# Instruction Set Assembly Guide for Armv7 and earlier Arm<sup>®</sup> architectures Version 2.0

**Reference Guide** 



# Instruction Set Assembly Guide for Armv7 and earlier Arm® architectures

#### **Reference Guide**

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# Contents Instruction Set Assembly Guide for Armv7 and earlier Arm<sup>®</sup> architectures Reference Guide

	Prefa	About this book	20
Part A	Inst	ruction Set Overview	
Chapter A1	Over	view of AArch32 state	
	A1.1	Terminology	A1-26
	A1.2	Changing between A32 and T32 instruction set states	A1-27
	A1.3	Processor modes, and privileged and unprivileged software execution	A1-28
	A1.4	Processor modes in Armv6-M, Armv7-M, and Armv8-M	A1-29
	A1.5	Registers in AArch32 state	A1-30
	A1.6	General-purpose registers in AArch32 state	A1-32
	A1.7	Register accesses in AArch32 state	A1-33
	A1.8	Predeclared core register names in AArch32 state	A1-34
	A1.9	Predeclared extension register names in AArch32 state	A1-35
	A1.10	Program Counter in AArch32 state	A1-36
	A1.11	The Q flag in AArch32 state	A1-37
	A1.12	Application Program Status Register	A1-38
	A1.13	Current Program Status Register in AArch32 state	A1-39
	A1.14	Saved Program Status Registers in AArch32 state	A1-40
	A1.15	A32 and T32 instruction set overview	A1-41

# Part B

# 3 Advanced SIMD and Floating-point Programming

Chapter B1	Adva	nced SIMD Programming	
	B1.1	Architecture support for Advanced SIMD	B1-46
	B1.2	Extension register bank mapping for Advanced SIMD in AArch32 state	B1-47
	B1.3	Views of the Advanced SIMD register bank in AArch32 state	B1-49
	B1.4	Load values to Advanced SIMD registers	B1-50
	B1.5	Conditional execution of A32/T32 Advanced SIMD instructions	B1-51
	B1.6	Floating-point exceptions for Advanced SIMD in A32/T32 instructions	B1-52
	B1.7	Advanced SIMD data types in A32/T32 instructions	B1-53
	B1.8	Polynomial arithmetic over {0,1}	B1-54
	B1.9	Advanced SIMD vectors	B1-55
	B1.10	Normal, long, wide, and narrow Advanced SIMD instructions	B1-56
	B1.11	Saturating Advanced SIMD instructions	B1-57
	B1.12	Advanced SIMD scalars	B1-58
	B1.13	Extended notation extension for Advanced SIMD	B1-59
	B1.14	Advanced SIMD system registers in AArch32 state	B1-60
	B1.15	Flush-to-zero mode in Advanced SIMD	B1-61
	B1.16	When to use flush-to-zero mode in Advanced SIMD	B1-62
	B1.17	The effects of using flush-to-zero mode in Advanced SIMD	B1-63
	B1.18	Advanced SIMD operations not affected by flush-to-zero mode	B1-64
Chapter B2	Float	ing-point Programming	
	B2.1	Architecture support for floating-point	B2-66
	B2.2	Extension register bank mapping for floating-point in AArch32 state	B2-67
	B2.3	Views of the floating-point extension register bank in AArch32 state	B2-69
	B2.4	Load values to floating-point registers	B2-70
	B2.5	Conditional execution of A32/T32 floating-point instructions	B2-71
	B2.6	Floating-point exceptions for floating-point in A32/T32 instructions	B2-72
	B2.7	Floating-point data types in A32/T32 instructions	B2-73
	B2.8	Extended notation extension for floating-point code	B2-74
	B2.9	Floating-point system registers in AArch32 state	B2-75
	B2.10	Flush-to-zero mode in floating-point	B2-76
	B2.11	When to use flush-to-zero mode in floating-point	B2-77
	B2.12	The effects of using flush-to-zero mode in floating-point	B2-78
	B2.13	Floating-point operations not affected by flush-to-zero mode	B2-79
Part C	A32	/T32 Instruction Set Reference	
Chapter C1	Cond	lition Codes	
	C1.1	Conditional instructions	C1-84
	C1.2	Conditional execution in A32 code	C1-85
	C1.3	Conditional execution in T32 code	C1-86
	C1.4	Condition flags	C1-87
	C1.5	Updates to the condition flags in A32/T32 code	C1-88
	C1.6	Floating-point instructions that update the condition flags	C1-89
	C1.7	Carry flag	C1-90

C1.8

	C1.9	Condition code suffixes	C1-92
	C1.10	Condition code suffixes and related flags	C1-93
	C1.11	Comparison of condition code meanings in integer and floating-point code	C1-94
	C1.12	Benefits of using conditional execution in A32 and T32 code	C1-96
	C1.13	Example showing the benefits of conditional instructions in A32 and T32 code	C1-97
	C1.14	Optimization for execution speed	. C1-100
Chapter C2	A32 a	and T32 Instructions	
	C2.1	A32 and T32 instruction summary	. C2-106
	C2.2	Instruction width specifiers	. C2-111
	C2.3	Flexible second operand (Operand2)	. C2-112
	C2.4	Syntax of Operand2 as a constant	. C2-113
	C2.5	Syntax of Operand2 as a register with optional shift	C2-114
	C2.6	Shift operations	C2-115
	C2.7	Saturating instructions	. C2-118
	C2.8	ADC	. C2-119
	C2.9	ADD	C2-121
	C2.10	ADR (PC-relative)	C2-124
	C2.11	ADR (register-relative)	. C2-126
	C2.12	AND	C2-128
	C2.13	ASR	C2-130
	C2.14	В	. C2-132
	C2.15	BFC	C2-134
	C2.16	BFI	C2-135
	C2.17	BIC	. C2-136
	C2.18	BKPT	C2-138
	C2.19	BL	. C2-139
	C2.20	BLX. BLXNS	C2-140
	C2.21	BX. BXNS	C2-142
	C2.22	BXJ	C2-144
	C2.23	CBZ and CBNZ	C2-145
	C2.24	CDP and CDP2	C2-146
	C2.25	CLREX	. C2-147
	C2.26	CLZ	C2-148
	C2.27	CMP and CMN	C2-149
	C2.28	CPS	C2-151
	C2.29	CRC32	C2-153
	C2.30	CRC32C	C2-154
	C2.31	CSDB	C2-155
	C2.32	DBG	C2-157
	C2 33	DMB	C2-158
	C2 34	DSB	C2-160
	C2 35	FOR	C2-162
	C2.36	ERET	C2-164
	C2.37	ESB	C2-165
	C2.38	HLT	C2-166
	C2.39	HVC	. C2-167
	C2.40	ISB	. C2-168
	C2.41	ΙΤ	C2-169
	C2.42	LDA	C2-172

C2.43	LDAEX	C2-173
C2.44	LDC and LDC2	C2-175
C2.45	LDM	C2-177
C2.46	LDR (immediate offset)	C2-179
C2.47	LDR (PC-relative)	C2-181
C2.48	LDR (register offset)	C2-183
C2.49	LDR (register-relative)	C2-185
C2.50	LDR, unprivileged	C2-187
C2.51	LDREX	C2-189
C2.52	LSL	C2-191
C2.53	LSR	C2-193
C2.54	MCR and MCR2	C2-195
C2.55	MCRR and MCRR2	C2-196
C2.56	MLA	C2-197
C2.57	MLS	C2-198
C2.58	MOV	C2-199
C2.59	MOVT	C2-201
C2.60	MRC and MRC2	C2-202
C2.61	MRRC and MRRC2	C2-203
C2.62	MRS (PSR to general-purpose register)	C2-204
C2.63	MRS (system coprocessor register to general-purpose register)	C2-206
C2 64	MSR (general-purpose register to system coprocessor register)	C2-207
C2.65	MSR (general-purpose register to PSR)	C2-208
C2 66	MUI	C2-210
C2 67	MVN	C2-211
C2 68	NOP	C2-213
C2 69	ORN (T32 only)	C2-214
C2 70	ORR	C2-215
C2 71	PKHRT and PKHTR	C2-217
C2 72	PID PIDW and PII	C2-210
C2 73		C2_221
C2 74	PIISH	C2-227
$C_{2.77}$		C2-222
C2.75		C2 223
C2.70		C2 224
02.77		02-225
02.70		02-220
62.79		02-227
02.80		02-228
62.81		62-229
C2.82	QSUB	02-230
C2.83	QSUB8	C2-231
C2.84	QSUB16	C2-232
C2.85		C2-233
C2.86		C2-234
C2.87	REV16	C2-235
C2.88	REVSH	C2-236
C2.89		C2-237
C2.90	ROR	C2-239
C2.91	RRX	C2-241
C2.92	RSB	C2-243

C2.93	RSC	C2-245
C2.94	SADD8	C2-247
C2.95	SADD16	C2-249
C2.96	SASX	C2-251
C2.97	SBC	C2-253
C2.98	SBFX	C2-255
C2.99	SDIV	C2-256
C2.100	SEL	C2-257
C2.101	SETEND	C2-259
C2.102	SETPAN	C2-260
C2.103	SEV	C2-261
C2.104	SEVL	C2-262
C2.105	SG	C2-263
C2.106	SHADD8	C2-264
C2.107	SHADD16	C2-265
C2.108	SHASX	C2-266
C2.109	SHSAX	C2-267
C2 110	SHSUB8	C2-268
C2 111	SHSUB16	C2-269
C2 112	SMC	C2-270
C2 113	SMLAXV	C2-271
C2 114	SMLAD	C2-273
C2 115	SMLAD	C2-274
C2 116	SMLAL D	$C_{2-275}$
C2 117	SMLALD	C2 276
C2.117	SMEALXY	C2-270
C2.110	SMLAWY	02-270
02.119	SMLSD	02-279
02.120		02-280
02.121	SMMLA	02-281
C2.122	SMMLS	C2-282
C2.123	SMMUL	C2-283
C2.124	SMUAD	C2-284
C2.125	SMULxy	C2-285
C2.126	SMULL	C2-286
C2.127	SMULWy	C2-287
C2.128	SMUSD	C2-288
C2.129	SRS	C2-289
C2.130	SSAT	C2-291
C2.131	SSAT16	C2-292
C2.132	SSAX	C2-293
C2.133	SSUB8	C2-295
C2.134	SSUB16	C2-297
C2.135	STC and STC2	C2-299
C2.136	STL	C2-301
C2.137	STLEX	C2-302
C2.138	STM	C2-304
C2.139	STR (immediate offset)	C2-306
C2.140	STR (register offset)	C2-308
C2.141	STR, unprivileged	C2-310
C2.142	STREX	C2-312

C2.143	SUB	C2-314
C2.144	SUBS pc, Ir	C2-317
C2.145	SVC	C2-319
C2.146	SWP and SWPB	C2-320
C2.147	SXTAB	C2-321
C2.148	SXTAB16	C2-323
C2.149	SXTAH	C2-325
C2.150	SXTB	C2-327
C2.151	SXTB16	C2-329
C2.152	SXTH	C2-330
C2.153	SYS	C2-332
C2.154	TBB and TBH	C2-333
C2.155	TEQ	C2-334
C2.156	TST	C2-336
C2.157	TT. TTT. TTA. TTAT	C2-338
C2.158	UADD8	C2-340
C2.159	UADD16	C2-342
C2.160	UASX	C2-344
C2 161	UBEX	C2-346
C2 162		C2-347
C2 163		C2-348
C2 164		C2-349
C2 165		C2-350
C2 166	UHASY	C2-351
C2 167	UHSAX	C2-352
C2 168	UHSUB8	C2-353
C2 160		C2-354
C2 170		C2-355
C2 171		C2-356
$C_{2.171}$		C2-357
C2.172		C2-357
C2.173	UQADD8	C2-350
C2.174		C2-309
C2.175		C2-300
C2.170	UQSAX	02-307
02.177		02-302
02.170		02-303
02.179		02-304
C2.180		02-365
C2.181	USAT	C2-366
C2.182	USA116	C2-367
C2.183		C2-368
C2.184		C2-370
C2.185	USUB16	C2-372
C2.186		C2-373
C2.187	UX IAB16	C2-375
C2.188	UX IAH	C2-377
C2.189	UXTB	C2-379
C2.190	UXTB16	C2-381
C2.191	UXTH	C2-382
C2.192	WFE	C2-384

	C2.193	WF1	C2-385
	C2.194	YIELD	C2-386
Chapter C3	Advan	nced SIMD Instructions (32-bit)	
	C3.1	Summary of Advanced SIMD instructions	C3-391
	C3.2	Summary of shared Advanced SIMD and floating-point instructions	C3-394
	C3.3	Interleaving provided by load and store element and structure instructions	C3-395
	C3.4	Alianment restrictions in load and store element and structure instructions	C3-396
	C3.5	FLDMDBX. FLDMIAX	C3-397
	C3.6	FSTMDBX, FSTMIAX	C3-398
	C3.7	VABA and VABAL	C3-399
	C3.8	VABD and VABDL	C3-400
	C3.9	VABS	C3-401
	C3.10	VACLE, VACLT, VACGE and VACGT	C3-402
	C3.11	VADD	C3-403
	C3.12	VADDHN	C3-404
	C3.13	VADDL and VADDW	C3-405
	C3.14	VAND (immediate)	C3-406
	C3.15	VAND (register)	C3-407
	C3.16	VBIC (immediate)	C3-408
	C3.17	VBIC (register)	C3-409
	C3.18	VBIF	C3-410
	C3.19	VBIT	C3-411
	C3.20	VBSL	C3-412
	C3.21	VCADD	C3-413
	C3.22	VCEQ (immediate #0)	C3-414
	C3.23	VCEQ (register)	C3-415
	C3.24	VCGE (immediate #0)	C3-416
	C3.25	VCGE (register)	C3-417
	C3.26	VCGT (immediate #0)	C3-418
	C3.27	VCGT (register)	C3-419
	C3.28	VCLE (immediate #0)	C3-420
	C3.29	VCLS	C3-421
	C3.30	VCLE (register)	C3-422
	C3.31	VCLT (immediate #0)	C3-423
	C3.32	VCLT (register)	C3-424
	C3.33	VCLZ	C3-425
	C3.34	VCMLA	C3-426
	C3.35	VCMLA (by element)	C3-427
	C3.36	VCNT	C3-428
	C3.37	VCVT (between fixed-point or integer, and floating-point)	C3-429
	C3.38	VCVT (between half-precision and single-precision floating-point)	C3-430
	C3.39	VCVT (from floating-point to integer with directed rounding modes)	C3-431
	C3.40	VCVTB, VCVTT (between half-precision and double-precision)	C3-432
	C3.41	VDUP	C3-433
	C3.42	VEOR	C3-434
	C3.43	VEXT	C3-435
	C3.44	VFMA, VFMS	C3-436
	C3.45	VFMAL (by scalar)	C3-437
	C3.46	VFMAL (vector)	C3-438

C3.47	VFMSL (by scalar)	C3-439
C3.48	VFMSL (vector)	C3-440
C3.49	VHADD	C3-441
C3.50	VHSUB	C3-442
C3.51	VLDn (single n-element structure to one lane)	C3-443
C3.52	VLDn (single n-element structure to all lanes)	C3-445
C3.53	VLDn (multiple n-element structures)	C3-447
C3.54	VLDM	C3-449
C3.55	VLDR	C3-450
C3.56	VLDR (post-increment and pre-decrement)	C3-451
C3.57	VLDR pseudo-instruction	C3-452
C3.58	VMAX and VMIN	C3-453
C3.59	VMAXNM, VMINNM	C3-454
C3.60	VMLA	C3-455
C3.61	VMLA (by scalar)	C3-456
C3.62	VMLAL (by scalar)	C3-457
C3.63	VMLAL	C3-458
C3.64	VMLS (by scalar)	C3-459
C3.65	VMLS	C3-460
C3 66	VMI SI	C3-461
C3 67	VMLSL (by scalar)	C3-462
C3 68	VMOV (immediate)	C3-463
C3 69	VMOV (millioutic)	C3-464
C3 70	VMOV (register)	00 101
00.70		C3-465
C3.71	VMOV (between a general-purpose register and an Advanced SIMD scalar)	C3-466
C3.71 C3.72	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL	C3-466 C3-467
C3.71 C3.72 C3.73	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN	C3-466 C3-467 C3-468
C3.71 C3.72 C3.73 C3.74	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2	C3-466 C3-467 C3-468 C3-469
C3.71 C3.72 C3.73 C3.74 C3.75	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS	C3-466 C3-467 C3-468 C3-469 C3-470
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMSR	C3-466 C3-467 C3-468 C3-469 C3-470 C3-471
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMSR	C3-466 C3-467 C3-468 C3-469 C3-470 C3-471 C3-472
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMSR VMUL VMUL VMUL (by scalar)	C3-466 C3-467 C3-468 C3-469 C3-470 C3-471 C3-472 C3-473
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRR VMSR VMUL VMUL (by scalar)	C3-466 C3-467 C3-468 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRS VMSR VMUL VMUL (by scalar)	C3-466 C3-467 C3-469 C3-470 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.81	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMSR VMUL VMUL (by scalar) VMULL (by scalar) VMULL (by scalar)	C3-466 C3-467 C3-468 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.81 C3.82	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRR VMSR VMUL VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register)	C3-466 C3-467 C3-469 C3-470 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.80 C3.81 C3.82 C3.83	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRS VMSR VMUL VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register) VMVN (immediate)	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-478
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.81 C3.82 C3.83 C3.83	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRS VMSR VMUL VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register) VMVN (immediate) VNEG	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-470
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.81 C3.82 C3.83 C3.84 C3.84	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMSR VMUL VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register) VMVN (register) VMVN (immediate) VNEG VORN (register)	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-479 C2 480
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.81 C3.82 C3.83 C3.84 C3.85 C3.85	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRS VMSR VMUL VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register) VMVN (register) VMVN (immediate) VNEG VORN (register) VORN (register)	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-479 C3-480 C2 481
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.81 C3.82 C3.83 C3.84 C3.85 C3.86 C3.87	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRS VMSR VMUL VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register) VMVN (register) VMVN (immediate) VNEG VORN (register) VORN (register)	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-479 C3-480 C3-481
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.81 C3.82 C3.83 C3.84 C3.85 C3.86 C3.87 C3.87	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRS VMSR VMUL VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register) VMVN (register) VMVN (immediate) VNEG VORN (register) VORN (register) VORN (immediate) VORR (immediate)	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-479 C3-480 C3-481 C3-482
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.81 C3.82 C3.83 C3.84 C3.85 C3.86 C3.87 C3.88	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRS VMSR VMUL VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register) VMVN (register) VMVN (immediate) VNEG VORN (register) VORN (register) VORR (immediate) VORR (immediate) VORR (immediate)	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-480 C3-480 C3-481 C3-482 C3-483
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.80 C3.81 C3.82 C3.83 C3.84 C3.85 C3.86 C3.87 C3.88 C3.89 C3.20	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-479 C3-480 C3-481 C3-482 C3-483 C3-484
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.80 C3.81 C3.82 C3.83 C3.84 C3.85 C3.86 C3.87 C3.88 C3.87 C3.88 C3.89 C3.90 C3.90	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRS VMSR VMUL VMUL (by scalar) VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register) VMVN (register) VMVN (immediate) VNEG VORN (register) VORN (immediate) VORR (register) VORR (immediate) VORR (immediate) VORR (immediate) VPADAL VPADD	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-479 C3-480 C3-481 C3-482 C3-483 C3-484 C3-485
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.81 C3.82 C3.83 C3.84 C3.85 C3.86 C3.87 C3.86 C3.87 C3.88 C3.89 C3.90 C3.91	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRS VMSR VMUL VMUL (by scalar) VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register) VMVN (register) VMVN (immediate) VNEG VORN (register) VORN (register) VORR (register) VORR (register) VORR (immediate) VORR (immediate) VPADAL VPADD VPADD	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-480 C3-480 C3-481 C3-482 C3-483 C3-484 C3-485 C3-485
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.80 C3.81 C3.82 C3.83 C3.84 C3.85 C3.86 C3.87 C3.86 C3.87 C3.88 C3.89 C3.90 C3.91 C3.92	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL VMOVN VMOV2 VMRS VMRS VMUL VMUL (by scalar) VMUL (by scalar) VMULL (by scalar) VMULL (by scalar) VMULL (by scalar) VMVN (register) VMVN (register) VMVN (immediate) VNEG VORN (register) VORN (register) VORR (register) VORR (immediate) VORR (immediate) VPADAL VPADD VPADD VPADD	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-479 C3-480 C3-481 C3-482 C3-483 C3-484 C3-485 C3-486 C3-487
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.80 C3.81 C3.82 C3.83 C3.84 C3.85 C3.86 C3.87 C3.86 C3.87 C3.88 C3.89 C3.90 C3.90 C3.91 C3.92 C3.93	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-480 C3-481 C3-482 C3-483 C3-485 C3-485 C3-486 C3-487 C3-488
C3.71 C3.72 C3.73 C3.74 C3.75 C3.76 C3.77 C3.78 C3.79 C3.80 C3.81 C3.82 C3.83 C3.84 C3.85 C3.86 C3.87 C3.86 C3.87 C3.88 C3.89 C3.90 C3.90 C3.91 C3.92 C3.93 C3.94	VMOV (between a general-purpose register and an Advanced SIMD scalar) VMOVL	C3-466 C3-467 C3-469 C3-470 C3-471 C3-472 C3-473 C3-473 C3-474 C3-475 C3-476 C3-477 C3-478 C3-480 C3-481 C3-482 C3-483 C3-484 C3-485 C3-486 C3-487 C3-488 C3-489

C3.96	VQDMLAL and VQDMLSL (by vector or by scalar)	C3-491
C3.97	VQDMULH (by vector or by scalar)	C3-492
C3.98	VQDMULL (by vector or by scalar)	C3-493
C3.99	VQMOVN and VQMOVUN	C3-494
C3.100	VQNEG	C3-495
C3.101	VQRDMULH (by vector or by scalar)	C3-496
C3.102	VQRSHL (by signed variable)	C3-497
C3.103	VQRSHRN and VQRSHRUN (by immediate)	C3-498
C3.104	VQSHL (by signed variable)	C3-499
C3.105	VQSHL and VQSHLU (by immediate)	C3-500
C3.106	VQSHRN and VQSHRUN (by immediate)	C3-501
C3.107	VQSUB	C3-502
C3.108	VRADDHN	C3-503
C3.109	VRECPE	C3-504
C3.110	VRECPS	C3-505
C3.111	VREV16, VREV32, and VREV64	C3-506
C3.112	VRHADD	C3-507
C3.113	VRSHL (by signed variable)	C3-508
C3.114	VRSHR (by immediate)	C3-509
C3.115	VRSHRN (by immediate)	C3-510
C3.116	VRINT	C3-511
C3.117	VRSORTE	C3-512
C3.118	VRSORTS	C3-513
C3.119	VRSRA (by immediate)	C3-514
C3.120	VRSUBHN	C3-515
C3.121	VSDOT (vector)	C3-516
C3.122	VSDOT (by element)	C3-517
C3.123	VSHL (by immediate)	C3-518
C3.124	VSHL (by signed variable)	C3-519
C3.125	VSHLL (by immediate)	C3-520
C3 126	VSHR (by immediate)	C3-521
C3 127	VSHRN (by immediate)	C3-522
C3 128	VSLI	C3-523
C3 129	VSRA (by immediate)	C3-524
C3 130	VSRI	C3-525
C3 131	VSTM	C3-526
C3 132	VSTn (multiple n-element structures)	C3-527
C3 133	VSTn (single n-element structure to one lane)	C3-529
C3 134	VSTR	C3-531
C3 135	VSTR (nost-increment and nre-decrement)	C3-532
C2 126		C2 522
C2 127		C2 524
C2 122	VSUBL and VSUBM	C2 525
C2 120		C2 526
C3.139		C3-530
C2 1 4 4		03-33/
03.141		03-538
03.142	VIDOT (vector)	03-539
03.143	VUDUT (vector)	03-540
03.144		03-541
63.145	VULF	63-542

	C3.146	5 VZIP	C3-543
Chapter C4	Float	ing-point Instructions (32-bit)	
	C4.1	Summary of floating-point instructions	C4-547
	C4.2	VABS (floating-point)	C4-549
	C4.3	VADD (floating-point)	C4-550
	C4.4	VCMP, VCMPE	C4-551
	C4.5	VCVT (between single-precision and double-precision)	C4-552
	C4.6	VCVT (between floating-point and integer)	C4-553
	C4.7	VCVT (from floating-point to integer with directed rounding modes)	C4-554
	C4.8	VCVT (between floating-point and fixed-point)	C4-555
	C4.9	VCVTB, VCVTT (half-precision extension)	C4-556
	C4.10	VCVTB, VCVTT (between half-precision and double-precision)	C4-557
	C4.11	VDIV	C4-558
	C4.12	VFMA, VFMS, VFNMA, VFNMS (floating-point)	C4-559
	C4.13	VJCVT	C4-560
	C4.14	VLDM (floating-point)	C4-561
	C4.15	VLDR (floating-point)	C4-562
	C4.16	VLDR (post-increment and pre-decrement, floating-point)	C4-563
	C4.17	VLLDM	C4-564
	C4.18	VLSTM	C4-565
	C4.19	VMAXNM, VMINNM (floating-point)	C4-566
	C4.20	VMLA (floating-point)	C4-567
	C4.21	VMLS (floating-point)	C4-568
	C4.22	VMOV (floating-point)	C4-569
	C4.23	VMOV (between one general-purpose register and single precision floating	g-point
		register)	C4-570
	C4.24	VMOV (between two general-purpose registers and one or two extension	registers) C4-571
	C4.25	VMOV (between a general-purpose register and half a double precision flo	pating-point
		register)	C4-572
	C4.26	VMRS (floating-point)	C4-573
	C4.27	VMSR (floating-point)	C4-574
	C4.28	VMUL (floating-point)	C4-575
	C4.29	VNEG (floating-point)	C4-576
	C4.30	VNMLA (floating-point)	C4-577
	C4.31	VNMLS (floating-point)	C4-578
	C4.32	VNMUL (floating-point)	C4-579
	C4.33	VPOP (floating-point)	C4-580
	C4.34	VPUSH (floating-point)	C4-581
	C4.35	VRINT (floating-point)	C4-582
	C4.36	VSEL	C4-583
	C4.37	VSQRT	C4-584
	C4.38	VSTM (floating-point)	C4-585
	C4.39	VSTR (floating-point)	C4-586
	C4.40	VSTR (post-increment and pre-decrement, floating-point)	C4-587
	C4.41	VSUB (floating-point)	C4-588
Chapter C5	A32/1	T32 Cryptographic Algorithms	
	C5.1	A32/T32 Cryptographic instructions	C5-590

# List of Figures Instruction Set Assembly Guide for Armv7 and earlier Arm<sup>®</sup> architectures Reference Guide

Figure A1-1	Organization of general-purpose registers and Program Status Registers	A1-31
Figure B1-1	Extension register bank for Advanced SIMD in AArch32 state	B1-47
Figure B2-1	Extension register bank for floating-point in AArch32 state	B2-67
Figure C2-1	ASR #3	C2-115
Figure C2-2	LSR #3	C2-116
Figure C2-3	LSL #3	C2-116
Figure C2-4	ROR #3	C2-116
Figure C2-5	RRX	C2-117
Figure C3-1	De-interleaving an array of 3-element structures	C3-395
Figure C3-2	Operation of doubleword VEXT for imm = 3	C3-435
Figure C3-3	Example of operation of VPADAL (in this case for data type S16)	C3-483
Figure C3-4	Example of operation of VPADD (in this case, for data type I16)	C3-484
Figure C3-5	Example of operation of doubleword VPADDL (in this case, for data type S16)	C3-485
Figure C3-6	Operation of quadword VSHL.I64 Qd, Qm, #1	C3-518
Figure C3-7	Operation of quadword VSLI.64 Qd, Qm, #1	C3-523
Figure C3-8	Operation of doubleword VSRI.64 Dd, Dm, #2	C3-525
Figure C3-9	Operation of doubleword VTRN.8	C3-538
Figure C3-10	Operation of doubleword VTRN.32	C3-538

