ACPI for Memory System Resource Partitioning and Monitoring 2.0

Platform Design Document

Non-confidential

Contents

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About this document

Terms and abbreviations

References

This section lists publications by Arm and by third parties.

See Arm Developer (http://developer.arm.com) for access to Arm documentation.

[1] *Arm® Architecture Reference Manual Supplement Memory System Resource Partitioning and Monitoring(MPAM), for Armv8, DDI 0598A.a, ID103018A*. Arm Limited.

[2] *Advanced Configuration and Power Interface Specification 6.3*. UEFI Forum.

[3] *Arm® System Memory Management Unit Architecture Specification SMMU architecture versions 3.0, 3.1 and 3.2, IHI 0070C.a*. Arm Limited.

[4] *DEN0049E IO Remapping Table*. Arm Limited.

[5] *DEN0093 ACPI for Arm Components 1.0*. Arm Limited.

[6] *Arm® Architecture Reference Manual ARMv8, for the ARMv8-A architecture profile, Arm DDI 0487*. Arm Limited.

[7] *DSD Implementation Guide v2.0*. UEFI Forum.

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Arm also welcomes general suggestions for additions and improvements.

1 Introduction

This document describes the specification for the ACPI description of the Arm Memory System-Resource Partitioning and Monitoring feature, MPAM [\[1\]](#page-6-1).

Note

Version 1.0 of this specification is deprecated and must not be referenced.

2 The ACPI MPAM table

The MPAM capabilities in a system are described by the ACPI MPAM table. Memory requests from requesters are handled by Memory-system Components or MSCs. SMMUs, caches, TLBs and memory channel controllers are examples of an MSC. An MSC provides partitioning and monitoring controls for managing system memory resources that provide performance to memory transactions.

The MPAM table describes the properties of MSCs in the system. The table also describes the topological arrangement of MSCs and resources in the system. The topology is expressed in terms of the location of resources within the system and the relation between an MSC and the resources that it is manages.

When MPAM is enabled, all MSCs within the MPAM topology must be programmed and enabled to support partitioning and monitoring of memory requests that are associated with a given range of PARTIDs. Different MSCs might support different PARTID and PMG ranges, and hence the smallest common value is required to be programmed into each MSC in the system to allow MPAM to operate correctly at a system level.

All MSCs in the system must be described to allow the OS to discover this common value.

The table format is decribed in Table [3.](#page-8-2)

Table 3: The MPAM table

2.1 MPAM MSC node

The MPAM MSC node describes an MSC. The format of the MSC node is specified below in Table [4.](#page-8-3)

Table 4: MPAM MSC node body

ACPI for Memory System Resource Partitioning and Monitoring

2.1.1 Interrupt Flags

The interrupt flags are for both overflow and error interrupts, and are described in Table [5.](#page-11-2)

Table 5: Interrupt flags

2.1.2 MPAM PCC Interface Type

If the PCC interface type is used, the MPAM registers for an MPAM MSC node reside in the PCC Generic Communication Shared Memory region for the specified subspace ID. On UEFI based systems, the memory attribute of this region must be specified by the EFI memory map. On non-UEFI based systems, this region of memory must be exposed as Device nGnRnE memory.

The PCC subspace structure must be of Type 1 (HW-reduced communications subspace) as defined in Chapter 14 of the ACPI specification [\[2\]](#page-6-2).

The base address of the PCC region is retrieved from the PCCT. The Base Address field of the MPAM MSC node points to the sub-space ID of the PCC subspace that describes the PCC-based shared memory region that holds the registers of the MPAM MSC. The register layout itself follows the MPAM feature page described in [\[1\]](#page-6-1).

The shared memory region of the PCC subspace is defined in Table [6.](#page-12-1)

Table 6: MPAM PCC Generic Communication Shared Memory Region

To amortize the cost of PCC transactions, OSPM should read or write all PCC registers in a single read or write command. The commands are described in Table [7.](#page-12-2)

Table 7: MPAM PCC Commands

2.2 MPAM resource node

From a software viewpoint, an MSC is a container of resources. The MPAM resource node specifies the properties of a resource.

