
        bx  lr
```


Note

Arm Compiler for Embedded FuSa 6 supports inline assembly using the `__asm` or `asm` keywords. However, the `asm` keyword is accepted only when:

- Used within C++ language source files.
- Used within C language source files without strict ISO C Standard compliance. For example, `asm` is accepted when using `-std=gnu11`.

The compiler supports the GNU form of inline assembly. The compiler does not support the Microsoft form of inline assembly. More detailed documentation of the `asm` construct is available at https://gcc.gnu.org/onlinedocs/gcc/Extended-Asm.html.

Related information

armclang Inline Assembler
How to Use Inline Assembly Language in C Code
Constraints for asm Operands
Constraint Modifier Characters

4.5 Migrating architecture and processor names for command-line options

There are minor differences between the architecture and processor names that Arm® Compiler for Embedded FuSa 6 recognizes, and the names that Arm Compiler 5 recognizes. Within Arm Compiler for Embedded FuSa 6, there are differences in the architecture and processor names that `armclang` recognizes and the names that `armasm`, `armlink`, and `fromelf` recognize. This topic shows the differences in the architecture and processor names for the different tools in Arm Compiler 5 and Arm Compiler for Embedded FuSa 6.

The tables show the documented `--cpu` options in Arm Compiler 5 and their corresponding options for migrating your Arm Compiler 5 command-line options to Arm Compiler for Embedded FuSa 6.


Note

The tables assume the default floating-point unit derived from the `--cpu` option in Arm Compiler 5. However, in Arm Compiler for Embedded FuSa 6, `armclang` selects different defaults for floating-point unit (VFP) and Advanced SIMD. Therefore, the tables also show how to use the `armclang` options `-mfloat-abi` and `-mfpu` to be compatible with the default floating-point unit in Arm Compiler 5. The tables do not provide an exhaustive list.

Table 4-2: Architecture selection in Arm Compiler 5 and Arm Compiler for Embedded 6

armcc, armlink, armasm, and fromelf option in Arm Compiler 5	armclang option in Arm Compiler for Embedded FuSa 6	armlink, armasm, and fromelf option in Arm Compiler for Embedded FuSa 6	Architecture description
--cpu=4	Not supported	Not supported	Armv4
--cpu=4T	Not supported	Not supported	Armv4T
--cpu=5T	Not supported	Not supported	Armv5T
--cpu=5TE	Not supported	Not supported	Armv5TE
--cpu=5TEJ	Not supported	Not supported	Armv5TEJ
--cpu=6	Not supported	Not supported	Generic Armv6
--cpu=6-K	Not supported	Not supported	Armv6 -K
--cpu=6-Z	Not supported	Not supported	Armv6 -Z
--cpu=6T2	Not supported	Not supported	Armv6 T2
--cpu=6-M	--target=arm-arm-none-eabi -march=armv6-m	--cpu=6S-M	Armv6-M
--cpu=6S-M	--target=arm-arm-none-eabi -march=armv6s-m	--cpu=6S-M	Armv6 S-M
--cpu=7-A --cpu=7-A.security	--target=arm-arm-none-eabi -march=armv7-a -mfloat-abi=soft	--cpu=7-A.security	Armv7-A without VFP and Advanced SIMD. In Arm Compiler 5, security extension is not enabled with --cpu=7-A but is enabled with --cpu=7-A.security. In Arm Compiler for Embedded FuSa 6, armclang always enables the Armv7-A TrustZone security extension with -march=armv7-a. However, armclang does not generate an SMC instruction unless you specify it with an intrinsic or inline assembly.
--cpu=7-R	--target=arm-arm-none-eabi -march=armv7-r -mfloat-abi=soft	--cpu=7-R	Armv7-R without VFP and Advanced SIMD
--cpu=7-M	--target=arm-arm-none-eabi -march=armv7-m	--cpu=7-M	Armv7-M
--cpu=7E-M	--target=arm-arm-none-eabi -march=armv7e-m -mfloat-abi=soft	--cpu=7E-M	Armv7 E-M

Table 4-3: Processor selection in Arm Compiler 5 and Arm Compiler for Embedded 6

armcc, armlink, armasm, and fromelf option in Arm Compiler 5	armclang option in Arm Compiler for Embedded FuSa 6	armlink, armasm, and fromelf option in Arm Compiler for Embedded FuSa 6	Description
--cpu=Cortex-A5	--target=arm-arm-none-eabi -mcpu=cortex-a5 -mfloat-abi=soft	--cpu=Cortex-A5.no_neon.no_vfp	Cortex®-A5 without Advanced SIMD and VFP

armcc, armlink, armasm, and fromelf option in Arm Compiler 5	armclang option in Arm Compiler for Embedded FuSa 6	armlink, armasm, and fromelf option in Arm Compiler for Embedded FuSa 6	Description
--cpu=Cortex-A5.neon	--target=arm-arm-none-eabi -mcpu=cortex-a5 -mfloat-abi=hard	--cpu=Cortex-A5	Cortex-A5 with Advanced SIMD and VFP
--cpu=Cortex-A5.vfp	--target=arm-arm-none-eabi -mcpu=cortex-a5 -mfloat-abi=hard -mfpu=vfpv4-d16	--cpu=Cortex-A5.no_neon	Cortex-A5 with VFP, without Advanced SIMD
--cpu=Cortex-A7	--target=arm-arm-none-eabi -mcpu=cortex-a7 -mfloat-abi=hard	--cpu=Cortex-A7	Cortex-A7 with Advanced SIMD and VFP
--cpu=Cortex-A7.no_neon.no_vfp	--target=arm-arm-none-eabi -mcpu=cortex-a7 -mfloat-abi=soft	--cpu=Cortex-A7.no_neon.no_vfp	Cortex-A7 without Advanced SIMD and VFP
--cpu=Cortex-A7.no_neon	--target=arm-arm-none-eabi -mcpu=cortex-a7 -mfloat-abi=hard -mfpu=vfpv4-d16	--cpu=Cortex-A7.no_neon	Cortex-A7 with VFP, without Advanced SIMD
--cpu=Cortex-A8	--target=arm-arm-none-eabi -mcpu=cortex-a8 -mfloat-abi=hard	--cpu=Cortex-A8	Cortex-A8 with VFP and Advanced SIMD
--cpu=Cortex-A8.no_neon	--target=arm-arm-none-eabi -mcpu=cortex-a8 -mfloat-abi=soft	--cpu=Cortex-A8.no_neon	Cortex-A8 without Advanced SIMD and VFP
--cpu=Cortex-A9	--target=arm-arm-none-eabi -mcpu=cortex-a9 -mfloat-abi=hard	--cpu=Cortex-A9	Cortex-A9 with Advanced SIMD and VFP
--cpu=Cortex-A9.no_neon.no_vfp	--target=arm-arm-none-eabi -mcpu=cortex-a9 -mfloat-abi=soft	--cpu=Cortex-A9.no_neon.no_vfp	Cortex-A9 without Advanced SIMD and VFP
--cpu=Cortex-A9.no_neon	--target=arm-arm-none-eabi -mcpu=cortex-a9 -mfloat-abi=hard -mfpu=vfpv3-d16-fp16	--cpu=Cortex-A9.no_neon	Cortex-A9 with VFP but without Advanced SIMD
--cpu=Cortex-A12	--target=arm-arm-none-eabi -mcpu=cortex-a12 -mfloat-abi=hard	--cpu=Cortex-A12	Cortex-A12 with Advanced SIMD and VFP
--cpu=Cortex-A12.no_neon.no_vfp	--target=arm-arm-none-eabi -mcpu=cortex-a12 -mfloat-abi=soft	--cpu=Cortex-A12.no_neon.no_vfp	Cortex-A12 without Advanced SIMD and VFP
--cpu=Cortex-A15	--target=arm-arm-none-eabi -mcpu=cortex-a15 -mfloat-abi=hard	--cpu=Cortex-A15	Cortex-A15 with Advanced SIMD and VFP
--cpu=Cortex-A15.no_neon	--target=arm-arm-none-eabi -mcpu=cortex-a15 -mfloat-abi=hard -mfpu=vfpv4-d16	--cpu=Cortex-A15.no_neon	Cortex-A15 with VFP, without Advanced SIMD
--cpu=Cortex-A15.no_neon.no_vfp	--target=arm-arm-none-eabi -mcpu=cortex-a15 -mfloat-abi=soft	--cpu=Cortex-A15.no_neon.no_vfp	Cortex-A15 without Advanced SIMD and VFP

armcc, armlink, armasm, and fromelf option in Arm Compiler 5	armclang option in Arm Compiler for Embedded FuSa 6	armlink, armasm, and fromelf option in Arm Compiler for Embedded FuSa 6	Description
--cpu=Cortex-A17	--target=arm-arm-none-eabi -mcpu=cortex-a17 -mfloat-abi=hard	--cpu=Cortex-A17	Cortex-A17 with Advanced SIMD and VFP
--cpu=Cortex-A17.no_neon.no_vfp	--target=arm-arm-none-eabi -mcpu=cortex-a17 -mfloat-abi=soft	--cpu=Cortex-A17.no_neon.no_vfp	Cortex-A17 without Advanced SIMD and VFP
--cpu=Cortex-R4	--target=arm-arm-none-eabi -mcpu=cortex-r4	--cpu=Cortex-R4	Cortex-R4 without VFP
--cpu=Cortex-R4F	--target=arm-arm-none-eabi -mcpu=cortex-r4f -mfloat-abi=hard	--cpu=Cortex-R4F	Cortex-R4 with VFP
--cpu=Cortex-R5	--target=arm-arm-none-eabi -mcpu=cortex-r5 -mfloat-abi=soft	--cpu=Cortex-R5.no_vfp	Cortex-R5 without VFP
--cpu=Cortex-R5F	--target=arm-arm-none-eabi -mcpu=cortex-r5 -mfloat-abi=hard	--cpu=Cortex-R5	Cortex-R5 with double precision VFP
--cpu=Cortex-R5F-rev1.sp	--target=arm-arm-none-eabi -mcpu=cortex-r5 -mfloat-abi=hard -mfpu=vfpv3xd	--cpu=Cortex-R5.sp	Cortex-R5 with single precision VFP
--cpu=Cortex-R7	--target=arm-arm-none-eabi -mcpu=cortex-r7 -mfloat-abi=hard	--cpu=Cortex-R7	Cortex-R7 with VFP
--cpu=Cortex-R7.no_vfp	--target=arm-arm-none-eabi -mcpu=cortex-r7 -mfloat-abi=soft	--cpu=Cortex-R7.no_vfp	Cortex-R7 without VFP
--cpu=Cortex-R8	--target=arm-arm-none-eabi -mcpu=cortex-r8 -mfloat-abi=hard	--cpu=Cortex-R8	Cortex-R8 with VFP
--cpu=Cortex-R8.no_vfp	--target=arm-arm-none-eabi -mcpu=cortex-r8 -mfloat-abi=soft	--cpu=Cortex-R8.no_vfp	Cortex-R8 without VFP
--cpu=Cortex-M0	--target=arm-arm-none-eabi -mcpu=cortex-m0	--cpu=Cortex-M0	Cortex-M0
--cpu=Cortex-M0plus	--target=arm-arm-none-eabi -mcpu=cortex-m0plus	--cpu=Cortex-M0plus	Cortex-M0+
--cpu=Cortex-M1	--target=arm-arm-none-eabi -mcpu=cortex-m1	--cpu=Cortex-M1	Cortex-M1
--cpu=Cortex-M3	--target=arm-arm-none-eabi -mcpu=cortex-m3	--cpu=Cortex-M3	Cortex-M3
--cpu=Cortex-M4	--target=arm-arm-none-eabi -mcpu=cortex-m4 -mfloat-abi=soft	--cpu=Cortex-M4.no_fp	Cortex-M4 without VFP
--cpu=Cortex-M4.fp	--target=arm-arm-none-eabi -mcpu=cortex-m4 -mfloat-abi=hard	--cpu=Cortex-M4	Cortex-M4 with VFP

armcc, armlink, armasm, and fromelf option in Arm Compiler 5	armclang option in Arm Compiler for Embedded FuSa 6	armlink, armasm, and fromelf option in Arm Compiler for Embedded FuSa 6	Description
`--cpu=Cortex-M7`	`--target=arm-arm-none-eabi -mcpu=cortex-m7 -mfloat-abi=soft`	`--cpu=Cortex-M7.no_fp`	Cortex-M7 without VFP
`--cpu=Cortex-M7.fp.dp`	`--target=arm-arm-none-eabi -mcpu=cortex-m7 -mfloat-abi=hard`	`--cpu=Cortex-M7`	Cortex-M7 with double precision VFP
`--cpu=Cortex-M7.fp.sp`	`--target=arm-arm-none-eabi -mcpu=cortex-m7 -mfloat-abi=hard -mfpu=fpv5-sp-d16`	`--cpu=Cortex-M7.fp.sp`	Cortex-M7 with single precision VFP

Enabling or disabling architectural features in Arm Compiler for Embedded FuSa 6

Arm Compiler for Embedded FuSa 6, by default, automatically enables or disables certain architectural features such as the floating-point unit, Advanced SIMD, and Cryptographic extensions depending on the specified architecture or processor. For a list of architectural features, see `-mcpu` in the *Arm Compiler for Embedded FuSa Reference Guide*. You can override the defaults using other options.

For `armclang`:

- For AArch64 targets, you must use either `-march` or `-mcpu` to specify the architecture or processor and the required architectural features. You can use `+[no]feature` with `-march` or `-mcpu` to override any architectural feature.
- For AArch32 targets, you must use either `-march` or `-mcpu` to specify the architecture or processor and the required architectural features. You can use `-mfloat-abi` to override floating-point linkage. You can use `-mfpu` to override floating-point unit, Advanced SIMD, and Cryptographic extensions. You can use `+[no]feature` with `-march` or `-mcpu` to override certain other architectural features.

For `armasm`, `armlink`, and `fromelf`, you must use the `--cpu` option to specify the architecture or processor and the required architectural features. You can use `--fpu` to override the floating-point unit and floating-point linkage. The `--cpu` option is not mandatory for `armlink` and `fromelf`, but is mandatory for `armasm`.

- In Arm Compiler 5, if you use the `armcc` option `--fpu=none`, the compiler generates an error if it detects floating-point code. This behavior is different in Arm Compiler for Embedded FuSa 6. If you use the `armclang` option `-mfpu=none`, the compiler automatically uses software floating-point libraries if it detects any floating-point code. You cannot use the `armlink` option `--fpu=none` to link object files created using `armclang`.
- To link object files created using the `armclang` option `-mfpu=none`, you must set the `armlink` option `--fpu` to an option that supports software floating-point linkage, for example `--fpu=SoftVFP`, rather than using `--fpu=none`.

Related information

-mcpu (armclang)
-march (armclang)
-mfloat-abi (armclang)
-mfpu (armclang)
--target (armclang)
--cpu (armlink)
--fpu (armlink)
--cpu (fromelf)
--fpu (fromelf)
--cpu (armasm)
--fpu (armasm)

4.6 Preprocessing a scatter file when linking with armlink

Preprocessing a scatter file when linking with `armlink` in Arm® Compiler for Embedded FuSa 6 requires extra options.

The following shows the required change to the first line of the scatter file:

Arm Compiler 5