# List of Tables Instruction Set Assembly Guide for Armv7 and earlier Arm<sup>®</sup> architectures Reference Guide

Table A1-1	AArch32 processor modes	A1-28
Table A1-2	Predeclared core registers in AArch32 state	A1-34
Table A1-3	Predeclared extension registers in AArch32 state	A1-35
Table A1-4	A32 instruction groups	A1-41
Table B1-1	Advanced SIMD data types	B1-53
Table B1-2	Advanced SIMD saturation ranges	B1-57
Table C1-1	Condition code suffixes	C1-92
Table C1-2	Condition code suffixes and related flags	C1-93
Table C1-3	Condition codes	C1-94
Table C1-4	Conditional branches only	C1-97
Table C1-5	All instructions conditional	C1-98
Table C2-1	Summary of instructions	C2-106
Table C2-2	PC-relative offsets	C2-124
Table C2-3	Register-relative offsets	C2-126
Table C2-4	B instruction availability and range	C2-132
Table C2-5	BL instruction availability and range	C2-139
Table C2-6	BLX instruction availability and range	C2-140
Table C2-7	BX instruction availability and range	C2-142
Table C2-8	BXJ instruction availability and range	C2-144
Table C2-9	Permitted instructions inside an IT block	C2-170
Table C2-10	Offsets and architectures, LDR, word, halfword, and byte	C2-179
Table C2-11	PC-relative offsets	C2-181

Table C2-12	Options and architectures, LDR (register offsets)	C2-184
Table C2-13	Register-relative offsets	C2-185
Table C2-14	Offsets and architectures, LDR (User mode)	C2-187
Table C2-15	Offsets and architectures, STR, word, halfword, and byte	C2-306
Table C2-16	Options and architectures, STR (register offsets)	C2-308
Table C2-17	Offsets and architectures, STR (User mode)	C2-311
Table C3-1	Summary of Advanced SIMD instructions	C3-391
Table C3-2	Summary of shared Advanced SIMD and floating-point instructions	C3-394
Table C3-3	Patterns for immediate value in VBIC (immediate)	C3-408
Table C3-4	Permitted combinations of parameters for VLDn (single n-element structure to one lane) 443	C3-
Table C3-5	Permitted combinations of parameters for VLDn (single n-element structure to all lanes) 445	C3-
Table C3-6	Permitted combinations of parameters for VLDn (multiple n-element structures)	C3-447
Table C3-7	Available immediate values in VMOV (immediate)	C3-463
Table C3-8	Available immediate values in VMVN (immediate)	C3-477
Table C3-9	Patterns for immediate value in VORR (immediate)	C3-482
Table C3-10	Available immediate ranges in VQRSHRN and VQRSHRUN (by immediate)	C3-498
Table C3-11	Available immediate ranges in VQSHL and VQSHLU (by immediate)	C3-500
Table C3-12	Available immediate ranges in VQSHRN and VQSHRUN (by immediate)	C3-501
Table C3-13	Results for out-of-range inputs in VRECPE	C3-504
Table C3-14	Results for out-of-range inputs in VRECPS	C3-505
Table C3-15	Available immediate ranges in VRSHR (by immediate)	C3-509
Table C3-16	Available immediate ranges in VRSHRN (by immediate)	C3-510
Table C3-17	Results for out-of-range inputs in VRSQRTE	C3-512
Table C3-18	Results for out-of-range inputs in VRSQRTS	C3-513
Table C3-19	Available immediate ranges in VRSRA (by immediate)	C3-514
Table C3-20	Available immediate ranges in VSHL (by immediate)	C3-518
Table C3-21	Available immediate ranges in VSHLL (by immediate)	C3-520
Table C3-22	Available immediate ranges in VSHR (by immediate)	C3-521
Table C3-23	Available immediate ranges in VSHRN (by immediate)	C3-522
Table C3-24	Available immediate ranges in VSRA (by immediate)	C3-524
Table C3-25	Permitted combinations of parameters for VSTn (multiple n-element structures)	C3-527
Table C3-26	Permitted combinations of parameters for VSTn (single n-element structure to one lane) 529	C3-
Table C3-27	Operation of doubleword VUZP.8	C3-542
Table C3-28	Operation of quadword VUZP.32	C3-542
Table C3-29	Operation of doubleword VZIP.8	C3-543
Table C3-30	Operation of quadword VZIP.32	C3-543
Table C4-1	Summary of floating-point instructions	C4-547
Table C5-1	Summary of A32/T32 cryptographic instructions	C5-590

# Preface

This preface introduces the Instruction Set Assembly Guide for Armv7 and earlier Arm<sup>®</sup> architectures Reference Guide.

It contains the following:

• *About this book* on page 20.

## About this book

Arm<sup>®</sup> Instruction Set Assembly Guide for Armv7 and earlier Arm architectures. This document contains an overview of the Arm architecture and information on A32 and T32 instruction sets. For assembler-specific features, such as additional pseudo-instructions, see the documentation for your assembler.

#### Using this book

This book is organized into the following chapters:

Part A Instruction Set Overview

Chapter A1 Overview of AArch32 state Gives an overview of the AArch32 state.

Part B Advanced SIMD and Floating-point Programming

Chapter B1 Advanced SIMD Programming Describes Advanced SIMD assembly language programming.

### Chapter B2 Floating-point Programming

Describes floating-point assembly language programming.

#### Part C A32/T32 Instruction Set Reference

Chapter C1 Condition Codes Describes condition codes and conditional execution of A32 and T32 code.

## Chapter C2 A32 and T32 Instructions

Describes the A32 and T32 instructions supported in AArch32 state.

Chapter C3 Advanced SIMD Instructions (32-bit) Describes Advanced SIMD assembly language instructions.

#### Chapter C4 Floating-point Instructions (32-bit)

Describes floating-point assembly language instructions.

#### Chapter C5 A32/T32 Cryptographic Algorithms

Lists the cryptographic algorithms that A32 and T32 SIMD instructions support.

#### Glossary

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# Part A Instruction Set Overview

# Chapter A1 Overview of AArch32 state

#### Gives an overview of the AArch32 state.

It contains the following sections:

- A1.1 Terminology on page A1-26.
- A1.2 Changing between A32 and T32 instruction set states on page A1-27.
- A1.3 Processor modes, and privileged and unprivileged software execution on page A1-28.
- A1.4 Processor modes in Armv6-M, Armv7-M, and Armv8-M on page A1-29.
- A1.5 Registers in AArch32 state on page A1-30.
- A1.6 General-purpose registers in AArch32 state on page A1-32.
- *A1.7 Register accesses in AArch32 state* on page A1-33.
- A1.8 Predeclared core register names in AArch32 state on page A1-34.
- A1.9 Predeclared extension register names in AArch32 state on page A1-35.
- A1.10 Program Counter in AArch32 state on page A1-36.
- A1.11 The Q flag in AArch32 state on page A1-37.
- A1.12 Application Program Status Register on page A1-38.
- A1.13 Current Program Status Register in AArch32 state on page A1-39.
- *A1.14 Saved Program Status Registers in AArch32 state* on page A1-40.
- A1.15 A32 and T32 instruction set overview on page A1-41.
- A1.16 Access to the inline barrel shifter in AArch32 state on page A1-42.

# A1.1 Terminology

This document uses the following terms to refer to instruction sets.

Instruction sets for Armv7 and earlier architectures were called the ARM and Thumb instruction sets.

This document describes the instruction sets for Armv7 and earlier architectures, but uses terminology that is introduced with Armv8:

A32

The A32 instruction set was previously called the ARM instruction set. It is a fixed-length instruction set that uses 32-bit instruction encodings.

#### T32

The T32 instruction set was previously called the Thumb instruction set. It is a variable-length instruction set that uses both 16-bit and 32-bit instruction.

#### AArch32

The AArch32 Execution state supports the A32 and T32 instruction sets.

The Arm 32-bit Execution state uses 32-bit general purpose registers, and a 32-bit program counter (PC), stack pointer (SP), and link register (LR). In implementations of the Arm architecture beforeArmv8, execution is always in AArch32 state.

#### - Note -

Some examples and descriptions in this document might apply only to the armasm legacy assembler.

# A1.2 Changing between A32 and T32 instruction set states

A processor that is executing A32 instructions is operating in *A32 instruction set state*. A processor that is executing T32 instructions is operating in *T32 instruction set state*. For brevity, this document refers to them as the *A32 state* and *T32 state* respectively.

A processor in A32 state cannot execute T32 instructions, and a processor in T32 state cannot execute A32 instructions. You must ensure that the processor never receives instructions of the wrong instruction set for the current state.

The initial state after reset depends on the processor being used and its configuration.

To direct armasm to generate A32 or T32 instruction encodings, you must set the assembler mode using an ARM or THUMB directive. Assembly code using CODE32 and CODE16 directives can still be assembled, but Arm recommends you use the ARM and THUMB directives for new code.

These directives do not change the instruction set state of the processor. To do this, you must use an appropriate instruction, for example BX or BLX to change between A32 and T32 states when performing a branch.

#### **Related references**

*C2.20 BLX, BLXNS* on page C2-140 *C2.21 BX, BXNS* on page C2-142

## A1.3 Processor modes, and privileged and unprivileged software execution

The Arm architecture supports different levels of execution privilege. The privilege level depends on the processor mode.

\_\_\_\_\_ Note \_\_\_\_\_

Armv6-M, Armv7-M, Armv8-M Baseline, and Armv8-M Mainline do not support the same modes as other Arm architectures and profiles. Some of the processor modes listed here do not apply to these architectures.

#### Table A1-1 AArch32 processor modes

Processor mode	Mode number
User	0b10000
FIQ	0b10001
IRQ	0b10010
Supervisor	0b10011
Monitor	0b10110
Abort	0b10111
Нур	0b11010
Undefined	0b11011
System	0b11111

User mode is an unprivileged mode, and has restricted access to system resources. All other modes have full access to system resources in the current security state, can change mode freely, and execute software as privileged.

Applications that require task protection usually execute in User mode. Some embedded applications might run entirely in any mode other than User mode. An application that requires full access to system resources usually executes in System mode.

Modes other than User mode are entered to service exceptions, or to access privileged resources.

Code can run in either a Secure state or in a Non-secure state. Hypervisor (Hyp) mode has privileged execution in Non-secure state.

**Related concepts** A1.4 Processor modes in Armv6-M, Armv7-M, and Armv8-M on page A1-29 **Related information** Arm Architecture Reference Manual

# A1.4 Processor modes in Armv6-M, Armv7-M, and Armv8-M

The processor modes available in Armv6-M, Armv7-M, Armv8-M Baseline, and Armv8-M Mainline are Thread mode and Handler mode.

Thread mode is the normal mode that programs run in. Thread mode can be privileged or unprivileged software execution. Handler mode is the mode that exceptions are handled in. It is always privileged software execution.

#### **Related concepts**

A1.3 Processor modes, and privileged and unprivileged software execution on page A1-28 **Related information** Arm Architecture Reference Manual

# A1.5 Registers in AArch32 state

Arm processors provide general-purpose and special-purpose registers. Some additional registers are available in privileged execution modes.

In all Arm processors in AArch32 state, the following registers are available and accessible in any processor mode:

- 15 general-purpose registers R0-R12, the Stack Pointer (SP), and Link Register (LR).
- 1 Program Counter (PC).
- 1 Application Program Status Register (APSR).

\_\_\_\_\_ Note \_\_\_\_\_

• SP and LR can be used as general-purpose registers, although Arm deprecates using SP other than as a stack pointer.

Additional registers are available in privileged software execution. Arm processors have a total of 43 registers. The registers are arranged in partially overlapping banks. There is a different register bank for each processor mode. The banked registers give rapid context switching for dealing with processor exceptions and privileged operations.

The additional registers in Arm processors are:

- 2 supervisor mode registers for banked SP and LR.
- 2 abort mode registers for banked SP and LR.
- 2 undefined mode registers for banked SP and LR.
- 2 interrupt mode registers for banked SP and LR.
- 7 FIQ mode registers for banked R8-R12, SP and LR.
- 2 monitor mode registers for banked SP and LR.
- 1 Hyp mode register for banked SP.
- 7 Saved Program Status Register (SPSRs), one for each exception mode.
- 1 Hyp mode register for ELR\_Hyp to store the preferred return address from Hyp mode.

\_\_\_\_\_ Note \_\_\_\_\_

In privileged software execution, CPSR is an alias for APSR and gives access to additional bits.

The following figure shows how the registers are banked in the Arm architecture.

Applicatior	l								
level view	System level view								
í )	[ 		1	1	1		1		
	User	System	Hyp †	Supervisor	Abort	Undefined	Monitor <sup>‡</sup>	IRQ	FIQ
R0	R0_usr								
R1	R1_usr								
R2	R2_usr								
R3	R3_usr								
R4	R4_usr								
R5	R5_usr								
R6	R6_usr								
R7	R7_usr								
R8	R8_usr								R8_fiq
R9	R9_usr								R9_fiq
R10	R10_usr								R10_fiq
R11	R11_usr								R11_fiq
R12	R12_usr								R12_fiq
SP	SP_usr		SP_hyp	SP_svc	SP_abt	SP_und	SP_mon	SP_irq	SP_fiq
LR	LR_usr			LR_svc	LR_abt	LR_und	LR_mon	LR_irq	LR_fiq
PC	PC								
APSR	CPSR								
			SPSR_hyp	SPSR_svc	SPSR_abt	SPSR_und	SPSR_mon	SPSR_irq	SPSR_fiq

ELR\_hyp

‡ Exists only in Secure state.

† Exists only in Non-secure state.

Cells with no entry indicate that the User mode register is used.

#### Figure A1-1 Organization of general-purpose registers and Program Status Registers

In Armv6-M, Armv7-M, Armv8-M Baseline, and Armv8-M Mainline based processors, SP is an alias for the two banked stack pointer registers:

- Main stack pointer register, that is only available in privileged software execution.
- Process stack pointer register.

#### **Related concepts**

A1.6 General-purpose registers in AArch32 state on page A1-32

A1.10 Program Counter in AArch32 state on page A1-36

A1.12 Application Program Status Register on page A1-38

A1.14 Saved Program Status Registers in AArch32 state on page A1-40

A1.13 Current Program Status Register in AArch32 state on page A1-39

A1.3 Processor modes, and privileged and unprivileged software execution on page A1-28

#### **Related information**

Arm Architecture Reference Manual

# A1.6 General-purpose registers in AArch32 state

There are restrictions on the use of SP and LR as general-purpose registers.

With the exception of Armv6-M, Armv7-M, Armv8-M Baseline, and Armv8-M Mainline based processors, there are 33 general-purpose 32-bit registers, including the banked SP and LR registers. Fifteen general-purpose registers are visible at any one time, depending on the current processor mode. These are R0-R12, SP, and LR. The PC (R15) is not considered a general-purpose register.

SP (or R13) is the *stack pointer*. The C and C++ compilers always use SP as the stack pointer. Arm deprecates most uses of SP as a general purpose register. In T32 state, SP is strictly defined as the stack pointer. The instruction descriptions in *Chapter C2 A32 and T32 Instructions* on page C2-101 describe when SP and PC can be used.

In User mode, LR (or R14) is used as a *link register* to store the return address when a subroutine call is made. It can also be used as a general-purpose register if the return address is stored on the stack.

In the exception handling modes, LR holds the return address for the exception, or a subroutine return address if subroutine calls are executed within an exception. LR can be used as a general-purpose register if the return address is stored on the stack.

#### **Related concepts**

A1.10 Program Counter in AArch32 state on page A1-36 A1.7 Register accesses in AArch32 state on page A1-33 **Related references** A1.8 Predeclared core register names in AArch32 state on page A1-34 C2.62 MRS (PSR to general-purpose register) on page C2-204 C2.65 MSR (general-purpose register to PSR) on page C2-208

# A1.7 Register accesses in AArch32 state

16-bit T32 instructions can access only a limited set of registers. There are also some restrictions on the use of special-purpose registers by A32 and 32-bit T32 instructions.

Most 16-bit T32 instructions can only access R0 to R7. Only a small number of T32 instructions can access R8-R12, SP, LR, and PC. Registers R0 to R7 are called Lo registers. Registers R8-R12, SP, LR, and PC are called Hi registers.

All 32-bit T32 instructions can access R0 to R12, and LR. However, apart from a few designated stack manipulation instructions, most T32 instructions cannot use SP. Except for a few specific instructions where PC is useful, most T32 instructions cannot use PC.

In A32 state, all instructions can access R0 to R12, SP, and LR, and most instructions can also access PC (R15). However, the use of the SP in an A32 instruction, in any way that is not possible in the corresponding T32 instruction, is deprecated. Explicit use of the PC in an A32 instruction is not usually useful, and except for specific instances that are useful, such use is deprecated. Implicit use of the PC, for example in branch instructions or load (literal) instructions, is never deprecated.

The MRS instructions can move the contents of a status register to a general-purpose register, where they can be manipulated by normal data processing operations. You can use the MSR instruction to move the contents of a general-purpose register to a status register.

#### **Related concepts**

A1.6 General-purpose registers in AArch32 state on page A1-32
A1.10 Program Counter in AArch32 state on page A1-36
A1.12 Application Program Status Register on page A1-38
A1.13 Current Program Status Register in AArch32 state on page A1-39
A1.14 Saved Program Status Registers in AArch32 state on page A1-40
Related references
A1.8 Predeclared core register names in AArch32 state on page A1-34
C2.62 MRS (PSR to general-purpose register) on page C2-204

C2.65 MSR (general-purpose register to PSR) on page C2-208

# A1.8 Predeclared core register names in AArch32 state

Many of the core register names have synonyms.

The following table shows the predeclared core registers:

#### Table A1-2 Predeclared core registers in AArch32 state

Register names	Meaning
r0-r15 and R0-R15	General purpose registers.
a1-a4	Argument, result or scratch registers. These are synonyms for R0 to R3.
v1-v8	Variable registers. These are synonyms for R4 to R11.
SB	Static base register. This is a synonym for R9.
IP	Intra-procedure call scratch register. This is a synonym for R12.
SP	Stack pointer. This is a synonym for R13.
LR	Link register. This is a synonym for R14.
PC	Program counter. This is a synonym for R15.

With the exception of a1-a4 and v1-v8, you can write the register names either in all upper case or all lower case.

## **Related concepts**

A1.6 General-purpose registers in AArch32 state on page A1-32

# A1.9 Predeclared extension register names in AArch32 state

You can write the names of Advanced SIMD and floating-point registers either in upper case or lower case.

The following table shows the predeclared extension register names:

Register names	Meaning
Q0-Q15	Advanced SIMD quadword registers
D0-D31	Advanced SIMD doubleword registers, floating-point double-precision registers
S0-S31	Floating-point single-precision registers

#### Table A1-3 Predeclared extension registers in AArch32 state

You can write the register names either in upper case or lower case.

## A1.10 Program Counter in AArch32 state

You can use the Program Counter explicitly, for example in some T32 data processing instructions, and implicitly, for example in branch instructions.

The *Program Counter* (PC) is accessed as PC (or R15). It is incremented by the size of the instruction executed, which is always four bytes in A32 state. Branch instructions load the destination address into the PC. You can also load the PC directly using data operation instructions. For example, to branch to the address in a general purpose register, use:

MOV PC,RØ

During execution, the PC does not contain the address of the currently executing instruction. The address of the currently executing instruction is typically PC-8 for A32, or PC-4 for T32.

—— Note —

Arm recommends you use the BX instruction to jump to an address or to return from a function, rather than writing to the PC directly.

#### **Related references**

*C2.14 B* on page C2-132 *C2.21 BX, BXNS* on page C2-142 *C2.23 CBZ and CBNZ* on page C2-145 *C2.154 TBB and TBH* on page C2-333
## A1.11 The Q flag in AArch32 state

The Q flag indicates overflow or saturation. It is one of the program status flags held in the APSR.

The Q flag is set to 1 when saturation occurs in saturating arithmetic instructions, or when overflow occurs in certain multiply instructions.

The Q flag is a *sticky* flag. Although the saturating and certain multiply instructions can set the flag, they cannot clear it. You can execute a series of such instructions, and then test the flag to find out whether saturation or overflow occurred at any point in the series, without having to check the flag after each instruction.

To clear the Q flag, use an MSR instruction to read-modify-write the APSR:

```
MRS r5, APSR
BIC r5, r5, #(1<<27)
MSR APSR_nzcvq, r5
```

The state of the Q flag cannot be tested directly by the condition codes. To read the state of the Q flag, use an MRS instruction.

MRS r6, APSR TST r6, #(1<<27); Z is clear if Q flag was set

#### **Related references**

C2.62 MRS (PSR to general-purpose register) on page C2-204 C2.65 MSR (general-purpose register to PSR) on page C2-208 C2.75 QADD on page C2-223 C2.125 SMULxy on page C2-285 C2.127 SMULWy on page C2-287

## A1.12 Application Program Status Register

The Application Program Status Register (APSR) holds the program status flags that are accessible in any processor mode.

It holds copies of the N, Z, C, and V *condition flags*. The processor uses them to determine whether or not to execute conditional instructions.

The APSR also holds:

- The Q (saturation) flag.
- The APSR also holds the GE (Greater than or Equal) flags. The GE flags can be set by the parallel add and subtract instructions. They are used by the SEL instruction to perform byte-based selection from two registers.

These flags are accessible in all modes, using the MSR and MRS instructions.

#### **Related concepts**

C1.1 Conditional instructions on page C1-84 **Related references** C1.5 Updates to the condition flags in A32/T32 code on page C1-88 C2.62 MRS (PSR to general-purpose register) on page C2-204 C2.65 MSR (general-purpose register to PSR) on page C2-208 C2.100 SEL on page C2-257

## A1.13 Current Program Status Register in AArch32 state

The *Current Program Status Register* (CPSR) holds the same program status flags as the APSR, and some additional information.

It holds:

- The APSR flags.
- The processor mode.
- The interrupt disable flags.
- The instruction set state (A32 or T32).
- The endianness state.
- The execution state bits for the IT block.

The execution state bits control conditional execution in the IT block.

Only the APSR flags are accessible in all modes. Arm deprecates using an MSR instruction to change the endianness bit (E) of the CPSR, in any mode. Each exception level can have its own endianness, but mixed endianness within an exception level is deprecated.

The SETEND instruction is deprecated.

The execution state bits for the IT block (IT[1:0]) and the T32 bit (T) can be accessed by MRS only in Debug state.

#### **Related concepts**

A1.14 Saved Program Status Registers in AArch32 state on page A1-40 **Related references** C2.41 IT on page C2-169 C2.62 MRS (PSR to general-purpose register) on page C2-204 C2.65 MSR (general-purpose register to PSR) on page C2-208 C2.101 SETEND on page C2-259 C1.5 Updates to the condition flags in A32/T32 code on page C1-88

## A1.14 Saved Program Status Registers in AArch32 state

The *Saved Program Status Register* (SPSR) stores the current value of the CPSR when an exception is taken so that it can be restored after handling the exception.

Each exception handling mode can access its own SPSR. User mode and System mode do not have an SPSR because they are not exception handling modes.

The execution state bits, including the endianness state and current instruction set state can be accessed from the SPSR in any exception mode, using the MSR and MRS instructions. You cannot access the SPSR using MSR or MRS in User or System mode.

#### **Related concepts**

A1.13 Current Program Status Register in AArch32 state on page A1-39

## A1.15 A32 and T32 instruction set overview

A32 and T32 instructions can be grouped by functional area.

All A32 instructions are 32 bits long. Instructions are stored word-aligned, so the least significant two bits of instruction addresses are always zero in A32 state.

T32 instructions are either 16 or 32 bits long. Instructions are stored half-word aligned. Some instructions use the least significant bit of the address to determine whether the code being branched to is T32 or A32.

Before the introduction of 32-bit T32 instructions, the T32 instruction set was limited to a restricted subset of the functionality of the A32 instruction set. Almost all T32 instructions were 16-bit. Together, the 32-bit and 16-bit T32 instructions provide functionality that is almost identical to that of the A32 instruction set.

The following table describes some of the functional groupings of the available instructions.

#### Table A1-4 A32 instruction groups

Instruction group	Description
Branch and control	<ul> <li>These instructions do the following:</li> <li>Branch to subroutines.</li> <li>Branch backwards to form loops.</li> <li>Branch forward in conditional structures.</li> <li>Make the following instruction conditional without branching.</li> <li>Change the processor between A32 state and T32 state.</li> </ul>
Data processing	These instructions operate on the general-purpose registers. They can perform operations such as addition, subtraction, or bitwise logic on the contents of two registers and place the result in a third register. They can also operate on the value in a single register, or on a value in a register and an immediate value supplied within the instruction. Long multiply instructions give a 64-bit result in two registers.
Register load and store	These instructions load or store the value of a single register from or to memory. They can load or store a 32- bit word, a 16-bit halfword, or an 8-bit unsigned byte. Byte and halfword loads can either be sign extended or zero extended to fill the 32-bit register. A few instructions are also defined that can load or store 64-bit doubleword values into two 32-bit registers.
Multiple register load and store	These instructions load or store any subset of the general-purpose registers from or to memory.
Status register access	These instructions move the contents of a status register to or from a general-purpose register.

## A1.16 Access to the inline barrel shifter in AArch32 state

The AArch32 arithmetic logic unit has a 32-bit barrel shifter that is capable of shift and rotate operations.

The second operand to many A32 and T32 data-processing and single register data-transfer instructions can be shifted, before the data-processing or data-transfer is executed, as part of the instruction. This supports, but is not limited to:

- Scaled addressing.
- Multiplication by an immediate value.
- Constructing immediate values.

32-bit T32 instructions give almost the same access to the barrel shifter as A32 instructions.

16-bit T32 instructions only allow access to the barrel shifter using separate instructions.

# Part B Advanced SIMD and Floating-point Programming

## Chapter B1 Advanced SIMD Programming

#### Describes Advanced SIMD assembly language programming.

It contains the following sections:

- B1.1 Architecture support for Advanced SIMD on page B1-46.
- B1.2 Extension register bank mapping for Advanced SIMD in AArch32 state on page B1-47.
- B1.3 Views of the Advanced SIMD register bank in AArch32 state on page B1-49.
- B1.4 Load values to Advanced SIMD registers on page B1-50.
- B1.5 Conditional execution of A32/T32 Advanced SIMD instructions on page B1-51.
- B1.6 Floating-point exceptions for Advanced SIMD in A32/T32 instructions on page B1-52.
- B1.7 Advanced SIMD data types in A32/T32 instructions on page B1-53.
- *B1.8 Polynomial arithmetic over {0,1}* on page B1-54.
- B1.9 Advanced SIMD vectors on page B1-55.
- B1.10 Normal, long, wide, and narrow Advanced SIMD instructions on page B1-56.
- B1.11 Saturating Advanced SIMD instructions on page B1-57.
- B1.12 Advanced SIMD scalars on page B1-58.
- B1.13 Extended notation extension for Advanced SIMD on page B1-59.
- B1.14 Advanced SIMD system registers in AArch32 state on page B1-60.
- B1.15 Flush-to-zero mode in Advanced SIMD on page B1-61.
- *B1.16 When to use flush-to-zero mode in Advanced SIMD* on page B1-62.
- B1.17 The effects of using flush-to-zero mode in Advanced SIMD on page B1-63.
- B1.18 Advanced SIMD operations not affected by flush-to-zero mode on page B1-64.

## B1.1 Architecture support for Advanced SIMD

Advanced SIMD is an optional extension to the Armv7 architecture.

All Advanced SIMD instructions are available on systems that support Advanced SIMD. Some of these instructions are also available on systems that implement the floating-point extension without Advanced SIMD. These are called shared instructions.

The Advanced SIMD register bank consists of thirty-two 64-bit registers, and smaller registers are packed into larger ones.

\_\_\_\_\_ Note \_\_\_\_\_

Advanced SIMD and floating-point instructions share the same extension register bank.

**Related information** Floating-point support

## B1.2 Extension register bank mapping for Advanced SIMD in AArch32 state

The Advanced SIMD extension register bank is a collection of registers that can be accessed as either 64bit or 128-bit registers.