An MSC has resource partitioning controls that operate on resources.

The MPAM specification [\[1\]](#page-6-1) describes the following standard resources:

• Cache storage

- Memory bandwidth
- Priority
- Implementation-specific

The MPAM specification also describes standard resource partitioning controls, or simply, controls:

- Cache-portion partitioning (CPOR).
- Cache maximum-capacity partitioning (CCAP).
- Memory-bandwidth portion partitioning (MBW).
- Priority partitioning (PRI).
- Implementation-specific partitioning (IMPL).

Controls are associated with specific resource types as follows:

Table 8: Resource and control types

This specification assumes that all controls of a particular control type in an MSC shall operate on *one and only one* resource instance of the corresponding type as described in Table [8.](#page-13-0) If a component has multiple resource instances of the same type, then it must either implement an MSC that supports the RIS feature or separate MSCs for each resource instance of the same resource type. For example, if a cache unit implements multiple caches as distinct resources, then the cache unit must implement one MSC per cache if the MSCs do not support RIS. Alternatively, the cache unit must implement a single MSC that applies to all caches and uses the RIS feature to provide independent controls to each cache.

This specification currently only supports discovery of cache storage and memory bandwidth resources. That is because these resources can be readily identified using existing ACPI constructs that software can understand and use. Other resource types are declared as unknown resources.

See Appendix (Section [3\)](#page-24-0) for an example system that illustrates these points.

The OS must check the MPAMF_IDR.HAS_RIS field of the MSC to determine whether it supports the RIS feature.

The location of the resource is useful for the OS to uniquely identify the resource in a system. For example, if the resource is cache storage, then the location identifies which physical cache contains the cache storage. This information enables resource management software frameworks to utilize the MPAM capabilities of the system efficiently.

Table 9: Resource node

2.2.1 Functional dependencies between MSCs

If an MSC has a resource partitioning control whose operation is dependent on or is influenced by resource in another MSC, then that dependency must be described using the functional dependency descriptor. MSC dependencies are explained in Section [2.5.](#page-20-1)

Table 10: Functional dependency descriptor

2.2.2 Empty MSC node

An empty MSC node has no resource nodes, and its number of resource nodes is set to 0.

If an MSC is described using an empty MSC node, its resources are still discoverable, but without a firmware description the OS is expected to program the controls to be unrestricted (e.g. all 1s for a CPOR bitmap) for any PARTID that it is using.

MSCs whose resources are not located on known components must be described using the empty MSC node. This allows the OS to discover the supported range of PARTID and PMG on that MSC and program all controls to be unrestricted.

2.3 Locators

Locators are a generic construct that specify where a component is situated in the system.

The Location field of an MPAM resource node specifies its location. The resource node is described in Table [9.](#page-13-1)

The format of the Location fields is based on the Locator structure, described in Section [2.3.2.](#page-15-2)

The location is expressed in terms of the ACPI identifier of the component that the resource instance is associated with.

2.3.1 Location types

Table 11: Location types

2.3.2 Locator structure

Table 12: Locator structure

2.3.3 Location descriptors

2.3.3.1 Processor cache locator descriptor

The processor cache locator descriptor is associated with a Location type value of 0x00.

For a resource node, this descriptor points to the processor cache that contains the cache storage being used as the MPAM resource.

The format of this locator is outlined in Table [13.](#page-16-0)

The cache locator is described in terms of the cache's topological position within the processor hierarchy.

The position is derived from the ACPI PPTT table [\[2\]](#page-6-2) , and is expressed as a reference to the cache (Type 1) structure within the PPTT table that describes the cache.

This locator works with PPTT tables of revisions 3 and above.

Table 13: Processor cache locator descriptor

2.3.3.2 Memory locator descriptor

The memory locator descriptor is associated with a Location type value of 0x01.

Memory bandwidth associated with memory regions can be managed as an MPAM resource. Memory bandwidth resources are located using the memory locator.

The format of the memory locator is outlined in Table [14.](#page-16-1)

The locator is expressed in the form of the proximity domain associated with the memory region.

It is assumed that the memory bandwidth applies to all memory locations within the proximity domain.

The SRAT table is a prerequisite and must be present.