```
#!armcc -E
```

Arm Compiler for Embedded FuSa 6

```
#!armclang -E --target=arm-arm-none-eabi -mcpu=cortex-m7 -xc
```

The mandatory option `--target` specifies the target state, either AArch32 state, as shown in this example, or AArch64 state. See --target.

The option `-mcpu` specifies a processor, Cortex-M7 in this example. Alternatively, you can use `-march` to specify an architecture. See -mcpu or -march.

The option `-x` specifies the source language. See -x.

The option `-E` makes `armclang` only execute the preprocessor step. See -E.

4.7 Migrating predefined macros

The functionality of the Arm® Compiler 5 predefined macro `__MODULE__` is provded by the `__FILE_NAME__` macro in Arm Compiler for Embedded FuSa 6.

Related information

Predefined macros

5. Compiler Source Code Compatibility

Provides details of source code compatibility between Arm® Compiler for Embedded FuSa 6 and older `armcc` compiler versions.

5.1 Language extension compatibility: keywords

Arm® Compiler for Embedded FuSa 6 supports some keywords that are supported in Arm Compiler 5.

This topic includes descriptions of [COMMUNITY] features. See Support level definitions.

The following table lists some of the commonly used keywords that Arm Compiler 5 supports and shows whether Arm Compiler for Embedded FuSa 6 supports them using `__attribute__`. Replace any instances of these keywords in your code with the recommended alternative where available or use inline assembly instructions.

This table is not an exhaustive list of all keywords.

Table 5-1: Keyword language extensions in Arm Compiler 5 and Arm Compiler for Embedded FuSa 6

Keyword supported by Arm Compiler 5	Recommended Arm Compiler for Embedded FuSa 6 keyword or alternative
`__align(x)`	`__attribute__((aligned(x)))`
`__alignof__`	`__alignof__`
`__ALIGNOF__`	`__alignof__`
Embedded assembly using `__asm`	Arm Compiler for Embedded FuSa 6 does not support the `__asm` keyword on function definitions and declarations for embedded assembly. Instead, you can write embedded assembly using the `__attribute__((naked))` function attribute. See __attribute__((naked)).
`__const`	`__attribute__((const))` **Note:** Older versions of `armcc` supported the `__const` keyword. The equivalent for this keyword in Arm Compiler 5 and Arm Compiler for Embedded FuSa 6 is `__attribute__((const))`.
`__attribute__((const))`	`__attribute__((const))`

Keyword supported by Arm Compiler 5	Recommended Arm Compiler for Embedded FuSa 6 keyword or alternative
`__forceinline`	• For C90, use `__inline__` and `__attribute__((always_inline))` • For other source languages, use `inline` and `__attribute__((always_inline))`. See _attribute__((always_inline)).
`__global_reg(N)`	Use the `register` and `__asm` keywords for global named register variables using core registers. For example: `register int Reg5 __asm("r5")` In Arm Compiler for Embedded FuSa 6, you must also use the relevant `armclang` option `-ffixed-r<N>`. Alternatively, you can use equivalent inline assembler instructions.
`__inline(x)`	`__inline__`. The use of this keyword depends on the language mode.
`__int64`	You can use `int64_t`, which is a 64-bit integer type defined in the header file `<stdint.h>` (for C source files) or `<cstdint>` (for C ++ source files). You can also use `long long`, however, if you use `long long` in C90 mode, the compiler gives: • a warning. • an error, if you also use `-pedantic-errors`.
`__INTADDR__`	No equivalent.
`__irq`	`__attribute__((interrupt))`. This keyword is not supported in AArch64.
`__packed` for removing padding within structures.	`__attribute__((packed))`. This keyword provides limited functionality when compared to `__packed`: • The `__attribute__((packed))` variable attribute applies to members of a structure or union. It does not apply to variables that are not members of a structure or union. • `__attribute__((packed))` is not a type qualifier. Taking the address of a packed member can result in unaligned pointers, and usually the compiler generates a warning. We recommend upgrading this warning to an error when migrating code that uses `__packed`. To upgrade the warning to an error, use the `armclang` option `-Werror=<name>`. The placement of the attribute is different from the placement of `__packed`. If your legacy code contains `typedef __packed struct`, then replace it with: `typedef struct __attribute__((packed))`

Keyword supported by Arm Compiler 5	Recommended Arm Compiler for Embedded FuSa 6 keyword or alternative
`__packed` as a type qualifier for unaligned access.	`__unaligned`. This keyword provides limited functionality when compared to the `__packed` type qualifier. You can use the `__unaligned` type qualifier over a structure only when using `typedef` or when declaring a structure variable. This limitation does not apply when using `__packed` in Arm Compiler 5. Therefore, there is no migration for legacy code that contains `__packed struct S{...};`.
`__pure`	`__attribute__((const))`
`__smc`	Use inline assembler instructions or equivalent routine.
`__softfp`	`__attribute__((pcs("aapcs")))`
`__svc`	Use inline assembler instructions or equivalent routine.
`__svc_indirect`	Use inline assembler instructions or equivalent routine.
`__svc_indirect_r7`	Use inline assembler instructions or equivalent routine.
`__thread`	`__thread`
`__value_in_regs`	`__attribute__((value_in_regs))`
`__weak`	`__attribute__((weak))`
`__writeonly`	No equivalent.
Named register variables for direct manipulation of a core register as if it were a C variable. For example: `register int R5 __asm("r5")`	Use the `register` and `__asm` keywords for global named register variables using core registers. For example: `register int Reg5__asm("r5")` In Arm Compiler for Embedded FuSa 6, you must also use the relevant `armclang` option `-ffixed-r<N>`.
Named register variables for direct manipulation of a system register, other than core registers, as if it were a C variable. For example: `register int fpscr__asm("fpscr")`	No equivalent. To access `FPSCR`, use the `__vfp_status` intrinsic or inline assembly instructions.

Migrating the __packed keyword from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6

The `__packed` keyword in Arm Compiler 5 has the effect of:

- Removing the padding within structures.
- Qualifying the variable for unaligned access.

Arm Compiler for Embedded FuSa 6 does not support `__packed`, but supports the `__attribute__((packed))` attribute and the `__unaligned` keyword. Depending on the use, you might need to replace `__packed` with both `__attribute__((packed))` and `__unaligned`. The following table shows the migration paths for various uses of `__packed`.

Table 5-2: Migrating the `__packed` keyword

Arm Compiler 5	Arm Compiler for Embedded FuSa 6
`__packed int x;`	`__unaligned int x;`
`__packed int *x;`	`__unaligned int *x;`
`int * __packed x;`	`int * __unaligned x;`
`__unaligned int * __packed x;`	`__unaligned int * __unaligned x;`
`typedef __packed struct S{...} s;`	`typedef __unaligned struct __attribute__((packed)) S{...} s;`
`__packed struct S{...};`	There is no migration. Use a `typedef` instead.
`__packed struct S{...} s;`	`__unaligned struct __attribute__((packed)) S{...} s;` Subsequent declarations of variables of type `struct S` must use `__unaligned`, for example `__unaligned struct S s2`.
`struct S {__packed int a;}`	`struct S {__attribute__((packed)) __unaligned int a;}`

Related information

Unaligned access support in Arm Compiler for Embedded
Compiler-specific Keywords and Operators
Compiler-specific Function, Variable, and Type Attributes
-W

5.2 Language extension compatibility: attributes

Arm® Compiler for Embedded FuSa 6 supports some function, variable, and type attributes that were supported in Arm Compiler 5. Other attributes are not supported, or have an alternate implementation.

This topic includes descriptions of [COMMUNITY] features. See Support level definitions.

Arm Compiler 5 and Arm Compiler for Embedded FuSa 6 support the following attributes. These attributes do not require modification in your code:

The `__declspec` keyword is deprecated.

- `__attribute__((aligned(<n>)))`

- `__attribute__((const))`
- `__attribute__((deprecated))`
- `__attribute__((noinline))`
- `__declspec(noinline)`
- `__attribute__((nonnull))`
- `__attribute__((noreturn))`
- `__declspec(noreturn)`
- `__attribute__((nothrow))`
- `__declspec(nothrow)`
- `__attribute__((pcs("<calling convention>")))`
- `__attribute__((pure))`
- `__attribute__((unused))`
- `__attribute__((used))`
- `__attribute__((visibility))`
- `__attribute__((weak))`
- `__attribute__((weakref))`

The following Arm Compiler 5 attributes are not supported by Arm Compiler for Embedded FuSa 6:

- `__attribute__((nomerge))`
- `__attribute__((notailcall))`

However, because Arm Compiler for Embedded FuSa 6 is built on LLVM technology and preserves the functionality of that technology where possible, you might consider using the following [COMMUNITY] (open-source Clang) features instead:

- `__attribute__((nomerge))`
- `__attribute__((not_tail_called))`

[COMMUNITY] features are not supported by Arm and are used at your own risk. You are responsible for making sure that any generated code using [COMMUNITY] features is operating correctly. For more information, see Support level definitions.

__declspec attributes

Though Arm Compiler for Embedded FuSa 6 supports certain `__declspec` attributes, Arm recommends using `__attribute__` where available.

Table 5-3: Support for __declspec attributes

declspec supported by Arm Compiler 5	Recommended Arm Compiler for Embedded FuSa 6 alternative
`__declspec(dllimport)`	None. There is no support for BPABI linking models.
`__declspec(dllexport)`	None. There is no support for BPABI linking models.

declspec supported by Arm Compiler 5	Recommended Arm Compiler for Embedded FuSa 6 alternative
`__declspec(noinline)`	`__attribute__((noinline))`
`__declspec(noreturn)`	`__attribute__((noreturn))`
`__declspec(nothrow)`	`__attribute__((nothrow))`
`__declspec(notshared)`	None. There is no support for BPABI linking models.
`__declspec(thread)`	`__thread`

__attribute__((always_inline))

Arm Compiler 5 and Arm Compiler for Embedded FuSa 6 support `__attribute__((always_inline))`. However, this attribute might require modification in your code.

When using Arm Compiler 5, `__attribute__((always_inline))` affects the linkage of the function according to the inline semantics of the source language.

When using Arm Compiler for Embedded FuSa 6, `__attribute__((always_inline))` does not force inlining, but is a hint to the compiler to inline that function. `armclang` still decides whether to inline the function. You can also use the keyword `inline` or `__inline__` (for C90). To determine which functions have been inlined and which ones could not be inlined, you can consider using `-Rpass=inline` and the [COMMUNITY] option `-Rpass-missed=inline`. For more information, see:

- -Rpass.
- __attribute__((always_inline)).
- Inline functions
- Inlining functions.

__attribute__((section("name")))

Arm Compiler 5 and Arm Compiler for Embedded FuSa 6 support `__attribute__((section("<name>")))`. However, this attribute might require modification in your code.

When using Arm Compiler 5, section names do not need to be unique. Therefore, you could use the same section name to create different section types.

When using Arm Compiler for Embedded FuSa 6, you must ensure that variables of different types do not have the same section name.

Arm Compiler for Embedded FuSa 6 supports multiple sections with the same section name only if you use the `.section` assembly directive with a unique ID. For more information, see Section directives.

If you use the same section name for another section or symbol without a unique ID, then `armclang` integrated assembler merges the sections and gives the merged section the flags of the first section it discovers with that name.

Migrating __attribute__((at(address))) and zero-initialized __attribute__((section("name"))) from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6

Arm Compiler 5 supports the following attributes, which Arm Compiler for Embedded FuSa 6 does not support:

- `__attribute__((at(<address>)))` to specify the absolute address of a function or variable.
- `__attribute__((at(<address>), zero_init))` to specify the absolute address of a zero-initialized variable.
- `__attribute__((section(<name>), zero_init))` to place a zero-initialized variable in a zero-initialized section with the given `<name>`.
- `__attribute__((zero_init))` to generate an error if the variable has an initializer.

The following table shows migration paths for these features using Arm Compiler for Embedded FuSa 6 supported features:

Table 5-4: Migrating __attribute__((at(<address>))) and zero-initialized __attribute__((section("<name>")))

Arm Compiler 5 attribute	Arm Compiler for Embedded FuSa 6 attribute	Description
`__attribute__((at(<address>)))`	`__attribute__((section(".ARM.__at_<address>")))`	Although `armlink` in Arm Compiler for Embedded FuSa 6 supports the placement of sections in the form of `.ARM.__at_<address>`, the implementation is not the same as in Arm Compiler 5. **Note:** The Arm Compiler for Embedded FuSa 6 attribute only supports a string to specify the section. To use an arithmetic expression, see Supporting arithmetic expressions in the at(address) attribute in Arm Compiler for Embedded FuSa 6.
`__attribute__((at(<address>), zero_init))`	`__attribute__((section(".bss.ARM.__at_<address>")))`	`armlink` in Arm Compiler for Embedded FuSa 6 supports the placement of zero-initialized sections in the form of `.bss.ARM.__at_<address>`. The `.bss` prefix is case-sensitive and must be all lowercase.
`__attribute__((section(<name>), zero_init))`	`__attribute__((section(".bss.<name>")))`	`<name>` is a name of your choice. The `.bss` prefix is case-sensitive and must be all lowercase.
`__attribute__((zero_init))`	Arm Compiler for Embedded FuSa 6 by default places zero-initialized variables in a `.bss` section. However, there is no equivalent to generate an error when you specify an initializer.	If the variable has an initializer, Arm Compiler 5 generates an error. Otherwise, it places the zero-initialized variable in a `.bss` section.

Supporting arithmetic expressions in the at(address) attribute in Arm Compiler for Embedded FuSa 6

The `at(<address>)` attribute in Arm Compiler 5 supports arithmetic expressions to specify the section, for example:

```
#include <stdint.h>

/* Define the variable and place at calculated address directly */
__attribute__((at(0x30000000 + 0x4000))) volatile uint32_t foo = 0x11223344;
```

Arm Compiler for Embedded FuSa 6 does not support arithmetic expressions with `__attribute__((section(".ARM.__at_<address>")))`. To do the equivalent in Arm Compiler for Embedded FuSa 6, you must use a pointer-based approach as follows:

1. Use pointer arithmetic to define a pointer that points to the required address.
2. The value pointed to by the pointer is not automatically initialized. Instead, you must initialize the value manually within a function.

For example:

```
#include <stdio.h>
#include <stdint.h>

/* 1. Define pointer to point to a calculated address */
volatile uint32_t * const foo_ptr = (volatile uint32_t *) (0x30000000 + 0x4000);

int main(void)
{
    *foo_ptr = 0x11223344; /* 2. Initialize the value pointed to by the pointer */
    printf("%p: %8x\n", foo_ptr, *foo_ptr);  /* Use the pointer as needed */