Advanced SIMD and floating-point instructions use the same extension register bank, and is distinct from the Arm core register bank.

The following figure shows the views of the extension register bank, and the overlap between the different size registers. For example, the 128-bit register Q0 is an alias for two consecutive 64-bit registers D0 and D1. The 128-bit register Q8 is an alias for 2 consecutive 64-bit registers D16 and D17.





——— Note —

If your processor supports both Advanced SIMD and floating-point, all the Advanced SIMD registers overlap with the floating-point registers.

The aliased views enable half-precision, single-precision, and double-precision values, and Advanced SIMD vectors to coexist in different non-overlapped registers at the same time.

You can also use the same overlapped registers to store half-precision, single-precision, and doubleprecision values, and Advanced SIMD vectors at different times. Do not attempt to use overlapped 64-bit and 128-bit registers at the same time because it creates meaningless results.

The mapping between the registers is as follows:

- D<2n> maps to the least significant half of Q<n>
- D<2n+1> maps to the most significant half of Q<n>.

For example, you can access the least significant half of the elements of a vector in Q6 by referring to D12, and the most significant half of the elements by referring to D13.

#### **Related concepts**

*B2.3 Views of the floating-point extension register bank in AArch32 state* on page B2-69 *B1.3 Views of the Advanced SIMD register bank in AArch32 state* on page B1-49

## B1.3 Views of the Advanced SIMD register bank in AArch32 state

Advanced SIMD can have different views of the extension register bank in AArch32 state.

It can view the extension register bank as:

- Sixteen 128-bit registers, Q0-Q15.
- Thirty-two 64-bit registers, D0-D31.
- A combination of registers from these views.

Advanced SIMD views each register as containing a *vector* of 1, 2, 4, 8, or 16 elements, all of the same size and type. Individual elements can also be accessed as *scalars*.

In Advanced SIMD, the 64-bit registers are called doubleword registers and the 128-bit registers are called quadword registers.

#### **Related concepts**

*B1.2 Extension register bank mapping for Advanced SIMD in AArch32 state* on page B1-47 *B2.3 Views of the floating-point extension register bank in AArch32 state* on page B2-69

## B1.4 Load values to Advanced SIMD registers

To load a register with a floating-point immediate value, use VMOV instruction. This instruction has scalar and vector forms.

The Advanced SIMD instructions VMOV and VMVN can also load integer immediates.

#### **Related references**

*C3.57 VLDR pseudo-instruction* on page C3-452 *C4.22 VMOV (floating-point)* on page C4-569 *C3.68 VMOV (immediate)* on page C3-463

## B1.5 Conditional execution of A32/T32 Advanced SIMD instructions

Most Advanced SIMD instructions always execute unconditionally.

You cannot use any of the following Advanced SIMD instructions in an IT block:

- VCVT {A, N, P, M}.
- VMAXNM.
- VMINNM.
- VRINT{N, X, A, Z, M, P}.
- All instructions in the Crypto extension.

In addition, specifying any other Advanced SIMD instruction in an IT block is deprecated.

Arm deprecates conditionally executing any Advanced SIMD instruction unless it is a shared Advanced SIMD and floating-point instruction.

#### **Related concepts**

C1.2 Conditional execution in A32 code on page C1-85 C1.3 Conditional execution in T32 code on page C1-86 **Related references** 

*C1.11 Comparison of condition code meanings in integer and floating-point code* on page C1-94 *C1.9 Condition code suffixes* on page C1-92

## B1.6 Floating-point exceptions for Advanced SIMD in A32/T32 instructions

The Advanced SIMD extension records floating-point exceptions in the FPSCR cumulative flags.

It records the following exceptions:

#### **Invalid** operation

The exception is caused if the result of an operation has no mathematical value or cannot be represented.

#### Division by zero

The exception is caused if a divide operation has a zero divisor and a dividend that is not zero, an infinity or a NaN.

#### Overflow

The exception is caused if the absolute value of the result of an operation, produced after rounding, is greater than the maximum positive normalized number for the destination precision.

#### Underflow

The exception is caused if the absolute value of the result of an operation, produced before rounding, is less than the minimum positive normalized number for the destination precision, and the rounded result is inexact.

#### Inexact

The exception is caused if the result of an operation is not equivalent to the value that would be produced if the operation were performed with unbounded precision and exponent range.

#### Input denormal

The exception is caused if a denormalized input operand is replaced in the computation by a zero.

The descriptions of the Advanced SIMD instructions that can cause floating-point exceptions include a subsection listing the exceptions. If there is no such subsection, that instruction cannot cause any floating-point exception.

#### **Related concepts**

B1.15 Flush-to-zero mode in Advanced SIMD on page B1-61 Related references Chapter B1 Advanced SIMD Programming on page B1-45 Related information Arm Architecture Reference Manual

## B1.7 Advanced SIMD data types in A32/T32 instructions

Most Advanced SIMD instructions use a data type specifier to define the size and type of data that the instruction operates on.

Data type specifiers in Advanced SIMD instructions consist of a letter indicating the type of data, usually followed by a number indicating the width. They are separated from the instruction mnemonic by a point. The following table shows the data types available in Advanced SIMD instructions:

	8-bit	16-bit	32-bit	64-bit
Unsigned integer	U8	U16	U32	U64
Signed integer	S8	S16	\$32	S64
Integer of unspecified type	18	I16	132	164
Floating-point number	not available	F16	F32 (or F)	not available
Polynomial over {0,1}	P8	P16	not available	not available

Table B1-1 Advanced SIMD data types

The datatype of the second (or only) operand is specified in the instruction.

\_\_\_\_\_ Note \_\_\_\_

Most instructions have a restricted range of permitted data types. See the instruction descriptions for details. However, the data type description is flexible:

- If the description specifies I, you can also use the S or U data types.
- If only the data size is specified, you can specify a type (I, S, U, P or F).
- If no data type is specified, you can specify a data type.

#### **Related concepts**

*B1.7 Advanced SIMD data types in A32/T32 instructions* on page B1-53 *B1.8 Polynomial arithmetic over {0,1}* on page B1-54

## B1.8 Polynomial arithmetic over {0,1}

The coefficients 0 and 1 are manipulated using the rules of Boolean arithmetic.

The following rules apply:

- 0+0=1+1=0.
- 0+1=1+0=1.
- 0 \* 0 = 0 \* 1 = 1 \* 0 = 0.
- 1 \* 1 = 1.

That is, adding two polynomials over  $\{0,1\}$  is the same as a bitwise exclusive OR, and multiplying two polynomials over  $\{0,1\}$  is the same as integer multiplication except that partial products are exclusive-ORed instead of being added.

**Related concepts** 

B1.7 Advanced SIMD data types in A32/T32 instructions on page B1-53

## B1.9 Advanced SIMD vectors

An Advanced SIMD operand can be a vector or a scalar. An Advanced SIMD vector can be a 64-bit doubleword vector or a 128-bit quadword vector.

The size of the elements in an Advanced SIMD vector is specified by a datatype suffix appended to the mnemonic.

Doubleword vectors can contain:

- Eight 8-bit elements.
- Four 16-bit elements.
- Two 32-bit elements.
- One 64-bit element.

Quadword vectors can contain:

- Sixteen 8-bit elements.
- Eight 16-bit elements.
- Four 32-bit elements.
- Two 64-bit elements.

#### **Related concepts**

B1.12 Advanced SIMD scalars on page B1-58

B1.2 Extension register bank mapping for Advanced SIMD in AArch32 state on page B1-47

- B1.13 Extended notation extension for Advanced SIMD on page B1-59
- B1.7 Advanced SIMD data types in A32/T32 instructions on page B1-53

B1.10 Normal, long, wide, and narrow Advanced SIMD instructions on page B1-56

## B1.10 Normal, long, wide, and narrow Advanced SIMD instructions

Many Advanced SIMD data processing instructions are available in Normal, Long, Wide, Narrow, and saturating variants.

#### Normal operation

The operands can be any of the vector types. The result vector is the same width, and usually the same type, as the operand vectors, for example:

VADD.I16 D0, D1, D2

You can specify that the operands and result of a normal Advanced SIMD instruction must all be quadwords by appending a Q to the instruction mnemonic. If you do this, armasm produces an error if the operands or result are not quadwords.

#### Long operation

The operands are doubleword vectors and the result is a quadword vector. The elements of the result are usually twice the width of the elements of the operands, and the same type.

Long operation is specified using an L appended to the instruction mnemonic, for example:

VADDL.S16 Q0, D2, D3

#### Wide operation

One operand vector is doubleword and the other is quadword. The result vector is quadword. The elements of the result and the first operand are twice the width of the elements of the second operand.

Wide operation is specified using a W appended to the instruction mnemonic, for example:

VADDW.S16 Q0, Q1, D4

#### **Narrow operation**

The operands are quadword vectors and the result is a doubleword vector. The elements of the result are half the width of the elements of the operands.

Narrow operation is specified using an N appended to the instruction mnemonic, for example:

VADDHN.I16 D0, Q1, Q2

#### **Related concepts**

B1.9 Advanced SIMD vectors on page B1-55

## B1.11 Saturating Advanced SIMD instructions

Saturating instructions saturate the result to the value of the upper limit or lower limit if the result overflows or underflows.

The saturation limits depend on the datatype of the instruction. The following table shows the ranges that Advanced SIMD saturating instructions saturate to, where x is the result of the operation.

Data type	Saturation range of <i>x</i>		
Signed byte (S8)	$-2^7 \ll x < 2^7$		
Signed halfword (S16)	$-2^{15} \le x \le 2^{15}$		
Signed word (S32)	$-2^{31} \le x < 2^{31}$		
Signed doubleword (S64)	$-2^{63} \le x < 2^{63}$		
Unsigned byte (U8)	$0 \le x \le 2^8$		
Unsigned halfword (U16)	$0 \le x \le 2^{16}$		
Unsigned word (U32)	$0 \le x \le 2^{32}$		
Unsigned doubleword (U64)	$0 \le x \le 2^{64}$		

#### Table B1-2 Advanced SIMD saturation ranges

Saturating Advanced SIMD arithmetic instructions set the QC bit in the floating-point status register (FPSCR) to indicate that saturation has occurred.

Saturating instructions are specified using a Q prefix, which is inserted between the V and the instruction mnemonic.

#### **Related references**

C2.7 Saturating instructions on page C2-118

## B1.12 Advanced SIMD scalars

Some Advanced SIMD instructions act on scalars in combination with vectors. Advanced SIMD scalars can be 8-bit, 16-bit, 32-bit, or 64-bit.

The instruction syntax refers to a single element in a vector register using an index, x, into the vector, so that Dm[x] is the xth element in vector Dm.

Except for Advanced SIMD multiply instructions, instructions that access scalars can access any element in the register bank.

Advanced SIMD multiply instructions only allow 16-bit or 32-bit scalars, and can only access the first 32 scalars in the register bank.

In multiply instructions:

- 16-bit scalars are restricted to registers D0-D7, with x in the range 0-3.
- 32-bit scalars are restricted to registers D0-D15, with x either 0 or 1.

#### **Related concepts**

*B1.9 Advanced SIMD vectors* on page B1-55 *B1.2 Extension register bank mapping for Advanced SIMD in AArch32 state* on page B1-47

## B1.13 Extended notation extension for Advanced SIMD

armasm implements an extension to the architectural Advanced SIMD assembly syntax, called *extended notation*. This extension allows you to include datatype information or scalar indexes in register names.

If you use extended notation, you do not have to include the data type or scalar index information in every instruction.

Register names can be any of the following:

#### Untyped

The register name specifies the register, but not what datatype it contains, nor any index to a particular scalar within the register.

#### Untyped with scalar index

The register name specifies the register, but not what datatype it contains, It specifies an index to a particular scalar within the register.

#### Typed

The register name specifies the register, and what datatype it contains, but not any index to a particular scalar within the register.

#### Typed with scalar index

The register name specifies the register, what datatype it contains, and an index to a particular scalar within the register.

Use the DN and QN directives to define names for typed and scalar registers.

#### **Related concepts**

*B1.9 Advanced SIMD vectors* on page B1-55 *B1.7 Advanced SIMD data types in A32/T32 instructions* on page B1-53 *B1.12 Advanced SIMD scalars* on page B1-58

## B1.14 Advanced SIMD system registers in AArch32 state

Advanced SIMD system registers are accessible in all implementations of Advanced SIMD.

For exception levels using AArch32, the following Advanced SIMD system registers are accessible in all Advanced SIMD implementations:

- FPSCR, the floating-point status and control register.
- FPEXC, the floating-point exception register.
- FPSID, the floating-point system ID register.

A particular Advanced SIMD implementation can have additional registers. For more information, see the Technical Reference Manual for your processor.

— Note —

Advanced SIMD technology shares the same set of system registers as floating-point.

**Related information** Arm Architecture Reference Manual

### B1.15 Flush-to-zero mode in Advanced SIMD

Flush-to-zero mode replaces denormalized numbers with zero. This does not comply with IEEE 754 arithmetic, but in some circumstances can improve performance considerably.

Flush-to-zero mode in Advanced SIMD always preserves the sign bit.

Advanced SIMD always uses flush-to-zero mode.

**Related concepts** 

B1.17 The effects of using flush-to-zero mode in Advanced SIMD on page B1-63

**Related references** 

B1.16 When to use flush-to-zero mode in Advanced SIMD on page B1-62

B1.18 Advanced SIMD operations not affected by flush-to-zero mode on page B1-64

## B1.16 When to use flush-to-zero mode in Advanced SIMD

You can change between flush-to-zero mode and normal mode, depending on the requirements of different parts of your code.

You can change between flush-to-zero mode and normal mode, depending on the requirements of different parts of your code.

You must select flush-to-zero mode if all the following are true:

- IEEE 754 compliance is not a requirement for your system.
- The algorithms you are using sometimes generate denormalized numbers.
- Your system uses support code to handle denormalized numbers.
- The algorithms you are using do not depend for their accuracy on the preservation of denormalized numbers.
- The algorithms you are using do not generate frequent exceptions as a result of replacing denormalized numbers with 0.

You select flush-to-zero mode by setting the FZ bit in the FPSCR to 1. You do this using the VMRS and VMSR instructions.

You can change between flush-to-zero and normal mode at any time, if different parts of your code have different requirements. Numbers already in registers are not affected by changing mode.

#### **Related concepts**

*B1.15 Flush-to-zero mode in Advanced SIMD* on page B1-61 *B1.17 The effects of using flush-to-zero mode in Advanced SIMD* on page B1-63

## B1.17 The effects of using flush-to-zero mode in Advanced SIMD

In flush-to-zero mode, denormalized inputs are treated as zero. Results that are too small to be represented in a normalized number are replaced with zero.

With certain exceptions, flush-to-zero mode has the following effects on floating-point operations:

- A denormalized number is treated as 0 when used as an input to a floating-point operation. The source register is not altered.
- If the result of a single-precision floating-point operation, before rounding, is in the range  $-2^{-126}$  to  $+2^{-126}$ , it is replaced by 0.
- If the result of a double-precision floating-point operation, before rounding, is in the range  $-2^{-1022}$  to  $+2^{-1022}$ , it is replaced by 0.

In flush-to-zero mode, an Input Denormal exception occurs whenever a denormalized number is used as an operand. An Underflow exception occurs when a result is flushed-to-zero.

#### **Related concepts**

B1.15 Flush-to-zero mode in Advanced SIMD on page B1-61

**Related references** 

B1.18 Advanced SIMD operations not affected by flush-to-zero mode on page B1-64

## B1.18 Advanced SIMD operations not affected by flush-to-zero mode

Some Advanced SIMD instructions can be carried out on denormalized numbers even in flush-to-zero mode, without flushing the results to zero.

These instructions are as follows:

- Copy, absolute value, and negate (VMOV, VMVN, V{Q}ABS, and V{Q}NEG).
- Duplicate (VDUP).
- Swap (VSWP).
- Load and store (VLDR and VSTR).
- Load multiple and store multiple (VLDM and VSTM).
- Transfer between extension registers and AArch32 general-purpose registers (VMOV).

#### **Related concepts**

*B1.15 Flush-to-zero mode in Advanced SIMD* on page B1-61 *Related references C3.9 VABS* on page C3-401 *C4.2 VABS (floating-point)* on page C4-549 *C3.41 VDUP* on page C3-433 *C3.54 VLDM* on page C3-449

*C3.55 VLDR* on page C3-450

C3.69 VMOV (register) on page C3-464

C3.70 VMOV (between two general-purpose registers and a 64-bit extension register) on page C3-465

*C3.71 VMOV (between a general-purpose register and an Advanced SIMD scalar)* on page C3-466 *C3.139 VSWP* on page C3-536

## Chapter B2 Floating-point Programming

Describes floating-point assembly language programming.

It contains the following sections:

- *B2.1 Architecture support for floating-point* on page B2-66.
- B2.2 Extension register bank mapping for floating-point in AArch32 state on page B2-67.
- B2.3 Views of the floating-point extension register bank in AArch32 state on page B2-69.
- B2.4 Load values to floating-point registers on page B2-70.
- *B2.5 Conditional execution of A32/T32 floating-point instructions* on page B2-71.
- B2.6 Floating-point exceptions for floating-point in A32/T32 instructions on page B2-72.
- B2.7 Floating-point data types in A32/T32 instructions on page B2-73.
- B2.8 Extended notation extension for floating-point code on page B2-74.
- B2.9 Floating-point system registers in AArch32 state on page B2-75.
- B2.10 Flush-to-zero mode in floating-point on page B2-76.
- *B2.11 When to use flush-to-zero mode in floating-point* on page B2-77.
- *B2.12 The effects of using flush-to-zero mode in floating-point* on page B2-78.
- B2.13 Floating-point operations not affected by flush-to-zero mode on page B2-79.

## B2.1 Architecture support for floating-point

Floating-point is an optional extension to the Arm architecture. There are versions that provide additional instructions.

The floating-point instruction set is based on VFPv4, but with the addition of some new instructions, including the following:

- Floating-point round to integral.
- Conversion from floating-point to integer with a directed rounding mode.
- Direct conversion between half-precision and double-precision floating-point.
- Floating-point conditional select.

The register bank consists of thirty-two 64-bit registers, and smaller registers are packed into larger ones, as in Armv7 and earlier.

## B2.2 Extension register bank mapping for floating-point in AArch32 state

The floating-point extension register bank is a collection of registers that can be accessed as either 32-bit or 64-bit registers. It is distinct from the Arm core register bank.

The following figure shows the views of the extension register bank, and the overlap between the different size registers. For example, the 64-bit register D0 is an alias for two consecutive 32-bit registers S0 and S1. The 64-bit registers D16 and D17 do not have an alias.



#### Figure B2-1 Extension register bank for floating-point in AArch32 state

The aliased views enable half-precision, single-precision, and double-precision values to coexist in different non-overlapped registers at the same time.

You can also use the same overlapped registers to store half-precision, single-precision, and double-precision values at different times.

Do not attempt to use overlapped 32-bit and 64-bit registers at the same time because it creates meaningless results.

The mapping between the registers is as follows:

- S<2n> maps to the least significant half of D<n>
- S<2n+1> maps to the most significant half of D<n>

For example, you can access the least significant half of register D6 by referring to S12, and the most significant half of D6 by referring to S13.

**Related concepts** B2.3 Views of the floating-point extension register bank in AArch32 state on page B2-69

## B2.3 Views of the floating-point extension register bank in AArch32 state

Floating-point can have different views of the extension register bank in AArch32 state.

The floating-point extension register bank can be viewed as:

- Thirty-two 64-bit registers, D0-D31.
- Thirty-two 32-bit registers, S0-S31. Only half of the register bank is accessible in this view.
- A combination of registers from these views.

64-bit floating-point registers are called double-precision registers and can contain double-precision floating-point values. 32-bit floating-point registers are called single-precision registers and can contain either a single-precision or two half-precision floating-point values.

#### **Related concepts**

B2.2 Extension register bank mapping for floating-point in AArch32 state on page B2-67

## B2.4 Load values to floating-point registers

To load a register with a floating-point immediate value, use VMOV. This instruction has scalar and vector forms.

#### **Related references**

*VLDR pseudo-instruction (floating-point) C4.22 VMOV (floating-point)* on page C4-569

## B2.5 Conditional execution of A32/T32 floating-point instructions

You can execute floating-point instructions conditionally, in the same way as most A32 and T32 instructions.

You cannot use any of the following floating-point instructions in an IT block:

- VRINT{A, N, P, M}.
- VSEL.
- VCVT {A, N, P, M}.
- VMAXNM.
- VMINNM.

In addition, specifying any other floating-point instruction in an IT block is deprecated.

Most A32 floating-point instructions can be conditionally executed, by appending a condition code suffix to the instruction.

#### **Related concepts**

C1.2 Conditional execution in A32 code on page C1-85

C1.3 Conditional execution in T32 code on page C1-86

#### **Related references**

*C1.11 Comparison of condition code meanings in integer and floating-point code* on page C1-94 *C1.9 Condition code suffixes* on page C1-92

## B2.6 Floating-point exceptions for floating-point in A32/T32 instructions

The floating-point extension records floating-point exceptions in the FPSCR cumulative flags.

It records the following exceptions:

#### **Invalid** operation

The exception is caused if the result of an operation has no mathematical value or cannot be represented.

#### Division by zero

The exception is caused if a divide operation has a zero divisor and a dividend that is not zero, an infinity or a NaN.

#### Overflow

The exception is caused if the absolute value of the result of an operation, produced after rounding, is greater than the maximum positive normalized number for the destination precision.

#### Underflow

The exception is caused if the absolute value of the result of an operation, produced before rounding, is less than the minimum positive normalized number for the destination precision, and the rounded result is inexact.

#### Inexact

The exception is caused if the result of an operation is not equivalent to the value that would be produced if the operation were performed with unbounded precision and exponent range.

#### Input denormal

The exception is caused if a denormalized input operand is replaced in the computation by a zero.

The descriptions of the floating-point instructions that can cause floating-point exceptions include a subsection listing the exceptions. If there is no such subsection, that instruction cannot cause any floating-point exception.

#### **Related concepts**

*B2.10 Flush-to-zero mode in floating-point* on page B2-76 *Related references Chapter C4 Floating-point Instructions (32-bit)* on page C4-545 *Related information Arm Architecture Reference Manual*
## B2.7 Floating-point data types in A32/T32 instructions

Most floating-point instructions use a data type specifier to define the size and type of data that the instruction operates on.

Data type specifiers in floating-point instructions consist of a letter indicating the type of data, usually followed by a number indicating the width. They are separated from the instruction mnemonic by a point.

The following data types are available in floating-point instructions:

16-bit

F16

32-bit

F32 (or F)

**64-bit** F64 (or D)

The datatype of the second (or only) operand is specified in the instruction.

## \_\_\_\_\_ Note –

- Most instructions have a restricted range of permitted data types. See the instruction descriptions for details. However, the data type description is flexible:
  - If the description specifies I, you can also use the S or U data types.
  - If only the data size is specified, you can specify a type (S, U, P or F).
  - If no data type is specified, you can specify a data type.

## **Related concepts**

B1.8 Polynomial arithmetic over {0,1} on page B1-54

## B2.8 Extended notation extension for floating-point code

armasm implements an extension to the architectural floating-point assembly syntax, called *extended notation*. This extension allows you to include datatype information or scalar indexes in register names.

If you use extended notation, you do not have to include the data type or scalar index information in every instruction.

Register names can be any of the following:

#### Untyped

The register name specifies the register, but not what datatype it contains, nor any index to a particular scalar within the register.

#### Untyped with scalar index

The register name specifies the register, but not what datatype it contains, It specifies an index to a particular scalar within the register.

#### Typed

The register name specifies the register, and what datatype it contains, but not any index to a particular scalar within the register.

#### Typed with scalar index

The register name specifies the register, what datatype it contains, and an index to a particular scalar within the register.

Use the SN and DN directives to define names for typed and scalar registers.

#### **Related concepts**

B2.7 Floating-point data types in A32/T32 instructions on page B2-73

## B2.9 Floating-point system registers in AArch32 state

Floating-point system registers are accessible in all implementations of floating-point.

For exception levels using AArch32, the following floating-point system registers are accessible in all floating-point implementations:

- FPSCR, the floating-point status and control register.
- FPEXC, the floating-point exception register.
- FPSID, the floating-point system ID register.

A particular floating-point implementation can have additional registers. For more information, see the Technical Reference Manual for your processor.

#### **Related information**

Arm Architecture Reference Manual

## B2.10 Flush-to-zero mode in floating-point

Flush-to-zero mode replaces denormalized numbers with zero. This does not comply with IEEE 754 arithmetic, but in some circumstances can improve performance considerably.

Some implementations of floating-point use support code to handle denormalized numbers. The performance of such systems, in calculations involving denormalized numbers, is much less than it is in normal calculations.

Flush-to-zero mode in floating-point always preserves the sign bit.

#### **Related concepts**

B2.12 The effects of using flush-to-zero mode in floating-point on page B2-78
Related references
B2.11 When to use flush-to-zero mode in floating-point on page B2-77
B2.13 Floating-point operations not affected by flush-to-zero mode on page B2-79

## B2.11 When to use flush-to-zero mode in floating-point

You can change between flush-to-zero mode and normal mode, depending on the requirements of different parts of your code.

You can change between flush-to-zero mode and normal mode, depending on the requirements of different parts of your code.

You must select flush-to-zero mode if all the following are true:

- IEEE 754 compliance is not a requirement for your system.
- The algorithms you are using sometimes generate denormalized numbers.
- Your system uses support code to handle denormalized numbers.
- The algorithms you are using do not depend for their accuracy on the preservation of denormalized numbers.
- The algorithms you are using do not generate frequent exceptions as a result of replacing denormalized numbers with 0.

You select flush-to-zero mode by setting the FZ bit in the FPSCR to 1. You do this using the VMRS and VMSR instructions.

You can change between flush-to-zero and normal mode at any time, if different parts of your code have different requirements. Numbers already in registers are not affected by changing mode.

#### **Related concepts**

*B2.10 Flush-to-zero mode in floating-point* on page B2-76 *B2.12 The effects of using flush-to-zero mode in floating-point* on page B2-78

## B2.12 The effects of using flush-to-zero mode in floating-point

In flush-to-zero mode, denormalized inputs are treated as zero. Results that are too small to be represented in a normalized number are replaced with zero.

With certain exceptions, flush-to-zero mode has the following effects on floating-point operations:

- A denormalized number is treated as 0 when used as an input to a floating-point operation. The source register is not altered.
- If the result of a single-precision floating-point operation, before rounding, is in the range  $-2^{-126}$  to  $+2^{-126}$ , it is replaced by 0.
- If the result of a double-precision floating-point operation, before rounding, is in the range  $-2^{-1022}$  to  $+2^{-1022}$ , it is replaced by 0.

In flush-to-zero mode, an Input Denormal exception occurs whenever a denormalized number is used as an operand. An Underflow exception occurs when a result is flushed-to-zero.

## **Related concepts**

*B2.10 Flush-to-zero mode in floating-point* on page B2-76

**Related references** 

B2.13 Floating-point operations not affected by flush-to-zero mode on page B2-79

## B2.13 Floating-point operations not affected by flush-to-zero mode

Some floating-point instructions can be carried out on denormalized numbers even in flush-to-zero mode, without flushing the results to zero.

These instructions are as follows:

- Absolute value and negate (VABS and VNEG).
- Load and store (VLDR and VSTR).
- Load multiple and store multiple (VLDM and VSTM).
- Transfer between extension registers and general-purpose registers (VMOV).

#### **Related concepts**

B2.10 Flush-to-zero mode in floating-point on page B2-76

**Related references** 

C4.2 VABS (floating-point) on page C4-549

C4.14 VLDM (floating-point) on page C4-561

C4.15 VLDR (floating-point) on page C4-562

C4.38 VSTM (floating-point) on page C4-585

C4.39 VSTR (floating-point) on page C4-586

C3.54 VLDM on page C3-449

*C3.55 VLDR* on page C3-450

C3.131 VSTM on page C3-526

*C3.134 VSTR* on page C3-531

*C4.23 VMOV (between one general-purpose register and single precision floating-point register)* on page C4-570

*C3.70 VMOV (between two general-purpose registers and a 64-bit extension register)* on page C3-465 *C4.29 VNEG (floating-point)* on page C4-576

*C3.83 VNEG* on page C3-478

*B2 Floating-point Programming B2.13 Floating-point operations not affected by flush-to-zero mode* 

# Part C A32/T32 Instruction Set Reference

## Chapter C1 Condition Codes

Describes condition codes and conditional execution of A32 and T32 code.