2.3.3.3 SMMU locator descriptor

The SMMU locator descriptor is associated with a Location type value of 0x02.

An SMMU [\[3\]](#page-6-3) implementation can support MPAM through built-in MSCs that manage MPAM resources within the SMMU.

Examples of internal units in an SMMU that can be managed as MPAM resources are IO TLBs and translation caches in the SMMU itself, e.g., in the control unit of the SMMU.

For resource nodes, the SMMU locator describes the location of MPAM resources within the SMMU.

The format of this locator is outlined in Table [15.](#page-16-2)

The location information is provided in the form of a reference to the IORT[\[4\]](#page-6-4) node that describes the internal unit in the SMMU.

Table 15: SMMU locator descriptor

2.3.3.4 Memory-side cache locator descriptor

The Memory-side cache locator descriptor is associated with a Location type value of 0x03.

Memory-side caches operate as the front-end for memory devices. These caches are distinct from processor caches. Memory-side caches and their properties are defined in the ACPI HMAT table. The HMAT table is mandatory for this locator descriptor.

Memory-side caches in a system can function as MPAM resources that are managed by MSCs.

Memory-side caches are located by the memory-side cache locator. There can be multiple levels of memory side caches associated with a region of far memory. Therefore, the tuple {Proximity Domain, Cache level} is used to uniquely identify the MSC interface of a particular memory side cache in the system.

The format of the locator is outlined in Table [16.](#page-17-0)

Table 16: Memory-side cache locator descriptor

2.3.3.5 ACPI device locator descriptor

The ACPI device locator descriptor is associated with a Location type value of 0x04.

A system might have various other components that lie in the path of memory transactions. Such components might support MPAM in the form of implementation-defined resources that are managed by MSCs.

Implementation-defined resources must be managed using the implementation-specific controls described in this section. Implementation-specific resources are managed by specific software drivers. The resources must be described as an ACPI device to assist these drivers to bind to their respective resources.

The ACPI device locator is used for describing such resources.

The format of the locator is outlined in Table [17.](#page-17-1)

Table 17: ACPI device locator descriptor

2.3.3.6 Interconnect locator descriptor

The Interconnect locator descriptor is associated with a Location type value of 0x05.

A system might have various interconnects between components or sub-systems along the path of memory transactions. These interconnects might support MPAM. MSCs on these interconnects are described using this locator.

This specification focuses on two types of interconnects:

- NUMA interconnects: interconnects between NUMA nodes.
- PE cluster interconnects: interconnects between groups of processors.

The format of the locator is outlined in Table [18.](#page-18-0)

Table 18: Interconnect locator descriptor

Interconnect descriptor

The term interconnect is used in this specifiation to refer to the path or link between two components in the system. This path might in turn be composed of multiple intermediate interconnected components. The interconnect descriptor specifies the source, destination and type of a one-to-one interconnect between two components.

Many-to-one interconnects are described by multiple interconnect descriptors with the same source ID. Many-to-one links cannot have a mix of link types.

One-to-one interconnects are described using an interconnect descriptor table with a single interconnect descriptor entry. One-to-many interconnects are described using an interconnect descriptor table with multiple descriptors, each specifying one of the links of the interconnect.

Table 19: Interconnect descriptor

The interconnect descriptor table format is as specified below:

Table 20: Interconnect descriptor table

The UUID used for locating the interconnect descriptor table is fe2bd645-033b-49e6-9479-2e0b8b21d1cd.

2.3.3.7 Unknown locator descriptor

The Unknown locator is associated with a Location type of 0xFF. This locator is useful for describing resources that are located in components that cannot be described in ACPI. An MPAM-enabled buffer in the SoC interconnect that contains an MSC, is an example of a component that cannot be described in ACPI. The buffer must hence be declared as an unknown resource.

2.4 MSC groups

Some MSCs in a system might be organized as a logical group. MSCs in such a logical group affect the same underlying resouce of a common component. OS can recognize the presence of a logical group through examination of the Location field of the resource nodes of the MSC nodes in the group. Each MSC node in the group must have at least one resource node that has its Location field set to the same common location.