    return 0;
}
```

Related information

Placing functions and data in a named section
Placement of __at sections at a specific address

5.3 Language extension compatibility: pragmas

Arm® Compiler for Embedded FuSa 6 provides support for some pragmas that are supported in Arm Compiler 5. Other pragmas are not supported, or must be replaced with alternatives.

The following table lists some of the commonly used pragmas that are supported by Arm Compiler 5 but are not supported by Arm Compiler for Embedded FuSa 6. Replace any instances of these pragmas in your code with the recommended alternative.

Table 5-5: Pragma language extensions that must be replaced

Pragma supported by Arm Compiler 5	Recommended Arm Compiler for Embedded FuSa 6 alternative
`#pragma import (<symbol>)`	`__asm(".global <symbol>\\n\\t");`

Pragma supported by Arm Compiler 5	Recommended Arm Compiler for Embedded FuSa 6 alternative

`#pragma anon_unions`
 	
`#pragma no_anon_unions`
	In C, anonymous structs and unions are a C11 extension which is enabled by default in `armclang`. If you specify the `-pedantic` option, the compiler emits warnings about extensions do not match the specified language standard. For example:
	
	`armclang --target=aarch64-arm-none-eabi -c -pedantic --std=c90 test.c`
	
	`test.c:3:5: warning: anonymous structs are a C11 extension [-Wc11-extensions]`
	
	In C++, anonymous unions are part of the language standard, and are always enabled. However, anonymous structs and classes are an extension. If you specify the `-pedantic` option, the compiler emits warnings about anonymous structs and classes. For example:
	
	`armclang --target=aarch64-arm-none-eabi -c -pedantic -xc++ test.c`
	
	`test.c:3:5: warning: anonymous structs are a GNU extension [-Wgnu-anonymous-struct]`
	
	Introducing anonymous unions, struct and classes using a `typedef` is a separate extension in `armclang`, which must be enabled using the `-fms-extensions` option.

`#pragma arm`
 	
`#pragma thumb`
	`armclang` provides the `__attribute__((target("arm"|"thumb")))` function attribute to specify the instruction set for a function. You can also use the command-line options `-marm` and `-mthumb` to specify the instruction set for a whole file.

`#pragma arm section`	`#pragma clang section` In Arm Compiler 5, the section types you can use this pragma with are `rodata`, `rwdata`, `zidata`, and `code`. In Arm Compiler for Embedded FuSa 6, the equivalent section types are `rodata`, `data`, `bss`, and `text` respectively.

Pragma supported by Arm Compiler 5	Recommended Arm Compiler for Embedded FuSa 6 alternative

`#pragma diag_default`
 	
`#pragma diag_suppress`
 	
`#pragma diag_remark`
 	
`#pragma diag_warning`
 	
`#pragma diag_error`
	The following pragmas provide equivalent functionality for `diag_suppress`, `diag_warning`, and `diag_error`:
	• `#pragma clang diagnostic ignored "-Wmultichar"`
	• `#pragma clang diagnostic warning "-Wmultichar"`
	• `#pragma clang diagnostic error "-Wmultichar"`
	
	Note that these pragmas use `armclang` diagnostic groups, which do not have a precise mapping to `armcc` diagnostic tags.
	
	`armclang` has no equivalent to `diag_default` or `diag_remark`. `diag_default` can be replaced by wrapping the change of diagnostic level with `#pragma clang diagnostic push` and `#pragma clang diagnostic pop`, or by manually returning the diagnostic to the default level.
	
	There is an additional diagnostic level supported in armclang, `fatal`, which causes compilation to fail without processing the rest of the file. You can set this as follows:
	
	`#pragma clang diagnostic fatal "-Wmultichar"`

`#pragma exceptions_unwind`
 	
`#pragma no_exceptions_unwind`
	`armclang` does not support these pragmas.
	
	Use the `__attribute__((nothrow))` function attribute instead.

`#pragma GCC system_header`	This pragma is supported by both `armcc` and `armclang`, but `#pragma clang system_header` is the preferred spelling in `armclang` for new code.

`#pragma hdrstop`
 	
`#pragma no_pch`
	`armclang` does not support these pragmas.

`#pragma import(__use_no_semihosting)`
 	
`#pragma import(__use_no_semihosting_swi)`
	`armclang` does not support these pragmas. However, in C code, you can replace these pragmas with:
	
	`__asm(".global __use_no_semihosting\n\t");`

`#pragma import(__use_two_region_memory)`	This pragma is required for scatter-loading when the stack and heap are separate. `armclang` does not support this pragma. However, in C code, you can replace this pragma with: `__asm(".global __use_two_region_memory\n\t");`

`#pragma inline`
 	
`#pragma no_inline`
	`armclang` does not support these pragmas. However, inlining can be disabled on a per-function basis using the `__attribute__((noinline))` function attribute.
	
	The default behavior of both `armcc` and `armclang` is to inline functions when the compiler considers this worthwhile, and this is the behavior selected by using `#pragma inline` in `armcc`. To force a function to be inlined in `armclang`, use the `__attribute__((always_inline))` function attribute.

Pragma supported by Arm Compiler 5	Recommended Arm Compiler for Embedded FuSa 6 alternative

`#pragma Onum`
 	
`#pragma Ospace`
 	
`#pragma Otime`
	`armclang` does not support changing optimization options within a file. Instead these must be set on a per-file basis using command-line options.

`#pragma pop`
 	
`#pragma push`
	`armclang` does not support these pragmas. Therefore, you cannot push and pop the state of all supported pragmas.
	
	However, you can push and pop the state of the diagnostic pragmas and the state of the pack pragma.
	
	To control the state of the diagnostic pragmas, use `#pragma clang diagnostic push` and `#pragma clang diagnostic pop`.
	
	To control the state of the pack pragma, use `#pragma pack(push)` and `#pragma pack(pop)`.

`#pragma softfp_linkage`	`armclang` does not support this pragma. Instead, use the `__attribute__((pcs("aapcs")))` function attribute to set the calling convention on a per-function basis, or use the `-mfloat-abi=soft` command-line option to set the calling convention on a per-file basis.
`#pragma no_softfp_linkage`	`armclang` does not support this pragma. Instead, use the `__attribute__((pcs("aapcs-vfp")))` function attribute to set the calling convention on a per-function basis, or use the `-mfloat-abi=hard` command-line option to set the calling convention on a per-file basis.

`#pragma unroll[(<n>)]`
 	
`#pragma unroll_completely`
	`armclang` supports these pragmas.
	
	The default for `#pragma unroll` (that is, with no iteration count specified) differs between `armclang` and `armcc`:
	• With `armclang`, the default is to fully unroll a loop.
	• With `armcc`, the default is `#pragma unroll(4)`.

Related information

Compiler-specific Pragmas
Compiler-specific Function, Variable, and Type Attributes

5.4 Language extension compatibility: intrinsics

Arm® Compiler for Embedded FuSa 6 provides support for some intrinsics that are supported in Arm Compiler 5.

The following table lists some of the commonly used intrinsics that are supported by Arm Compiler 5 and shows whether Arm Compiler for Embedded FuSa 6 supports them or provides an alternative. If there is no support in Arm Compiler for Embedded FuSa 6, you must replace them with suitable inline assembly instructions or calls to the standard library. To use the intrinsic in Arm Compiler for Embedded FuSa 6, you must include the appropriate header file. The ACLE intrinsics

that are supported by Arm Compiler 5 are described in the Arm C Language Extensions 2.1. For more information on the ACLE intrinsics that are supported by Arm Compiler for Embedded FuSa 6, see the latest Arm C Language Extensions.


Note

- This is not an exhaustive list of all the intrinsics.
- The intrinsics provided in `<arm_compat.h>` are only supported for AArch32.

Table 5-6: Compiler intrinsic support in Arm Compiler for Embedded FuSa 6

Intrinsic in Arm Compiler 5	Function	Support in Arm Compiler for Embedded FuSa 6	Header file for Arm Compiler for Embedded FuSa 6
`__breakpoint`	Inserts a `BKPT` instruction.	Yes	`arm_compat.h`
`__cdp`	Inserts a coprocessor instruction.	Yes. In Arm Compiler for Embedded FuSa 6, the equivalent intrinsic is `__arm_cdp`.	`arm_acle.h`
`__clrex`	Inserts a `CLREX` instruction.	No	-
`__clz`	Inserts a `CLZ` instruction or equivalent routine.	Yes	`arm_acle.h`
`__current_pc`	Returns the program counter at this point.	Yes	`arm_compat.h`
`__current_sp`	Returns the stack pointer at this point.	Yes	`arm_compat.h`
`__isb`	Inserts `ISB` or equivalent.	Yes	`arm_acle.h`
`__disable_fiq`	Disables FIQ interrupts (Arm®v7 architecture only). Returns previous value of FIQ mask.	Yes	`arm_compat.h`
`__disable_irq`	Disable IRQ interrupts. Returns previous value of IRQ mask.	Yes	`arm_compat.h`
`__dmb`	Inserts a `DMB` instruction or equivalent.	Yes	`arm_acle.h`
`__dsb`	Inserts a `DSB` instruction or equivalent.	Yes	`arm_acle.h`
`__enable_fiq`	Enables fast interrupts.	Yes	`arm_compat.h`
`__enable_irq`	Enables IRQ interrupts.	Yes	`arm_compat.h`
`__fabs`	Inserts a `VABS` or equivalent code sequence.	No. Arm recommends using the standard C library function `fabs()`.	-
`__fabsf`	Single precision version of `__fabs`.	No. Arm recommends using the standard C library function `fabsf()`.	-
`__force_stores`	Flushes all external variables visible from this function, if they have been changed.	Yes	`arm_compat.h`
`__ldrex`	Inserts an appropriately sized Load Exclusive instruction.	No. This intrinsic is deprecated in ACLE 2.0.	-
`__ldrexd`	Inserts an `LDREXD` instruction.	No. This intrinsic is deprecated in ACLE 2.0.	-
`__ldrt`	Inserts an appropriately sized user-mode load instruction.	No	-

Intrinsic in Arm Compiler 5	Function	Support in Arm Compiler for Embedded FuSa 6	Header file for Arm Compiler for Embedded FuSa 6
`__memory_changed`	Is similar to `__force_stores`, but also reloads the values from memory.	Yes	`arm_compat.h`
`__nop`	Inserts a `NOP` or equivalent instruction that will not be optimized away. It also inserts a sequence point, and scheduling barrier for side-effecting function calls.	Yes	`arm_acle.h`
`__pld`	Inserts a PLD instruction, if supported.	Yes	`arm_acle.h`
`__pldw`	Inserts a `PLDW` instruction, if supported (Arm®v7 architecture with MP).	No. Arm recommends using `__pldx` described in the ACLE document.	`arm_acle.h`
`__pli`	Inserts a PLI instruction, if supported.	Yes	`arm_acle.h`
`__promise`	Compiler assertion that the expression always has a nonzero value. If asserts are enabled then the promise is checked at runtime by evaluating `<expr>` using `assert(<expr>)`.	Yes. However, you must `#include <assert.h>` to use `__promise`. `__promise` has the same behavior as `assert()` unless at least one of `NDEBUG` or `__DO_NOT_LINK_PROMISE_WITH_ASSERT` is defined.	`assert.h`
`__qadd`	Inserts a saturating add instruction, if supported.	Yes	`arm_acle.h`
`__qdbl`	Inserts instructions equivalent to `qadd(val,val)`, if supported.	Yes	`arm_acle.h`
`__qsub`	Inserts a saturating subtract, or equivalent routine, if supported.	Yes	`arm_acle.h`
`__rbit`	Inserts a bit reverse instruction.	Yes	`arm_acle.h`
`__rev`	Insert a `REV`, or endian swap instruction.	Yes	`arm_acle.h`
`__return_address`	Returns value of `LR` when returning from current function, without inhibiting optimizations like inlining or tailcalling.	No. Arm recommends using inline assembly instructions.	-
`__ror`	Insert an `ROR` instruction.	Yes	`arm_acle.h`
`__schedule_barrier`	Create a sequence point without effecting memory or inserting `NOP` instructions. Functions with side effects cannot move past the new sequence point.	Yes	`arm_compat.h`
`__semihost`	Inserts an `SVC` or `BKPT` instruction.	Yes	`arm_compat.h`
`__sev`	Insert a `SEV` instruction. Error if the `SEV` instruction is not supported.	Yes	`arm_acle.h`
`__sqrt`	Inserts a `VSQRT` instruction on targets with a VFP coprocessor.	No	-

Intrinsic in Arm Compiler 5	Function	Support in Arm Compiler for Embedded FuSa 6	Header file for Arm Compiler for Embedded FuSa 6
`__sqrtf`	single precision version of `__sqrt`.	No	-
`__ssat`	Inserts an `SSAT` instruction. Error if the `SSAT` instruction is not supported.	Yes	`arm_acle.h`
`__strex`	Inserts an appropriately sized Store Exclusive instruction.	No. This intrinsic is deprecated in ACLE 2.0.	-
`__strexd`	Inserts a doubleword Store Exclusive instruction.	No. This intrinsic is deprecated in ACLE 2.0.	-
`__strt`	Insert an appropriately sized `STRT` instruction.	No	-
`__swp`	Inserts an appropriately sized `SWP` instruction.	Yes. However, the `SWP` instruction is deprecated, and Arm does not recommend the use of `__swp`.	`arm_acle.h`
`__usat`	Inserts a `USAT` instruction. Error if the `USAT` instruction is not supported.	Yes	`arm_acle.h`
`__wfe`	Inserts a `WFE` instruction. Error if the `WFE` instruction is not supported.	Yes	`arm_acle.h`
`__wfi`	Inserts a `WFI` instruction. Error if the `WFI` instruction is not supported.	Yes	`arm_acle.h`
`__yield`	Inserts a `YIELD` instruction. Error if the `YIELD` instruction is not supported.	Yes	`arm_acle.h`
Armv6 SIMD intrinsics	Inserts an Armv6 SIMD instruction.	No	-
ETSI intrinsics	35 intrinsic functions and 2 global variable flags specified in ETSI G729 used for speech encoding. These are provided in the Arm headers in `dspfns.h`.	No	-
C55x intrinsics	Emulation of selected TI C55x compiler intrinsics.	No	-
`__vfp_status`	Reads the FPSCR.	Yes	`arm_compat.h`
FMA intrinsics	Intrinsics for fused-multiply-add on the Cortex®-M4 or Cortex-A5 processor in c99 mode.	No	-

5.5 Diagnostics for pragma compatibility

Older `armcc` compiler versions supported many pragmas which are not supported by `armclang`, but which could change the semantics of code. When `armclang` encounters these pragmas, it generates diagnostic messages.

The following table shows which diagnostics are generated for each pragma type, and the diagnostic group to which that diagnostic belongs. `armclang` generates diagnostics as follows:

- Errors indicate use of an `armcc` pragma which could change the semantics of code.
- Warnings indicate use of any other `armcc` pragma which is ignored by armclang.
- Pragmas other than those listed are silently ignored.

Table 5-7: Pragma diagnostics

Pragma supported by older compiler versions	Default diagnostic type	Diagnostic group
`#pragma anon_unions`	Warning	`armcc-pragma-anon-unions`
`#pragma no_anon_unions`	Warning	`armcc-pragma-anon-unions`
`#pragma arm`	Error	`armcc-pragma-arm`
`#pragma arm section [<section_type_list>]`	Error	`armcc-pragma-arm`
`#pragma diag_default <tag>[,<tag>,...]`	Error	`armcc-pragma-diag`
`#pragma diag_error <tag>[,<tag>,...]`	Error	`armcc-pragma-diag`
`#pragma diag_remark <tag>[,<tag>,...]`	Warning	`armcc-pragma-diag`
`#pragma diag_suppress <tag>[,<tag>,...]`	Warning	`armcc-pragma-diag`
`#pragma diag_warning <tag>[,<tag>,...]`	Warning	`armcc-pragma-diag`
`#pragma exceptions_unwind`	Error	`armcc-pragma-exceptions-unwind`
`#pragma no_exceptions_unwind`	Error	`armcc-pragma-exceptions-unwind`
`#pragma GCC system_header`	None	-
`#pragma hdrstop`	Warning	`armcc-pragma-hdrstop`
`#pragma import <symbol_name>`	Error	`armcc-pragma-import`
`#pragma inline`	Warning	`armcc-pragma-inline`
`#pragma no_inline`	Warning	`armcc-pragma-inline`
`#pragma no_pch`	Warning	`armcc-pragma-no-pch`
`#pragma O<num>`	Warning	`armcc-pragma-optimization`
`#pragma once`	None	-
`#pragma Ospace`	Warning	`armcc-pragma-optimization`
`#pragma Otime`	Warning	`armcc-pragma-optimization`
`#pragma pack`	None	-
`#pragma pop`	Error	`armcc-pragma-push-pop`

Pragma supported by older compiler versions	Default diagnostic type	Diagnostic group
`#pragma push`	Error	`armcc-pragma-push-pop`
`#pragma softfp_linkage`	Error	`armcc-pragma-softfp-linkage`
`#pragma no_softfp_linkage`	Error	`armcc-pragma-softfp-linkage`
`#pragma thumb`	Error	`armcc-pragma-thumb`
`#pragma weak <symbol>`	None	-
`#pragma weak <symbol1> = <symbol2>`	None	-

In addition to the above diagnostic groups, there are the following additional diagnostic groups:

armcc-pragmas
Contains all of the above diagnostic groups.

unknown-pragmas
Contains diagnostics about pragmas which are not known to armclang, and are not in the above table.

pragmas
Contains all pragma-related diagnostics, including `armcc-pragmas` and `unknown-pragmas`.

Any non-fatal `armclang` diagnostic group can be ignored, upgraded, or downgraded using the following command-line options:

Suppress a group of diagnostics:

```
-Wno-<diag-group>
```

Upgrade a group of diagnostics to warnings:

```
-W<diag-group>
```

Upgrade a group of diagnostics to errors:

```
-Werror=<diag-group>
```

Downgrade a group of diagnostics to warnings:

```
-Wno-error=<diag-group>
```

Related information

Language extension compatibility: pragmas on page 62

5.6 C and C++ implementation compatibility

Arm® Compiler for Embedded FuSa 6 C and C++ implementation details differ from previous compiler versions.

The following table describes the C and C++ implementation detail differences.

Table 5-8: C and C++ implementation detail differences

Feature	Older versions of Arm Compiler	Arm Compiler for Embedded 6
Integer operations		

Shifts	`int shifts > 0 && < 127`
	
	`int left_shifts > 31 == 0`
	
	`int right_shifts > 31 == 0`
	
	(for unsigned or positive)
	
	`int right_shifts > 31 == -1`
	
	(for negative)
	
	`long long shifts > 0 && < 63`
		Warns when shift amount > width of type.
		
		You can use the `-Wshift-count-overflow` option to suppress this warning.

Integer division	Checks that the sign of the remainder matches the sign of the numerator	The sign of the remainder is not necessarily the same as the sign of the numerator.
Floating-point operations		
Default standard	IEEE 754 standard, rounding to nearest representable value, exceptions disabled by default.	All facilities, operations, and representations guaranteed by the IEEE standard are available in single and double-precision. Modes of operation can be selected dynamically at runtime. This is equivalent to the `--fpmode=ieee_full` option in older versions of Arm Compiler.
`#pragma STDC FP_CONTRACT`	`#pragma STDC FP_CONTRACT`	Might affect code generation.
Unions, enums and structs		
Enum packing	Enums are implemented in the smallest integral type of the correct sign to hold the range of the enum values, except for when compiling in C++ mode with `--enum_is_int`.	By default enums are implemented as int, with long long used when required.
Allocation of bit-fields in containers	Allocation of bit-fields in containers.	A container is an object, aligned as the declared type. Its size is sufficient to contain the bit-field, but might be smaller or larger than the bit-field declared type.
Signedness of plain bit-fields	Unsigned. Plain bit-fields declared without either the signed or unsigned qualifiers default to unsigned. The `--signed_bitfields` option treats plain bit-fields as signed.	Signed. Plain bit-fields declared without either the signed or unsigned qualifiers default to signed. There is no equivalent to either the `--signed_bitfields` or `--no_signed_bitfields` options.
Arrays and pointers		
Casting between integers and pointers	No change of representation	Converting a signed integer to a pointer type with greater bit width sign-extends the integer. Converting an unsigned integer to a pointer type with greater bit width zero-extends the integer.
Misc C		
`sizeof(wchar_t)`	2 bytes	4 bytes

Feature	Older versions of Arm Compiler	Arm Compiler for Embedded 6
`size_t`	Defined as unsigned int, 32-bit.	Defined as unsigned int in 32-bit architectures, and unsigned long; in 64-bit architectures.
`ptrdiff_t`	Defined as signed int, 32-bit.	Defined as unsigned int in 32-bit architectures, and signed long in 64-bit architectures.
Misc C++		
C++ library	Rogue Wave Standard C++ Library	LLVM libc++ Library **Note:** When the C++ library is used in source code, there is limited compatibility between object code created with Arm Compiler for Embedded 6 and object code created with Arm Compiler 5. This also applies to indirect use of the C++ library, for example memory allocation or exception handling.
Implicit inclusion	If compilation requires a template definition from a template declared in a header file `xyz.h`, the compiler implicitly includes the file `xyz.cc` or `xyz.CC`.	Not supported.
Alternative template lookup algorithms	When performing referencing context lookups, name lookup matches against names from the instantiation context as well as from the template definition context.	Not supported.
Exceptions	Off by default, function unwinding on with `--exceptions` by default.	On by default in C++ mode. **Note:** For C++ code, `-fexceptions` has a large increase in the code size. If you use `-fno_exceptions`, then the code size is in the range of that created with Arm Compiler 5.
Translation		
Diagnostics messages format	`source-file, line-number : severity : error-code : explanation`	`source-file:line-number:char-number: description [diagnostic-flag]`
Environment		
Physical source file bytes interpretation	Current system locale dependent or set using the `--locale` command-line option.	UTF-8, either with or without the *Byte Order Mark* (BOM).

Related information

Language extension compatibility: keywords on page 55
Language extension compatibility: attributes on page 58
Language extension compatibility: pragmas on page 62

5.7 Compatibility of C++ objects

The compatibility of C++ objects compiled with Arm® Compiler 5 depends on the C++ libraries used.

Compatibility with objects compiled using Rogue Wave standard library headers

Arm Compiler for Embedded FuSa 6 does not support binary compatibility with objects compiled using the Rogue Wave standard library include files.

There are warnings at link time when objects are mixed. `L6869W` is reported if an object requests the Rogue Wave standard library. `L6870W` is reported when using an object that is compiled with Arm Compiler 5 with exceptions support.

The impact of mixing objects that have been compiled against different C++ standard library headers might include:

- Undefined symbol errors.
- Increased code size.
- Possible runtime errors.

If you have Arm Compiler for Embedded FuSa 6 objects that have been compiled with the legacy `--stdlib=legacy_cpplib` option then these objects use the Rogue Wave standard library and therefore might be incompatible with objects created using Arm Compiler 6.4 or later. To resolve these issues, you must recompile all object files with Arm Compiler 6.4 or later.

Compatibility with C++ objects compiled using Arm Compiler 5

The choice of C++ libraries at link time must match the choice of C++ include files at compile time for all input objects. Arm Compiler 5 objects that use the Rogue Wave C++ libraries are not compatible with Arm Compiler for Embedded FuSa 6 objects. Arm Compiler 5 objects that use C++ but do not make use of the Rogue Wave header files can be compatible with Arm Compiler for Embedded FuSa 6 objects that use libc++ but this is not guaranteed.

Arm recommends using Arm Compiler for Embedded FuSa 6 for building the object files.

Compatibility of arrays of objects compiled using Arm Compiler 5

Arm Compiler for Embedded FuSa 6 is not compatible with objects from Arm Compiler 5 that use operator `new[]` and `delete[]`. Undefined symbol errors result at link time because Arm Compiler for Embedded FuSa 6 does not provide the helper functions that Arm Compiler 5 depends on. For example:

```
//construct.cpp:

class Foo
{
public:
    Foo() : x_(new int) { *x_ = 0; }
    void setX(int x) { *x_ = x; }
    ~Foo() { delete x_; }
private:
    int* x_;
```

```
};

void func(void)
{
    Foo* array;
    array = new Foo [10];
    array[0].setX(1);
    delete[] array;
}
```

Build this example with the Arm Compiler 5 compiler, `armcc`, and link with the Arm Compiler for Embedded FuSa 6 linker, `armlink`, using:

```
armcc -c construct.cpp -Ospace -O1 --cpu=cortex-a9
armlink construct.o -o construct.axf
```

The linker reports:

```
Error: L6218E: Undefined symbol __aeabi_vec_delete (referred from construct.o).
Error: L6218E: Undefined symbol __aeabi_vec_new_cookie_nodtor (referred from
 construct.o).
```

To resolve these linker errors, you must use the Arm Compiler for Embedded FuSa 6 compiler, `armclang`, to compile all C++ files that use the `new[]` and `delete[]` operators.


Note

You do not have to specify `--stdlib=libc++` for `armlink`, because this is the default and only option in Arm Compiler 6.4, and later.

Related information

--stdlib

6. Migrating from armasm to the armclang Integrated Assembler

Describes how to migrate assembly code from legacy `armasm` syntax to GNU syntax (used by `armclang`).

The `armasm` legacy assembler is deprecated, and it has not been updated since Arm® Compiler 6.10. Also, `armasm` does not support:

- Armv8.4-A or later architectures.
- Certain backported options in Armv8.2-A and Armv8.3-A.
- Assembling `SVE` instructions.
- Armv8.1-M or later architectures, including MVE.
- All versions of the Armv8-R architecture.

As a reminder, `armasm` always reports the deprecation warning `A1950W`. To suppress this message, specify the `--diag_suppress=1950` option.

6.1 Migration of assembler command-line options from armasm to the armclang integrated assembler

Arm® Compiler for Embedded FuSa 6 provides many command-line options, including most Clang command-line options as well as several Arm-specific options.

This topic includes descriptions of [COMMUNITY] features. See Support level definitions.

The following GNU assembly directives are [COMMUNITY] features:

- `.eabi_attribute Tag_ABI_PCS_RO_data, <value>`
- `.eabi_attribute Tag_ABI_PCS_R9_use, <value>`
- `.eabi_attribute Tag_ABI_PCS_RW_data, <value>`
- `.eabi_attribute Tag_ABI_VFP_args, <value>`
- `.eabi_attribute Tag_CPU_unaligned_access, <value>`
- `.ident`
- `.protected`

- `.section .note.GNU-stack, "x"`
- `-Wa,--noexecstack`
- `-Wa,-L`
- `-Wa,-defsym,<symbol>=<value>`

The following table describes the most common `armasm` command-line options, and shows the equivalent options for the `armclang` integrated assembler.

Additional information about command-line options is available:

- The *Arm Compiler for Embedded FuSa Reference Guide* provides more detail about the command-line options.
- For a full list of Clang command-line options, consult the Clang and LLVM documentation.

Table 6-1: Comparison of command-line options in armasm and the armclang integrated assembler

`armasm` option	`armclang` integrated assembler option	Description
`--arm_only`	No equivalent.	Enforces A32 instructions only.
`--apcs=/nointerwork`	No equivalent.	Specifies that the code in the input file can interwork between A32 and T32 safely. Interworking is always enabled in Arm Compiler for Embedded FuSa 6.
`--apcs=/ropi`, `--apcs=/noropi`	No direct equivalent.	With `armasm`, the options specify whether the code in the input file is Read-Only Position Independent (ROPI) code. With the `armclang` integrated assembler, use the GNU assembly `.eabi_attribute` directive instead. To specify that the code is ROPI code, use the directive as follows: `.eabi_attribute Tag_ABI_PCS_RO_data, 1` The code is marked as not ROPI code by default.

`--apcs=/rwpi`,
 	
`--apcs=/norwpi`
	No direct equivalent.	With `armasm`, the options specify whether the code in the input file is *Read/Write Position Independent* (RWPI) code.
		
		With the `armclang` integrated assembler, use the GNU assembly `.eabi_attribute` directive instead.
		
		To specify that the code is RWPI code, use the directive as follows:
		
		`.eabi_attribute Tag_ABI_PCS_R9_use, 1`
		
		`.eabi_attribute Tag_ABI_PCS_RW_data, 2`
		
		The code is marked as not RWPI code by default.

armasm option	armclang integrated assembler option	Description

`--apcs=/hardfp`,
 	
`--apcs=/softfp`
	No direct equivalent.	With `armasm`, the options set attributes in the object file to request hardware or software floating-point linkage.
		
		With the `armclang` integrated assembler, use the GNU assembly `.eabi_attribute` directive instead.
		
		To request hardware floating-point linkage, use the directive as follows:
		
		`.eabi_attribute Tag_ABI_VFP_args, 1`
		
		To request software floating-point linkage, use the directive as follows:
		
		`.eabi_attribute Tag_ABI_VFP_args, 0`

`--checkreglist`, `--diag_warning=1206`	This is the default.	Generates warnings if register lists in `LDM` and `STM` instructions are not provided in increasing register number order. **Note:** This warning cannot be suppressed or upgraded to an error.
`--comment_section`, `--no_comment_section`	No direct equivalent.	With `armasm`, the option controls the inclusion of a comment section `.comment` in object files. With the `armclang` integrated assembler, use the GNU assembly `.ident` directive to manually add a comment section.
`--debug`, `-g`	`-g`	Instructs the assembler to generate DWARF debug tables. With `armasm`, the default format for debug tables is DWARF 3. Named local labels are not preserved in the object file, unless the `--keep` option is used. With the `armclang` integrated assembler, the default format for debug tables is DWARF 4. Named local labels are always preserved in the object file. See the entry for `--keep` in this table for details.
`--diag_warning=1645`	No equivalent.	With `armasm`, the option enables warnings about instruction substitutions. With the `armclang` integrated assembler, instruction substitution support is limited. Where it is not supported, the assembler generates an error message. Use the `armasm` warning when migrating code to find instructions being substituted and perform the substitution manually.

armasm option	armclang integrated assembler option	Description
`--diag_warning=1763`	No equivalent.	With `armasm`, the option enables warnings about automatic generation of `IT` blocks when assembling T32 code (formerly Thumb code). With the `armclang` integrated assembler, automatic generation of `IT` blocks is disabled by default. The assembler generates an error message when assembling conditional instructions without an enclosing `IT` block. To enable automatic generation of `IT` blocks, use the command-line option `-mimplicit-it=always` or `-mimplicit-it=thumb`.
`--dllexport_all`	No direct equivalent.	With `armasm`, the option gives all exported global symbols `STV_PROTECTED` visibility in `ELF` rather than `STV_HIDDEN`, unless overridden by source directives. With the `armclang` integrated assembler, use the GNU assembly `.protected` directive to manually give exported symbols `STV_PROTECTED` visibility.
`--execstack`, `--no_execstack`	`-Wa,--noexecstack` No direct equivalent for `--execstack`.	With `armasm`, the option generates a `.note.GNU-stack` section marking the stack as either executable or non-executable. With the `armclang` integrated assembler, the equivalent option can be used to generate a `.note.GNU-stack` section marking the stack as non-executable. To generate such a section and mark the stack as executable, use the GNU assembly `.section` directive as follows: `.section .note.GNU-stack, "x"` The command-line option `-Wa,--noexecstack` overrides the use of the `.section` directive.
`--keep`	No direct equivalent.	With `armasm`, the option instructs the assembler to keep named local labels in the symbol table of the object file, for use by the debugger. With the `armclang` integrated assembler, named local labels defined without using the GNU assembly local symbol name prefix `.L` are always preserved in the object file. Use the command-line option `-Wa,-L` to automatically preserve all named local labels defined using the GNU assembly local symbol name prefix.

armasm option	armclang integrated assembler option	Description
-M	-M	Instructs the assembler to produce a list of makefile dependency lines suitable for use by a make utility. **Note:** Only dependencies visible to the preprocessor are included. Files added using the GNU assembler syntax .incbin or .include directives, or armasm syntax INCBIN, INCLUDE, or GET directives, are not included. **Note:** With the armclang integrated assembler, using this option with -o outputs the makefile dependency lines to the file specified. An object file is not produced.
--mm	-MM	Creates a single makefile dependency file, without the system header files. **Note:** Only dependencies visible to the preprocessor are included. Files added using the GNU assembler syntax .incbin or .include directives (or armasm syntax INCBIN, INCLUDE, or GET directives) are not included. **Note:** With the armclang integrated assembler, using this option with -o outputs the makefile dependency file to the file specified. An object file is not produced.
--no_hide_all	-fvisibility=default	Gives all exported and imported global symbols STV_DEFAULT visibility in ELF rather than STV_HIDDEN, unless overridden using source directives.
--predefine "<directive>", --pd "<directive>"	-Wa,-defsym,<symbol>=<value>	With armasm, the option instructs the assembler to pre-execute one of the SETA, SETL, or SETS directives as specified using <directive>. With the armclang integrated assembler, the option instructs the assembler to pre-define the symbol <symbol> with the value <value>. This GNU assembly .set directive can be used to change this value in the file being assembled.
--reduce_paths, --no_reduce_paths	No direct equivalent.	Windows systems impose a 260 character limit on file paths. Arm recommends that you avoid using long and deeply nested file paths, in preference to minimizing path lengths using the armasm option --reduce_paths, which only works on 32-bit Windows systems.

armasm option	armclang integrated assembler option	Description
--unaligned_access, --no_unaligned_access	No direct equivalent.	With armasm, the options instruct the assembler to set an attribute in the object file to enable or disable the use of unaligned accesses. With the armclang integrated assembler, use the GNU assembly .eabi_attribute directive instead. To enable the use of unaligned access, use the directive as follows: .eabi_attribute Tag_CPU_unaligned_access, 1 To disable the use of unaligned access, use the directive as follows: .eabi_attribute Tag_CPU_unaligned_access, 0
--unsafe	No direct equivalent.	With armasm, the option enables instructions for architectures other than the target architecture to be assembled without error. With the armclang integrated assembler, use the GNU assembly .inst directive to generate such instructions.

Related information

GNU Binutils - Using as: .section

6.2 Overview of differences between armasm and GNU syntax assembly code

armasm (for assembling legacy assembly code) uses armasm syntax assembly code.

armclang aims to be compatible with GNU syntax assembly code (that is, the assembly code syntax supported by the GNU assembler, as).

If you have legacy assembly code that you want to assemble with armclang, you must convert that assembly code from armasm syntax to GNU syntax.

The specific instructions and order of operands in your UAL syntax assembly code do not change during this migration process.

However, you need to make changes to the syntax of your assembly code. These changes include:

- The directives in your code.
- The format of labels, comments, and some types of literals.

- Some symbol names.
- The operators in your code.

The following examples show simple, equivalent, assembly code in both `armasm` and GNU syntax.

GNU syntax

```
// Simple GNU syntax example [1]
//
// Iterate round a loop 10 times, adding 1 to a register each time.