It contains the following sections:

- C1.1 Conditional instructions on page C1-84.
- *C1.2 Conditional execution in A32 code* on page C1-85.
- C1.3 Conditional execution in T32 code on page C1-86.
- *C1.4 Condition flags* on page C1-87.
- *C1.5 Updates to the condition flags in A32/T32 code* on page C1-88.
- C1.6 Floating-point instructions that update the condition flags on page C1-89.
- *C1.7 Carry flag* on page C1-90.
- *C1.8 Overflow flag* on page C1-91.
- *C1.9 Condition code suffixes* on page C1-92.
- C1.10 Condition code suffixes and related flags on page C1-93.
- C1.11 Comparison of condition code meanings in integer and floating-point code on page C1-94.
- C1.12 Benefits of using conditional execution in A32 and T32 code on page C1-96.
- *C1.13 Example showing the benefits of conditional instructions in A32 and T32 code* on page C1-97.
- *C1.14 Optimization for execution speed* on page C1-100.

## C1.1 Conditional instructions

A32 and T32 instructions can execute conditionally on the condition flags set by a previous instruction.

The conditional instruction can occur either:

- Immediately after the instruction that updated the flags.
- After any number of intervening instructions that have not updated the flags.

In AArch32 state, whether an instruction can be conditional or not depends on the instruction set state that the processor is in.

To make an instruction conditional, you must add a condition code suffix to the instruction mnemonic. The condition code suffix enables the processor to test a condition based on the flags. If the condition test of a conditional instruction fails, the instruction:

- Does not execute.
- Does not write any value to its destination register.
- Does not affect any of the flags.
- Does not generate any exception.

#### **Related concepts**

*C1.2 Conditional execution in A32 code* on page C1-85 *C1.3 Conditional execution in T32 code* on page C1-86

#### **Related references**

*C1.10 Condition code suffixes and related flags* on page C1-93 *C1.5 Updates to the condition flags in A32/T32 code* on page C1-88

## C1.2 Conditional execution in A32 code

Almost all A32 instructions can be executed conditionally on the value of the condition flags in the APSR. You can either add a condition code suffix to the instruction or you can conditionally skip over the instruction using a conditional branch instruction.

Using conditional branch instructions to control the flow of execution can be more efficient when a series of instructions depend on the same condition.

#### Conditional instructions to control execution

```
; flags set by a previous instruction
LSLEQ r0, r0, #24
ADDEQ r0, r0, #2
;...
```

#### Conditional branch to control execution

```
; flags set by a previous instruction
BNE over
LSL r0, r0, #24
ADD r0, r0, #2
over
;...
```

#### **Related concepts**

C1.3 Conditional execution in T32 code on page C1-86

## C1.3 Conditional execution in T32 code

In T32 code, there are several ways to achieve conditional execution. You can conditionally skip over the instruction using a conditional branch instruction.

Instructions can also be conditionally executed by using either of the following:

- CBZ and CBNZ.
- The IT (If-Then) instruction.

The T32 CBZ (Conditional Branch on Zero) and CBNZ (Conditional Branch on Non-Zero) instructions compare the value of a register against zero and branch on the result.

IT is a 16-bit instruction that enables a single subsequent 16-bit T32 instruction from a restricted set to be conditionally executed, based on the value of the condition flags, and the condition code suffix specified.

## Conditional instructions using IT block

```
; flags set by a previous instruction
IT EQ
LSLEQ r0, r0, #24
:...
```

The use of the IT instruction is deprecated when any of the following are true:

- There is more than one instruction in the IT block.
- There is a 32-bit instruction in the IT block.
- The instruction in the IT block references the PC.

## **Related concepts**

C1.2 Conditional execution in A32 code on page C1-85 **Related references** C2.41 IT on page C2-169 C2.23 CBZ and CBNZ on page C2-145

## C1.4 Condition flags

The N, Z, C, and V condition flags are held in the APSR.

The condition flags are held in the APSR. They are set or cleared as follows:

N

Set to 1 when the result of the operation is negative, cleared to 0 otherwise.

Z

Set to 1 when the result of the operation is zero, cleared to 0 otherwise.

С

Set to 1 when the operation results in a carry, or when a subtraction results in no borrow, cleared to 0 otherwise.

V

Set to 1 when the operation causes overflow, cleared to 0 otherwise.

C is set in one of the following ways:

- For an addition, including the comparison instruction CMN, C is set to 1 if the addition produced a carry (that is, an unsigned overflow), and to 0 otherwise.
- For a subtraction, including the comparison instruction CMP, C is set to 0 if the subtraction produced a borrow (that is, an unsigned underflow), and to 1 otherwise.
- For non-addition/subtractions that incorporate a shift operation, C is set to the last bit shifted out of the value by the shifter.
- For other non-addition/subtractions, C is normally left unchanged, but see the individual instruction descriptions for any special cases.

Overflow occurs if the result of a signed add, subtract, or compare is greater than or equal to  $2^{31}$ , or less than  $-2^{31}$ .

## **Related references**

*C1.5 Updates to the condition flags in A32/T32 code* on page C1-88 *C1.10 Condition code suffixes and related flags* on page C1-93

## C1.5 Updates to the condition flags in A32/T32 code

In AArch32 state, the condition flags are held in the *Application Program Status Register* (APSR). You can read and modify the flags using the read-modify-write procedure.

Most A32 and T32 data processing instructions have an option to update the condition flags according to the result of the operation. Instructions with the optional S suffix update the flags. Conditional instructions that are not executed have no effect on the flags.

Which flags are updated depends on the instruction. Some instructions update all flags, and some update a subset of the flags. If a flag is not updated, the original value is preserved. The description of each instruction mentions the effect that it has on the flags.

— Note –

Most instructions update the condition flags only if the S suffix is specified. The instructions CMP, CMN, TEQ, and TST always update the flags.

## **Related concepts**

C1.1 Conditional instructions on page C1-84 **Related references** C1.4 Condition flags on page C1-87 C1.10 Condition code suffixes and related flags on page C1-93 Chapter C2 A32 and T32 Instructions on page C2-101

## C1.6 Floating-point instructions that update the condition flags

The only A32/T32 floating-point instructions that can update the condition flags are VCMP and VCMPE. Other floating-point or Advanced SIMD instructions cannot modify the flags.

VCMP and VCMPE do not update the flags directly, but update a separate set of flags in the *Floating-Point Status and Control Register* (FPSCR). To use these flags to control conditional instructions, including conditional floating-point instructions, you must first update the condition flags yourself. To do this, copy the flags from the FPSCR into the APSR using a VMRS instruction:

VMRS APSR\_nzcv, FPSCR

Related conceptsC1.7 Carry flag on page C1-90C1.8 Overflow flag on page C1-91Related referencesC4.4 VCMP, VCMPE on page C4-551C3.75 VMRS on page C3-470C4.26 VMRS (floating-point) on page C4-573Related informationArm Architecture Reference Manual

## C1.7 Carry flag

The carry (C) flag is set when an operation results in a carry, or when a subtraction results in no borrow.

In A32/T32 code, C is set in one of the following ways:

- For an addition, including the comparison instruction CMN, C is set to 1 if the addition produced a carry (that is, an unsigned overflow), and to 0 otherwise.
- For a subtraction, including the comparison instruction CMP, C is set to 0 if the subtraction produced a borrow (that is, an unsigned underflow), and to 1 otherwise.
- For non-additions/subtractions that incorporate a shift operation, C is set to the last bit shifted out of the value by the shifter.
- For other non-additions/subtractions, C is normally left unchanged, but see the individual instruction descriptions for any special cases.
- The floating-point compare instructions, VCMP and VCMPE set the C flag and the other condition flags in the FPSCR to the result of the comparison.

## **Related concepts**

C1.8 Overflow flag on page C1-91

## **Related references**

A1.8 Predeclared core register names in AArch32 state on page A1-34 C1.10 Condition code suffixes and related flags on page C1-93 C1.5 Updates to the condition flags in A32/T32 code on page C1-88

## C1.8 Overflow flag

Overflow can occur for add, subtract, and compare operations.

In A32/T32 code, overflow occurs if the result of the operation is greater than or equal to  $2^{31}$ , or less than  $-2^{31}$ .

## **Related concepts**

C1.7 Carry flag on page C1-90

## **Related references**

A1.8 Predeclared core register names in AArch32 state on page A1-34

C1.5 Updates to the condition flags in A32/T32 code on page C1-88

## C1.9 Condition code suffixes

Instructions that can be conditional have an optional two character condition code suffix.

Condition codes are shown in syntax descriptions as {*cond*}. The following table shows the condition codes that you can use:

Suffix	Meaning
EQ	Equal
NE	Not equal
CS	Carry set (identical to HS)
HS	Unsigned higher or same (identical to CS)
сс	Carry clear (identical to LO)
LO	Unsigned lower (identical to CC)
MI	Minus or negative result
PL	Positive or zero result
VS	Overflow
VC	No overflow
HI	Unsigned higher
LS	Unsigned lower or same
GE	Signed greater than or equal
LT	Signed less than
GT	Signed greater than
LE	Signed less than or equal
AL	Always (this is the default)

#### Table C1-1 Condition code suffixes

The meaning of some of these condition codes depends on whether the instruction that last updated the condition flags is a floating-point or integer instruction.

#### **Related references**

- Note -

*C1.11 Comparison of condition code meanings in integer and floating-point code* on page C1-94 *C2.41 IT* on page C2-169 *C3.75 VMRS* on page C3-470

C4.26 VMRS (floating-point) on page C4-573

## C1.10 Condition code suffixes and related flags

Condition code suffixes define the conditions that must be met for the instruction to execute.

The following table shows the condition codes that you can use and the flag settings they depend on:

Suffix	Flags	Meaning
EQ	Z set	Equal
NE	Z clear	Not equal
CS or HS	C set	Higher or same (unsigned >= )
CC or LO	C clear	Lower (unsigned < )
MI	N set	Negative
PL	N clear	Positive or zero
VS	V set	Overflow
VC	V clear	No overflow
HI	C set and Z clear	Higher (unsigned >)
LS	C clear or Z set	Lower or same (unsigned <=)
GE	N and V the same	Signed >=
LT	N and V differ	Signed <
GT	Z clear, N and V the same	Signed >
LE	Z set, N and V differ	Signed <=
AL	Any	Always. This suffix is normally omitted.

The optional condition code is shown in syntax descriptions as {*cond*}. This condition is encoded in A32 instructions. For T32 instructions, the condition is encoded in a preceding IT instruction. An instruction with a condition code is only executed if the condition flags meet the specified condition.

The following is an example of conditional execution in A32 code:

ADD r0, r1, r2 ADDS r0, r1, r2	; $r0 = r1 + r2$ , don't update flags : $r0 = r1 + r2$ , and update flags
ADDSCS r0, r1, r2	; If C flag set then $r0 = r1 + r2$ ,
CMP r0, r1	; update flags based on r0-r1.

## **Related concepts**

C1.1 Conditional instructions on page C1-84

**Related references** 

C1.4 Condition flags on page C1-87

C1.11 Comparison of condition code meanings in integer and floating-point code on page C1-94 C1.5 Updates to the condition flags in A32/T32 code on page C1-88 Chapter C2 A32 and T32 Instructions on page C2-101

## C1.11 Comparison of condition code meanings in integer and floating-point code

The meaning of the condition code mnemonic suffixes depends on whether the condition flags were set by a floating-point instruction or by an A32 or T32 data processing instruction.

This is because:

- Floating-point values are never unsigned, so the unsigned conditions are not required.
- Not-a-Number (NaN) values have no ordering relationship with numbers or with each other, so additional conditions are required to account for unordered results.

The meaning of the condition code mnemonic suffixes is shown in the following table:

#### Table C1-3 Condition codes

Suffix	Meaning after integer data processing instruction	Meaning after floating-point instruction
EQ	Equal	Equal
NE	Not equal	Not equal, or unordered
CS	Carry set	Greater than or equal, or unordered
HS	Unsigned higher or same	Greater than or equal, or unordered
СС	Carry clear	Less than
LO	Unsigned lower	Less than
MI	Negative	Less than
PL	Positive or zero	Greater than or equal, or unordered
VS	Overflow	Unordered (at least one NaN operand)
VC	No overflow	Not unordered
HI	Unsigned higher	Greater than, or unordered
LS	Unsigned lower or same	Less than or equal
GE	Signed greater than or equal	Greater than or equal
LT	Signed less than	Less than, or unordered
GT	Signed greater than	Greater than
LE	Signed less than or equal	Less than or equal, or unordered
AL	Always (normally omitted)	Always (normally omitted)

— Note —

The type of the instruction that last updated the condition flags determines the meaning of the condition codes.

Related concepts C1.1 Conditional instructions on page C1-84 Related references C1.10 Condition code suffixes and related flags on page C1-93 C1.5 Updates to the condition flags in A32/T32 code on page C1-88 C4.4 VCMP, VCMPE on page C4-551 C3.75 VMRS on page C3-470 C4.26 VMRS (floating-point) on page C4-573 **Related information** Arm Architecture Reference Manual

## C1.12 Benefits of using conditional execution in A32 and T32 code

It can be more efficient to use conditional instructions rather than conditional branches.

You can use conditional execution of A32 instructions to reduce the number of branch instructions in your code, and improve code density. The IT instruction in T32 achieves a similar improvement.

Branch instructions are also expensive in processor cycles. On Arm processors without branch prediction hardware, it typically takes three processor cycles to refill the processor pipeline each time a branch is taken.

Some Arm processors have branch prediction hardware. In systems using these processors, the pipeline only has to be flushed and refilled when there is a misprediction.

## **Related concepts**

C1.13 Example showing the benefits of conditional instructions in A32 and T32 code on page C1-97

# C1.13 Example showing the benefits of conditional instructions in A32 and T32 code

Using conditional instructions rather than conditional branches can save both code size and cycles.

This example shows the difference between using branches and using conditional instructions. It uses the Euclid algorithm for the *Greatest Common Divisor* (gcd) to show how conditional instructions improve code size and speed.

In C the gcd algorithm can be expressed as:

The following examples show implementations of the gcd algorithm with and without conditional instructions.

## Example of conditional execution using branches in A32 code

This example is an A32 code implementation of the gcd algorithm. It achieves conditional execution by using conditional branches, rather than individual conditional instructions:

gcd	CMP BEQ BLT	r0, r1 end less		
less	SUBS B	r0, r0, r1 gcd	; could be SUB r0, r0, r1 for A32	
end	SUBS B	r1, r1, r0 gcd	; could be SUB r1, r1, r0 for A32	

The code is seven instructions long because of the number of branches. Every time a branch is taken, the processor must refill the pipeline and continue from the new location. The other instructions and non-executed branches use a single cycle each.

The following table shows the number of cycles this implementation uses on an Arm7<sup>™</sup> processor when R0 equals 1 and R1 equals 2.

## Table C1-4 Conditional branches only

R0: a	R1: b	Instruction	Cycles (Arm7)
1	2	CMP r0, r1	1
1	2	BEQ end	1 (not executed)
1	2	BLT less	3
1	2	SUB r1, r1, r0	1
1	2	B gcd	3
1	1	CMP r0, r1	1
1	1	BEQ end	3
			Total = 13

#### Example of conditional execution using conditional instructions in A32 code

This example is an A32 code implementation of the gcd algorithm using individual conditional instructions in A32 code. The gcd algorithm only takes four instructions:

gcd

```
CMP
         r0, r1
SUBGT
         r0, r0, r1
SUBLE
         r1, r1, r0
BNE
         gcd
```

In addition to improving code size, in most cases this code executes faster than the version that uses only branches.

The following table shows the number of cycles this implementation uses on an Arm7 processor when R0 equals 1 and R1 equals 2.

R0: a	R1: b	Instruction	Cycles (Arm7)
1	2	CMP r0, r1	1
1	2	SUBGT r0,r0,r1	1 (not executed)
1	1	SUBLT r1,r1,r0	1
1	1	BNE gcd	3
1	1	CMP r0,r1	1
1	1	SUBGT r0,r0,r1	1 (not executed)
1	1	SUBLT r1,r1,r0	1 (not executed)
1	1	BNE gcd	1 (not executed)
			Total = 10

#### Table C1-5 All instructions conditional

Comparing this with the example that uses only branches:

- Replacing branches with conditional execution of all instructions saves three cycles.
- Where R0 equals R1, both implementations execute in the same number of cycles. For all other cases, the implementation that uses conditional instructions executes in fewer cycles than the implementation that uses branches only.

#### Example of conditional execution using conditional instructions in T32 code

You can use the IT instruction to write conditional instructions in T32 code. The T32 code implementation of the gcd algorithm using conditional instructions is similar to the implementation in A32 code. The implementation in T32 code is:

gcd CMP r0, r1 ITE GT SUBGT r0, r0, r1 SUBLE r1, r1, r0 BNE gcd

These instructions assemble equally well to A32 or T32 code. The assembler checks the IT instructions, but omits them on assembly to A32 code.

It requires one more instruction in T32 code (the IT instruction) than in A32 code, but the overall code size is 10 bytes in T32 code, compared with 16 bytes in A32 code.

#### Example of conditional execution code using branches in T32 code

In architectures before Armv6T2, there is no IT instruction and therefore T32 instructions cannot be executed conditionally except for the B branch instruction. The gcd algorithm must be written with

conditional branches and is similar to the A32 code implementation using branches, without conditional instructions.

The T32 code implementation of the gcd algorithm without conditional instructions requires seven instructions. The overall code size is 14 bytes. This figure is even less than the A32 implementation that uses conditional instructions, which uses 16 bytes.

In addition, on a system using 16-bit memory this T32 implementation runs faster than both A32 implementations because only one memory access is required for each 16-bit T32 instruction, whereas each 32-bit A32 instruction requires two fetches.

## **Related concepts**

C1.12 Benefits of using conditional execution in A32 and T32 code on page C1-96 C1.14 Optimization for execution speed on page C1-100 **Related references** C2.41 IT on page C2-169 C1.10 Condition code suffixes and related flags on page C1-93 **Related information** Arm Architecture Reference Manual

## C1.14 Optimization for execution speed

To optimize code for execution speed you must have detailed knowledge of the instruction timings, branch prediction logic, and cache behavior of your target system.

For more information, see the Technical Reference Manual for your processor.

**Related information** Arm Architecture Reference Manual Further reading

# Chapter C2 A32 and T32 Instructions

Describes the A32 and T32 instructions supported in AArch32 state.

It contains the following sections:

- C2.1 A32 and T32 instruction summary on page C2-106.
- C2.2 Instruction width specifiers on page C2-111.
- *C2.3 Flexible second operand (Operand2)* on page C2-112.
- C2.4 Syntax of Operand2 as a constant on page C2-113.
- *C2.5 Syntax of Operand2 as a register with optional shift* on page C2-114.
- C2.6 Shift operations on page C2-115.
- *C2.7 Saturating instructions* on page C2-118.
- *C2.8 ADC* on page C2-119.
- *C2.9 ADD* on page C2-121.
- C2.10 ADR (PC-relative) on page C2-124.
- C2.11 ADR (register-relative) on page C2-126.
- *C2.12 AND* on page C2-128.
- C2.13 ASR on page C2-130.
- *C2.14 B* on page C2-132.
- *C2.15 BFC* on page C2-134.
- *C2.16 BFI* on page C2-135.
- C2.17 BIC on page C2-136.
- *C2.18 BKPT* on page C2-138.
- *C2.19 BL* on page C2-139.
- *C2.20 BLX, BLXNS* on page C2-140.
- *C2.21 BX, BXNS* on page C2-142.
- C2.22 BXJ on page C2-144.
- C2.23 CBZ and CBNZ on page C2-145.

- C2.24 CDP and CDP2 on page C2-146.
- *C2.25 CLREX* on page C2-147.
- *C2.26 CLZ* on page C2-148.
- *C2.27 CMP and CMN* on page C2-149.
- *C2.28 CPS* on page C2-151.
- C2.29 CRC32 on page C2-153.
- C2.30 CRC32C on page C2-154.
- C2.31 CSDB on page C2-155.
- *C2.32 DBG* on page C2-157.
- C2.33 DMB on page C2-158.
- C2.34 DSB on page C2-160.
- *C2.35 EOR* on page C2-162.
- *C2.36 ERET* on page C2-164.
- *C2.37 ESB* on page C2-165.
- *C2.38 HLT* on page C2-166.
- *C2.39 HVC* on page C2-167.
- *C2.40 ISB* on page C2-168.
- C2.41 IT on page C2-169.
- *C2.42 LDA* on page C2-172.
- *C2.43 LDAEX* on page C2-173.
- *C2.44 LDC and LDC2* on page C2-175.
- *C2.45 LDM* on page C2-177.
- C2.46 LDR (immediate offset) on page C2-179.
- C2.47 LDR (PC-relative) on page C2-181.
- *C2.48 LDR (register offset)* on page C2-183.
- C2.49 LDR (register-relative) on page C2-185.
- *C2.50 LDR, unprivileged* on page C2-187.
- *C2.51 LDREX* on page C2-189.
- *C2.52 LSL* on page C2-191.
- C2.53 LSR on page C2-193.
- C2.54 MCR and MCR2 on page C2-195.
- C2.55 MCRR and MCRR2 on page C2-196.
- *C2.56 MLA* on page C2-197.
- *C2.57 MLS* on page C2-198.
- *C2.58 MOV* on page C2-199.
- *C2.59 MOVT* on page C2-201.
- C2.60 MRC and MRC2 on page C2-202.
- C2.61 MRRC and MRRC2 on page C2-203.
- C2.62 MRS (PSR to general-purpose register) on page C2-204.
- C2.63 MRS (system coprocessor register to general-purpose register) on page C2-206.
- C2.64 MSR (general-purpose register to system coprocessor register) on page C2-207.
- C2.65 MSR (general-purpose register to PSR) on page C2-208.
- *C2.66 MUL* on page C2-210.
- *C2.67 MVN* on page C2-211.
- *C2.68 NOP* on page C2-213.
- C2.69 ORN (T32 only) on page C2-214.
- C2.70 ORR on page C2-215.
- C2.71 PKHBT and PKHTB on page C2-217.
- C2.72 PLD, PLDW, and PLI on page C2-219.
- *C2.73 POP* on page C2-221.
- *C2.74 PUSH* on page C2-222.
- C2.75 QADD on page C2-223.
- *C2.76 QADD8* on page C2-224.
- C2.77 QADD16 on page C2-225.
- *C2.78 QASX* on page C2-226.
- *C2.79 QDADD* on page C2-227.

- *C2.80 QDSUB* on page C2-228.
- *C2.81 QSAX* on page C2-229.
- *C2.82 QSUB* on page C2-230.
- *C2.83 QSUB8* on page C2-231.
- C2.84 QSUB16 on page C2-232.
- *C2.85 RBIT* on page C2-233.
- *C2.86 REV* on page C2-234.
- C2.87 REV16 on page C2-235.
- C2.88 REVSH on page C2-236.
- *C2.89 RFE* on page C2-237.
- *C2.90 ROR* on page C2-239.
- *C2.91 RRX* on page C2-241.
- *C2.92 RSB* on page C2-243.
- *C2.93 RSC* on page C2-245.
- *C2.94 SADD8* on page C2-247.
- *C2.95 SADD16* on page C2-249.
- *C2.96 SASX* on page C2-251.
- *C2.97 SBC* on page C2-253.
- *C2.98 SBFX* on page C2-255.
- *C2.99 SDIV* on page C2-256.
- *C2.100 SEL* on page C2-257.
- C2.101 SETEND on page C2-259.
- C2.102 SETPAN on page C2-260.
- C2.103 SEV on page C2-261.
- *C2.104 SEVL* on page C2-262.
- *C2.105 SG* on page C2-263.
- C2.106 SHADD8 on page C2-264.
- *C2.107 SHADD16* on page C2-265.
- *C2.108 SHASX* on page C2-266.
- *C2.109 SHSAX* on page C2-267.
- C2.110 SHSUB8 on page C2-268.
- C2.111 SHSUB16 on page C2-269.
- *C2.112 SMC* on page C2-270.
- *C2.113 SMLAxy* on page C2-271.
- *C2.114 SMLAD* on page C2-273.
- *C2.115 SMLAL* on page C2-274.
- C2.116 SMLALD on page C2-275.
- C2.117 SMLALxy on page C2-276.
- C2.118 SMLAWy on page C2-278.
- *C2.119 SMLSD* on page C2-279.
- C2.120 SMLSLD on page C2-280.
- *C2.121 SMMLA* on page C2-281.
- *C2.122 SMMLS* on page C2-282.
- C2.123 SMMUL on page C2-283.
- C2.124 SMUAD on page C2-284.
- C2.125 SMULxy on page C2-285.
- *C2.126 SMULL* on page C2-286.
- *C2.127 SMULWy* on page C2-287.
- *C2.128 SMUSD* on page C2-288.
- C2.129 SRS on page C2-289.
- C2.130 SSAT on page C2-291.
- C2.131 SSAT16 on page C2-292.
- *C2.132 SSAX* on page C2-293.
- C2.133 SSUB8 on page C2-295.
- C2.134 SSUB16 on page C2-297.
- C2.135 STC and STC2 on page C2-299.

- C2.136 STL on page C2-301.
- *C2.137 STLEX* on page C2-302.
- *C2.138 STM* on page C2-304.
- *C2.139 STR (immediate offset)* on page C2-306.
- *C2.140 STR (register offset)* on page C2-308.
- C2.141 STR, unprivileged on page C2-310.
- C2.142 STREX on page C2-312.
- C2.143 SUB on page C2-314.
- *C2.144 SUBS pc, lr* on page C2-317.
- C2.145 SVC on page C2-319.
- C2.146 SWP and SWPB on page C2-320.
- *C2.147 SXTAB* on page C2-321.
- *C2.148 SXTAB16* on page C2-323.
- *C2.149 SXTAH* on page C2-325.
- *C2.150 SXTB* on page C2-327.
- C2.151 SXTB16 on page C2-329.
- *C2.152 SXTH* on page C2-330.
- *C2.153 SYS* on page C2-332.
- *C2.154 TBB and TBH* on page C2-333.
- *C2.155 TEQ* on page C2-334.
- *C2.156 TST* on page C2-336.
- *C2.157 TT, TTT, TTA, TTAT* on page C2-338.
- C2.158 UADD8 on page C2-340.
- *C2.159 UADD16* on page C2-342.
- *C2.160 UASX* on page C2-344.
- *C2.161 UBFX* on page C2-346.
- *C2.162 UDF* on page C2-347.
- *C2.163 UDIV* on page C2-348.
- C2.164 UHADD8 on page C2-349.
- C2.165 UHADD16 on page C2-350.
- *C2.166 UHASX* on page C2-351.
- *C2.167 UHSAX* on page C2-352.
- *C2.168 UHSUB8* on page C2-353.
- C2.169 UHSUB16 on page C2-354.
- C2.170 UMAAL on page C2-355.
- C2.171 UMLAL on page C2-356.
- C2.172 UMULL on page C2-357.
- C2.173 UQADD8 on page C2-358.
- C2.174 UQADD16 on page C2-359.
- C2.175 UQASX on page C2-360.
- *C2.176 UQSAX* on page C2-361.
- C2.177 UQSUB8 on page C2-362.
- C2.178 UQSUB16 on page C2-363.
- C2.179 USAD8 on page C2-364.
- C2.180 USADA8 on page C2-365.
- C2.181 USAT on page C2-366.
- C2.182 USAT16 on page C2-367.
- C2.183 USAX on page C2-368.
- C2.184 USUB8 on page C2-370.
- C2.185 USUB16 on page C2-372.
- C2.186 UXTAB on page C2-373.
- C2.187 UXTAB16 on page C2-375.
- C2.188 UXTAH on page C2-377.
- C2.189 UXTB on page C2-379.
- C2.190 UXTB16 on page C2-381.
- *C2.191 UXTH* on page C2-382.