Controls that operate on the common resource of an MSC logical group must be configured identically in all MSCs belonging to that logical group. Note that this programming requirement only applies to controls that operate on the common resource, not to controls that operate on other resources. Therefore, if an MSC within a logical group is managing multiple resources, one of which is common to the logical group, then only the controls that are managing the common resource must be configured identically with respect to other MSCs in the logical group.

Note

MSC groups and MSC functional dependencies are different, mutually independent concepts. Functional dependencies are explicitly specified in the functional dependency list of resource nodes and involve two differently-located MSCs. Secondly, functional dependencies are directional in nature: from the producer to the dependent. OSPM is required to understand these aspects and configure the MSCs accordingly.

2.5 MSC functional dependencies

MSCs in a system have implicit dependencies that follow the natural flow of memory transactions in a system. For example, the control action of an MSC in an L2 cache implicitly affects the monitored data or control action in a downstream L3 cache. Since these inter-dependencies are implicit, they need not be described in ACPI.

It is possible for MSCs to have explicit functional dependencies on other MSCs that are against the natural dataflow. Such dependencies might be of the form:

- the control policy applied on a first MSC, called the dependent MSC, might be influenced by the output of a monitor on a second MSC, called the producer MSC.
- the control policy applied on a dependent MSC might be influenced by the control policy settings of a producer MSC.

In both cases, the dependent MSC must not be the immediate downstream neighbour of the producer MSC, or in a position that falls in the natural flow of memory transactions from the producer MSC to the dependent MSC.

An example of a functional dependency would be a system that has an L3 cache that is an inclusive cache. Policies applied to the L3 cache, e.g., on eviction rates, could thus influence policies applied on the upstream L2 cache. The L2 cache is then said to be *functionally dependent* on the L3 cache.

A functional dependency is expressed as the tuple: {Producer MSC, Producer unit, Dependent MSC, Dependent unit} where:

- the Producer unit is a resource control in the producer MSC
- the Dependent unit is a resource control in the dependent MSC

MSC dependencies are expressed in resource nodes. See Section [2.2.](#page-12-0) The ACPI description of explicit dependencies helps the OS to make judicious decisions while programming the MSCs for MPAM functionality.

2.6 Representation of MSCs as ACPI devices

The MSC is a logic block or unit that has its own memory-mapped register space and interrupts. These characteristics make the MSC appear as a device to software, even though the MSC hardware might be a part of another device.

The MSC can thus be described optionally as a device object in ACPI namespace. The device model is useful for declaring requirements and operations for an MSC in addition to those that are presented through the MSC node in the MPAM table. Specifically, the device model is useful for supporting power management of the MSC, where the power state dependencies of the MSC can be expressed in ACPI, and additional requirements and programming relevant to power state transitions can be supplied through ACPI PSx methods. See [\[2\]](#page-6-2) for more information on these methods.

Note

MSCs must mandatorily be described in the MPAM table as the MSC node provides the canonical properties of the MSC. The device object representation should be considered as an optional auxilliary extension to the MSC node.

2.6.1 ACPI Hardware Identifiers

MSC devices in ACPI are identified using the HID of "ARMHAA5C". If present, the CID object of the device must also be set to the same value.

Note that the MSC might be implemented as a sub-component within another component. The device view of the MSC has no relation to the container component which might be modeled as a separate ACPI device with its own _HID.

2.6.2 Unique Identifier

Each MSC device object must be declared with a distinct UID value that must be set to the same value as the Identifier field of the MSC node in the MPAM table that describes the MSC.

2.6.3 Example MSC device

The following ASL code describes the power management requirements for an example MSC.

```
Device (MSCO) { // MSC device
      Name (_HID , " ARMHAA5C ")
      Name (_CID, "ARMHAA5C")
       Name (_UID , 0)
       Name (_STR , Unicode (" MSC0 ") )
}
```
2.7 MSI support

If the MSC supports MSI generation for its overflow or error interrupt, then it must be described as a device object in the DSDT. This device object can then be presented as being a part of the IO topology of the system. The OS can then walk the IO topology to determine the target ITS unit or group of units that the MSIs from the MSC are routed to. The OS can also use this information to program the MSI registers for this MSC. More information on IO topologies is available in [\[4\]](#page-6-4).