  .section .text,"ax"    // [2]
  .global main
  .balign 4
  .type main, %function
main:                    // [3]
  MOV      w5,#0x64      // W5 = 100  [4]
  MOV      w4,#0         // W4 = 0
  B        test_loop     // branch to test_loop
loop:
  ADD      w5,w5,#1      // Add 1 to W5
  ADD      w4,w4,#1      // Add 1 to W4
test_loop:
  CMP      w4,#0xa       // if W4 < 10, branch back to loop
  BLT      loop
  .end                   // [5]
```

Example notes

[1] See Comments.

[2] See Sections.

[3] See Labels.

[4] See Numeric literals.

[5] See Miscellaneous directives.

armasm syntax

```
; Simple armasm syntax example
;
; Iterate round a loop 10 times, adding 1 to a register each time.
  AREA ||.text||, CODE, READONLY, ALIGN=2
  ENTRY
main PROC
  MOV      w5,#0x64      ; W5 = 100
  MOV      w4,#0         ; W4 = 0
  B        test_loop     ; branch to test_loop
loop
  ADD      w5,w5,#1      ; Add 1 to W5
  ADD      w4,w4,#1      ; Add 1 to W4
test_loop
  CMP      w4,#0xa       ; if W4 < 10, branch back to loop
  BLT      loop
  ENDP

  END
```

Related information

Comments on page 82
Labels on page 83
Numeric local labels on page 83
Functions on page 85
Sections on page 86
Symbol naming rules on page 88
Numeric literals on page 88
Operators on page 90
Alignment on page 90
PC-relative addressing on page 91
Conditional directives on page 93
Data definition directives on page 94
Instruction set directives on page 96
Miscellaneous directives on page 96
Symbol definition directives on page 98
About the Unified Assembler Language

6.3 Comments

A comment identifies text that the assembler ignores.

GNU syntax

GNU syntax assembly code provides two different methods for marking comments:

- The `/*` and `*/` markers identify multiline comments:

```
/* This is a comment
that spans multiple
lines */
```

- The `//` marker identifies the remainder of a line as a comment:

```
    MOV R0,#16    // Load R0 with 16
```

armasm syntax

A comment is the final part of a source line. The first semicolon on a line marks the beginning of a comment except where the semicolon appears inside a string literal.

The end of the line is the end of the comment. A comment alone is a valid line.

For example:

```
; This whole line is a comment
```

```
; And also this line

myProc: PROC
    MOV     r1, #16    ; Load R0 with 16
```

Related information

GNU Binutils - Using as: Comments

6.4 Labels

Labels are symbolic representations of addresses. You can use labels to mark specific addresses that you want to refer to from other parts of the code.

GNU syntax

A label is written as a symbol that either begins in the first column, or has nothing but whitespace between the first column and the label. A label can appear either in a line on its own, or in a line with an instruction or directive. A colon ":" follows the label (whitespace is allowed between the label and the colon):

```
      MOV R0,#16
loop:               // "loop" label on its own line
      SUB R0,R0,#1
      CMP R0,#0
      BGT loop
```

```
      MOV R0,#16
loop: SUB R0,R0,#1  // "loop" label in a line with an instruction
      CMP R0,#0
      BGT loop
```

armasm syntax

A label is written as a symbol beginning in the first column. A label can appear either in a line on its own, or in a line with an instruction or directive. Whitespace separates the label from any following instruction or directive:

```
     MOV R0,#16
loop SUB R0,R0,#1 ; "loop" is a label
     CMP R0,#0
     BGT loop
```

Related information

GNU Binutils - Using as: Labels

6.5 Numeric local labels

Numeric local labels are a type of label that you refer to by a number rather than by name. Unlike other labels, the same numeric local label can be used multiple times and the same number can be used for more than one numeric local label.

GNU syntax

A numeric local label is a number in the range 0-99.

Numeric local labels follow the same syntax as all other labels.

Refer to numeric local labels using the following syntax:

```
<n>{f|b}
```

Where:

- `<n>` is the number of the numeric local label in the range 0-99.
- `f` and `b` instruct the `armclang` integrated assembler to search forwards and backwards respectively. There is no default. You must specify one of `f` or `b`.

For example, the following code implements an incrementing loop:

```
        MOV     r4,#1       // r4=1

1:                          // Local label
        ADD     r4,r4,#1    // Increment r4
        CMP     r4,#0x5     // if r4 < 5...
        BLT     1b          // ...branch backwards to local label "1"
```


Note

GNU syntax assembly code does not provide mechanisms for restricting the scope of local labels.

armasm syntax

A numeric local label is a number in the range 0-99, optionally followed by a scope name corresponding to a `ROUT` directive.

Numeric local labels follow the same syntax as all other labels.

Refer to numeric local labels using the following syntax:

```
%[F|B][A|T]<n>[<routname>]
```

Where:

- `F` and `B` instruct the legacy assembler to search forwards and backwards respectively. By default, the legacy assembler searches backwards first, then forwards.

- `A` and `T` instruct the legacy assembler to search all macro levels or only the current macro level respectively. By default, the assembler searches all macros from the current level to the top level, but does not search lower level macros.
- `<n>` is the number of the numeric local label in the range 0-99.
- `<routname>` is an optional scope label corresponding to a `ROUT` directive. If `<routname>` is specified in either a label or a reference to a label, the legacy assembler checks it against the name of the nearest preceding `ROUT` directive. If it does not match, the legacy assembler generates an error message and the assembly fails.

For example, the following code implements an incrementing loop:

```
        MOV     r4,#1       ; r4=1

1                           ; Local label
        ADD     r4,r4,#1    ; Increment r4
        CMP     r4,#0x5     ; if r4 < 5...
        BLT     %b1         ; ...branch backwards to local label "1"
```

Here is the same example using a `ROUT` directive to restrict the scope of the local label:

```
routA   ROUT                ; Start of "routA" scope

        MOV     r4,#1       ; r4=1
1routA                      ; Local label
        ADD     r4,r4,#1    ; Increment r4
        CMP     r4,#0x9     ; if r4 < 9...
        BLT     %b1routA    ; ...branch backwards to local label "1routA"
routB   ROUT                ; Start of "routB" scope (and therefore end of "routA"
 scope)
```

Related information

GNU Binutils - Using as: Labels
ROUT directive

6.6 Functions

Assemblers can identify the start of a function when producing DWARF call frame information for ELF.

GNU syntax

Use the `.type` directive to identify symbols as functions. For example:

```
        .type myproc, "function"

myproc:
        // Procedure body
```

GNU syntax assembly code provides the `.func` and `.endfunc` directives. However, these are not supported by `armclang`. `armclang` uses the `.size` directive to set the symbol size:

```
        .type myproc, "function"

myproc:
        // Procedure body
.Lmyproc_end0:
        .size myproc, .Lmyproc_end0-myproc
```

Functions must be typed to link properly.

armasm syntax

The `FUNCTION` directive marks the start of a function. `PROC` is a synonym for `FUNCTION`.

The `ENDFUNC` directive marks the end of a function. `ENDP` is a synonym for `ENDFUNC`.

For example:

```
myproc  PROC

        ; Procedure body
        ENDP
```

Related information

GNU Binutils - Using as: .type

6.7 Sections

Sections are independent, named, indivisible chunks of code or data that are manipulated by the linker.

GNU syntax

The `.section` directive instructs the `armclang` integrated assembler to assemble a new code or data section.

Flags provide information about the section. Available section flags include the following:

- `a` specifies that the section is allocatable.
- `x` specifies that the section is executable.
- `w` specifies that the section is writable.
- `s` specifies that the section contains null-terminated strings.

For example:

```
    .section  mysection,"ax"
```

Not all `armasm` syntax `AREA` attributes map onto GNU syntax `.section` flags. For example, the `armasm` syntax `ALIGN` attribute corresponds to the GNU syntax `.balign` directive, rather than a `.section` flag:

```
    .section  mysection,"ax"
    .balign 8
```

When using Arm® Compiler 5, section names do not need to be unique. Therefore, you could use the same section name to create different section types.

Arm Compiler for Embedded FuSa 6 supports multiple sections with the same section name only if you specify a unique ID. You must ensure that different section types either:

- Have a unique section name.
- Have a unique ID, if they have the same section name.


Note

If you use the same section name for another section or symbol, without a unique ID, then integrated assembler gives an error.

```
    .section test, "ax", %progbits
    nop

    .section test, "aw", %progbits
    .word 0
```

The integrated assembler gives an error when you assemble this example with:

```
armclang --target=arm-arm-none-eabi -c -mcpu=cortex-a8 err.s
err.s:4:9: error: changed section flags for test, expected: 0x6
        .section test, "aw", %progbits
        ^
```

---

armasm syntax

The `AREA` directive instructs the legacy assembler to assemble a new code or data section.

Section attributes within the `AREA` directive provide information about the section. Available section attributes include the following:

- `CODE` specifies that the section contains machine instructions.
- `READONLY` specifies that the section must not be written to.
- `ALIGN=<n>` specifies that the section is aligned on a $2^{<n>}$ byte boundary

For example:

```
AREA mysection, CODE, READONLY, ALIGN=3
```

The `ALIGN` attribute does not take the same values as the `ALIGN` directive. The `ALIGN=<n>` attribute on the `AREA` directive aligns on a $2^{<n>}$ byte boundary. The `ALIGN <n>` directive aligns on an `<n>`-byte boundary.

Related information

GNU Binutils - Using as: .section

6.8 Symbol naming rules

`armasm` syntax assembly code and GNU syntax assembly code use similar, but different naming rules for symbols.

Symbol naming rules which are common to both `armasm` syntax and GNU syntax include:

- Symbol names must be unique within their scope.
- Symbol names are case-sensitive, and all characters in the symbol name are significant.
- Symbols must not use the same name as built-in variable names or predefined symbol names.

Symbol naming rules which differ between `armasm` syntax and GNU syntax include:

- `armasm` syntax symbols must start with a letter or the underscore character "_".

  GNU syntax symbols must start with a letter, the underscore character "_", or a period ".".
- `armasm` syntax symbols use double bars to delimit symbol names containing non-alphanumeric characters (except for the underscore):

  ```
  IMPORT ||Image$$ARM_LIB_STACKHEAP$$ZI$$Limit||
  ```

  GNU syntax symbols do not require double bars:

  ```
  .global Image$$ARM_LIB_STACKHEAP$$ZI$$Limit
  ```

Related information

GNU Binutils - Using as: Symbol Names

6.9 Numeric literals

armasm syntax assembly and GNU syntax assembly provide different methods for specifying some types of numeric literal.

Implicit shift operations

armasm syntax assembly allows immediate values with an implicit shift operation. For example, the MOVK instruction takes a 16-bit operand with an optional left shift. armasm accepts the instruction `MOVK x1, #0x40000`, converting the operand automatically to `MOVK x1, #0x4, LSL #16`.

GNU syntax assembly expects immediate values to be presented as encoded. The instruction `MOVK x1, #0x40000` results in the following message: `error: immediate must be an integer in range [0, 65535].`

Hexadecimal literals

armasm syntax assembly provides two methods for specifying hexadecimal literals, the prefixes "&" and "0x".

For example, the following are equivalent:

```
    ADD     r1, #0xAF
    ADD     r1, #&AF
```

GNU syntax assembly only supports the "0x" prefix for specifying hexadecimal literals. Convert any "&" prefixes to "0x".

<n-base>_<n-digits> format

armasm syntax assembly lets you specify numeric literals using the following format:

```
<n-base>_<n-digits>
```

For example:

- `2_1101` is the binary literal 1101 (13 in decimal).
- `8_27` is the octal literal 27 (23 in decimal).

GNU syntax assembly does not support the `<n-base>_<n-digits>` format. Convert all instances to a supported numeric literal form.

For example:

```
    ADD     r1, #2_1101
```

You could convert this instruction to:

```
    ADD     r1, #13
```

or:

```
    ADD     r1, #0xD
```

Related information

GNU Binutils - Using as: Integers

6.10 Operators

`armasm` syntax assembly and GNU syntax assembly provide different methods for specifying some operators.

The following table shows how to translate `armasm` syntax operators to GNU syntax operators.

Table 6-2: Operator translation

`armasm` syntax operator	GNU syntax operator
`:OR:`	`|`
`:EOR:`	`^`
`:AND:`	`&`
`:NOT:`	`~`
`:SHL:`	`<<`
`:SHR:`	`>>`
`:LOR:`	`||`
`:LAND:`	`&&`
`:ROL:`	No GNU equivalent
`:ROR:`	No GNU equivalent

Related information

GNU Binutils - Using as: Infix Operators

6.11 Alignment

Data and code must be aligned to appropriate boundaries.

For example, The T32 pseudo-instruction `ADR` can only load addresses that are word aligned, but a label within T32 code might not be word aligned. You must use an alignment directive to ensure four-byte alignment of an address within T32 code.

An alignment directive aligns the current location to a specified boundary by padding with zeros or `NOP` instructions.


Note

The integrated assembler sets a minimum alignment of 4 bytes for a `.text` section. However, if you define your own sections with the integrated assembler, then you must include the `.balign` directive to set the correct alignment. For a section containing T32 instructions, set the alignment to 2 bytes. For a section containing A32 instructions, set the alignment to 4 bytes.

GNU syntax

GNU syntax assembly provides the `.balign <n>` directive, which uses the same format as `ALIGN`.

Convert all instances of `ALIGN <n>` to `.balign <n>`.


Note

GNU syntax assembly also provides the `.align <n>` directive. However, the format of `<n>` varies from system to system. The `.balign` directive provides the same alignment functionality as `.align` with a consistent behavior across all architectures.

Convert all instances of `PRESERVE8` to `.eabi_attribute Tag_ABI_align_preserved, 1`.

armasm syntax

`armasm` syntax assembly provides the `ALIGN <n>` directive, where `<n>` specifies the alignment boundary in bytes. For example, the directive `ALIGN 128` aligns addresses to 128-byte boundaries.

`armasm` syntax assembly also provides the `PRESERVE8` directive. The `PRESERVE8` directive specifies that the current file preserves eight-byte alignment of the stack.

Related information

GNU Binutils - Using as: ARM Machine Directives

6.12 PC-relative addressing

`armasm` syntax assembly and GNU syntax assembly provide different methods for performing PC-relative addressing.

GNU syntax

GNU syntax assembly does not support the `{pc}` symbol. Instead, it uses the special dot "." character, as follows:

```
    ADRP x0, .
```

armasm syntax

`armasm` syntax assembly provides the symbol `{pc}` to let you specify an address relative to the current instruction.

For example:

```
    ADRP x0, {pc}
```

Related information

GNU Binutils - Using as: The Special Dot Symbol

6.13 Instruction substitutions

When the value of an Operand2 constant is not available with a given instruction, but its logical inverse or negation is available, then both `armasm` and `armclang` produce an equivalent instruction with the inverted or negated constant.

For more information, see A32 and T32 instruction substitutions.

Substitutions when using armasm

To find instruction substitutions in code assembled using `armasm`, use the command-line option `--diag_warning=1645`.

Substitutions when using armclang integrated assembler

`armclang` does not generate a warning when instruction substitutions occur. You can disable this substitution using the `armclang` option `-mno-neg-immediates`.

Related information

-mno-neg-immediates armclang option

6.14 A32 and T32 pseudo-instructions

`armasm` supports several A32 and T32 pseudo-instructions. The support for the pseudo-instructions varies with the `armclang` integrated assembler.

More information about the A32 and T32 pseudo-instructions is available in the *Arm Compiler for Embedded FuSa Reference Guide*. The following table shows how to migrate the pseudo-instructions for use with the `armclang` integrated assembler:

Table 6-3: A32 and T32 pseudo-instruction migration

A32 and T32 pseudo-instruction	`armclang` integrated assembler equivalent
`ADRL`*`cond`* `<Rd>, <label>`	No equivalent. Use an `ADR` instruction if *label* is within the supported offset range. Use an `LDR` pseudo-instruction if *label* is outside the supported offset range for an `ADR` instruction.
`CPY`*`cond`* `<Rd>, <Rm>`	`mov`*`cond`* `<Rd>, <Rm>`

A32 and T32 pseudo-instruction	armclang integrated assembler equivalent
`LDR`*cond*`{.W} <Rt>, =<expr>`	Identical.
`LDR`*cond*`{.W} <Rt>, =<label_expr>`	Identical.

`MOV32`*cond* `<Rd>, <expr>`	Use the following instruction sequence:
	
	`movw{cond} Rd, #:lower16:expr`
	
	`movt{cond} Rd, #:upper16:expr`

`NEG`*cond* `<Rd>, <Rm>`	`rsbs`*cond* `<Rd>, <Rm>, #0`

`UND`*cond*`{.W} {#<expr>}`	Use the following instruction for the A32 instruction set:
	
	`udf{c}{q} {#}imm`
	
	Use the following instruction for the T32 instruction set with 8-bit encoding:
	
	`udf{c}{q} {#}imm`
	
	Use the following instruction for the T32 instruction set with 16-bit encoding:
	
	`udf{c}.w {#}imm`

Related information

ADRL pseudo-instruction

6.15 Conditional directives

Conditional directives specify conditions that control whether or not to assemble a sequence of assembly code.

The following table shows how to translate `armasm` syntax conditional directives to GNU syntax directives:

Table 6-4: Conditional directive translation

armasm syntax directive	GNU syntax directive
`IF`	`.if` family of directives
`IF :DEF:`	`.ifdef`
`IF :LNOT::DEF:`	`.ifndef`
`ELSE`	`.else`
`ELSEIF`	`.elseif`
`ENDIF`	`.endif`

In addition to the change in directives shown, the following syntax differences apply:

- In `armasm` syntax, the conditional directives can use forward references. This is possible as `armasm` is a two-pass assembler. In GNU syntax, forward references are not supported, as the `armclang` integrated assembler only performs one pass over the main text.

  If a forward reference is used with the `.ifdef` directive, the condition will always fail implicitly. Similarly, if a forward reference is used with the `.ifndef` directive, the condition will always pass implicitly.
- In `armasm` syntax, the maximum total nesting depth for directive structures such as `IF...ELSE...ENDIF` is 256. In GNU syntax, this limit is not applicable.

Related information

GNU Binutils - Using as: .if

6.16 Data definition directives

Data definition directives allocate memory, define data structures, and set initial contents of memory.

The following table shows how to translate `armasm` syntax data definition directives to GNU syntax directives:


Note

This list only contains examples of common data definition assembly directives. It is not exhaustive.

Table 6-5: Data definition directives translation

`armasm` syntax directive	GNU syntax directive	Description
`DCB`	`.byte`	Allocate one-byte blocks of memory, and specify the initial contents.
`DCW`	`.hword`	Allocate two-byte blocks of memory, and specify the initial contents.
`DCD`	`.word`	Allocate four-byte blocks of memory, and specify the initial contents.
`DCI`	`.inst`	Allocate a block of memory in the code, and specify the opcode. In A32 code, this is a four-byte block. In T32 code, this can be a two-byte or four-byte block. `.inst.n` allocates a two-byte block and `.inst.w` allocates a four-byte block.
`DCQ`	`.quad`	Allocate eight-byte blocks of memory, and specify the initial contents.

armasm syntax directive	GNU syntax directive	Description
SPACE	.org	Allocate a zeroed block of memory. The armasm syntax SPACE directive allocates a zeroed block of memory with the specified size. The GNU assembly .org directive zeroes the memory up to the given address. The address must be greater than the address at which the directive is placed.

Example: Creating a 100-byte zeroed block of memory using the armasm syntax SPACE directive

The following example shows the armasm syntax and GNU syntax methods of creating a 100-byte zeroed block of memory using these directives:

```
; armasm syntax
; implementation

start_address   SPACE   0x100
```

Example: Creating a 100-byte zeroed block of memory using the GNU syntax .org directive

```
// GNU syntax implementation
start_address:
.org    start_address + 0x100
```

If label arithmetic is not required, you can use the GNU assembly .space directive instead of the .org directive. However, Arm recommends using the .org directive wherever possible.

Example: Write a vector table in armasm syntax

```
Vectors
                LDR PC, Reset_Addr
                LDR PC, Undefined_Addr
                LDR PC, SVC_Addr
                LDR PC, Prefetch_Addr
                LDR PC, Abort_Addr
                B .          ; Reserved vector
                LDR PC, IRQ_Addr
                LDR PC, FIQ_Addr

Reset_Addr      DCD     Reset_Handler
Undefined_Addr  DCD     Undefined_Handler
SVC_Addr        DCD     SVC_Handler
Prefetch_Addr   DCD     Prefetch_Handler
Abort_Addr      DCD     Abort_Handler
IRQ_Addr        DCD     IRQ_Handler
FIQ_Addr        DCD     FIQ_Handler
```

Example: Rewrite a vector table in GNU syntax

```
Vectors:
                ldr pc, Reset_Addr
```

```
                ldr pc, Undefined_Addr
                ldr pc, SVC_Addr
                ldr pc, Prefetch_Addr
                ldr pc, Abort_Addr
                b .                         // Reserved vector
                ldr pc, IRQ_Addr
                ldr pc, FIQ_Addr

                .balign 4
Reset_Addr:
                .word Reset_Handler
Undefined_Addr:
                .word Undefined_Handler
SVC_Addr:
                .word SVC_Handler
Prefetch_Addr:
                .word Prefetch_Handler
Abort_Addr:
                .word Abort_Handler
IRQ_Addr:
                .word IRQ_Handler
FIQ_Addr:
                word FIQ_Handler
```

Related information

GNU Binutils - Using as: .byte

6.17 Instruction set directives

Instruction set directives instruct the assembler to interpret subsequent instructions as either A32 or T32 instructions.

The following table shows how to translate `armasm` syntax instruction set directives to GNU syntax directives:

Table 6-6: Instruction set directives translation

armasm syntax directive	GNU syntax directive	Description
`ARM` or `CODE32`	`.arm` or `.code 32`	Interpret subsequent instructions as A32 instructions.
`THUMB` or `CODE16`	`.thumb` or `.code 16`	Interpret subsequent instructions as T32 instructions.

Related information

GNU Binutils - Using as: ARM Machine Directives

6.18 Miscellaneous directives

Miscellaneous directives perform a range of different functions.

This topic includes descriptions of [COMMUNITY] features. See Support level definitions.

The following table shows how to translate `armasm` syntax miscellaneous directives to GNU syntax directives:

Table 6-7: Miscellaneous directives translation

armasm syntax directive	GNU syntax directive	Description
`foo EQU 0x1C`	`.equ foo, 0x1C`	Assigns a value to a symbol. Note the rearrangement of operands. `.equ` is a synonym for `.set`.

`EXPORT StartHere`
 	
`GLOBAL StartHere`
	`.global StartHere`	Declares a symbol that can be used by the linker (that is, a symbol that is visible to the linker).
		
		`armasm` automatically determines the types of exported symbols. However, by default `armclang` declares symbols as the `%object` type. For a function call or function address you must specify the `%function` type using the `.type` directive, for example:
		
		`.type StartHere, %function`
		
		For more information, see Type directive.
		
		If the symbol type is incorrect, the linker outputs warnings of the form:
		
		`Warning: L6437W: Relocation #RELA:1 in test.o(.text) with respect to <symbol>...`
		
		`Warning: L6318W: test.o(.text) contains branch to a non-code symbol <symbol>.`

`GET file`
 	
`INCLUDE file`
	`.include file`	Includes a file within the file being assembled.

`IMPORT foo`	`.global foo`	Provides the assembler with a name that is not defined in the current assembly.
`INCBIN`	`.incbin`	Includes a file within the file being assembled. The file is included verbatim. The assembler always emits a `$d` (data) mapping symbol for the `.incbin` directive. [COMMUNITY]

armasm syntax directive	GNU syntax directive	Description
INFO <n>, "string"	.warning "string"	The INFO directive supports diagnostic generation on either pass of the assembly (specified by <n>). The .warning directive does not let you specify a particular pass, because the armclang integrated assembler only performs one pass.
ENTRY	armlink --entry=<location>	The ENTRY directive declares an entry point in an armasm legacy assembler file. armclang does not provide an equivalent directive. Use either the armclang option -e or the armlink option --entry=<location> to specify the initial entry point directly to the linker. If you need additional entry points in other objects, then use the armlink option --keep=<section_id> to identify them. This option ensures the sections for the additional entry points are not removed by unused section elimination.
END	.end	Marks the end of the assembly file.
PRESERVE8	.eabi_attribute Tag_ABI_align_preserved, 1	Emits a build attribute which guarantees that the functions in the file preserve 8-byte stack alignment. **Note:** For armasm syntax assembly language source files, even if you do not specify the PRESERVE8 directive, armasm automatically emits the build attribute if all functions in the file preserve 8-byte stack alignment. For GNU syntax assembly language source files, the armclang integrated assembler does not automatically emit this build attribute. Therefore you must manually inspect and ensure that all functions in your GNU syntax assembly language source file preserve 8-byte stack alignment and then manually add the directive to the file.

Related information

-e
--entry=location
--keep=section_id (armlink)
GNU Binutils - Using as: .type

6.19 Symbol definition directives

In armasm, symbol definition directives declare and set arithmetic, logical, or string variables. In the GNU assembler syntax, these directives define ELF symbols. There are no direct GNU syntax equivalents for armasm variables.

The following table shows how to translate armasm syntax symbol definition directives to GNU syntax directives:


Note

This list only contains examples of common symbol definition directives. It is not exhaustive.

Table 6-8: Symbol definition directives translation

armasm syntax directive	GNU syntax directive	Description
`foo RN 11`	`foo .req r11`	Define an alias foo for register R11.

`foo QN q5.I32`
 	
`VADD foo, foo, foo`
	`foo .req q5`
	
	`VADD.I32 foo, foo, foo`
		Define an `I32`-typed alias `foo` for the quad-precision register `Q5`.
		
		When using the `armasm` syntax, you can specify a typed alias for quad-precision registers. The example defines an `I32`-typed alias `foo` for the quad-precision register `Q5`.
		
		When using GNU syntax, you must specify the type on the instruction rather than on the register. The example specifies the `I32` type on the `VADD` instruction.

`foo DN d2.I32`
 	
`VADD foo, foo, foo`
	`foo .req d2`
	
	`VADD.I32 foo, foo, foo`
		Define an `I32`-typed alias `foo` for the double-precision register `D2`.
		
		When using the `armasm` syntax, you can specify a typed alias for double-precision registers. The example defines an `I32`-typed alias `foo` for the double-precision register `D2`.
		
		When using GNU syntax, you must specify the type on the instruction rather than on the register. The example specifies the `I32` type on the `VADD` instruction.

Related information

GNU Binutils - Using as: ARM Machine Directives

6.20 Migration of armasm macros to integrated assembler macros

The `armclang` integrated assembler provides similar macro features to those provided by `armasm`. The macro syntax is based on GNU assembler macro syntax.

Additional information about macro features is available:

- The *Arm Compiler for Embedded FuSa Reference Guide* provides more detail about the macro directives supported, and examples of using macros.
- The *GNU Binutils - Using as* document provides more detail about GNU assembly macro directives.

Macro directive features

The following table describes the most common `armasm` macro directive features, and shows the equivalent features for the `armclang` integrated assembler.

Table 6-9: Comparison of macro directive features provided by armasm and the armclang integrated assembler

`armasm` feature	`armclang` integrated assembler feature	Description
`MACRO`, `MEND` directives	`.macro`, `.endm` directives	Directives to mark the start and end of the definition of a macro.
`{$label}` macro parameter	Use a normal macro parameter.	Optionally define an internal label to use within the macro.
`{$cond}` macro parameter	Use a normal macro parameter.	Optionally define a condition code to use within the macro.
`{$parameter{,$parameter}...}` custom macro parameter specification	`{parameter{:type}{,parameter{:type}}...}` custom macro parameter and parameter type specification	With `armasm`, any number of custom macro parameters can be defined. Unspecified parameters are substituted with an empty string. With the `armclang` integrated assembler, the custom macro parameters can optionally have a parameter type `type`. This can be either `req` or `vararg`. Unspecified parameters are substituted with an empty string. The `req` type specifies a required parameter. The assembler generates an error when instantiating a macro if a required parameter is missing and a default value is not available. The `vararg` type collects all remaining parameters as one parameter. It can only be used as the last parameter within the list of parameters for a given macro. Only one `vararg` parameter can be specified.
`MEXIT` directive	`.exitm` directive	Exit early from a macro definition.

armasm feature	armclang integrated assembler feature	Description
IF, ELSE, ELIF, ENDIF conditional assembly directives	.if family of directives, and the .else, .elseif, .endif directives	The directives allow conditional assembly of instructions. With armasm, the conditional assembly directives use a logical expression that evaluates to either TRUE or FALSE as their controlling expression. With the armclang integrated assembler, multiple variants of the GNU assembly .if directive are available, referred to as the .if family of directives. For the .if and .elseif directives, the controlling expression is a logical expression that evaluates to either TRUE or FALSE. For other directives in the .if family of directives, the controlling expression is an implicit part of the directive used, and varies for each such directive.
WHILE, WEND directives	.rept, .endr directives	The directives allow a sequence of instructions or directives to be assembled repeatedly. With armasm, the WHILE directive uses a logical expression that evaluates to either TRUE or FALSE as its controlling expression. The sequence enclosed between a WHILE and WEND directive pair is assembled until the logical expression evaluates to FALSE. With the armclang integrated assembler, the GNU assembly .rept directive takes a fixed number of repetitions as a parameter. The sequence enclosed between a .rept and .endr directive pair is assembled the specified fixed number of times. To replicate the effect of using a logical expression to repeatedly assemble a code sequence, the .rept directive can be used within a macro. See the example provided later in this section.

armasm feature	armclang integrated assembler feature	Description
ASSERT directive	Use a combination of the .if family of directives and the .error directive.	With armasm, the ASSERT directive generates an error message during assembly if a given assertion is false. A logical expression that evaluates to TRUE or FALSE is used as the assertion. With the armclang integrated assembler, this functionality can be achieved by using a GNU assembly directive from the .if family of directives to conditionally display an error message during assembly using the GNU assembly .error directive. Macros can be created to simplify this process. See the example provided later in this section.

Notable differences between armasm macro syntax and GNU macro syntax

The following syntax restrictions apply to GNU macro syntax in addition to the differences due to macro directives:

- In armasm macro syntax, using the pipe character \| as the parameter value when instantiating a macro selects the default value of the parameter. In GNU macro syntax, leaving the parameter value empty when instantiating a macro selects the default value of the parameter. If a default value is not specified in the macro definition, an empty string is used.
- In armasm macro syntax, a dot can be used between a parameter and subsequent text, or another parameter, if a space is not required in the expansion. In GNU macro syntax, a set of parentheses () can be used between a parameter and subsequent text, if a space is not required in the expansion. There is no need to separate a parameter from another subsequent parameter.
- Although the integrated assembler is case-insensitive to register names, the GNU assembly .ifc directive always performs a case-sensitive comparison. Manually check that the register names use the same case-sense when comparing them using the directive.

Migration of macro examples provided in the Arm Compiler for Embedded FuSa Reference Guide

NOT EQUALS assertion - armasm syntax implementation:

```
    ASSERT  arg1 <> arg2
```

NOT EQUALS assertion - GNU syntax implementation:

```
    /* Helper macro to replicate ASSERT <> directive
       functionality from armasm.
       Displays error if NE assertion fails. */
    .macro  assertNE arg1:req, arg2:req, message:req
    .ifc \arg1, \arg2
        .error "\message"
    .endif
    .endm
```

Unsigned integer division macro - armasm syntax implementation

The macro takes the following parameters:

$Bot

The register that holds the divisor.

$Top

The register that holds the dividend before the instructions are executed. After the instructions are executed, it holds the remainder.

$Div

The register where the quotient of the division is placed. It can be `NULL` (`""`) if only the remainder is required.

$Temp

A temporary register used during the calculation.