- *C2.192 WFE* on page C2-384.
- *C2.193 WFI* on page C2-385.
- *C2.194 YIELD* on page C2-386.

## C2.1 A32 and T32 instruction summary

An overview of the instructions available in the A32 and T32 instruction sets.

## Table C2-1 Summary of instructions

Mnemonic	Brief description
ADC, ADD	Add with Carry, Add
ADR	Load program or register-relative address (short range)
AND	Logical AND
ASR	Arithmetic Shift Right
В	Branch
BFC, BFI	Bit Field Clear and Insert
BIC	Bit Clear
ВКРТ	Software breakpoint
BL	Branch with Link
BLX, BLXNS	Branch with Link, change instruction set, Branch with Link and Exchange (Non-secure)
BX, BXNS	Branch, change instruction set, Branch and Exchange (Non-secure)
CBZ, CBNZ	Compare and Branch if {Non}Zero
CDP	Coprocessor Data Processing operation
CDP2	Coprocessor Data Processing operation
CLREX	Clear Exclusive
CLZ	Count leading zeros
CMN, CMP	Compare Negative, Compare
CPS	Change Processor State
CRC32	CRC32
CRC32C	CRC32C
CSDB	Consumption of Speculative Data Barrier
DBG	Debug
DCPS1	Debug switch to exception level 1
DCPS2	Debug switch to exception level 2
DCPS3	Debug switch to exception level 3
DMB, DSB	Data Memory Barrier, Data Synchronization Barrier
DSB	Data Synchronization Barrier
EOR	Exclusive OR
ERET	Exception Return
ESB	Error Synchronization Barrier
HLT	Halting breakpoint
HVC	Hypervisor Call

## Table C2-1 Summary of instructions (continued)

Mnemonic	Brief description
ISB	Instruction Synchronization Barrier
IT	If-Then
LDAEX, LDAEXB, LDAEXH, LDAEXD	Load-Acquire Register Exclusive Word, Byte, Halfword, Doubleword
LDC, LDC2	Load Coprocessor
LDM	Load Multiple registers
LDR	Load Register with word
LDA, LDAB, LDAH	Load-Acquire Register Word, Byte, Halfword
LDRB	Load Register with Byte
LDRBT	Load Register with Byte, user mode
LDRD	Load Registers with two words
LDREX, LDREXB, LDREXH, LDREXD	Load Register Exclusive Word, Byte, Halfword, Doubleword
LDRH	Load Register with Halfword
LDRHT	Load Register with Halfword, user mode
LDRSB	Load Register with Signed Byte
LDRSBT	Load Register with Signed Byte, user mode
LDRSH	Load Register with Signed Halfword
LDRSHT	Load Register with Signed Halfword, user mode
LDRT	Load Register with word, user mode
LSL, LSR	Logical Shift Left, Logical Shift Right
MCR	Move from Register to Coprocessor
MCRR	Move from Registers to Coprocessor
MLA	Multiply Accumulate
MLS	Multiply and Subtract
MOV	Move
MOVT	Move Top
MRC	Move from Coprocessor to Register
MRRC	Move from Coprocessor to Registers
MRS	Move from PSR to Register
MSR	Move from Register to PSR
MUL	Multiply
MVN	Move Not
NOP	No Operation
ORN	Logical OR NOT
ORR	Logical OR
РКНВТ, РКНТВ	Pack Halfwords

## Table C2-1 Summary of instructions (continued)

Mnemonic	Brief description
PLD	Preload Data
PLDW	Preload Data with intent to Write
PLI	Preload Instruction
PUSH, POP	PUSH registers to stack, POP registers from stack
QADD, QDADD, QDSUB, QSUB	Saturating arithmetic
QADD8, QADD16, QASX, QSUB8, QSUB16, QSAX	Parallel signed saturating arithmetic
RBIT	Reverse Bits
REV, REV16, REVSH	Reverse byte order
RFE	Return From Exception
ROR	Rotate Right Register
RRX	Rotate Right with Extend
RSB	Reverse Subtract
RSC	Reverse Subtract with Carry
SADD8, SADD16, SASX	Parallel Signed arithmetic
SBC	Subtract with Carry
SBFX, UBFX	Signed, Unsigned Bit Field eXtract
SDIV	Signed Divide
SEL	Select bytes according to APSR GE flags
SETEND	Set Endianness for memory accesses
SETPAN	Set Privileged Access Never
SEV	Set Event
SEVL	Set Event Locally
SG	Secure Gateway
SHADD8, SHADD16, SHASX, SHSUB8, SHSUB16, SHSAX	Parallel Signed Halving arithmetic
SMC	Secure Monitor Call
SMLAxy	Signed Multiply with Accumulate $(32 \le 16 \times 16 + 32)$
SMLAD	Dual Signed Multiply Accumulate
	$(32 \le 32 + 16 \times 16 + 16 \times 16)$
SMLAL	Signed Multiply Accumulate (64 <= 64 + 32 x 32)
SMLALxy	Signed Multiply Accumulate (64 <= 64 + 16 x 16)
SMLALD	Dual Signed Multiply Accumulate Long
	$(64 \le 64 + 16 \times 16 + 16 \times 16)$
SMLAWy	Signed Multiply with Accumulate (32 <= 32 x 16 + 32)
### Table C2-1 Summary of instructions (continued)

Mnemonic	Brief description	
SMLSD	Dual Signed Multiply Subtract Accumulate	
	$(32 \le 32 + 16 \times 16 - 16 \times 16)$	
SMLSLD	Dual Signed Multiply Subtract Accumulate Long	
	$(64 \le 64 + 16 x 16 - 16 x 16)$	
SMMLA	Signed top word Multiply with Accumulate (32 <= TopWord(32 x 32 + 32))	
SMMLS	Signed top word Multiply with Subtract (32 <= TopWord(32 - 32 x 32))	
SMMUL	Signed top word Multiply (32 <= TopWord(32 x 32))	
SMUAD, SMUSD	Dual Signed Multiply, and Add or Subtract products	
SMULxy	Signed Multiply (32 <= 16 x 16)	
SMULL	Signed Multiply (64 <= 32 x 32)	
SMULWy	Signed Multiply (32 <= 32 x 16)	
SRS	Store Return State	
SSAT	Signed Saturate	
SSAT16	Signed Saturate, parallel halfwords	
SSUB8, SSUB16, SSAX	Parallel Signed arithmetic	
STC	Store Coprocessor	
STM	Store Multiple registers	
STR	Store Register with word	
STRB	Store Register with Byte	
STRBT	Store Register with Byte, user mode	
STRD	Store Registers with two words	
STREX, STREXB, STREXH,STREXD	Store Register Exclusive Word, Byte, Halfword, Doubleword	
STRH	Store Register with Halfword	
STRHT	Store Register with Halfword, user mode	
STL, STLB, STLH	Store-Release Word, Byte, Halfword	
STLEX, STLEXB, STLEXH, STLEXD	Store-Release Exclusive Word, Byte, Halfword, Doubleword	
STRT	Store Register with word, user mode	
SUB	Subtract	
SUBS pc, lr	Exception return, no stack	
SVC (formerly SWI)	Supervisor Call	
SXTAB, SXTAB16, SXTAH	Signed extend, with Addition	
SXTB, SXTH	Signed extend	
SXTB16	Signed extend	
SYS	Execute System coprocessor instruction	
ТВВ, ТВН	Table Branch Byte, Halfword	

### Table C2-1 Summary of instructions (continued)

Mnemonic	Brief description	
TEQ	Test Equivalence	
TST	Test	
ΤΤ, ΤΤΤ, ΤΤΑ, ΤΤΑΤ	Test Target (Alternate Domain, Unprivileged)	
UADD8, UADD16, UASX	Parallel Unsigned arithmetic	
UDF	Permanently Undefined	
UDIV	Unsigned Divide	
UHADD8, UHADD16, UHASX, UHSUB8, UHSUB16, UHSAX	Parallel Unsigned Halving arithmetic	
UMAAL	Unsigned Multiply Accumulate Accumulate Long	
	$(64 \le 32 + 32 + 32 \times 32)$	
UMLAL, UMULL	Unsigned Multiply Accumulate, Unsigned Multiply	
	$(64 \le 32 \ge 32 + 64), (64 \le 32 \ge 32)$	
UQADD8, UQADD16, UQASX, UQSUB8, UQSUB16, UQSAX	Parallel Unsigned Saturating arithmetic	
USAD8	Unsigned Sum of Absolute Differences	
USADA8	Accumulate Unsigned Sum of Absolute Differences	
USAT	Unsigned Saturate	
USAT16	Unsigned Saturate, parallel halfwords	
USUB8, USUB16, USAX	Parallel Unsigned arithmetic	
UXTAB, UXTAB16, UXTAH	Unsigned extend with Addition	
UXTB, UXTH	Unsigned extend	
UXTB16	Unsigned extend	
V*	See Chapter C3 Advanced SIMD Instructions (32-bit) on page C3-387 and Chapter C4 Floating-point Instructions (32-bit) on page C4-545	
WFE, WFI, YIELD	Wait For Event, Wait For Interrupt, Yield	

# C2.2 Instruction width specifiers

The instruction width specifiers .W and .N control the size of T32 instruction encodings.

In T32 code the .W width specifier forces the assembler to generate a 32-bit encoding, even if a 16-bit encoding is available. The .W specifier has no effect when assembling to A32 code.

In T32 code the .N width specifier forces the assembler to generate a 16-bit encoding. In this case, if the instruction cannot be encoded in 16 bits or if .N is used in A32 code, the assembler generates an error.

If you use an instruction width specifier, you must place it immediately after the instruction mnemonic and any condition code, for example:

BCS.W label ; forces 32-bit instruction even for a short branch B.N label ; faults if label out of range for 16-bit instruction

# C2.3 Flexible second operand (Operand2)

Many A32 and T32 general data processing instructions have a flexible second operand.

This is shown as *Operand2* in the descriptions of the syntax of each instruction.

*Operand2* can be a:

- Constant.
- Register with optional shift.

**Related concepts** 

C2.6 Shift operations on page C2-115

## **Related references**

- C2.4 Syntax of Operand2 as a constant on page C2-113
- C2.5 Syntax of Operand2 as a register with optional shift on page C2-114

# C2.4 Syntax of Operand2 as a constant

An Operand2 constant in an instruction has a limited range of values.

#### **Syntax**

#constant

where *constant* is an expression evaluating to a numeric value.

### Usage

In A32 instructions, *constant* can have any value that can be produced by rotating an 8-bit value right by any even number of bits within a 32-bit word.

In T32 instructions, constant can be:

- Any constant that can be produced by shifting an 8-bit value left by any number of bits within a 32-bit word.
- Any constant of the form 0x00XY00XY.
- Any constant of the form 0xXY00XY00.
- Any constant of the form ØxXYXYXYXY.

\_\_\_\_\_ Note \_\_\_\_\_

In these constants, X and Y are hexadecimal digits.

In addition, in a small number of instructions, *constant* can take a wider range of values. These are listed in the individual instruction descriptions.

When an Operand2 constant is used with the instructions MOVS, MVNS, ANDS, ORRS, ORNS, EORS, BICS, TEQ or TST, the carry flag is updated to bit[31] of the constant, if the constant is greater than 255 and can be produced by shifting an 8-bit value. These instructions do not affect the carry flag if Operand2 is any other constant.

#### Instruction substitution

If the value of an Operand2 constant is not available, but its logical inverse or negation is available, then the assembler produces an equivalent instruction and inverts or negates the constant.

For example, an assembler might assemble the instruction CMP *Rd*, #0xFFFFFFE as the equivalent instruction CMN *Rd*, #0x2.

Be aware of this when comparing disassembly listings with source code.

Related concepts C2.6 Shift operations on page C2-115 Related references C2.3 Flexible second operand (Operand2) on page C2-112 C2.5 Syntax of Operand2 as a register with optional shift on page C2-114

# C2.5 Syntax of Operand2 as a register with optional shift

When you use an Operand2 register in an instruction, you can optionally also specify a shift value.

**Syntax** 

```
Rm {, shift}
```

where:

Rm

is the register holding the data for the second operand.

#### shift

is an optional constant or register-controlled shift to be applied to Rm. It can be one of:

ASR #n

arithmetic shift right *n* bits,  $1 \le n \le 32$ .

LSL #n

logical shift left *n* bits,  $1 \le n \le 31$ .

LSR #n

logical shift right *n* bits,  $1 \le n \le 32$ .

ROR #n

rotate right *n* bits,  $1 \le n \le 31$ .

#### RRX

rotate right one bit, with extend.

#### type Rs

register-controlled shift is available in Arm code only, where:

type

is one of ASR, LSL, LSR, ROR.

Rs

is a register supplying the shift amount, and only the least significant byte is used.

if omitted, no shift occurs, equivalent to LSL #0.

#### Usage

If you omit the shift, or specify LSL #0, the instruction uses the value in Rm.

If you specify a shift, the shift is applied to the value in Rm, and the resulting 32-bit value is used by the instruction. However, the contents of the register Rm remain unchanged. Specifying a register with shift also updates the carry flag when used with certain instructions.

Related concepts C2.6 Shift operations on page C2-115 Related references C2.3 Flexible second operand (Operand2) on page C2-112 C2.4 Syntax of Operand2 as a constant on page C2-113

# C2.6 Shift operations

Register shift operations move the bits in a register left or right by a specified number of bits, called the shift length.

Register shift can be performed:

- Directly by the instructions ASR, LSR, LSL, ROR, and RRX, and the result is written to a destination register.
- During the calculation of *Operand2* by the instructions that specify the second operand as a register with shift. The result is used by the instruction.

The permitted shift lengths depend on the shift type and the instruction, see the individual instruction description or the flexible second operand description. If the shift length is 0, no shift occurs. Register shift operations update the carry flag except when the specified shift length is 0.

# Arithmetic shift right (ASR)

Arithmetic shift right by n bits moves the left-hand 32-n bits of a register to the right by n places, into the right-hand 32-n bits of the result. It copies the original bit[31] of the register into the left-hand n bits of the result.

You can use the ASR #*n* operation to divide the value in the register Rm by  $2^n$ , with the result being rounded towards negative-infinity.

When the instruction is ASRS or when ASR #n is used in *Operand2* with the instructions MOVS, MVNS, ANDS, ORRS, ORNS, EORS, BICS, TEQ or TST, the carry flag is updated to the last bit shifted out, bit[n-1], of the register Rm.

\_\_\_\_\_ Note \_\_\_\_\_

- If *n* is 32 or more, then all the bits in the result are set to the value of bit[31] of *Rm*.
- If n is 32 or more and the carry flag is updated, it is updated to the value of bit[31] of Rm.



Figure C2-1 ASR #3

# Logical shift right (LSR)

Logical shift right by n bits moves the left-hand 32-n bits of a register to the right by n places, into the right-hand 32-n bits of the result. It sets the left-hand n bits of the result to 0.

You can use the LSR #*n* operation to divide the value in the register Rm by  $2^n$ , if the value is regarded as an unsigned integer.

When the instruction is LSRS or when LSR #n is used in *Operand2* with the instructions MOVS, MVNS, ANDS, ORRS, ORNS, EORS, BICS, TEQ or TST, the carry flag is updated to the last bit shifted out, bit[n-1], of the register Rm.

——— Note —

- If *n* is 32 or more, then all the bits in the result are cleared to 0.
- If *n* is 33 or more and the carry flag is updated, it is updated to 0.



Figure C2-2 LSR #3

# Logical shift left (LSL)

– Note -

Logical shift left by n bits moves the right-hand 32-n bits of a register to the left by n places, into the left-hand 32-n bits of the result. It sets the right-hand n bits of the result to 0.

You can use the LSL #*n* operation to multiply the value in the register Rm by  $2^n$ , if the value is regarded as an unsigned integer or a two's complement signed integer. Overflow can occur without warning.

When the instruction is LSLS or when LSL #n, with non-zero n, is used in *Operand2* with the instructions MOVS, MVNS, ANDS, ORRS, ORNS, EORS, BICS, TEQ or TST, the carry flag is updated to the last bit shifted out, bit[32-n], of the register Rm. These instructions do not affect the carry flag when used with LSL #0.

- If *n* is 32 or more, then all the bits in the result are cleared to 0.
- If *n* is 33 or more and the carry flag is updated, it is updated to 0.



Figure C2-3 LSL #3

# Rotate right (ROR)

Rotate right by n bits moves the left-hand 32-n bits of a register to the right by n places, into the right-hand 32-n bits of the result. It also moves the right-hand n bits of the register into the left-hand n bits of the result.

When the instruction is RORS or when ROR #n is used in *Operand2* with the instructions MOVS, MVNS, ANDS, ORRS, ORNS, EORS, BICS, TEQ or TST, the carry flag is updated to the last bit rotation, bit[n-1], of the register Rm.

#### ——Note ——

- If *n* is 32, then the value of the result is same as the value in *Rm*, and if the carry flag is updated, it is updated to bit[31] of *Rm*.
- ROR with shift length, *n*, more than 32 is the same as ROR with shift length *n*-32.



Figure C2-4 ROR #3

# Rotate right with extend (RRX)

Rotate right with extend moves the bits of a register to the right by one bit. It copies the carry flag into bit[31] of the result.

When the instruction is RRXS or when RRX is used in *Operand2* with the instructions MOVS, MVNS, ANDS, ORRS, ORNS, EORS, BICS, TEQ or TST, the carry flag is updated to bit[0] of the register *Rm*.



Figure C2-5 RRX

### **Related references**

C2.3 Flexible second operand (Operand2) on page C2-112 C2.4 Syntax of Operand2 as a constant on page C2-113 C2.5 Syntax of Operand2 as a register with optional shift on page C2-114

# C2.7 Saturating instructions

Some A32 and T32 instructions perform saturating arithmetic.

The saturating instructions are:

- QADD.
- QDADD.
- QDSUB.
- QSUB.
- SSAT.
- USAT.

Some of the parallel instructions are also saturating.

#### Saturating arithmetic

– Note –

Saturation means that, for some value of  $2^n$  that depends on the instruction:

- For a signed saturating operation, if the full result would be less than  $-2^n$ , the result returned is  $-2^n$ .
- For an unsigned saturating operation, if the full result would be negative, the result returned is zero.
- If the full result would be greater than  $2^{n}$ -1, the result returned is  $2^{n}$ -1.

When any of these occurs, it is called saturation. Some instructions set the Q flag when saturation occurs.

Saturating instructions do not clear the Q flag when saturation does not occur. To clear the Q flag, use an MSR instruction.

The Q flag can also be set by two other instructions, but these instructions do not saturate.

#### **Related references**

C2.75 QADD on page C2-223 C2.82 QSUB on page C2-230 C2.79 QDADD on page C2-227 C2.80 QDSUB on page C2-228 C2.113 SMLAxy on page C2-271 C2.118 SMLAWy on page C2-278 C2.125 SMULxy on page C2-285 C2.127 SMULWy on page C2-287 C2.130 SSAT on page C2-291 C2.181 USAT on page C2-366 C2.65 MSR (general-purpose register to PSR) on page C2-208

# C2.8 ADC

Add with Carry.

# Syntax

ADC{S}{cond} {Rd}, Rn, Operand2

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

Rd

is the destination register.

is an optional condition code.

Rn

is the register holding the first operand.

Operand2

is a flexible second operand.

# Usage

The ADC (Add with Carry) instruction adds the values in Rn and Operand2, together with the carry flag.

You can use ADC to synthesize multiword arithmetic.

In certain circumstances, the assembler can substitute one instruction for another. Be aware of this when reading disassembly listings.

# Use of PC and SP in T32 instructions

You cannot use PC (R15) for Rd, or any operand with the ADC command.

You cannot use SP (R13) for *Rd*, or any operand with the ADC command.

# Use of PC and SP in A32 instructions

You cannot use PC for *Rd* or any operand in any data processing instruction that has a register-controlled shift.

Use of PC for any operand, in instructions without register-controlled shift, is deprecated.

If you use PC (R15) as Rn or Operand2, the value used is the address of the instruction plus 8.

If you use PC as Rd:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, 1r instruction.

Use of SP with the ADC A32 instruction is deprecated.

# **Condition flags**

If S is specified, the ADC instruction updates the N, Z, C and V flags according to the result.

# **16-bit instructions**

The following forms of this instruction are available in T32 code, and are 16-bit instructions:

# ADCS Rd, Rd, Rm

*Rd* and *Rm* must both be Lo registers. This form can only be used outside an IT block.

#### ADC{cond} Rd, Rd, Rm

*Rd* and *Rm* must both be Lo registers. This form can only be used inside an IT block.

#### **Multiword arithmetic examples**

These two instructions add a 64-bit integer contained in R2 and R3 to another 64-bit integer contained in R0 and R1, and place the result in R4 and R5.

ADDS r4, r0, r2 ; adding the least significant words ADC r5, r1, r3 ; adding the most significant words

**Related references** 

*C2.3 Flexible second operand (Operand2)* on page C2-112 *C1.9 Condition code suffixes* on page C1-92

# C2.9 ADD

Add without Carry.

# Syntax

ADD{S}{cond} {Rd}, Rn, Operand2

ADD{cond} {Rd}, Rn, #imm12 ; T32, 32-bit encoding only

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

Rd

is the destination register.

Rn

is the register holding the first operand.

Operand2

imm12

is a flexible second operand.

is any value in the range 0-4095.

# Operation

The ADD instruction adds the values in *Rn* and *Operand2* or *imm12*.

In certain circumstances, the assembler can substitute one instruction for another. Be aware of this when reading disassembly listings.

# Use of PC and SP in T32 instructions

Generally, you cannot use PC (R15) for *Rd*, or any operand.

The exceptions are:

- you can use PC for *Rn* in 32-bit encodings of T32 ADD instructions, with a constant *Operand2* value in the range 0-4095, and no S suffix. These instructions are useful for generating PC-relative addresses. Bit[1] of the PC value reads as 0 in this case, so that the base address for the calculation is always word-aligned.
- you can use PC in 16-bit encodings of T32 ADD{*cond*} Rd, Rd, Rm instructions, where both registers cannot be PC. However, the following 16-bit T32 instructions are deprecated:
  - ADD{cond} PC, SP, PC.
  - ADD{cond} SP, SP, PC.

Generally, you cannot use SP (R13) for Rd, or any operand. Except that:

- You can use SP for Rn in ADD instructions.
- ADD{*cond*} SP, SP, SP is permitted but is deprecated in Armv6T2 and above.
- ADD{S}{cond} SP, SP, Rm{, shift} and SUB{S}{cond} SP, SP, Rm{, shift} are permitted if shift is omitted or LSL #1, LSL #2, or LSL #3.

# Use of PC and SP in A32 instructions

You cannot use PC for *Rd* or any operand in any data processing instruction that has a register-controlled shift.

In ADD instructions without register-controlled shift, use of PC is deprecated except for the following cases:

- Use of PC for Rd in instructions that do not add SP to a register.
- Use of PC for Rn and use of PC for Rm in instructions that add two registers other than SP.
- Use of PC for Rn in the instruction ADD{cond} Rd, Rn, #Constant.

If you use PC (R15) as Rn or Rm, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, lr instruction.

You can use SP for Rn in ADD instructions, however, ADDS PC, SP, #Constant is deprecated.

You can use SP in ADD (register) if Rn is SP and shift is omitted or LSL #1, LSL #2, or LSL #3.

Other uses of SP in these A32 instructions are deprecated.

#### **Condition flags**

If S is specified, these instructions update the N, Z, C and V flags according to the result.

#### **16-bit instructions**

The following forms of these instructions are available in T32 code, and are 16-bit instructions:

ADDS Rd, Rn, #imm

*imm* range 0-7. *Rd* and *Rn* must both be Lo registers. This form can only be used outside an IT block.

ADD{cond} Rd, Rn, #imm

*imm* range 0-7. *Rd* and *Rn* must both be Lo registers. This form can only be used inside an IT block.

ADDS Rd, Rn, Rm

Rd, Rn and Rm must all be Lo registers. This form can only be used outside an IT block.

ADD{cond} Rd, Rn, Rm

Rd, Rn and Rm must all be Lo registers. This form can only be used inside an IT block.

ADDS Rd, Rd, #imm

*imm* range 0-255. *Rd* must be a Lo register. This form can only be used outside an IT block.

ADD{cond} Rd, Rd, #imm

imm range 0-255. Rd must be a Lo register. This form can only be used inside an IT block.

- ADD SP, SP, #imm imm range 0-508, word aligned.
- ADD Rd, SP, #imm imm range 0-1020, word aligned. Rd must be a Lo register.
- ADD Rd, pc, #imm

*imm* range 0-1020, word aligned. *Rd* must be a Lo register. Bits[1:0] of the PC are read as 0 in this instruction.

#### Example

ADD r2, r1, r3

#### Multiword arithmetic example

These two instructions add a 64-bit integer contained in R2 and R3 to another 64-bit integer contained in R0 and R1, and place the result in R4 and R5.

ADDS r4, r0, r2 ; adding the least significant words ADC r5, r1, r3 ; adding the most significant words

# **Related references**

C2.3 Flexible second operand (Operand2) on page C2-112 C1.9 Condition code suffixes on page C1-92 C2.144 SUBS pc, lr on page C2-317

# C2.10 ADR (PC-relative)

Generate a PC-relative address in the destination register, for a label in the current area.

### Syntax

ADR{cond}{.W} Rd,Label

where:

cond

.W

Rd

is an optional condition code.

is an optional instruction width specifier.

is the destination register to load.

Label

is a PC-relative expression.

Label must be within a limited distance of the current instruction.

### Usage

ADR produces position-independent code, because the assembler generates an instruction that adds or subtracts a value to the PC.

LabeL must evaluate to an address in the same assembler area as the ADR instruction.

If you use ADR to generate a target for a BX or BLX instruction, it is your responsibility to set the T32 bit (bit 0) of the address if the target contains T32 instructions.

## Offset range and architectures

The assembler calculates the offset from the PC for you. The assembler generates an error if *LabeL* is out of range.

The following table shows the possible offsets between the label and the current instruction:

#### Table C2-2 PC-relative offsets

Instruction	Offset range
A32 ADR	See C2.4 Syntax of Operand2 as a constant on page C2-113.
T32 ADR, 32-bit encoding	±4095
T32 ADR, 16-bit encoding <sup>a</sup>	0-1020 <sup>b</sup>

# ADR in T32

You can use the .W width specifier to force ADR to generate a 32-bit instruction in T32 code. ADR with .W always generates a 32-bit instruction, even if the address can be generated in a 16-bit instruction.

For forward references, ADR without .W always generates a 16-bit instruction in T32 code, even if that results in failure for an address that could be generated in a 32-bit T32 ADD instruction.

# Restrictions

In T32 code, Rd cannot be PC or SP.

In A32 code, Rd can be PC or SP but use of SP is deprecated.

a Rd must be in the range R0-R7.

b Must be a multiple of 4.

**Related references** C2.4 Syntax of Operand2 as a constant on page C2-113 C1.9 Condition code suffixes on page C1-92

# C2.11 ADR (register-relative)

Generate a register-relative address in the destination register, for a label defined in a storage map.

#### Syntax

ADR{cond}{.W} Rd,Label

where:

cond

is an optional condition code.

.W

Rd

is an optional instruction width specifier.

is the destination register to load.

Label

is a symbol defined by the FIELD directive. *LabeL* specifies an offset from the base register which is defined using the MAP directive.

LabeL must be within a limited distance from the base register.

#### Usage

ADR generates code to easily access named fields inside a storage map.

### Restrictions

In T32 code:

- Rd cannot be PC.
- Rd can be SP only if the base register is SP.

#### Offset range and architectures

The assembler calculates the offset from the base register for you. The assembler generates an error if *LabeL* is out of range.

The following table shows the possible offsets between the label and the current instruction:

#### Table C2-3 Register-relative offsets

Instruction	Offset range
A32 ADR	See C2.4 Syntax of Operand2 as a constant on page C2-113
T32 ADR, 32-bit encoding	±4095
T32 ADR, 16-bit encoding, base register is SP $^{\rm c}$	0-1020 <sup>d</sup>

#### ADR in T32

You can use the .W width specifier to force ADR to generate a 32-bit instruction in T32 code. ADR with .W always generates a 32-bit instruction, even if the address can be generated in a 16-bit instruction.