2.8 MSC Power Management

If an MSC has platform-specific programming requirements for power management, one approach to describing those requirements would be to represent the MSC in ACPI namespace as a device object. The device object description supplements the information in the MSC node that describes the MSC, as explained in Section [2.6.](#page-20-2)

The device object allows ACPI methods to be declared for specifying runtime power management properties of the MSC.

The following ASL code snippet illustrates how power management requirements for an example MSC is declared in DSDT.

```
Device (MSCO) { // MSC device
      Name (_HID, "ARMHAA5C")
      Name (_CID, "ARMHAA5C")
      Name (_UID , 0)
      Name (_STR, Unicode ("MSCO"))
      Method (_PS3, 0, Serialized) { // _PS3: Power State 3
             // Turn MSC off
      \mathbf{r}Method (_PSO, O, Serialized) { // _PSO: Power State 0
             // Turn MSC on
      }
}
```
2.8.1 MSC power state dependencies and accessibility

In this specification, the device where the MSC is located, or that the MSC is associated with, is called the linked device.

The MSC and its linked device might have power state dependencies. For example, the MSC and its linked device might share power resources. As a result, the MSC might enter low-power state and become inaccessible if the linked device enters low-power state.

If there is a power state inter-dependency between the MSC and its linked device, then:

- when transitioning to low-power state, the MSC and its linked device must enter low-power state together
- when transitioning into ON state, the MSC must enter running state *before* the linked device

If the MSC is modeled as an ACPI device, the OSPM can orchestrate power management of the MSC and its linked device, provided the firmware description includes an ACPI device representation for the MSC with the following:

- standard ACPI methods. PSx, for managing power states as specified in Section [2.8.](#page-21-4)
- the link between the MSC and the linked device. See Section [2.8.2.](#page-22-1)

This version of the specification focuses only on device linkage between MSCs and processors or processor clusters. Section [2.8.3](#page-22-2) provides more details.

2.8.2 Describing MSC device linkage

The linked device is specified in the MSC node in the form of the ACPI identifiers for the linked device.

2.8.3 MSCs associated with PEs and PE affinity

MSCs that are associated with PEs, such as MSCs on processor caches or in PE clusters can be placed in low-power state when the associated PE or cluster transitions to low-power state. A PE or a processor clusters enters low-power state in response to PSCI requests from the OS, notably CPU_SUSPEND. As such, low-power state entry of PEs is strictly the responsibility of the PSCI firmware and the OS has no control over these state transitions.

Hence, Arm strongly recommends that MSCs associated with PEs are power managed entirely by PSCI firmware.

MSCs on PEs or clusters are accessible only if the associated PE or processor cluster is in the running state. PE affinity is specified in the MSC node. The OS must use this affinity information to determine the PE or set of PEs that needs to be woken up before the MSC can be accessed.

3 Appendix

3.1 Example System with MPAM

Figure [1](#page-24-3) is an example system with MPAM support implemented in the form of MSCs distributed across various system memory components.

Figure 1: An example system with MPAM support

The example system is intended to illustrate how the MPAM description of a system might be provided in ACPI. It showcases the use of location of MSCs for power management, the association of MSCs to resources, how resources are defined and located, and special cases that highlight use of features such as RIS.

Note

This example system is intended to provide an illustration of how a reasonably complex SoC with MPAM support could be represented in ACPI. It must not be considered as a reference design for building MPAM support in a system.

The ACPI description of the MPAM properties of this example system is outlined in the sections that follow.

3.1.1 Notations

Single alphabetical letters in italics are used to represent numeric values assigned to ACPI identifiers: *a* to *z* and *A* to *Z*.

3.1.2 Prerequisites

3.1.2.1 The ACPI PPTT table

All processor caches in the example system must be described in the ACPI PPTT table.

The two slices of the L3 cache appear to software as a single monolithic L3 cache in this particular example. Hence, they are described using a single, common Type 1 cache structure in the PPTT as above.