```
        MACRO

$Lab    DivMod  $Div,$Top,$Bot,$Temp
        ASSERT  $Top <> $Bot        ; Produce an error message if the
        ASSERT  $Top <> $Temp       ; registers supplied are
        ASSERT  $Bot <> $Temp       ; not all different
        IF      "$Div" <> ""
            ASSERT  $Div <> $Top    ; These three only matter if $Div
            ASSERT  $Div <> $Bot    ; is not null ("")
            ASSERT  $Div <> $Temp   ;
        ENDIF
$Lab
        MOV     $Temp, $Bot                 ; Put divisor in $Temp
        CMP     $Temp, $Top, LSR #1         ; double it until
90      MOVLS   $Temp, $Temp, LSL #1        ; 2 * $Temp > $Top
        CMP     $Temp, $Top, LSR #1
        BLS     %b90                        ; The b means search backwards
        IF      "$Div" <> ""                ; Omit next instruction if $Div
                                            ; is null
            MOV     $Div, #0                ; Initialize quotient
        ENDIF
91      CMP     $Top, $Temp                 ; Can we subtract $Temp?
        SUBCS   $Top, $Top,$Temp            ; If we can, do so
        IF      "$Div" <> ""                ; Omit next instruction if $Div
                                            ; is null
            ADC     $Div, $Div, $Div        ; Double $Div
        ENDIF
        MOV     $Temp, $Temp, LSR #1        ; Halve $Temp,
        CMP     $Temp, $Bot                 ; and loop until
        BHS     %b91                        ; less than divisor
        MEND
```

Unsigned integer division macro - GNU syntax implementation

The macro takes the following parameters:

Lab

A label to mark the start of the code. This parameter is required.

BotRegNum

The register number for the register that holds the divisor. This parameter is required.

TopRegNum

The register number for the register that holds the dividend before the instructions are executed. After the instructions are executed, it holds the remainder. This parameter is required.

DivRegNum

The register number for the register where the quotient of the division is placed. It can be `NULL` (`""`) if only the remainder is required. This parameter is optional.

TempRegNum

The register number for a temporary register used during the calculation. This parameter is required.

```
    .macro  DivMod Lab:req, DivRegNum, TopRegNum:req, BotRegNum:req,
 TempRegNum:req
    assertNE \TopRegNum, \BotRegNum, "Top and Bottom cannot be the same
 register"
    assertNE \TopRegNum, \TempRegNum, "Top and Temp cannot be the same
 register"
    assertNE \BotRegNum, \TempRegNum, "Bottom and Temp cannot be the same
 register"
    .ifnb \DivRegNum
        assertNE \DivRegNum, \TopRegNum, "Div and Top cannot be the same
 register"
        assertNE \DivRegNum, \BotRegNum, "Div and Bottom cannot be the same
 register"
        assertNE \DivRegNum, \TempRegNum, "Div and Temp cannot be the same
 register"
    .endif
\Lab:
    mov     r\TempRegNum, r\BotRegNum           // Put divisor in r\TempRegNum
    cmp     r\TempRegNum, r\TopRegNum,  lsr #1  // double it until
90:
    movls   r\TempRegNum, r\TempRegNum, lsl #1  // 2 * r\TempRegNum > r
\TopRegNum
    cmp     r\TempRegNum, r\TopRegNum,  lsr #1
    bls     90b                 // The 'b' means search backwards
    .ifnb \DivRegNum            // Omit next instruction if r\DivRegNum is null
        mov r\DivRegNum, #0     // Initialize quotient
    .endif
91:
    cmp     r\TopRegNum, r\TempRegNum               // Can we subtract r
\TempRegNum?
    subcs   r\TopRegNum, r\TopRegNum, r\TempRegNum  // If we can, then do so
    .ifnb \DivRegNum            // Omit next instruction if r\DivRegNum is null
        adc r\DivRegNum, r\DivRegNum, r\DivRegNum   // Double r\DivRegNum
    .endif
    mov     r\TempRegNum, r\TempRegNum, lsr #1  // Halve r\TempRegNum
    cmp     r\TempRegNum, r\BotRegNum           // and loop until
    bhs     91b                                 // less than divisor
    .endm
```

Notable differences from the `armasm` syntax implementation:

- A custom macro, `assertNE`, is used instead of the `armasm` directive `ASSERT`.
- Register numbers are used instead of registers as parameters. This is because the GNU assembly `.ifc` directive used for the `assertNE` assertions treats its operands as case-sensitive.
- The GNU assembly `.ifnb` directive is used to check if the parameter `DivRegNum` has been defined. In the `armasm` syntax implementation, the `armasm` directive `IF` is used.

Assembly-time diagnostics macro - armasm syntax implementation

```
        MACRO                          ; Macro definition

        diagnose  $param1="default"  ; This macro produces
        INFO      0,"$param1"        ; assembly-time diagnostics
        MEND                           ; (on second assembly pass)
; macro expansion
        diagnose            ; Prints blank line at assembly-time
        diagnose "hello"    ; Prints "hello" at assembly-time
        diagnose |          ; Prints "default" at assembly-time
```

Assembly-time diagnostics macro - GNU syntax implementation

```
//  macro definition
    .macro  diagnose, param1="default"
    .warning "\param1"
    .endm
//  macro instantiation
    .section "diagnoseMacro", "ax"
    diagnose ""         // Prints a warning with an empty string at assembly-
time
                        // Cannot print blank line as the .print directive is
 not supported
    diagnose "hello"    // Prints a warning with the message "hello" at
 assembly-time
    diagnose            // Prints a warning with the default message "default"
                        // at assembly-time
```

Notable differences from the `armasm` syntax implementation:

- It is not possible to print a blank line at assembly-time using the GNU assembly `.warning` directive. Only a warning with an empty message can be printed.
- The format of the diagnostic message displayed is different between `armasm` and the `armclang` integrated assembler.

With `armasm`, the diagnostic messages displayed at assembly-time by the macro example are:

```
"macros_armasm.S", line 11:
"macros_armasm.S", line 12: hello
"macros_armasm.S", line 13: default
```

With the `armclang` integrated assembler, the diagnostic messages displayed at assembly-time by the macro example are:

```
<instantiation>:1:1: warning:
.warning ""
^
macros_armclang.S:11:5: note: while in macro instantiation
 diagnose ""
 ^
<instantiation>:1:1: warning: hello
.warning "hello"
^
macros_armclang.S:13:5: note: while in macro instantiation
 diagnose "hello"
 ^
<instantiation>:1:1: warning: default
.warning "default"
^
macros_armclang.S:14:5: note: while in macro instantiation
 diagnose
```

```
  ^
```

Conditional loop macro - armasm syntax implementation

The macro takes the following parameters:

`$counter`

The assembly-time variable for the loop counter. This parameter is required. The `{$label}` parameter for the `MACRO` directive has been used for this parameter. If a normal macro parameter is used, the parameter cannot be instantiated as a label.

`$N`

The maximum number of iterations for the loop. This parameter is required.

`$decr`

The loop decrement value. This parameter is optional.

`do`

The text to which `$counter` is appended in each iteration of the loop. This parameter is required.

```
    MACRO
$counter    WhileLoop $N, $decr="1", $do  ; macro definition
    ASSERT  "$counter" <> ""              ; check that $counter has been
                                          ; specified
    ASSERT  "$N" <> ""                    ; check that $N has been specified
    ASSERT  "$do" <> ""                   ; check that $do has been
                                          ; specified
    GBLA    $counter                      ; create new local variable
                                          ; $counter
$counter    SETA $N                       ; initialize $counter
    WHILE   $counter > 0                  ; loop while $counter > 0
            $do$counter                   ; assemble in each iteration
                                          ; of the loop
$counter    SETA $counter-$decr           ; decrement the counter by $decr
    WEND
    MEND
; macro instantiation
    AREA    WhileLoopMacro,CODE
    THUMB
counter     WhileLoop 10, 2, "mov r0, #"
    END
```

Conditional loop macro - GNU syntax implementation

The macro takes the following parameters:

`counter`

The assembly-time variable for the loop counter. This parameter is required.

`N`

The maximum number of iterations for the loop. This parameter is required.

`decr`

The loop decrement value. This parameter is optional.

do

The text to which `\counter` is appended in each iteration of the loop. This parameter is required.

```
    /* Macro that inserts the \counter value
       at the end of all \do varargs,
       up to N times. */
    .macro WhileLoop, counter:req, N:req, decr=1, do:vararg
    .set \counter, \N    // initialise the variable \counter to 0
    .rept \N             // loop up to \N times
    .ifgt \counter       // assemble only if \counter is greater than zero
        \do\counter
        .set \counter, \counter-\decr    // decrement the counter by \decr
    .endif
    .endr
    .endm
//  macro instantiation
    .section "WhileLoopMacro", "ax"
    WhileLoop counter, 10, 2, mov r0, #
```

The order in which the GNU assembly `.ifgt`, `.endif`, `.rept`, and `.endr` directives are used is important. Including the `.endr` directive as a statement within the `.ifgt ... .endif` structure produces an error. Similarly, placing the `.endif` directive outside the `.rept ... .endr` structure produces an error.

The macro expansion produces the following code:

```
    mov r0, #0xa
    mov r0, #8
    mov r0, #6
    mov r0, #4
    mov r0, #2
```

Notable differences from the `armasm` syntax implementation:

- In the `armasm` syntax implementation, the `ASSERT` directive is used to raise an error if a required parameter is missing. In the GNU syntax implementation, this can be achieved by using the parameter type `req` for required parameters in the macro definition.
- In the `armasm` syntax implementation, the macro instantiation uses a string as the value to the `$do` parameter. The quotes are implicitly removed at assembly-time. Quotes are required as the parameter value contains spaces. In the GNU syntax implementation, this is achieved using the parameter type `vararg` for the `\do` parameter in the macro definition.
- In the GNU syntax implementation, the `.rept ... .endr` structure is always evaluated `\N` times at assembly-time. This is because the `.ifgt ... .endif` structure must be placed within the `.rept ... .endr` structure. In the `armasm` syntax implementation, the `WHILE...WEND` structure is only evaluated the required number of times at assembly-time based on the controlling expression of the `WHILE` directive.

Related information

GNU Binutils - Using as: .error

7. Changes Between Different Versions of Arm Compiler for Embedded FuSa 6

A description of the changes that affect migration and compatibility between different versions of Arm® Compiler for Embedded FuSa 6.


Note

- Arm does not guarantee the compatibility of C++ compilation units compiled with different major or minor versions of Arm Compiler for Embedded FuSa and linked into a single image. Therefore, Arm recommends that you always build your C++ code from source with a single version of the toolchain.

  You can mix C++ with C code or C libraries.
- All C++ compilation units that are to be linked into a single image must be compiled with the same version of the C++ standard library ABI. If the ABI version changes between Arm Compiler for Embedded FuSa releases, then you must recompile your object files.

  If you are unable to recompile some of your object files, then contact Arm Support at https://developer.arm.com/support.


Note

The documentation changes for Arm Compiler for Embedded FuSa 6.22.1 releases are listed in an appendix for each document.

7.1 Documentation changes between Arm Compiler for Embedded FuSa releases

Each document contains a list of technical changes that have been made to the Arm® Compiler for Embedded FuSa 6.22.1 documentation.

The following appendixes list these changes:

- Arm Compiler for Embedded FuSa User Guide Changes.
- Arm Compiler for Embedded FuSa Reference Guide Changes.
- Arm Compiler for Embedded FuSa Migration and Compatibility Guide Changes.
- Arm Compiler for Embedded FuSa Arm C and C++ Libraries and Floating-Point Support User Guide Changes.
- Arm Compiler for Embedded FuSa Errors and Warnings Reference Guide Changes.

7.2 Summary of changes between Arm Compiler for Embedded FuSa 6.16 LTS and Arm Compiler for Embedded FuSa 6.22.1 LTS

A summary of the changes between Arm® Compiler for Embedded FuSa 6.16 LTS and Arm Compiler for Embedded FuSa 6.22.1 LTS.


Note

This topic includes descriptions of [ALPHA] and [BETA] features. See Support level definitions.

Architecture and optional extension changes

Architectures supported

- Armv8.8-A [ALPHA]
- Armv8.9-A
- Armv9-A
- Armv9.1-A
- Armv9.2-A
- Armv9.3-A
- Armv9.4-A
- Armv9.5-A
- Added support for Armv8-R AArch64 with and without hardware floating-point. Implementations without hardware floating-point are supported only in C language mode.
- The Cortex®-M85 processor features are fully supported.

Architecture extensions supported

- `b16b16` is supported as [ALPHA]
- `cpa` is supported as [ALPHA]
- `cssc`
- `d128`
- `faminmax`
- `fp8` is supported as [ALPHA]
- `fp8dot2`
- `fp8dot4`
- `fp8fma`
- `hbc`

- `ite`
- `lse128`
- `lut`
- `mops`
- `pactbi`
- `pauth-lr` is supported as [BETA]
- `pmuv3`
- `predres2`
- `rasv2`
- `rcpc3`
- *Realm Management Extension* (RME) [ALPHA]
- *Scalable Matrix Extension* (SME) [ALPHA]
- `sme-fp8f16`
- `sme-fp8f32`
- `sve2`
- `sve2p1` is supported as [ALPHA]
- `the`
- `tlbiw` is supported as [BETA]

For more information, see:

- -march
- -mcpu
- Predefined macros

Security features

The following security features are now supported:

- Return address signing hardening
- *Straight-Line Speculation* (SLS) hardening
- Stack tagging is now fully supported.
- Added a topic on memory-safety best practices. See Memory-safety best practices for more information.

Command-line option support

`armclang` options:

- `-faggressive-jump-threading` and `-mrestrict-it` options:
  - -faggressive-jump-threading, -fno-aggressive-jump-threading

    - -mrestrict-it, -fno-restrict-it
- `-faligned-new`
- `-fcomplete-member-pointers`
- `-feliminate-unused-debug-types` and `-fno-eliminate-unused-debug-types` are supported as [COMMUNITY] features.
- `-ffp-contract`
- `-ffreestanding`
- `-foptimize-sibling-calls` and `-fno-optimize-sibling-calls`
- `-fsanitize` and `-fno-sanitize`
- `-fsanitize=memtag-heap` and `-fsanitize=memtag-stack`
- `-fsanitize-ignorelist=<ignorelistfile>` and `-fno-sanitize-ignorelist`
- `-fsanitize-minimal-runtime`
- `-fsanitize-recover` and `-fno-sanitize-recover`
- `-fsanitize-trap=<option>`
- `-fstack-usage`
- `-isystem`
- `-mabi`
- `-mdefault-build-attributes` and `-mno-default-build-attributes`
- Compiling with `-mexecute-only` always generates an empty `.text` section that is read-only.
- `-mframe-chain`
- `-mtune` is supported as a [COMMUNITY] feature.
- `-mpure-code` is supported as an alias for `-mexecute-only`.
- `-mglobal-merge` and `-mno-global-merge`
- `-mharden-sls`
- `-mharden-pac-ret`
- `-nobuiltininc`
- `-Wformat=<n>`
- `--verbose`
- *Scalable Vector Extension* (SVE) auto-vectorization is supported, but without SVE optimized libraries:
    - -fvectorize, -fno-vectorize
    - -O
- The following `armclang` options are supported for the `__attribute__((target("<options>")))` function attribute:

- `harden-pac-ret=none`
- `harden-pac-ret=load-return-address`

`armlink` options:

- `--check_pac_mismatch` and `--info=pac`
- `--mcmodel=large` is now fully supported.
- `--elf-output-format`, `--scatterload-enabled`, and `--no-scatterload-enabled`
- `--require-bti` and `--info=bti` options, and there is a change in behavior when linking BTI with non-BTI user objects:
  - --info=topic (armlink)
  - --library_security=protection
  - --require-bti

For more information, see:

- armclang Command-line Options
- armlink Command-line Options

armclang attributes, pragmas, and predefined macros

Attributes supported

- `__attribute__((no_sanitize("<option>")))`
- `__attribute__((optnone))` function attribute
- `__attribute__((target("arm"|"thumb")))` function attribute

Pragmas supported

- `#pragma import(__use_two_region_memory)`
- `#pragma message` is supported
- `#pragma STDC FP_CONTRACT`
- The `relro` option is now supported for `#pragma clang section`.

Predefined macros supported

- `__ARM_FEATURE_MOPS`

For more information, see:

- Compiler-specific Function, Variable, and Type Attributes
- Compiler-specific Pragmas
- Predefined macros

Changes to default command-line options

The default C++ language standard is `gnu++17`.

C and C++ standards changes

Added support for C++17.

C and C++ Library changes

- The `strnlen()` library function is supported.
- The function `__ARM_TPL_condvar_monotonic_timedwait()` is supported as [ALPHA]:
  - Condition variables [ALPHA]

Deprecated features

The following features are deprecated:

- The `armasm` legacy assembler.
- The `_sys_tmpnam()` function.
- The Base Platform linking model and *Base Platform Application Binary Interface* (BPABI).
- The following linker options:
  - `--base_platform`
  - `--bpabi`
  - `--dll`
  - `--pltgot=type`
  - `--pltgot_opts=mode`

Other changes

The following are additional changes to Arm Compiler for Embedded FuSa:

- DWARF 5 is supported, except for `fromelf` disassembly.
- `-fsanitize=memtag` is not supported.
- The `_sys_tmpnam2()` function is supported.
- Execute-only code is now supported on the Armv6-M architecture. However, execute-only is not supported on Armv6-M for any form of position independent code.
- You can now use the `armlink` option `--cpu` for Armv8-R AArch64 targets.
- Added documentation for the `longjmp()` and `setjmp()` functions.
- Added information for `math_errhandling` in relation to the `-ffp-mode` command-line option.
- Added overview information for aligned and unaligned accesses. See Alignment support in Arm Compiler for Embedded FuSa 6.
- Added overview information and an example that you can build and run for *Thread Local Storage* (TLS). See Thread Local Storage.
- Added documentation on How to build for an Armv8-R AArch64 target without hardware floating-point support.

7.3 Summary of changes between Arm Compiler for Embedded 6.22 and Arm Compiler for Embedded FuSa 6.22.1 LTS

A summary of the changes between Arm® Compiler for Embedded 6.22 and Arm Compiler for Embedded FuSa 6.22.1 LTS.

Removed features

- Licensing through the FlexNet product is no longer supported. Use the User-based licensing model instead.

8. Code Examples

Provides source code examples for Arm® Compiler 5 and Arm Compiler for Embedded FuSa 6.

8.1 Example startup code for Arm Compiler 5 project

This is an example startup code that compiles without errors using Arm® Compiler 5.

This code has been modified to demonstrate migration from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6. This code requires other modifications for use in a real application.