For forward references, ADR without .W, with base register SP, always generates a 16-bit instruction in T32 code, even if that results in failure for an address that could be generated in a 32-bit T32 ADD instruction.

**Related references** C2.4 Syntax of Operand2 as a constant on page C2-113

Rd must be in the range R0-R7 or SP. If Rd is SP, the offset range is -508 to 508 and must be a multiple of 4
 Must be a multiple of 4.

C1.9 Condition code suffixes on page C1-92

# C2.12 AND

Logical AND.

# Syntax

AND{S}{cond} Rd, Rn, Operand2

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

is the destination register.

Rn

Rd

is the register holding the first operand.

Operand2

is a flexible second operand.

# Operation

The AND instruction performs bitwise AND operations on the values in Rn and Operand2.

In certain circumstances, the assembler can substitute BIC for AND, or AND for BIC. Be aware of this when reading disassembly listings.

# Use of PC in T32 instructions

You cannot use PC (R15) for Rd or any operand with the AND instruction.

# Use of PC and SP in A32 instructions

You can use PC and SP with the AND A32 instruction but this is deprecated.

If you use PC as Rn, the value used is the address of the instruction plus 8.

If you use PC as Rd:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, 1r instruction.

You cannot use PC for any operand in any data processing instruction that has a register-controlled shift.

# **Condition flags**

If S is specified, the AND instruction:

- Updates the N and Z flags according to the result.
- Can update the C flag during the calculation of *Operand2*.
- Does not affect the V flag.

# **16-bit instructions**

The following forms of this instruction are available in T32 code, and are 16-bit instructions:

ANDS Rd, Rd, Rm

*Rd* and *Rm* must both be Lo registers. This form can only be used outside an IT block.

# AND{cond} Rd, Rd, Rm

*Rd* and *Rm* must both be Lo registers. This form can only be used inside an IT block.

It does not matter if you specify AND{S} Rd, Rm, Rd. The instruction is the same.

# Examples

AND	r9,r2,#0xFF00
ANDS	r9, r8, #0x19

# **Related references**

C2.3 Flexible second operand (Operand2) on page C2-112

C2.144 SUBS pc, lr on page C2-317

*C1.9 Condition code suffixes* on page C1-92

# C2.13 ASR

Arithmetic Shift Right. This instruction is a preferred synonym for MOV instructions with shifted register operands.

### Syntax

ASR{S}{cond} Rd, Rm, Rs

ASR{S}{cond} Rd, Rm, #sh

where:

where.	
s	
	is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.
Rd	
	is the destination register.
Rm	
	is the register holding the first operand. This operand is shifted right.
Rs	
	is a register holding a shift value to apply to the value in <i>Rm</i> . Only the least significant byte is used.
sh	
	is a constant shift. The range of values permitted is 1-32.

### Operation

ASR provides the signed value of the contents of a register divided by a power of two. It copies the sign bit into vacated bit positions on the left.

# **Restrictions in T32 code**

T32 instructions must not use PC or SP.

# Use of SP and PC in A32 instructions

You can use SP in the ASR A32 instruction but this is deprecated.

You cannot use PC in instructions with the  $ASR{S}{cond} Rd$ , Rm, Rs syntax. You can use PC for Rd and Rm in the other syntax, but this is deprecated.

If you use PC as *Rm*, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, the SPSR of the current mode is copied to the CPSR. You can use this to return from exceptions.

---- Note -

The A32 instruction ASRS{*cond*} pc,Rm,#sh always disassembles to the preferred form MOVS{*cond*} pc,Rm{,shift}.

#### ------ Caution --

Do not use the S suffix when using PC as *Rd* in User mode or System mode. The assembler cannot warn you about this because it has no information about what the processor mode is likely to be at execution time.

You cannot use PC for Rd or any operand in the ASR instruction if it has a register-controlled shift.

### **Condition flags**

If S is specified, the ASR instruction updates the N and Z flags according to the result.

The C flag is unaffected if the shift value is 0. Otherwise, the C flag is updated to the last bit shifted out.

#### **16-bit instructions**

The following forms of these instructions are available in T32 code, and are 16-bit instructions:

ASRS Rd, Rm, #sh Rd and Rm must both be Lo registers. This form can only be used outside an IT block.

ASR{cond} Rd, Rm, #sh Rd and Rm must both be Lo registers. This form can only be used inside an IT block.

ASRS *Rd*, *Rd*, *Rs Rd* and *Rs* must both be Lo registers. This form can only be used outside an IT block.

ASR{cond} Rd, Rd, Rs Rd and Rs must both be Lo registers. This form can only be used inside an IT block.

#### Architectures

This instruction is available in A32 and T32.

### Example

ASR r7, r8, r9

Related references C2.58 MOV on page C2-199 C1.9 Condition code suffixes on page C1-92

# C2.14 B

Branch.

### Syntax

B{cond}{.W} Label

where:

cond

is an optional condition code.

.W

is an optional instruction width specifier to force the use of a 32-bit B instruction in T32.

Label .

is a PC-relative expression.

### Operation

The B instruction causes a branch to LabeL.

### Instruction availability and branch ranges

The following table shows the branch ranges that are available in A32 and T32 code. Instructions that are not shown in this table are not available.

#### Table C2-4 B instruction availability and range

Instruction	A32	T32, 16-bit encoding	T32, 32-bit encoding
B label	±32MB	±2KB	±16MB <sup>e</sup>
B{cond} label	±32MB	-252 to +258	±1MB <sup>e</sup>

#### **Extending branch ranges**

Machine-level B instructions have restricted ranges from the address of the current instruction. However, you can use these instructions even if *LabeL* is out of range. Often you do not know where the linker places *LabeL*. When necessary, the linker adds code to enable longer branches. The added code is called a veneer.

#### B in T32

You can use the .W width specifier to force B to generate a 32-bit instruction in T32 code.

B.W always generates a 32-bit instruction, even if the target could be reached using a 16-bit instruction.

For forward references, B without .W always generates a 16-bit instruction in T32 code, even if that results in failure for a target that could be reached using a 32-bit T32 instruction.

#### **Condition flags**

The B instruction does not change the flags.

#### Architectures

See the earlier table for details of availability of the B instruction.

#### Example

B loopA

e

Use .W to instruct the assembler to use this 32-bit instruction.

**Related references** C1.9 Condition code suffixes on page C1-92

# C2.15 BFC

Bit Field Clear.

# Syntax

BFC{cond} Rd, #Lsb, #width

where:

cond

is an optional condition code.

Rd

is the destination register. *Lsb* 

is the least significant bit that is to be cleared.

# width

is the number of bits to be cleared. *width* must not be 0, and (*width+Lsb*) must be less than or equal to 32.

# Operation

Clears adjacent bits in a register. *width* bits in *Rd* are cleared, starting at *Lsb*. Other bits in *Rd* are unchanged.

# **Register restrictions**

You cannot use PC for any register.

You can use SP in the BFC A32 instruction but this is deprecated. You cannot use SP in the BFC T32 instruction.

# **Condition flags**

The BFC instruction does not change the flags.

# Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# **Related references**

C1.9 Condition code suffixes on page C1-92

# C2.16 BFI

Bit Field Insert.

# Syntax

BFI{cond} Rd, Rn, #Lsb, #width
where:
cond
 is an optional condition code.
Rd
 is the destination register.
Rn
 is the source register.
Lsb
 is the least significant bit that is to be copied.
width
 is the number of bits to be copied. width must not be 0, and (width+Lsb) must be less than or

## Operation

Inserts adjacent bits from one register into another. *width* bits in *Rd*, starting at *Lsb*, are replaced by *width* bits from *Rn*, starting at bit[0]. Other bits in *Rd* are unchanged.

### **Register restrictions**

equal to 32.

You cannot use PC for any register.

You can use SP in the BFI A32 instruction but this is deprecated. You cannot use SP in the BFI T32 instruction.

# **Condition flags**

The BFI instruction does not change the flags.

# Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

## **Related references**

C1.9 Condition code suffixes on page C1-92

# C2.17 BIC

Bit Clear.

# Syntax

BIC{S}{cond} Rd, Rn, Operand2

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

is the destination register.

Rn

Rd

is the register holding the first operand.

Operand2

is a flexible second operand.

# Operation

The BIC (Bit Clear) instruction performs an AND operation on the bits in *Rn* with the complements of the corresponding bits in the value of *Operand2*.

In certain circumstances, the assembler can substitute BIC for AND, or AND for BIC. Be aware of this when reading disassembly listings.

# Use of PC in T32 instructions

You cannot use PC (R15) for Rd or any operand in a BIC instruction.

# Use of PC and SP in A32 instructions

You can use PC and SP with the BIC instruction but they are deprecated.

If you use PC as *Rn*, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, 1r instruction.

You cannot use PC for any operand in any data processing instruction that has a register-controlled shift.

# **Condition flags**

If  ${\tt S}$  is specified, the  ${\tt BIC}$  instruction:

- Updates the N and Z flags according to the result.
- Can update the C flag during the calculation of *Operand2*.
- Does not affect the V flag.

# **16-bit instructions**

The following forms of the BIC instruction are available in T32 code, and are 16-bit instructions:

### BICS Rd, Rd, Rm

*Rd* and *Rm* must both be Lo registers. This form can only be used outside an IT block.

# BIC{cond} Rd, Rd, Rm

*Rd* and *Rm* must both be Lo registers. This form can only be used inside an IT block.

# Example

BIC r0, r1, #0xab

**Related references** 

C2.3 Flexible second operand (Operand2) on page C2-112 C2.144 SUBS pc, lr on page C2-317 C1.9 Condition code suffixes on page C1-92

# C2.18 BKPT

Breakpoint.

Syntax

BKPT #imm

where:

imm

is an expression evaluating to an integer in the range:

- 0-65535 (a 16-bit value) in an A32 instruction.
- 0-255 (an 8-bit value) in a 16-bit T32 instruction.

# Usage

The BKPT instruction causes the processor to enter Debug state. Debug tools can use this to investigate system state when the instruction at a particular address is reached.

In both A32 state and T32 state, *imm* is ignored by the Arm hardware. However, a debugger can use it to store additional information about the breakpoint.

BKPT is an unconditional instruction. It must not have a condition code in A32 code. In T32 code, the BKPT instruction does not require a condition code suffix because BKPT always executes irrespective of its condition code suffix.

# Architectures

This instruction is available in A32 and T32.

In T32, it is only available as a 16-bit instruction.

# C2.19 BL

Branch with Link.

## Syntax

BL{cond}{.W} label

where:

cond

is an optional condition code. *cond* is not available on all forms of this instruction.

.W

is an optional instruction width specifier to force the use of a 32-bit BL instruction in T32.

LabeL is a PC-relative expression.

# Operation

The BL instruction causes a branch to *LabeL*, and copies the address of the next instruction into LR (R14, the link register).

# Instruction availability and branch ranges

The following table shows the BL instructions that are available in A32 and T32 state. Instructions that are not shown in this table are not available.

#### Table C2-5 BL instruction availability and range

Instruction	A32	T32, 16-bit encoding	T32, 32-bit encoding
BL label	±32MB	±4MB <sup>f</sup>	±16MB
<pre>BL{cond} label</pre>	±32MB	-	-

# Extending branch ranges

Machine-level BL instructions have restricted ranges from the address of the current instruction. However, you can use these instructions even if *Label* is out of range. Often you do not know where the linker places *Label*. When necessary, the linker adds code to enable longer branches. The added code is called a veneer.

# **Condition flags**

The BL instruction does not change the flags.

# Availability

See the preceding table for details of availability of the BL instruction in both instruction sets.

# Examples

BLE r	ng+8
BL s	subC
BLLT r	rtX

**Related references** 

C1.9 Condition code suffixes on page C1-92

f

BL label and BLX label are an instruction pair.

# C2.20 BLX, BLXNS

Branch with Link and exchange instruction set and Branch with Link and Exchange (Non-secure).

Syntax

BLX{cond}{q} label

BLX{cond}{q} Rm

BLXNS{cond}{q} Rm (Armv8-M only)

Where:

### cond

Is an optional condition code. cond is not available on all forms of this instruction.

q

Is an optional instruction width specifier. Must be set to .W when Label is used.

# Label

Rm

Is a PC-relative expression.

Is a register containing an address to branch to.

# Operation

The BLX instruction causes a branch to *LabeL*, or to the address contained in *Rm*. In addition:

- The BLX instruction copies the address of the next instruction into LR (R14, the link register).
- The BLX instruction can change the instruction set.

BLX *Label* always changes the instruction set. It changes a processor in A32 state to T32 state, or a processor in T32 state to A32 state.

BLX *Rm* derives the target instruction set from bit[0] of *Rm*:

- If bit[0] of *Rm* is 0, the processor changes to, or remains in, A32 state.
- If bit[0] of *Rm* is 1, the processor changes to, or remains in, T32 state.

\_\_\_\_\_ Note \_\_\_\_\_

• Armv7-M and Armv6-M only support the T32 instruction set. An attempt to change the instruction execution state causes the processor to take an exception on the instruction at the target address.

The BLXNS instruction calls a subroutine at an address and instruction set specified by a register, and causes a transition from the Secure to the Non-secure domain. This variant of the instruction must only be used when additional steps required to make such a transition safe are taken.

# Instruction availability and branch ranges

The following table shows the instructions that are available in A32 and T32 state. Instructions that are not shown in this table are not available.

#### Table C2-6 BLX instruction availability and range

Instruction	A32	T32, 16-bit encoding	T32, 32-bit encoding
BLX label	±32MB	±4MB <sup>g</sup>	±16MB
BLX Rm	Available	Available	Use 16-bit
BLX{cond} Rm	Available	-	-
BLXNS	-	Available	-

g BLX label and BL label are an instruction pair.

### **Register restrictions**

You can use PC for Rm in the A32 BLX instruction, but this is deprecated. You cannot use PC in other A32 instructions.

You can use PC for Rm in the T32 BLX instruction. You cannot use PC in other T32 instructions.

You can use SP for Rm in this A32 instruction but this is deprecated.

You can use SP for Rm in the T32 BLX and BLXNS instructions, but this is deprecated. You cannot use SP in the other T32 instructions.

## **Condition flags**

These instructions do not change the flags.

### Availability

See the preceding table for details of availability of the BLX and BLXNS instructions in both instruction sets.

#### **Related references**

*C1.9 Condition code suffixes* on page C1-92 *C2.2 Instruction width specifiers* on page C2-111

# C2.21 BX, BXNS

Branch and exchange instruction set and Branch and Exchange Non-secure.

Syntax

BX{cond}{q} Rm

BXNS{cond}{q} Rm (Armv8-M only)

Where:

cond

Is an optional condition code. *cond* is not available on all forms of this instruction.

q

Is an optional instruction width specifier.

Rm

Is a register containing an address to branch to.

# Operation

The BX instruction causes a branch to the address contained in Rm and exchanges the instruction set, if necessary. The BX instruction can change the instruction set.

BX *Rm* derives the target instruction set from bit[0] of *Rm*:

- If bit[0] of *Rm* is 0, the processor changes to, or remains in, A32 state.
- If bit[0] of Rm is 1, the processor changes to, or remains in, T32 state.

\_\_\_\_\_ Note \_\_\_\_

• Armv7-M and Armv6-M only support the T32 instruction set. An attempt to change the instruction execution state causes the processor to take an exception on the instruction at the target address.

BX can also be used for an exception return.

The BXNS instruction causes a branch to an address and instruction set specified by a register, and causes a transition from the Secure to the Non-secure domain. This variant of the instruction must only be used when additional steps required to make such a transition safe are taken.

#### Instruction availability and branch ranges

The following table shows the instructions that are available in A32 and T32 state. Instructions that are not shown in this table are not available.

Instruction	A32	T32, 16-bit encoding	T32, 32-bit encoding
BX Rm	Available	Available	Use 16-bit
BX{cond} Rm	Available	-	-
BXNS	-	Available	-

#### Table C2-7 BX instruction availability and range

#### **Register restrictions**

You can use PC for Rm in the A32 BX instruction, but this is deprecated. You cannot use PC in other A32 instructions.

You can use PC for Rm in the T32 BX and BXNS instructions. You cannot use PC in other T32 instructions.

You can use SP for Rm in the A32 BX instruction but this is deprecated.

You can use SP for Rm in the T32 BX and BXNS instructions, but this is deprecated.

### **Condition flags**

These instructions do not change the flags.

### Availability

See the preceding table for details of availability of the BX and BXNS instructions in both instruction sets.

**Related references** C1.9 Condition code suffixes on page C1-92 C2.2 Instruction width specifiers on page C2-111

# C2.22 BXJ

Branch and change to Jazelle state.

### Syntax

BXJ{cond} Rm

where:

cond

is an optional condition code. *cond* is not available on all forms of this instruction.

Rm

is a register containing an address to branch to.

# Operation

The BXJ instruction causes a branch to the address contained in *Rm* and changes the instruction set state to Jazelle.

\_\_\_\_\_ Note \_\_\_\_\_

In Armv8, BXJ behaves as a BX instruction. This means it causes a branch to an address and instruction set specified by a register.

### Instruction availability and branch ranges

The following table shows the BXJ instructions that are available in A32 and T32 state. Instructions that are not shown in this table are not available.

#### Table C2-8 BXJ instruction availability and range

Instruction	A32	T32, 16-bit encoding	T32, 32-bit encoding
BXJ Rm	Available	-	Available
BXJ{cond} Rm	Available	-	-

# **Register restrictions**

You can use SP for Rm in the BXJ A32 instruction but this is deprecated.

You cannot use SP in the BXJ T32 instruction.

# **Condition flags**

The BXJ instruction does not change the flags.

# Availability

See the preceding table for details of availability of the BXJ instruction in both instruction sets.

#### **Related references**

C1.9 Condition code suffixes on page C1-92
# C2.23 CBZ and CBNZ

Compare and Branch on Zero, Compare and Branch on Non-Zero.

Syntax

CBZ{q} Rn, LabeL CBNZ{q} Rn, LabeL where: q Is an optional instruction width specifier. Rn Is the register holding the operand. LabeL Is the branch destination.

# Usage

You can use the CBZ or CBNZ instructions to avoid changing the condition flags and to reduce the number of instructions.

Except that it does not change the condition flags, CBZ Rn, label is equivalent to:

CMP Rn, #0 BEQ label

Except that it does not change the condition flags, CBNZ Rn, label is equivalent to:

CMP Rn, #0 BNE label

#### Restrictions

The branch destination must be a multiple of 2 in the range 0 to 126 bytes after the instruction and in the same execution state.

These instructions must not be used inside an IT block.

# **Condition flags**

These instructions do not change the flags.

#### Architectures

These 16-bit instructions are available in Armv7-A T32, Armv8-A T32, and Armv8-M only.

There are no Armv7-A A32, or Armv8-A A32 or 32-bit T32 encodings of these instructions.

Related references C2.14 B on page C2-132 C2.27 CMP and CMN on page C2-149 C2.2 Instruction width specifiers on page C2-111

# C2.24 CDP and CDP2

Coprocessor data operations.

**CDP** and CDP2 are not supported in Armv8.

### Syntax

CDP{cond} coproc, #opcode1, CRd, CRn, CRm{, #opcode2}
CDP2{cond} coproc, #opcode1, CRd, CRn, CRm{, #opcode2}

where:

cond

is an optional condition code.

In A32 code, *cond* is not permitted for CDP2.

#### coproc

is the name of the coprocessor the instruction is for. The standard name is pn, where n is an integer in the range 0-15.

#### opcode1

is a 4-bit coprocessor-specific opcode.

### opcode2

is an optional 3-bit coprocessor-specific opcode.

CRd, CRn, CRm

are coprocessor registers.

# Usage

The use of these instructions depends on the coprocessor. See the coprocessor documentation for details.

# Architectures

These 32-bit instructions are available in A32 and T32.

There are no 16-bit versions of these instructions in T32.

**Related references** 

C1.9 Condition code suffixes on page C1-92

# C2.25 CLREX

Clear Exclusive.

Syntax

CLREX{cond}

where:

cond

is an optional condition code.

\_\_\_\_\_ Note \_\_\_\_\_

*cond* is permitted only in T32 code, using a preceding IT instruction, but this is deprecated in Armv8. This is an unconditional instruction in A32.

# Usage

Use the CLREX instruction to clear the local record of the executing processor that an address has had a request for an exclusive access.

CLREX returns a closely-coupled exclusive access monitor to its open-access state. This removes the requirement for a dummy store to memory.

It is implementation defined whether CLREX also clears the global record of the executing processor that an address has had a request for an exclusive access.

### Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit CLREX instruction in T32.

**Related references** C1.9 Condition code suffixes on page C1-92 **Related information** Arm Architecture Reference Manual

# C2.26 CLZ

Count Leading Zeros.

## Syntax

CLZ{cond} Rd, Rm where: cond is an optional condition code. Rd is the destination register. Rm is the operand register.

# Operation

The CLZ instruction counts the number of leading zeros in the value in *Rm* and returns the result in *Rd*. The result value is 32 if no bits are set in the source register, and zero if bit 31 is set.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in these A32 instructions but this is deprecated.

You cannot use SP in T32 instructions.

### **Condition flags**

This instruction does not change the flags.

# Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# Examples

CLZ r4,r9 CLZNE r2,r3

Use the CLZ T32 instruction followed by a left shift of *Rm* by the resulting *Rd* value to normalize the value of register *Rm*. Use MOVS, rather than MOV, to flag the case where *Rm* is zero:

CLZ r5, r9 MOVS r9, r9, LSL r5

**Related references** C1.9 Condition code suffixes on page C1-92

# C2.27 CMP and CMN

Compare and Compare Negative.

#### Syntax

```
CMP{cond} Rn, Operand2
CMN{cond} Rn, Operand2
where:
cond
is an optional condition code.
Rn
is the register holding the first operand.
Operand2
is a flexible second operand.
```

### Operation

These instructions compare the value in a register with *Operand2*. They update the condition flags on the result, but do not place the result in any register.

The CMP instruction subtracts the value of *Operand2* from the value in *Rn*. This is the same as a SUBS instruction, except that the result is discarded.

The CMN instruction adds the value of *Operand2* to the value in *Rn*. This is the same as an ADDS instruction, except that the result is discarded.

In certain circumstances, the assembler can substitute CMN for CMP, or CMP for CMN. Be aware of this when reading disassembly listings.

#### Use of PC in A32 and T32 instructions

You cannot use PC for any operand in any data processing instruction that has a register-controlled shift.

You can use PC (R15) in these A32 instructions without register controlled shift but this is deprecated.

If you use PC as Rn in A32 instructions, the value used is the address of the instruction plus 8.

You cannot use PC for any operand in these T32 instructions.

#### Use of SP in A32 and T32 instructions

You can use SP for Rn in A32 and T32 instructions.

You can use SP for Rm in A32 instructions but this is deprecated.

You can use SP for *Rm* in a 16-bit T32 CMP *Rn*, *Rm* instruction but this is deprecated. Other uses of SP for *Rm* are not permitted in T32.

#### **Condition flags**

These instructions update the N, Z, C and V flags according to the result.

#### **16-bit instructions**

The following forms of these instructions are available in T32 code, and are 16-bit instructions:

#### CMP Rn, Rm

Lo register restriction does not apply.

#### CMN Rn, Rm

Rn and Rm must both be Lo registers.

#### CMP Rn, #imm

Rn must be a Lo register. imm range 0-255.

#### **Correct examples**

CMP r2, r9 CMN r0, #6400 CMPGT sp, r7, LSL #2

#### Incorrect example

CMP r2, pc, ASR r0 ; PC not permitted with register-controlled ; shift.

### **Related references**

*C2.3 Flexible second operand (Operand2)* on page C2-112 *C1.9 Condition code suffixes* on page C1-92

# C2.28 CPS

Change Processor State.

### Syntax

CPSeffect ifLags{, #mode}

#### CPS #mode

where:

# effect

is one of:

Interrupt or abort enable.

# ID

Interrupt or abort disable.

### iflags

is a sequence of one or more of:

а	Enables or disables imprecise aborts.
i	Enables or disables IRQ interrupts.
t	Enables or disables FIQ interrupts.

mode

specifies the number of the mode to change to.

# Usage

Changes one or more of the mode, A, I, and F bits in the CPSR, without changing the other CPSR bits.

CPS is only permitted in privileged software execution, and has no effect in User mode.

CPS cannot be conditional, and is not permitted in an IT block.

# **Condition flags**

This instruction does not change the condition flags.

# **16-bit instructions**

The following forms of these instructions are available in T32 code, and are 16-bit instructions:

- CPSIE iflags.
- CPSID iflags.

You cannot specify a mode change in a 16-bit T32 instruction.

# Architectures

This instruction is available in A32 and T32.

In T32, 16-bit and 32-bit versions of this instruction are available.

# Examples

CPSIE if ; Enable IRQ and FIQ interrupts. CPSID A ; Disable imprecise aborts. CPSID ai, #17 ; Disable imprecise aborts and interrupts, and enter

	;	FIQ mode.
CPS #16	;	Enter User mode.

# **Related concepts**

A1.3 Processor modes, and privileged and unprivileged software execution on page A1-28

# C2.29 CRC32

CRC32 performs a cyclic redundancy check (CRC) calculation on a value held in a general-purpose register.

#### Syntax

```
CRC32B{q} Rd, Rn, Rm ; A1 Wd = CRC32(Wn, Rm[<7:0>])
CRC32H{q} Rd, Rn, Rm ; A1 Wd = CRC32(Wn, Rm[<15:0>])
CRC32W{q} Rd, Rn, Rm ; A1 Wd = CRC32(Wn, Rm[<15:0>])
CRC32B{q} Rd, Rn, Rm ; T1 Wd = CRC32(Wn, Rm[<7:0>])
CRC32H{q} Rd, Rn, Rm ; T1 Wd = CRC32(Wn, Rm[<7:0>])
CRC32H{q} Rd, Rn, Rm ; T1 Wd = CRC32(Wn, Rm[<15:0>])
CRC32W{q} Rd, Rn, Rm ; T1 Wd = CRC32(Wn, Rm[<15:0>])
CRC32W{q} Rd, Rn, Rm ; T1 Wd = CRC32(Wn, Rm[<31:0>])
Where:
```

q

Is an optional instruction width specifier. See *C2.2 Instruction width specifiers* on page C2-111. A CRC32 instruction must be unconditional.

Rd

Rn

Is the general-purpose accumulator output register.

Is the general-purpose accumulator input register.

Rm

Is the general-purpose data source register.

#### Architectures supported

Supported in architecture Armv8.1 and later. Optionally supported in the Armv8-A architecture.

#### Usage

CRC32 takes an input CRC value in the first source operand, performs a CRC on the input value in the second source operand, and returns the output CRC value. The second source operand can be 8, 16, or 32 bits. To align with common usage, the bit order of the values is reversed as part of the operation, and the polynomial  $0 \times 04 C11DB7$  is used for the CRC calculation.

——— Note —

ID\_ISAR5.CRC32 indicates whether this instruction is supported in the T32 and A32 instruction sets.

\_\_\_\_\_ Note \_\_\_\_\_

For more information about the CONSTRAINED UNPREDICTABLE behavior, see Architectural Constraints on UNPREDICTABLE behaviors in the Arm<sup>®</sup> Architecture Reference Manual Arm<sup>®</sup>v8, for Arm<sup>®</sup>v8-A architecture profile.

#### **Related references**

C2.29 CRC32 on page C2-153 C2.1 A32 and T32 instruction summary on page C2-106

# C2.30 CRC32C

CRC32C performs a cyclic redundancy check (CRC) calculation on a value held in a general-purpose register.