3.1.2.2 The ACPI SRAT table

SRAT	
.	.
MC 1 memory range	Proximity Domain = P
MC 2 memory range	Proximity Domain = Q

3.1.2.4 IORT table

The SMMUs, Device 1, and the root complexes are described using the ACPI IORT table.

SMMU node 1

The SMMU node 1 describes SMMU_A in the example system.

SMMU node

SMMU node 2

The SMMU node 2 describes SMMU_B in the example system.

SMMU node

Root complex node 1

Root complex node 2

Root complex node 3

Named component node 1

This named component node describes the properties of Device 1 in the example system.

3.1.3 The ACPI description of the PE topology

The PE topology is described in the PPTT. However, to avoid using pointers to nodes in the PPTT, the MPAM table uses the ACPI description of processors and processor containers in DSDT to cross-reference the latter.

The following DSDT reference code provides the ACPI description of the PE topology for the example system.

```
Device (SYST) { // (Top-) System-level processor container
   Name (_HID , " ACPI0010 ")
   Name (_UID , 0)
   Device (CLUO) { // PE Cluster
      Name (_HID , " ACPI0010 ")
      Name (_UID , 1)
      Device ( CPU0 ) { // PE1
          Name (_HID , " ACPI0007 ")
          Name ( _UID , 1)
          ...
      } // CPU0 description ends here
      Device ( CPU1 ) { // PE2
         Name (_HID, "ACPI0007")
         Name (_UID , 2)
          ...
      } // CPU1 description ends here
   }
}
```
3.1.4 The ACPI MPAM table

The MPAM table must describe every MSC in the system to aid software discovery of the MSCs.

MPAM Table

In this table, MSC node *i* is the descriptor for MSC*i*.

3.1.5 The L1 caches

The example L1 caches in Figure [1](#page-24-3) are intended to illustrate the simplest manner in which MPAM support might be built in a cache, and how controls in an MSC are associated with resources.

Figure [2](#page-29-1) provides details of MSCs MSC1-4.

Figure 2: Internal organization of the L1 caches in the example system

The controls implemented by each MSC are considered to relate directly to the cache storage in the cache. Since the MSCs do not support RIS, there is a single resource instance only, and the RIS index field is set to 0 accordingly. Note that the MPAMF_IDR.HAS_RIS bit of each MSC must return 0 on read.

Accordingly, the MSC nodes for MSC1-4 have a single resource node each that describes the cache storage part of the cache as a resource instance.

In this particular case, the control and resource types both pertain to cache storage, which is based on the association outlined in Table [8.](#page-13-0)

ACPI for Memory System Resource Partitioning and Monitoring

MSC node 4 Number of resource nodes 1 **Resource node 41** RIS Index 0 (Don't care) Locator descriptor Type = 0x00 (Processor cache) Cache reference = *q*

3.1.5.1 Power management

Power management of MSC1-4 must be performed by PSCI firmware as they are associated with PEs. The Locator fields of the MSC nodes describe the PE affinities of the MSCs.

3.1.6 L2 caches on PE1 and PE2

Figure [3](#page-32-0) provides an overview of MSC5, which operates on the L2 caches of both PEs, L2_1 and L2_2, respectively.

MSC5 is shown to have three partitioning controls: CPOR, CCAP and PRI. The CPOR and CCAP controls operate on cache storage resources, while the PRI controls operate on incoming DVM messages.

MSC5 is enabled with the RIS feature to enable it to support multiple controls of the same type that operate on different resource instances of the same resource type.

Figure 3: Organization of the common MSC for the L2 caches in the example system

3.1.6.1 Power management

Power management of MSC5 must be performed by PSCI firmware as it is associated with processor caches.

The PE affinity of MSC5 is described by its Locator field.

3.1.7 L3 cache on cluster C_1

Figure [4](#page-34-0) shows the internal layout of the L3 cache and its MPAM resources.

The example L3 cache is divided into two physical slices, L3_1 and L3_2 that appear as a monolithic single cache storage to the OS. Each cache slice is managed by a dedicated MSC.

Each slice has an MSC associated with it, as depicted in Figure [4.](#page-34-0) In accordance with the design rules assumed, both sets of controls, CCAP and CPOR, of each MSC, apply to the same resource instance - the cache storage part of the cache slice.