```
// startup_ac5.c:

/*
* Copyright (c) 2009-2017 ARM Limited. All rights reserved.
*
* SPDX-License-Identifier: Apache-2.0
*
* Licensed under the Apache License, Version 2.0 (the License); you may
* not use this file except in compliance with the License.
* You may obtain a copy of the License at
*
* www.apache.org/licenses/LICENSE-2.0
*
* Unless required by applicable law or agreed to in writing, software
* distributed under the License is distributed on an AS IS BASIS, WITHOUT
* WARRANTIES OR CONDITIONS OF ANY KIND, either express or implied.
* See the License for the specific language governing permissions and
* limitations under the License.
*/

/*----------------------------------------------------------------------------
  Definitions
 *----------------------------------------------------------------------------*/
#define USR_MODE 0x10            // User mode
#define FIQ_MODE 0x11            // Fast Interrupt Request mode
#define IRQ_MODE 0x12            // Interrupt Request mode
#define SVC_MODE 0x13            // Supervisor mode
#define ABT_MODE 0x17            // Abort mode
#define UND_MODE 0x1B            // Undefined Instruction mode
#define SYS_MODE 0x1F            // System mode

/*----------------------------------------------------------------------------
  Internal References
 *----------------------------------------------------------------------------*/
void Vectors       (void) __attribute__ ((section("RESET")));
void Reset_Handler(void);
extern int printf(const char *format, ...);

__declspec(noreturn) void main (void)
{
  __enable_irq();
  printf("Starting main\n");
  while(1);
}
#pragma import (__use_no_semihosting)

/*----------------------------------------------------------------------------
  Exception / Interrupt Handler
 *----------------------------------------------------------------------------*/
void Undef_Handler (void) __attribute__ ((weak, alias("Default_Handler")));
```

```
void SVC_Handler   (void) __attribute__ ((weak, alias("Default_Handler")));
void PAbt_Handler  (void) __attribute__ ((weak, alias("Default_Handler")));
void DAbt_Handler  (void) __attribute__ ((weak, alias("Default_Handler")));
void IRQ_Handler   (void) __attribute__ ((weak, alias("Default_Handler")));
void FIQ_Handler   (void) __attribute__ ((weak, alias("Default_Handler")));

/*------------------------------------------------------------------------------
  Exception / Interrupt Vector Table
 *------------------------------------------------------------------------------*/
__asm void Vectors(void) {
  IMPORT Undef_Handler
  IMPORT SVC_Handler
  IMPORT PAbt_Handler
  IMPORT DAbt_Handler
  IMPORT IRQ_Handler
  IMPORT FIQ_Handler
  LDR    PC, =Reset_Handler
  LDR    PC, =Undef_Handler
  LDR    PC, =SVC_Handler
  LDR    PC, =PAbt_Handler
  LDR    PC, =DAbt_Handler
  NOP
  LDR    PC, =IRQ_Handler
  LDR    PC, =FIQ_Handler
}

/*------------------------------------------------------------------------------
  Reset Handler called on controller reset
 *------------------------------------------------------------------------------*/
__asm void Reset_Handler(void) {

  // Mask interrupts
  CPSID   if

  // Put any cores other than 0 to sleep
  MRC     p15, 0, R0, c0, c0, 5       // Read MPIDR
  ANDS    R0, R0, #3
goToSleep
  WFINE
  BNE     goToSleep

  // Reset SCTLR Settings
  MRC     p15, 0, R0, c1, c0, 0       // Read CP15 System Control register
  BIC     R0, R0, #(0x1 << 12)        // Clear I bit 12 to disable I Cache
  BIC     R0, R0, #(0x1 <<  2)        // Clear C bit  2 to disable D Cache
  BIC     R0, R0, #0x1                // Clear M bit  0 to disable MMU
  BIC     R0, R0, #(0x1 << 11)        // Clear Z bit 11 to disable branch prediction
  BIC     R0, R0, #(0x1 << 13)        // Clear V bit 13 to disable hivecs
  MCR     p15, 0, R0, c1, c0, 0       // Write value back to CP15 System Control
 register
  ISB

  // Configure ACTLR
  MRC     p15, 0, r0, c1, c0, 1       // Read CP15 Auxiliary Control Register
  ORR     r0, r0, #(1 <<  1)          // Enable L2 prefetch hint (UNK/WI since r4p1)
  MCR     p15, 0, r0, c1, c0, 1       // Write CP15 Auxiliary Control Register

  // Set Vector Base Address Register (VBAR) to point to this application's vector
 table
  LDR    R0, =Vectors
  MCR    p15, 0, R0, c12, c0, 0

  // Setup Stack for each exceptional mode
  IMPORT |Image$$FIQ_STACK$$ZI$$Limit|
  IMPORT |Image$$IRQ_STACK$$ZI$$Limit|
  IMPORT |Image$$SVC_STACK$$ZI$$Limit|
  IMPORT |Image$$ABT_STACK$$ZI$$Limit|
  IMPORT |Image$$UND_STACK$$ZI$$Limit|
  IMPORT |Image$$ARM_LIB_STACK$$ZI$$Limit|
  CPS    #0x11
  LDR    SP, =|Image$$FIQ_STACK$$ZI$$Limit|
```

```
  CPS    #0x12
  LDR    SP, =|Image$$IRQ_STACK$$ZI$$Limit|
  CPS    #0x13
  LDR    SP, =|Image$$SVC_STACK$$ZI$$Limit|
  CPS    #0x17
  LDR    SP, =|Image$$ABT_STACK$$ZI$$Limit|
  CPS    #0x1B
  LDR    SP, =|Image$$UND_STACK$$ZI$$Limit|
  CPS    #0x1F
  LDR    SP, =|Image$$ARM_LIB_STACK$$ZI$$Limit|

  // Call SystemInit
  IMPORT SystemInit
  BL     SystemInit

  // Unmask interrupts
  CPSIE  if


  // Call main
  IMPORT main
  BL     main

}

/*----------------------------------------------------------------------------
  Default Handler for Exceptions / Interrupts
 *----------------------------------------------------------------------------*/
void Default_Handler(void) {
    while(1);
}
```

Related information

Apache License on page 120

8.2 Example startup code for Arm Compiler for Embedded FuSa 6 project

This is an example startup code that compiles without errors using Arm® Compiler for Embedded FuSa 6.

This code has been modified to demonstrate migration from Arm Compiler 5 to Arm Compiler for Embedded FuSa 6. This code requires other modifications for use in a real application.

```
// startup_ac6.c:

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```

```
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*/

/*----------------------------------------------------------------------------
  Definitions
 *----------------------------------------------------------------------------*/
#define USR_MODE 0x10           // User mode
#define FIQ_MODE 0x11           // Fast Interrupt Request mode
#define IRQ_MODE 0x12           // Interrupt Request mode
#define SVC_MODE 0x13           // Supervisor mode
#define ABT_MODE 0x17           // Abort mode
#define UND_MODE 0x1B           // Undefined Instruction mode
#define SYS_MODE 0x1F           // System mode

/*----------------------------------------------------------------------------
  Internal References
 *----------------------------------------------------------------------------*/
void Vectors       (void) __attribute__ ((naked, section("RESET")));
void Reset_Handler (void) __attribute__ ((naked));
extern int printf(const char *format, ...);

__declspec(noreturn) int main (void)
{
  __asm("CPSIE i");
  printf("Starting main\n");
  while(1) __asm volatile("");
}
__asm(".global __use_no_semihosting");

/*----------------------------------------------------------------------------
  Exception / Interrupt Handler
 *----------------------------------------------------------------------------*/
void Undef_Handler (void) __attribute__ ((weak, alias("Default_Handler")));
void SVC_Handler   (void) __attribute__ ((weak, alias("Default_Handler")));
void PAbt_Handler  (void) __attribute__ ((weak, alias("Default_Handler")));
void DAbt_Handler  (void) __attribute__ ((weak, alias("Default_Handler")));
void IRQ_Handler   (void) __attribute__ ((weak, alias("Default_Handler")));
void FIQ_Handler   (void) __attribute__ ((weak, alias("Default_Handler")));

/*----------------------------------------------------------------------------
  Exception / Interrupt Vector Table
 *----------------------------------------------------------------------------*/
void Vectors(void) {
  __asm volatile(
  "LDR    PC, =Reset_Handler                      \n"
  "LDR    PC, =Undef_Handler                      \n"
  "LDR    PC, =SVC_Handler                        \n"
  "LDR    PC, =PAbt_Handler                       \n"
  "LDR    PC, =DAbt_Handler                       \n"
  "NOP                                            \n"
  "LDR    PC, =IRQ_Handler                        \n"
  "LDR    PC, =FIQ_Handler                        \n"
  );
}

/*----------------------------------------------------------------------------
  Reset Handler called on controller reset
 *----------------------------------------------------------------------------*/
void Reset_Handler(void) {
  __asm volatile(

  // Mask interrupts
  "CPSID   if                                     \n"

  // Put any cores other than 0 to sleep
  "MRC     p15, 0, R0, c0, c0, 5                  \n"  // Read MPIDR
  "ANDS    R0, R0, #3                             \n"
  "goToSleep:                                     \n"
  "WFINE                                          \n"
  "BNE     goToSleep                              \n"
```

```
  // Reset SCTLR Settings
  "MRC     p15, 0, R0, c1, c0, 0                  \n"  // Read CP15 System Control
 register
  "BIC     R0, R0, #(0x1 << 12)                   \n"  // Clear I bit 12 to disable
 I Cache
  "BIC     R0, R0, #(0x1 <<  2)                   \n"  // Clear C bit  2 to disable
 D Cache
  "BIC     R0, R0, #0x1                           \n"  // Clear M bit  0 to disable
 MMU
  "BIC     R0, R0, #(0x1 << 11)                   \n"  // Clear Z bit 11 to disable
 branch prediction
  "BIC     R0, R0, #(0x1 << 13)                   \n"  // Clear V bit 13 to disable
 hivecs
  "MCR     p15, 0, R0, c1, c0, 0                  \n"  // Write value back to CP15
 System Control register
  "ISB                                            \n"

  // Configure ACTLR
  "MRC     p15, 0, r0, c1, c0, 1                  \n"  // Read CP15 Auxiliary
 Control Register
  "ORR     r0, r0, #(1 <<  1)                     \n"  // Enable L2 prefetch hint
 (UNK/WI since r4p1)
  "MCR     p15, 0, r0, c1, c0, 1                  \n"  // Write CP15 Auxiliary
 Control Register

  // Set Vector Base Address Register (VBAR) to point to this application's vector
 table
  "LDR    R0, =Vectors                            \n"
  "MCR    p15, 0, R0, c12, c0, 0                  \n"

  // Setup Stack for each exceptional mode
  "CPS    #0x11                                   \n"
  "LDR    SP, =Image$$FIQ_STACK$$ZI$$Limit        \n"
  "CPS    #0x12                                   \n"
  "LDR    SP, =Image$$IRQ_STACK$$ZI$$Limit        \n"
  "CPS    #0x13                                   \n"
  "LDR    SP, =Image$$SVC_STACK$$ZI$$Limit        \n"
  "CPS    #0x17                                   \n"
  "LDR    SP, =Image$$ABT_STACK$$ZI$$Limit        \n"
  "CPS    #0x1B                                   \n"
  "LDR    SP, =Image$$UND_STACK$$ZI$$Limit        \n"
  "CPS    #0x1F                                   \n"
  "LDR    SP, =Image$$ARM_LIB_STACK$$ZI$$Limit    \n"

  // Call SystemInit
  "BL     SystemInit                              \n"

  // Unmask interrupts
  "CPSIE  if                                      \n"

  // Call main
  "BL     main                                  \n"
  );
}

/*----------------------------------------------------------------------------
  Default Handler for Exceptions / Interrupts
 *----------------------------------------------------------------------------*/
void Default_Handler(void) {
  while(1);
}
```

Related information

Apache License on page 120

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Version 2.0, January 2004

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```

Appendix A Arm Compiler for Embedded FuSa Migration and Compatibility Guide Changes

Describes the technical changes that have been made to the Arm® Compiler for Embedded FuSa Migration and Compatibility Guide.

A.1 Changes for the Arm Compiler for Embedded FuSa Migration and Compatibility Guide

Changes that have been made to the Arm® Compiler for Embedded FuSa Migration and Compatibility Guide are listed with the latest version first.

Table A-1: Changes between 6.22.1 LTS and 6.22

Change	Topics affected
Removed information about FlexNet licensing and replaced with user-based licensing information.	• Summary of changes between Arm Compiler for Embedded 6.22 and Arm Compiler for Embedded FuSa 6.22.1 LTS. • Configuration and Support Information.
Added a summary of the changes between Arm Compiler for Embedded FuSa 6.16 LTS and Arm Compiler for Embedded FuSa 6.22 LTS.	• Summary of changes between Arm Compiler for Embedded FuSa 6.16 LTS and Arm Compiler for Embedded FuSa 6.22.1 LTS.
Moved the topic *Compiling with -mexecute-only generates an empty .text section* to the *User Guide*.	-