### Syntax

CRC32CB{q} Rd, Rn, Rm ; A1 Wd = CRC32C(Wn, Rm[<7:0>]) CRC32CH{q} Rd, Rn, Rm ; A1 Wd = CRC32C(Wn, Rm[<15:0>]) CRC32CW{q} Rd, Rn, Rm ; A1 Wd = CRC32C(Wn, Rm[<15:0>]) CRC32CB{q} Rd, Rn, Rm ; T1 Wd = CRC32C(Wn, Rm[<7:0>]) CRC32CH{q} Rd, Rn, Rm ; T1 Wd = CRC32C(Wn, Rm[<15:0>]) CRC32CW{q} Rd, Rn, Rm ; T1 Wd = CRC32C(Wn, Rm[<15:0>]) CRC32CW{q} Rd, Rn, Rm ; T1 Wd = CRC32C(Wn, Rm[<15:0>]) CRC32CW{q} Rd, Rn, Rm ; T1 Wd = CRC32C(Wn, Rm[<31:0>]) Where:

q

Is an optional instruction width specifier. See *C2.2 Instruction width specifiers* on page C2-111. A CRC32C instruction must be unconditional.

Rd

Is the general-purpose accumulator output register.

Is the general-purpose accumulator input register.

Rm

Is the general-purpose data source register.

#### Architectures supported

Supported in architecture Armv8-A.1 and later. Optionally supported in the Armv8-A architecture.

#### Usage

CRC32C takes an input CRC value in the first source operand, performs a CRC on the input value in the second source operand, and returns the output CRC value. The second source operand can be 8, 16, or 32 bits. To align with common usage, the bit order of the values is reversed as part of the operation, and the polynomial 0x1EDC6F41 is used for the CRC calculation.

——— Note —

ID\_ISAR5.CRC32 indicates whether this instruction is supported in the T32 and A32 instruction sets.

\_\_\_\_\_ Note \_\_\_\_\_

For more information about the CONSTRAINED UNPREDICTABLE behavior, see Architectural Constraints on UNPREDICTABLE behaviors in the Arm<sup>®</sup> Architecture Reference Manual Arm<sup>®</sup>v8, for Arm<sup>®</sup>v8-A architecture profile.

#### **Related references**

C2.29 CRC32 on page C2-153 C2.1 A32 and T32 instruction summary on page C2-106

# C2.31 CSDB

Consumption of Speculative Data Barrier.

## Syntax

```
CSDB{c}{q} ; A32
```

```
CSDB{c}.W ; T32
```

Where:

#### q

с

Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.

Is an optional condition code. See Chapter C1 Condition Codes on page C1-83.

# Usage

Consumption of Speculative Data Barrier is a memory barrier that controls Speculative execution and data value prediction. Arm Compiler supports the mitigation of the Variant 1 mechanism that is described in the whitepaper at *Vulnerability of Speculative Processors to Cache Timing Side-Channel Mechanism*.

The CSDB instruction allows Speculative execution of:

- Branch instructions.
- Instructions that write to the PC.
- Instructions that are not a result of data value predictions.
- Instructions that are the result of PSTATE. {N,Z,C,V} predictions from conditional branch instructions or from conditional instructions that write to the PC.

The CSDB instruction prevents Speculative execution of:

- Non-branch instructions.
- Instructions that do not write to the PC.
- Instructions that are the result of data value predictions.
- Instructions that are the result of PSTATE. {N,Z,C,V} predictions from instructions other than conditional branch instructions and conditional instructions that write to the PC.

# CONSTRAINED UNPREDICTABLE behavior

For conditional CSDB instructions that specify a condition  $\{c\}$  other than AL in A32, and for any condition  $\{c\}$  used inside an IT block in T32, then how the instructions are rejected depends on your assembler implementation. See your assembler documentation for details.

- Note -

For more information about the CONSTRAINED UNPREDICTABLE behavior, see Architectural Constraints on UNPREDICTABLE behaviors in the Arm<sup>®</sup> Architecture Reference Manual Arm<sup>®</sup>v8, for Arm<sup>®</sup>v8-A architecture profile.

# Examples

The following example shows a code sequence that could result in the processor loading data from an untrusted location that is provided by a user as the result of Speculative execution of instructions:

```
CMP R0, R1
BGE out_of_range
LDRB R4, [R5, R0] ; load data from list A
; speculative execution of this instruction
; must be prevented
AND R4, R4, #1
LSL R4, R4, #8
ADD R4, R4, #0x200
CMP R4, R6
BGE out_of_range
```

```
LDRB R7, [R8, R4] ; load data from list B out_of_range
```

In this example:

- There are two list objects A and B.
- A contains a list of values that are used to calculate offsets from which data can be loaded from B.
- R1 is the length of A.
- R5 is the base address of A.
- R6 is the length of B.
- R8 is the base address of B.
- R0 is an untrusted offset that is provided by a user, and is used to load an element from A.

When R0 is greater-than or equal-to the length of A, it is outside the address range of A. Therefore, the first branch instruction BGE out\_of\_range is taken, and instructions LDRB R4, [R5, R0] through LDRB R7, [R8, R4] are skipped.

Without a CSDB instruction, these skipped instructions can still be speculatively executed, and could result in:

- If R0 is maliciously set to an incorrect value, then data can be loaded into R4 from an address outside the address range of A.
- Data can be loaded into R7 from an address outside the address range of B.

To mitigate against these untrusted accesses, add a pair of MOVGE and CSDB instructions between the BGE out\_of\_range and LDRB R4, [R5, R0] instructions as follows:

```
CMP R0, R1
BGE out_of_range
MOVGE R0, #0
; conditonally clears the untrusted
; offset provided by the user so that
; it cannot affect any other code
CSDB
; new barrier instruction
LDRB R4, [R5, R0]; load data from list A
; speculative execution of this instruction
; is prevented
AND R4, R4, #1
LSL R4, R4, #8
ADD R4, R4, #0x200
CMP R4, R6
BGE out_of_range
LDRB R7, [R8, R4]; load data from list B
out_of_range
```

#### **Related references**

*C2.1 A32 and T32 instruction summary* on page C2-106 *C2.58 MOV* on page C2-199

#### **Related information**

Arm Processor Security Update Compiler support for mitigations

# C2.32 DBG

Debug.

# Syntax

DBG{cond} {option}

where:

cond

is an optional condition code.

option

is an optional limitation on the operation of the hint. The range is 0-15.

# Usage

DBG is a hint instruction. It is optional whether it is implemented or not. If it is not implemented, it behaves as a NOP. The assembler produces a diagnostic message if the instruction executes as NOP on the target.

Debug hint provides a hint to a debugger and related tools. See your debugger and related tools documentation to determine the use, if any, of this instruction.

# Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

**Related references** C2.68 NOP on page C2-213 C1.9 Condition code suffixes on page C1-92

# C2.33 DMB

Data Memory Barrier.

#### Syntax

DMB{cond} {option}

where:

### cond

is an optional condition code.

\_\_\_\_\_ Note \_\_\_\_\_

cond is permitted only in T32 code. This is an unconditional instruction in A32 code.

#### option

is an optional limitation on the operation of the hint. Permitted values are:

SY	Full system barrier operation. This is the default and can be omitted
LD	
ST	Barrier operation that waits only for loads to complete.
51	Barrier operation that waits only for stores to complete.
ISH	Barrier operation only to the inner shareable domain
ISHLD	Burner operation only to the niner shareable domain.
	Barrier operation that waits only for loads to complete, and only applies to the inner shareable domain
ISHST	
	Barrier operation that waits only for stores to complete, and only to the inner shareable
NSH	domani.
	Barrier operation only out to the point of unification.
NSILD	Barrier operation that waits only for loads to complete and only applies out to the point
NSHST	of unification.
101.01	Barrier operation that waits only for stores to complete and only out to the point of
OSH	unification.
	Barrier operation only to the outer shareable domain.
OSHLD	DMB operation that waits only for loads to complete and only applies to the outer
	shareable domain.
OSHST	Barrier operation that waits only for stores to complete and only to the outer shareable
	domain.
— Note	e

The options LD, ISHLD, NSHLD, and OSHLD are supported only in the Armv8-A and Armv8-R architectures.

# Operation

Data Memory Barrier acts as a memory barrier. It ensures that all explicit memory accesses that appear in program order before the DMB instruction are observed before any explicit memory accesses that appear in program order after the DMB instruction. It does not affect the ordering of any other instructions executing on the processor.

## Alias

The following alternative values of *option* are supported, but Arm recommends that you do not use them:

- SH is an alias for ISH.
- SHST is an alias for ISHST.
- UN is an alias for NSH.
- UNST is an alias for NSHST.

#### Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

### **Related references**

C1.9 Condition code suffixes on page C1-92

# C2.34 DSB

Data Synchronization Barrier.

### Syntax

DSB{cond} {option}

where:

### cond

is an optional condition code.

\_\_\_\_\_ Note \_\_\_\_\_

cond is permitted only in T32 code. This is an unconditional instruction in A32 code.

#### option

is an optional limitation on the operation of the hint. Permitted values are:

SY	Full system barrier operation. This is the default and can be omitted
LD	
sт	Barrier operation that waits only for loads to complete.
51	Barrier operation that waits only for stores to complete.
ISH	Barrier operation only to the inner shareable domain
ISHLD	Burner operation only to the niner shareable domain.
	Barrier operation that waits only for loads to complete, and only applies to the inner shareable domain
ISHST	
	Barrier operation that waits only for stores to complete, and only to the inner shareable
NSH	domani.
	Barrier operation only out to the point of unification.
NJILD	Barrier operation that waits only for loads to complete and only applies out to the point
ИЗНАТ	of unification.
	Barrier operation that waits only for stores to complete and only out to the point of
OSH	unification.
••••	Barrier operation only to the outer shareable domain.
OSHLD	DMB operation that waits only for loads to complete and only applies to the outer
	shareable domain.
OSHST	Barrier operation that waits only for stores to complete and only to the outer shareable
	domain.
Not	e

The options LD, ISHLD, NSHLD, and OSHLD are supported only in the Armv8-A and Armv8-R architectures.

### Operation

Data Synchronization Barrier acts as a special kind of memory barrier. No instruction in program order after this instruction executes until this instruction completes. This instruction completes when:

- All explicit memory accesses before this instruction complete.
- All Cache, Branch predictor and TLB maintenance operations before this instruction complete.

### Alias

The following alternative values of *option* are supported for DSB, but Arm recommends that you do not use them:

- SH is an alias for ISH.
- SHST is an alias for ISHST.
- UN is an alias for NSH.
- UNST is an alias for NSHST.

#### Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

## **Related references**

C1.9 Condition code suffixes on page C1-92

# C2.35 EOR

Logical Exclusive OR.

# Syntax

EOR{S}{cond} Rd, Rn, Operand2

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

is the destination register.

Rn

Rd

is the register holding the first operand.

Operand2

is a flexible second operand.

# Operation

The EOR instruction performs bitwise Exclusive OR operations on the values in Rn and Operand2.

# Use of PC in T32 instructions

You cannot use PC (R15) for Rd or any operand in an EOR instruction.

# Use of PC and SP in A32 instructions

You can use PC and SP with the EOR instruction but they are deprecated.

If you use PC as Rn, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, lr instruction.

You cannot use PC for any operand in any data processing instruction that has a register-controlled shift.

# **Condition flags**

If S is specified, the EOR instruction:

- Updates the N and Z flags according to the result.
- Can update the C flag during the calculation of *Operand2*.
- Does not affect the V flag.

# **16-bit instructions**

The following forms of the EOR instruction are available in T32 code, and are 16-bit instructions:

EORS Rd, Rd, Rm

Rd and Rm must both be Lo registers. This form can only be used outside an IT block.

EOR{cond} Rd, Rd, Rm

*Rd* and *Rm* must both be Lo registers. This form can only be used inside an IT block.

It does not matter if you specify EOR{S} Rd, Rm, Rd. The instruction is the same.

#### **Correct examples**

EORS r0,r0,r3,ROR r6 EORS r7, r11, #0x18181818

#### Incorrect example

EORS r0,pc,r3,ROR r6 ; PC not permitted with register ; controlled shift

### **Related references**

*C2.3 Flexible second operand (Operand2)* on page C2-112 *C2.144 SUBS pc, lr* on page C2-317 *C1.9 Condition code suffixes* on page C1-92

# C2.36 ERET

Exception Return.

### Syntax

ERET{cond}

where:

cond

is an optional condition code.

# Usage

In a processor that implements the Virtualization Extensions, you can use ERET to perform a return from an exception taken to Hyp mode.

# Operation

When executed in Hyp mode, ERET loads the PC from ELR\_hyp and loads the CPSR from SPSR\_hyp. When executed in any other mode, apart from User or System, it behaves as:

- MOVS PC, LR in the A32 instruction set.
- SUBS PC, LR, #0 in the T32 instruction set.

# Notes

You must not use ERET in User or System mode. The assembler cannot warn you about this because it has no information about what the processor mode is likely to be at execution time.

ERET is the preferred synonym for SUBS PC, LR, #0 in the T32 instruction set.

# Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# **Related concepts**

A1.3 Processor modes, and privileged and unprivileged software execution on page A1-28 **Related references** C2.58 MOV on page C2-199 C2.144 SUBS pc, lr on page C2-317 C1.9 Condition code suffixes on page C1-92 C2.39 HVC on page C2-167

# C2.37 ESB

Error Synchronization Barrier.

# Syntax

```
ESB{c}{q}
```

```
ESB{c}.W
```

Where:

q

с

Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.

Is an optional condition code. See Chapter C1 Condition Codes on page C1-83.

# Architectures supported

Supported in the Armv8-A and Armv8-R architectures.

# Usage

Error Synchronization Barrier.

*Related references C2.1 A32 and T32 instruction summary* on page C2-106

# C2.38 HLT

Halting breakpoint.

\_\_\_\_\_ Note \_\_\_\_

This instruction is supported only in the Armv8 architecture.

### Syntax

HLT{Q} #imm

Where:

Q

is an optional suffix. It only has an effect when Halting debug-mode is disabled. In this case, if Q is specified, the instruction behaves as a NOP. If Q is not specified, the instruction is UNDEFINED.

#### imm

is an expression evaluating to an integer in the range:

- 0-65535 (a 16-bit value) in an A32 instruction.
- 0-63 (a 6-bit value) in a 16-bit T32 instruction.

# Usage

The HLT instruction causes the processor to enter Debug state if Halting debug-mode is enabled.

In both A32 state and T32 state, imm is ignored by the Arm hardware. However, a debugger can use it to store additional information about the breakpoint.

HLT is an unconditional instruction. It must not have a condition code in A32 code. In T32 code, the HLT instruction does not require a condition code suffix because it always executes irrespective of its condition code suffix.

# Availability

This instruction is available in A32 and T32.

In T32, it is only available as a 16-bit instruction.

*Related references C2.68 NOP* on page C2-213

# C2.39 HVC

Hypervisor Call.

### Syntax

HVC #imm

where:

imm

is an expression evaluating to an integer in the range 0-65535.

# Operation

In a processor that implements the Virtualization Extensions, the HVC instruction causes a Hypervisor Call exception. This means that the processor enters Hyp mode, the CPSR value is saved to the Hyp mode SPSR, and execution branches to the HVC vector.

HVC must not be used if the processor is in Secure state, or in User mode in Non-secure state.

*imm* is ignored by the processor. However, it can be retrieved by the exception handler to determine what service is being requested.

HVC cannot be conditional, and is not permitted in an IT block.

# Notes

The ERET instruction performs an exception return from Hyp mode.

### Architectures

This 32-bit instruction is available in A32 and T32. It is available in Armv7 architectures that include the Virtualization Extensions.

There is no 16-bit version of this instruction in T32.

# **Related concepts**

A1.3 Processor modes, and privileged and unprivileged software execution on page A1-28 **Related references** C2.36 ERET on page C2-164

# C2.40 ISB

Instruction Synchronization Barrier.

### Syntax

ISB{cond} {option}

where:

cond

is an optional condition code.

\_\_\_\_\_ Note \_\_\_\_\_

cond is permitted only in T32 code. This is an unconditional instruction in A32 code.

option

is an optional limitation on the operation of the hint. The permitted value is:

SY

Full system barrier operation. This is the default and can be omitted.

# Operation

Instruction Synchronization Barrier flushes the pipeline in the processor, so that all instructions following the ISB are fetched from cache or memory, after the instruction has been completed. It ensures that the effects of context altering operations, such as changing the ASID, or completed TLB maintenance operations, or branch predictor maintenance operations, in addition to all changes to the CP15 registers, executed before the ISB instruction are visible to the instructions fetched after the ISB.

In addition, the ISB instruction ensures that any branches that appear in program order after it are always written into the branch prediction logic with the context that is visible after the ISB instruction. This is required to ensure correct execution of the instruction stream.

\_\_\_\_\_ Note \_\_\_\_

When the target architecture is Armv7-M, you cannot use an **ISB** instruction in an IT block, unless it is the last instruction in the block.

# Architectures

This 32-bit instructions are available in A32 and T32.

There is no 16-bit version of this instruction in T32.

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.41 IT

The IT (If-Then) instruction makes a single following instruction (the *IT block*) conditional. The conditional instruction must be from a restricted set of 16-bit instructions.

#### Syntax

IT cond

where:

cond

specifies the condition for the following instruction.

### **Deprecated syntax**

 $IT{x{y{z}}} {cond}$ 

where:

х

specifies the condition switch for the second instruction in the IT block.

у 7

specifies the condition switch for the third instruction in the IT block.

specifies the condition switch for the fourth instruction in the IT block.

cond

specifies the condition for the first instruction in the IT block.

The condition switches for the second, third, and fourth instructions in the IT block can be either:

Т

Then. Applies the condition *cond* to the instruction.

Ε

Else. Applies the inverse condition of *cond* to the instruction.

# Usage

The *IT block* can contain between two and four conditional instructions, where the conditions can be all the same, or some of them can be the logical inverse of the others, but this is deprecated in Armv8.

The conditional instruction (including branches, but excluding the BKPT instruction) must specify the condition in the {*cond*} part of its syntax.

You are not required to write IT instructions in your code, because the assembler generates them for you automatically according to the conditions specified on the following instructions. However, if you do write IT instructions, the assembler validates the conditions specified in the IT instructions against the conditions specified in the following instructions.

Writing the IT instructions ensures that you consider the placing of conditional instructions, and the choice of conditions, in the design of your code.

When assembling to A32 code, the assembler performs the same checks, but does not generate any IT instructions.

With the exception of CMP, CMN, and TST, the 16-bit instructions that normally affect the condition flags, do not affect them when used inside an IT block.

A BKPT instruction in an IT block is always executed, so it does not require a condition in the {cond} part of its syntax. The IT block continues from the next instruction. Using a BKPT or HLT instruction inside an IT block is deprecated.

\_\_\_\_\_ Note \_\_\_\_\_

You can use an IT block for unconditional instructions by using the AL condition.

Conditional branches inside an IT block have a longer branch range than those outside the IT block.

### Restrictions

The following instructions are not permitted in an IT block:

- IT.
- CBZ and CBNZ.
- TBB and TBH.
- CPS, CPSID and CPSIE.
- SETEND.

Other restrictions when using an IT block are:

- A branch or any instruction that modifies the PC is only permitted in an IT block if it is the last instruction in the block.
- You cannot branch to any instruction in an IT block, unless when returning from an exception handler.
- You cannot use any assembler directives in an IT block.

\_\_\_\_\_ Note \_\_\_\_\_

armasm shows a diagnostic message when any of these instructions are used in an IT block.

Using any instruction not listed in the following table in an IT block is deprecated. Also, any explicit reference to R15 (the PC) in the IT block is deprecated.

#### Table C2-9 Permitted instructions inside an IT block

16-bit instruction	When deprecated
MOV, MVN	When Rm or Rd is the PC
LDR, LDRB, LDRH, LDRSB, LDRSH	For PC-relative forms
STR, STRB, STRH	-
ADD, ADC, RSB, SBC, SUB	ADD SP, SP, #imm or SUB SP, SP, #imm or when Rm, Rdn or Rdm is the PC
CMP, CMN	When $Rm$ or $Rn$ is the PC
MUL	-
ASR, LSL, LSR, ROR	-
AND, BIC, EOR, ORR, TST	-
BX, BLX	When Rm is the PC

#### Condition flags

This instruction does not change the flags.

# Exceptions

Exceptions can occur between an IT instruction and the corresponding IT block, or within an IT block. This exception results in entry to the appropriate exception handler, with suitable return information in LR and SPSR.

Instructions designed for use as exception returns can be used as normal to return from the exception, and execution of the IT block resumes correctly. This is the only way that a PC-modifying instruction can branch to an instruction in an IT block.

## Availability

This 16-bit instruction is available in T32 only.

In A32 code, IT is a pseudo-instruction that does not generate any code.

There is no 32-bit version of this instruction.

#### **Correct examples**

IT GT LDRGT r0, [r1,#4] IT EQ ADDEQ r0, r1, r2

#### **Incorrect examples**

IT ADD	NE r0,r0,r1	; syntax error: no condition code used in IT block
ITT MOVEQ ADDEQ	EQ r0,r1 r0,r0,#1	; IT block covering more than one instruction is deprecated
IT LDRGT	GT r0,label	; LDR (PC-relative) is deprecated in an IT block
IT ADDEQ	EQ PC,r0	; ADD is deprecated when Rdn is the PC

# C2.42 LDA

Load-Acquire Register.

—— Note —

This instruction is supported only in Armv8.

# Syntax

LDA{cond} Rt, [Rn] LDAB{cond} Rt, [Rn] LDAH{cond} Rt, [Rn] where: cond is an optional condition code. Rt is the register to load. Rn

is the register on which the memory address is based.

# Operation

LDA loads data from memory. If any loads or stores appear after a load-acquire in program order, then all observers are guaranteed to observe the load-acquire before observing the loads and stores. Loads and stores appearing before a load-acquire are unaffected.

If a store-release follows a load-acquire, each observer is guaranteed to observe them in program order.

There is no requirement that a load-acquire be paired with a store-release.

# Restrictions

The address specified must be naturally aligned, or an alignment fault is generated.

The PC must not be used for *Rt* or *Rn*.

# Availability

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction.

Related references C2.43 LDAEX on page C2-173 C2.136 STL on page C2-301 C2.137 STLEX on page C2-302 C1.9 Condition code suffixes on page C1-92

# C2.43 LDAEX

Load-Acquire Register Exclusive.

## Syntax

LDAEX{cond} Rt, [Rn] LDAEXB{cond} Rt, [Rn] LDAEXH{cond} Rt, [Rn] LDAEXD{cond} Rt, Rt2, [Rn]

where:

cond

is an optional condition code.

is the register to load.

Rt2

Rt

is the second register for doubleword loads.

Rn

is the register on which the memory address is based.

# Operation

LDAEX loads data from memory.

- If the physical address has the Shared TLB attribute, LDAEX tags the physical address as exclusive access for the current processor, and clears any exclusive access tag for this processor for any other physical address.
- Otherwise, it tags the fact that the executing processor has an outstanding tagged physical address.
- If any loads or stores appear after LDAEX in program order, then all observers are guaranteed to observe the LDAEX before observing the loads and stores. Loads and stores appearing before LDAEX are unaffected.

# Restrictions

The PC must not be used for any of Rt, Rt2, or Rn.

For A32 instructions:

- SP can be used but use of SP for any of *Rt*, or *Rt2* is deprecated.
- For LDAEXD, *Rt* must be an even numbered register, and not LR.
- Rt2 must be R(t+1).

For T32 instructions:

- SP can be used for Rn, but must not be used for any of Rt, or Rt2.
- For LDAEXD, *Rt* and *Rt2* must not be the same register.

# Usage

Use LDAEX and STLEX to implement interprocess communication in multiple-processor and sharedmemory systems. For reasons of performance, keep the number of instructions between corresponding LDAEX and STLEX instructions to a minimum.

----- Note -----

The address used in a STLEX instruction must be the same as the address in the most recently executed LDAEX instruction.

### Availability

These 32-bit instructions are available in A32 and T32.

There are no 16-bit versions of these instructions.

#### **Related references**

C2.136 STL on page C2-301 C2.42 LDA on page C2-172 C2.137 STLEX on page C2-302 C1.9 Condition code suffixes on page C1-92

# C2.44 LDC and LDC2

Transfer Data from memory to Coprocessor.

**\_\_\_\_\_ Note \_\_\_\_\_** LDC2 is not supported in Armv8.

## Syntax

```
op{L}{cond} coproc, CRd, [Rn]
op{L}{cond} coproc, CRd, [Rn, #{-}offset]; offset addressing
op{L}{cond} coproc, CRd, [Rn, #{-}offset]!; pre-index addressing
op{L}{cond} coproc, CRd, [Rn], #{-}offset ; post-index addressing
op{L}{cond} coproc, CRd, Label
op{L}{cond} coproc, CRd, [Rn], {option}
where:
ор
        is LDC or LDC2.
cond
        is an optional condition code.
        In A32 code, cond is not permitted for LDC2.
L
        is an optional suffix specifying a long transfer.
coproc
        is the name of the coprocessor the instruction is for. The standard name is pn, where n is an
        integer whose value must be:
           In the range 0 to 15 in Armv7 and earlier.
           14 in Armv8.
CRd
        is the coprocessor register to load.
Rn
        is the register on which the memory address is based. If PC is specified, the value used is the
        address of the current instruction plus eight.
        is an optional minus sign. If - is present, the offset is subtracted from Rn. Otherwise, the offset is
        added to Rn.
offset
        is an expression evaluating to a multiple of 4, in the range 0 to 1020.
!
        is an optional suffix. If ! is present, the address including the offset is written back into Rn.
Label
        is a word-aligned PC-relative expression.
        Label must be within 1020 bytes of the current instruction.
option
        is a coprocessor option in the range 0-255, enclosed in braces.
```

# Usage

The use of these instructions depends on the coprocessor. See the coprocessor documentation for details.

# Architectures

These 32-bit instructions are available in A32 and T32.

There are no 16-bit versions of these instructions in T32.

### **Register restrictions**

You cannot use PC for Rn in the pre-index and post-index instructions. These are the forms that write back to Rn.

#### **Related references**

C1.9 Condition code suffixes on page C1-92

# C2.45 LDM

Load Multiple registers.

# Syntax

```
LDM{addr_mode}{cond} Rn{!}, reglist{^}
```

where:

addr\_mode

is any one of the following:

IA

Increment address After each transfer. T	This is the default, and can be omitted.
--	--

**IB** Increment address Before each transfer (A32 only).

DA

- Decrement address After each transfer (A32 only).
- DB Decrement address Before each transfer.

You can also use the stack oriented addressing mode suffixes, for example, when implementing stacks.

#### cond

is an optional condition code.

Rn

is the *base register*, the AArch32 register holding the initial address for the transfer. *Rn* must not be PC.

!

is an optional suffix. If ! is present, the final address is written back into Rn.

reglist

is a list of one or more registers to be loaded, enclosed in braces. It can contain register ranges. It must be comma separated if it contains more than one register or register range. Any combination of registers R0 to R15 (PC) can be transferred in A32 state, but there are some restrictions in T32 state.

^

is an optional suffix, available in A32 state only. You must not use it in User mode or System mode. It has the following purposes:

- If *regList* contains the PC (R15), in addition to the normal multiple register transfer, the SPSR is copied into the CPSR. This is for returning from exception handlers. Use this only from exception modes.
- Otherwise, data is transferred into or out of the User mode registers instead of the current mode registers.

# Restrictions on reglist in 32-bit T32 instructions

In 32-bit T32 instructions:

- The SP cannot be in the list.
- The PC and LR cannot both be in the list.
- There must be two or more registers in the list.

If you write an LDM instruction with only one register in reglist, the assembler automatically substitutes the equivalent LDR instruction. Be aware of this when comparing disassembly listings with source code.

# **Restrictions on reglist in A32 instructions**

A32 load instructions can have SP and PC in the *regList* but these instructions that include SP in the *regList* or both PC and LR in the *regList* are deprecated.

#### **16-bit instructions**

16-bit versions of a subset of these instructions are available in T32 code.

The following restrictions apply to the 16-bit instructions:

- All registers in *regList* must be Lo registers.
- *Rn* must be a Lo register.
- *addr\_mode* must be omitted (or IA), meaning increment address after each transfer.
- Writeback must be specified for LDM instructions where *Rn* is not in the *regList*.

In addition, the PUSH and POP instructions are subsets of the STM and LDM instructions and can therefore be expressed using the STM and LDM instructions. Some forms of PUSH and POP are also 16-bit instructions.