Since MSC6A and MSC6B are both operating on the same monolithic cache, both MSCs must be configured identically to allow uniform partitioning for all PARTIDs, and are considered as being part of an MSC group. MSC groups are explained in Section [2.4.](#page-20-0).

Figure 4: L3 cache in the example system

The combined cache storage of the L3 cache is located using the ACPI PPTT table, as explained in Section [2.3.3.](#page-15-3)

MSC node 6B

Resource node 6B1 RIS Index 0 (Don't care) Locator descriptor Type = 0x00 (Processor cache) Cache reference = *t*

3.1.7.1 Logical Grouping

MSC nodes for MSC6A and MSC6B have resources pointing to the same resource, the common cache storage that is part of the L3 cache. This is an indication for OSPM that the two MSCs are logically related and should be configured identically. MSC groups are explained in Section [2.4.](#page-20-0)

3.1.7.2 Power management considerations

Power management of MSC6A and MSC6B is aligned with that of the L3 cache, which in turn is managed by PSCI. The Locator fields of both MSC nodes point to cluster 0 to indicate that they are associated with all PEs that are part of this cluster.

3.1.8 SoC Interconnect

MSC7 in the SoC interconnect provides priority partitioning for requesters that interface with the interconnect.

Since the SoC interconnect is invisible to software, resources in MSC7 cannot be located. As a result, the MSC is described using an empty MSC node. This helps the OS discover the MSC and configure it with unrestricted access for all PARTIDs, as required in Section [2.2.2.](#page-14-1)

3.1.8.1 MSC Accessibility

MSC7 is present at the system level. Its PE affinity can therefore be optionally described using its Locator field.

3.1.9 Memory-side caches

Each memory-side cache in Figure [1](#page-24-3) has a dedicated MSC that allows it to be configured independently for MPAM. MSCache 1 acts as the memory-side cache for the proximity domain in which the memory ranges of

MC_1 lie. Likewise, MSCache_2 functions as the memory-side cache for the proximity domain associated with MC_2.

3.1.10 Memory channel controllers

Figure [5](#page-37-0) shows how MSCs MSC10 and MSC11 are designed. In particular, both offer a single set of controls for partitioning memory bandwidth on the channels.

The Locator reference for MC_1 and MC_2 is specified in the form of their proximity domains, which requires that the ACPI SRAT table must include a description of the memory ranges of these memory controllers. Section [3.1.2.2](#page-26-0) provides a snapshot of the SRAT table to be used for the example system.

3.1.10.1 Power management considerations

MSC11 has a power management dependency on memory controller MC_2, its linked device. MC_2 is capable of being offlined, and indicates support for it in its ACPI device object definition.

The reference ASL code below describes MC_2 as an ACPI device named MEM2, with a _UID of 17.

The MSC device object includes the PSx methods that OSPM can invoke to perform power management of the MSC.

```
Device (MEM2) { // Memory controller 2, MC_2
    Name (_HID, "PNP0C80")
    Name (_UID, 17)
    Method (_PS3, 0, Serialized) { // _PS3: Power State 3
          // Turn MC off
    }
    Method (_PSO, O, Serialized) { // _PSO: Power State 0
          // Turn MC on
    }
}
Device (MS11) {
    Name (_HID, "ARMHAA5C")
    Name (_CID, "ARMHAA5C")
    Name (_UID, 10) // _UID for MSC11, must be identical
                    // to the Identifier field of the MSC
                    // node .
    Name (_STR, Unicode ("MSC11"))
    Method (_PS3, 0, Serialized) { // _PS3: Power State 3
          // Turn MSC off
    }
    Method (_PS0, 0, Serialized) { // _PS0: Power State 0
          // Turn MSC on
    }
}
```
3.1.11 SMMU_A

Figure [6](#page-39-0) illustrates how SMMU_A is organized internally. shows an illustrative SMMU design that supports MPAM. The SMMU has two IO TLB units, TLB_11 and TLB_12, that service Device 1 and PCIe root complexes RC1, respectively.

Each TLB has a dedicated MSC. The TLB is identified using the Identifier field of the component that it interfaces. TLB 11 is thus identified using the Identifier assigned to the IORT Named component node that describes Device 1.

TLB_12 is identified using the Identifier given to the IORT root complex node that describes RC. These nodes and their identifiers are explained in Section [3.1.2.4.](#page-26-1)

Figure 6: SMMU_A in the example system

The ACPI description of the MSCs in SMMU_A is as follows:

MSC node 13

3.1.12 SMMU_B

Figure [7](#page-40-1) illustrates the internal layout of the MSCs in SMMU_B.

SMMU_B differs from SMMU_A in that it has a single MSC, MSC14, that implements the RIS feature to provide support for the independent translation caches in TLB_21, TLB_22 and the TCU.

Figure 7: SMMU_B in the example system

The ACPI description of the MSC in this SMMU can now be performed as follows.

3.1.13 Inter-socket interconnects supporting MPAM

MSCs on interconnects are discovered using the Interconnect resource described in Section [2.3.3.6.](#page-18-2) In this example, the system has two packages sitting on separate sockets within a system. Each socket must be described as an ACPI NUMA domain.

This example system and its NUMA treatment is illustrated in Figure [8.](#page-42-0) The interconnect between the two sockets implements two distinct MPAM interfaces with associated MPAM controls each, illustrated as MSC2 and MSC3 in Figure [8.](#page-42-0)

Figure 8: Example system with MSCs on interconnects

MSC2 monitors and regulates bi-directional cross-NUMA traffic from NUMA node 1 (Socket 1) to memory in NUMA node 2 (i.e., on Socket 2). MSC3 monitors and regulates cross-NUMA uni-directional memory traffic initiated from NUMA node 2 (Socket 2) and targeting memory in NUMA node 1 (i.e., on Socket 1).

Figure 9: MSC characteristics for the example system

The ACPI description of MSC2 and MSC3 is constructed as follows:

- 1. The two NUMA domains must be described in ACPI SRAT. For this example system, the proximity domain numbers are set as *X* and *Y*.
- 2. MSC1-4 are described as MPAM MSC nodes in the ACPI MPAM table.

3.1.13.1 MPAM MSC node for MSC2

This node has a single resource, which points to an interconnect descriptor table that has two entries.

MSC node Identifier k (any arbitrary but unique value. Linked device ID 0, 0 (not valid) Number of resource nodes 1 Resource-specific data **Offset to interconnect descriptor table.**

The resource-specific data region of the MPAM MSC node is valid and contains the interconnect descriptor table.

The interconnect descriptor table

Interconnect descriptor 1

Interconnect descriptor 2

3.1.13.2 MPAM MSC node for MSC3

This node has a single resource, which points to an interconnect descriptor table that has a single entry.

The resource-specific data region of the MPAM MSC node is valid and contains the interconnect descriptor table.

The interconnect descriptor table

3.1.14 MPAM-enabled NUMA links on complex systems

A complex example system is illustrated in Figure Figure [10.](#page-45-0)

The NUMA Links are described using the interconnect resource locators described in Section [2.3.3.6.](#page-18-2) In this example, the system has two chips with dedicated memory, and a central IO Hub that has additional DDR memory managed by memory controllers.

Figure Figure [10](#page-45-0) also illustrates the NUMA classification of the system. The links between the Chips and the

IO Hub carry cross-NUMA traffic between multiple NUMA domains.

Figure 10: Example system with MSCs on interconnects

The ACPI MPAM description can now be modeled as follows:

- 1. There are four NUMA nodes, described in HMAT and SRAT.
- 2. MSC1-5 are described as MPAM MSC nodes in the ACPI MPAM table.
- 3. MSC2 is described with a resource node with locator type set as Interconnect.
- 4. For the sake of simplicity, MSC2 only measures outbound memory traffic from Chip1.

3.1.14.2 MPAM MSC node for MSC2

This node has a single resource, which points to an interconnect descriptor table that has three entries.

MSC node

The resource-specific data region of the MPAM MSC node is valid and contains the interconnect descriptor table.

The interconnect descriptor table

ACPI for Memory System Resource Partitioning and Monitoring