#### Loading to the PC

A load to the PC causes a branch to the instruction at the address loaded.

Also:

- Bits[1:0] must not be 0b10.
- If bit[0] is 1, execution continues in T32 state.
- If bit[0] is 0, execution continues in A32 state.

#### Loading or storing the base register, with writeback

In A32 or 16-bit T32 instructions, if *Rn* is in *regList*, and writeback is specified with the ! suffix:

- If the instruction is STM{addr\_mode}{cond} and Rn is the lowest-numbered register in *regList*, the initial value of Rn is stored. These instructions are deprecated.
- Otherwise, the loaded or stored value of Rn cannot be relied on, so these instructions are not permitted.

32-bit T32 instructions are not permitted if Rn is in reglist, and writeback is specified with the ! suffix.

#### **Correct example**

LDM r8,{r0,r2,r9} ; LDMIA is a synonym for LDM

#### Incorrect example

LDMDA r2, {} ; must be at least one register in list

#### **Related references**

*C2.73 POP* on page C2-221 *C1.9 Condition code suffixes* on page C1-92

# C2.46 LDR (immediate offset)

Load with immediate offset, pre-indexed immediate offset, or post-indexed immediate offset.

# Syntax

LDR{type}{	<pre>cond} Rt, [Rn {, #offset}] ; immediate offset</pre>			
LDR{type}{	<pre>cond} Rt, [Rn, #offset]! ; pre-indexed</pre>			
LDR{type}{	<pre>cond} Rt, [Rn], #offset ; post-indexed</pre>			
LDRD{cond}	<pre>Rt, Rt2, [Rn {, #offset}] ; immediate offset, doubleword</pre>			
LDRD{cond}	<i>Rt, Rt2,</i> [ <i>Rn, #offset</i> ]! ; pre-indexed, doubleword			
LDRD{cond}	Rt, Rt2, [Rn], #offset ; post-indexed, doubleword			
where:				
type				
can	be any one of:			
В				
SB	unsigned Byte (Zero extend to 32 bits on loads.)			
	signed Byte (LDR only. Sign extend to 32 bits.)			
Н	unsigned Halfword (Zero extend to 32 bits on loads.)			
SH				
_	signed Halfword (LDR only. Sign extend to 32 bits.)			
	omitted, for Word.			
cond is an	n optional condition code.			
Rt				
1s th	is the register to load. is the register on which the memory address is based.			
is th				
offset is ar	n offset. If offset is omitted, the address is the contents of Rn.			
Rt2				
1s th	is the additional register to load for doubleword operations.			
Not all option	ns are available in every instruction set and architecture.			

#### Offset ranges and architectures

The following table shows the ranges of offsets and availability of these instructions:

#### Table C2-10 Offsets and architectures, LDR, word, halfword, and byte

Instruction	Immediate offset	Pre-indexed	Post-indexed
A32, word or byte <sup>h</sup>	-4095 to 4095	-4095 to 4095	-4095 to 4095
A32, signed byte, halfword, or signed halfword	-255 to 255	-255 to 255	-255 to 255
A32, doubleword	-255 to 255	-255 to 255	-255 to 255
T32 32-bit encoding, word, halfword, signed halfword, byte, or signed byte $^{\rm h}$	-255 to 4095	-255 to 255	-255 to 255
T32 32-bit encoding, doubleword	-1020 to 1020 <sup>i</sup>	-1020 to 1020 <sup>i</sup>	-1020 to 1020 $^{\rm i}$

#### Table C2-10 Offsets and architectures, LDR, word, halfword, and byte (continued)

Instruction	Immediate offset	Pre-indexed	Post-indexed
T32 16-bit encoding, word <sup>j</sup>	0 to 124 <sup>i</sup>	Not available	Not available
T32 16-bit encoding, unsigned halfword <sup>j</sup>	0 to 62 <sup>k</sup>	Not available	Not available
T32 16-bit encoding, unsigned byte <sup>j</sup>	0 to 31	Not available	Not available
T32 16-bit encoding, word, Rn is SP <sup>1</sup>	0 to 1020 <sup>i</sup>	Not available	Not available

#### **Register restrictions**

Rn must be different from Rt in the pre-index and post-index forms.

#### **Doubleword register restrictions**

Rn must be different from Rt2 in the pre-index and post-index forms.

For T32 instructions, you must not specify SP or PC for either Rt or Rt2.

For A32 instructions:

- *Rt* must be an even-numbered register.
- *Rt* must not be LR.
- Arm strongly recommends that you do not use R12 for Rt.
- Rt2 must be R(t + 1).

#### Use of PC

In A32 code you can use PC for Rt in LDR word instructions and PC for Rn in LDR instructions.

Other uses of PC are not permitted in these A32 instructions.

In T32 code you can use PC for Rt in LDR word instructions and PC for Rn in LDR instructions. Other uses of PC in these T32 instructions are not permitted.

#### Use of SP

You can use SP for Rn.

In A32 code, you can use SP for Rt in word instructions. You can use SP for Rt in non-word instructions in A32 code but this is deprecated.

In T32 code, you can use SP for Rt in word instructions only. All other use of SP for Rt in these instructions are not permitted in T32 code.

#### Examples

LDR r8,[r10] LDRNE r2,[r5,#960]! loads R8 from the address in R10. (conditionally) loads R2 from a word 960 bytes above the address in R5, and increments R5 by 960.

#### **Related references**

C1.9 Condition code suffixes on page C1-92

h For word loads, Rt can be the PC. A load to the PC causes a branch to the address loaded. In Armv4, bits[1:0] of the address loaded must be 0b00. In Armv5T and above, bits[1:0] must not be 0b10, and if bit[0] is 1, execution continues in T32 state, otherwise execution continues in A32 state.

Must be divisible by 4.

Rt and Rn must be in the range R0-R7.

<sup>k Must be divisible by 2.
l Rt must be in the range R0-R7.</sup>
# C2.47 LDR (PC-relative)

Load register. The address is an offset from the PC.

# Syntax

LDR{ <i>ty</i>	pe}{cond}{.W} Rt, LabeL
LDRD{ <i>c</i>	ond} Rt, Rt2, Label ; Doubleword
where: type	
	can be any one of:
	<ul> <li>B unsigned Byte (Zero extend to 32 bits on loads.)</li> <li>SB signed Byte (LDR only. Sign extend to 32 bits.)</li> </ul>
	<ul> <li>H unsigned Halfword (Zero extend to 32 bits on loads.)</li> <li>SH signed Halfword (LDR only. Sign extend to 32 bits.)</li> </ul>
cond	omitted, for Word.
. W	is an optional condition code.
Rt	is an optional instruction width specifier.
Rt2	is the register to load or store.
Label	is the second register to load or store.
	is a PC-relative expression.
	Label must be within a limited distance of the current instruction
	Note

Equivalent syntaxes are available for the STR instruction in A32 code but they are deprecated.

# Offset range and architectures

The assembler calculates the offset from the PC for you. The assembler generates an error if *LabeL* is out of range.

The following table shows the possible offsets between the label and the current instruction:

# Table C2-11 PC-relative offsets

Instruction	Offset range
A32 LDR, LDRB, LDRSB, LDRH, LDRSH <sup>m</sup>	±4095
A32 LDRD	±255

<sup>&</sup>lt;sup>m</sup> For word loads, Rt can be the PC. A load to the PC causes a branch to the address loaded. In Armv4, bits[1:0] of the address loaded must be 0b00. In Armv5T and above, bits[1:0] must not be 0b10, and if bit[0] is 1, execution continues in T32 state, otherwise execution continues in A32 state.

#### Table C2-11 PC-relative offsets (continued)

Instruction	Offset range
32-bit T32 LDR, LDRB, LDRSB, LDRH, LDRSH $^{\rm m}$	±4095
32-bit T32 LDRD <sup>n</sup>	±1020 °
16-bit T32 LDR <sup>p</sup>	0-1020 °

# LDR (PC-relative) in T32

You can use the .W width specifier to force LDR to generate a 32-bit instruction in T32 code. LDR.W always generates a 32-bit instruction, even if the target could be reached using a 16-bit LDR.

For forward references, LDR without .W always generates a 16-bit instruction in T32 code, even if that results in failure for a target that could be reached using a 32-bit T32 LDR instruction.

#### **Doubleword register restrictions**

For 32-bit T32 instructions, you must not specify SP or PC for either Rt or Rt2.

For A32 instructions:

- *Rt* must be an even-numbered register.
- Rt must not be LR.
- Arm strongly recommends that you do not use R12 for Rt.
- Rt2 must be R(t + 1).

# Use of SP

In A32 code, you can use SP for Rt in LDR word instructions. You can use SP for Rt in LDR non-word A32 instructions but this is deprecated.

In T32 code, you can use SP for Rt in LDR word instructions only. All other uses of SP in these instructions are not permitted in T32 code.

# **Related references**

C1.9 Condition code suffixes on page C1-92

In Armv7-M, LDRD (PC-relative) instructions must be on a word-aligned address.

m For word loads, Rt can be the PC. A load to the PC causes a branch to the address loaded. In Armv4, bits[1:0] of the address loaded must be 0b00. In Armv5T and above, bits[1:0] must not be 0b10, and if bit[0] is 1, execution continues in T32 state, otherwise execution continues in A32 state. n

Must be a multiple of 4.

р Rt must be in the range R0-R7. There are no byte, halfword, or doubleword 16-bit instructions.

# C2.48 LDR (register offset)

Load with register offset, pre-indexed register offset, or post-indexed register offset.

# Syntax

```
LDR{type}{cond} Rt, [Rn, ±Rm {, shift}]; register offset
LDR{type}{cond} Rt, [Rn, ±Rm {, shift}]!; pre-indexed; A32 only
LDR{type}{cond} Rt, [Rn], ±Rm {, shift}; post-indexed; A32 only
LDRD{cond} Rt, Rt2, [Rn, ±Rm]; register offset, doubleword; A32 only
LDRD{cond} Rt, Rt2, [Rn, ±Rm]!; pre-indexed, doubleword; A32 only
LDRD{cond} Rt, Rt2, [Rn], ±Rm; post-indexed, doubleword; A32 only
where:
```

type

can be any one of:

	В			
	CD.	unsigned Byte (Zero extend to 32 bits on loads.)		
	28	signed Byte (LDR only. Sign extend to 32 bits.)		
	н			
	сu	unsigned Halfword (Zero extend to 32 bits on loads.)		
	эп	signed Halfword (LDR only. Sign extend to 32 bits.)		
	-			
cond		omitted, for Word.		
cond	is an optional condition code.			
Rt	ia tha na			
Rn	is the register to load.			
	is the register on which the memory address is based.			
Rm	is a register containing a value to be used as the offset $-Pm$ is not permitted in T22 code			
shift	is a register containing a value to be used as the offsetkiii is not permitted in 152 code.			
	is an optional shift.			
Rt2	is the ad	ditional register to load for doubleword operations.		
Not all o	options a	re available in every instruction set and architecture.		

# Offset register and shift options

The following table shows the ranges of offsets and availability of these instructions:

#### Table C2-12 Options and architectures, LDR (register offsets)

Instruction	±Rm <sup>q</sup>	shift		
A32, word or byte <sup>r</sup>	±Rm	LSL #0-31	LSR #1-32	
		ASR #1-32	ROR #1-31	RRX
A32, signed byte, halfword, or signed halfword $\pm Rm$ Not available		;		
A32, doubleword	±Rm	Not available		
T32 32-bit encoding, word, halfword, signed halfword, byte, or signed byte <sup>r</sup>	+ <b>R</b> m	LSL #0-3		
T32 16-bit encoding, all except doubleword <sup>s</sup>	+Rm	Not available	;	

# **Register restrictions**

In the pre-index and post-index forms, Rn must be different from Rt.

#### **Doubleword register restrictions**

For A32 instructions:

- *Rt* must be an even-numbered register.
- *Rt* must not be LR.
- Arm strongly recommends that you do not use R12 for *Rt*.
- Rt2 must be R(t + 1).
- Rm must be different from Rt and Rt2 in LDRD instructions.
- Rn must be different from Rt2 in the pre-index and post-index forms.

# Use of PC

In A32 instructions you can use PC for Rt in LDR word instructions, and you can use PC for Rn in LDR instructions with register offset syntax (that is the forms that do not writeback to the Rn).

Other uses of PC are not permitted in A32 instructions.

In T32 instructions you can use PC for Rt in LDR word instructions. Other uses of PC in these T32 instructions are not permitted.

# Use of SP

You can use SP for Rn.

In A32 code, you can use SP for Rt in word instructions. You can use SP for Rt in non-word A32 instructions but this is deprecated.

You can use SP for Rm in A32 instructions but this is deprecated.

In T32 code, you can use SP for Rt in word instructions only. All other use of SP for Rt in these instructions are not permitted in T32 code.

Use of SP for Rm is not permitted in T32 state.

*Related references C1.9 Condition code suffixes* on page C1-92

q Where ±Rm is shown, you can use -Rm, +Rm, or Rm. Where +Rm is shown, you cannot use -Rm.

<sup>&</sup>lt;sup>r</sup> For word loads, Rt can be the PC. A load to the PC causes a branch to the address loaded. In Armv4, bits[1:0] of the address loaded must be 0b00. In Armv5T and above, bits[1:0] must not be 0b10, and if bit[0] is 1, execution continues in T32 state, otherwise execution continues in A32 state.

<sup>&</sup>lt;sup>5</sup> Rt, Rn, and Rm must all be in the range R0-R7.

#### LDR (register-relative) C2.49

Load register. The address is an offset from a base register.

# **Syntax**

LDR{ <i>typ</i>	pe}{cond}	-{.W} Rt, Label	
LDRD{ca	ond} Rt,	Rt2, Label ; Doubleword	
where:			
type			
	can be an	y one of:	
	<b>В</b> и	unsigned Byte (Zero extend to 32 bits on loads.)	
	sв К	signed Byte (LDR only. Sign extend to 32 bits.)	
	U SH S	unsigned Halfword (Zero extend to 32 bits on loads.) signed Halfword (LDR only. Sign extend to 32 bits.)	
cond	- c	omitted, for Word.	
.W	is an optio	onal condition code. onal instruction width specifier.	
Rt Rt2	is the register to load or store.		
Label	is the seco	ond register to load or store.	
	is a symbolis which is c	ol defined by the FIELD directive. <i>LabeL</i> specifies an offset from the base register defined using the MAP directive.	

LabeL must be within a limited distance of the value in the base register.

# Offset range and architectures

The assembler calculates the offset from the base register for you. The assembler generates an error if Label is out of range.

The following table shows the possible offsets between the label and the current instruction:

#### Table C2-13 Register-relative offsets

Instruction	Offset range
A32 LDR, LDRB <sup>t</sup>	±4095
A32 LDRSB, LDRH, LDRSH	±255
A32 LDRD	±255
T32, 32-bit LDR, LDRB, LDRSB, LDRH, LDRSH <sup>t</sup>	-255 to 4095

For word loads, Rt can be the PC. A load to the PC causes a branch to the address loaded. In Armv4, bits[1:0] of the address loaded must be 0b00. In Armv5T and above, bits[1:0] must not be 0b10, and if bit[0] is 1, execution continues in T32 state, otherwise execution continues in A32 state. u

Must be a multiple of 4.

# Table C2-13 Register-relative offsets (continued)

Instruction	Offset range
T32, 32-bit LDRD	±1020 <sup>u</sup>
T32, 16-bit LDR $^{v}$	0 to 124 <sup>u</sup>
T32, 16-bit LDRH $^{v}$	0 to 62 <sup>w</sup>
T32, 16-bit LDRB <sup>v</sup>	0 to 31
T32, 16-bit LDR, base register is SP <sup>x</sup>	0 to 1020 <sup>u</sup>

# LDR (register-relative) in T32

You can use the .W width specifier to force LDR to generate a 32-bit instruction in T32 code. LDR.W always generates a 32-bit instruction, even if the target could be reached using a 16-bit LDR.

For forward references, LDR without .W always generates a 16-bit instruction in T32 code, even if that results in failure for a target that could be reached using a 32-bit T32 LDR instruction.

# **Doubleword register restrictions**

For 32-bit T32 instructions, you must not specify SP or PC for either Rt or Rt2.

For A32 instructions:

- *Rt* must be an even-numbered register.
- *Rt* must not be LR.
- Arm strongly recommends that you do not use R12 for Rt.
- Rt2 must be R(t + 1).

# Use of PC

You can use PC for Rt in word instructions. Other uses of PC are not permitted in these instructions.

# Use of SP

In A32 code, you can use SP for Rt in word instructions. You can use SP for Rt in non-word A32 instructions but this is deprecated.

In T32 code, you can use SP for Rt in word instructions only. All other use of SP for Rt in these instructions are not permitted in T32 code.

# **Related references**

V Rt and base register must be in the range R0-R7.

W Must be a multiple of 2.

X Rt must be in the range R0-R7.

# C2.50 LDR, unprivileged

Unprivileged load byte, halfword, or word.

# Syntax

```
LDR{type}T{cond} Rt, [Rn {, #offset}] ; immediate offset (32-bit T32 encoding only)
LDR{type}T{cond} Rt, [Rn] {, #offset} ; post-indexed (A32 only)
LDR{type}T{cond} Rt, [Rn], ±Rm {, shift} ; post-indexed (register) (A32 only)
where:
```

type

can be any one of:

	В		
		unsigned Byte (Zero extend to 32 bits on loads.)	
	SB	signed Byte (Sign extend to 32 bits.)	
	н		
	unsigned Halfword (Zero extend to 32 bits on loads.)		
	511	signed Halfword (Sign extend to 32 bits.)	
	-	omitted for Word	
cond		onnited, for word.	
	is an optional condition code.		
Rt	is the register to load.		
Rn	is the re		
	is the re	gister on which the memory address is based.	
offset	is an off	set. If offset is omitted, the address is the value in <i>Rn</i> .	
Rm			
chift	is a register containing a value to be used as the offset. <i>Rm</i> must not be PC.		
Snift	is an opt	tional shift.	

# Operation

When these instructions are executed by privileged software, they access memory with the same restrictions as they would have if they were executed by unprivileged software.

When executed by unprivileged software these instructions behave in exactly the same way as the corresponding load instruction, for example LDRSBT behaves in the same way as LDRSB.

# Offset ranges and architectures

The following table shows the ranges of offsets and availability of these instructions.

# Table C2-14 Offsets and architectures, LDR (User mode)

Instruction	Immediate offset	Post-indexed	±Rm <sup>y</sup>	shift
A32, word or byte	Not available	-4095 to 4095	±Rm	LSL #0-31
				LSR #1-32

y You can use -Rm, +Rm, or Rm.

# Table C2-14 Offsets and architectures, LDR (User mode) (continued)

Instruction	Immediate offset	Post-indexed	±Rm <sup>y</sup>	shift
				ASR #1-32
				ROR #1-31
				RRX
A32, signed byte, halfword, or signed halfword	Not available	-255 to 255	±Rm	Not available
T32, 32-bit encoding, word, halfword, signed halfword, byte, or signed byte	0 to 255	Not available	Not av	ailable

# **Related references**

# C2.51 LDREX

Load Register Exclusive.

# Syntax

LDREX{cond} Rt, [Rn {, #offset}]

LDREXB{cond} Rt, [Rn]

LDREXH{cond} Rt, [Rn]

LDREXD{cond} Rt, Rt2, [Rn]

where:

cond	
	is an optional condition code.
Rt	
	is the register to load.
Rt2	
	is the second register for doubleword loads

Rn

is the register on which the memory address is based.

offset

is an optional offset applied to the value in *Rn. offset* is permitted only in 32-bit T32 instructions. If *offset* is omitted, an offset of zero is assumed.

# Operation

LDREX loads data from memory.

- If the physical address has the Shared TLB attribute, LDREX tags the physical address as exclusive access for the current processor, and clears any exclusive access tag for this processor for any other physical address.
- Otherwise, it tags the fact that the executing processor has an outstanding tagged physical address.

LDREXB and LDREXH zero extend the value loaded.

# Restrictions

PC must not be used for any of Rt, Rt2, or Rn.

For A32 instructions:

- SP can be used but use of SP for any of Rt, or Rt2 is deprecated.
- For LDREXD, *Rt* must be an even numbered register, and not LR.
- *Rt2* must be *R(t+1)*.
- offset is not permitted.

For T32 instructions:

- SP can be used for Rn, but must not be used for Rt or Rt2.
- For LDREXD, Rt and Rt2 must not be the same register.
- The value of offset can be any multiple of four in the range 0-1020.

# Usage

Use LDREX and STREX to implement interprocess communication in multiple-processor and sharedmemory systems. For reasons of performance, keep the number of instructions between corresponding LDREX and STREX instructions to a minimum.

\_\_\_\_\_ Note \_\_\_\_\_

The address used in a STREX instruction must be the same as the address in the most recently executed LDREX instruction.

# Architectures

These 32-bit instructions are available in A32 and T32.

The LDREXD instruction is not available in the Armv7-M architecture.

There are no 16-bit versions of these instructions in T32.

# Examples

MOV r1, #0x1	; load the 'lock taken' value
try LDREX r0, [LockAddr] CMP r0, #0 STREXEQ r0, r1, [LockAddr] CMPEQ r0, #0 BNE try	; load the lock value ; is the lock free? ; try and claim the lock ; did this succeed? ; no - try again : ves - we have the lock

#### **Related references**

# C2.52 LSL

Logical Shift Left. This instruction is a preferred synonym for MOV instructions with shifted register operands.

# Syntax

LSL{S}{cond} Rd, Rm, Rs

LSL{S}{cond} Rd, Rm, #sh

where:

s	
	is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.
Rd	
	is the destination register.
Rm	
	is the register holding the first operand. This operand is shifted left.
Rs	
	is a register holding a shift value to apply to the value in <i>Rm</i> . Only the least significant byte is used.
sh	
	is a constant shift. The range of values permitted is 0-31.

# Operation

LSL provides the value of a register multiplied by a power of two, inserting zeros into the vacated bit positions.

# **Restrictions in T32 code**

T32 instructions must not use PC or SP.

You cannot specify zero for the sh value in an LSL instruction in an IT block.

# Use of SP and PC in A32 instructions

You can use SP in these A32 instructions but this is deprecated.

You cannot use PC in instructions with the LSL{S}{cond} Rd, Rm, Rs syntax. You can use PC for Rd and Rm in the other syntax, but this is deprecated.

If you use PC as *Rm*, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, the SPSR of the current mode is copied to the CPSR. You can use this to return from exceptions.

\_\_\_\_\_ Note \_\_\_\_

The A32 instruction LSLS{*cond*} pc,Rm,#sh always disassembles to the preferred form MOVS{*cond*} pc,Rm{,shift}.

# — Caution —

Do not use the S suffix when using PC as *Rd* in User mode or System mode. The assembler cannot warn you about this because it has no information about what the processor mode is likely to be at execution time.

You cannot use PC for *Rd* or any operand in the LSL instruction if it has a register-controlled shift.

# **Condition flags**

If S is specified, the LSL instruction updates the N and Z flags according to the result.

The C flag is unaffected if the shift value is 0. Otherwise, the C flag is updated to the last bit shifted out.

# **16-bit instructions**

The following forms of these instructions are available in T32 code, and are 16-bit instructions:

- LSLS Rd, Rm, #sh Rd and Rm must both be Lo registers. This form can only be used outside an IT block.
- LSL{cond} Rd, Rm, #sh Rd and Rm must both be Lo registers. This form can only be used inside an IT block.
- LSLS *Rd*, *Rd*, *Rs Rd* and *Rs* must both be Lo registers. This form can only be used outside an IT block.
- LSL{cond} Rd, Rd, Rs Rd and Rs must both be Lo registers. This form can only be used inside an IT block.

# Architectures

This 32-bit instruction is available in A32 and T32.

This 16-bit T32 instruction is available in T32.

# Example

LSLS r1, r2, r3

# **Related references**

*C2.58 MOV* on page C2-199 *C1.9 Condition code suffixes* on page C1-92

# C2.53 LSR

Logical Shift Right. This instruction is a preferred synonym for MOV instructions with shifted register operands.

# Syntax

LSR{S}{cond} Rd, Rm, Rs

LSR{S}{cond} Rd, Rm, #sh

where:

where.	
s	
	is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.
Rd	
	is the destination register.
Rm	
	is the register holding the first operand. This operand is shifted right.
Rs	
	is a register holding a shift value to apply to the value in <i>Rm</i> . Only the least significant byte is used.
sh	
	is a constant shift. The range of values permitted is 1-32.

# Operation

LSR provides the unsigned value of a register divided by a variable power of two, inserting zeros into the vacated bit positions.

# **Restrictions in T32 code**

T32 instructions must not use PC or SP.

# Use of SP and PC in A32 instructions

You can use SP in these A32 instructions but they are deprecated.

You cannot use PC in instructions with the  $LSR{S}{cond} Rd$ , Rm, Rs syntax. You can use PC for Rd and Rm in the other syntax, but this is deprecated.

If you use PC as *Rm*, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, the SPSR of the current mode is copied to the CPSR. You can use this to return from exceptions.

---- Note -

The A32 instruction LSRS{*cond*} pc,*Rm*,*#sh* always disassembles to the preferred form MOVS{*cond*} pc,*Rm*{,shift}.

# 

Do not use the S suffix when using PC as *Rd* in User mode or System mode. The assembler cannot warn you about this because it has no information about what the processor mode is likely to be at execution time.

You cannot use PC for Rd or any operand in the LSR instruction if it has a register-controlled shift.

# **Condition flags**

If S is specified, the instruction updates the N and Z flags according to the result.

The C flag is unaffected if the shift value is 0. Otherwise, the C flag is updated to the last bit shifted out.

### **16-bit instructions**

The following forms of these instructions are available in T32 code, and are 16-bit instructions:

LSRS Rd, Rm, #sh Rd and Rm must both be Lo registers. This form can only be used outside an IT block.

LSR{cond} Rd, Rm, #sh Rd and Rm must both be Lo registers. This form can only be used inside an IT block.

- LSRS *Rd*, *Rd*, *Rs Rd* and *Rs* must both be Lo registers. This form can only be used outside an IT block.
- LSR{cond} Rd, Rd, Rs Rd and Rs must both be Lo registers. This form can only be used inside an IT block.

# Architectures

This 32-bit instruction is available in A32 and T32.

This 16-bit T32 instruction is available in T32.

# Example

LSR r4, r5, r6

*Related references C2.58 MOV* on page C2-199 *C1.9 Condition code suffixes* on page C1-92

#### C2 A32 and T32 Instructions C2.54 MCR and MCR2

# C2.54 MCR and MCR2

Move to Coprocessor from general-purpose register. Depending on the coprocessor, you might be able to specify various additional operations.

\_\_\_\_\_ Note \_\_\_\_\_

MCR2 is not supported in Armv8.

### **Syntax**

MCR{cond} coproc, #opcode1, Rt, CRn, CRm{, #opcode2}
MCR2{cond} coproc, #opcode1, Rt, CRn, CRm{, #opcode2}

where: cond

is an optional condition code.

In A32 code, cond is not permitted for MCR2.

#### coproc

is the name of the coprocessor the instruction is for. The standard name is pn, where n is an integer whose value must be:

- In the range 0-15 in Armv7 and earlier.
- 14 or 15 in Armv8.

#### opcode1

is a 3-bit coprocessor-specific opcode.

opcode2

is an optional 3-bit coprocessor-specific opcode.

Rt

is a general-purpose register. Rt must not be PC.

CRn, CRm

are coprocessor registers.

# Usage

The use of these instructions depends on the coprocessor. See the coprocessor documentation for details.

# Architectures

These 32-bit instructions are available in A32 and T32.

There are no 16-bit versions of these instructions in T32.

**Related references** 

# C2.55 MCRR and MCRR2

Move to Coprocessor from two general-purpose registers. Depending on the coprocessor, you might be able to specify various additional operations.

\_\_\_\_\_ Note \_\_\_\_\_

MCRR2 is not supported in Armv8.

# **Syntax**

MCRR{cond} coproc, #opcode, Rt, Rt2, CRn
MCRR2{cond} coproc, #opcode, Rt, Rt2, CRn

where: cond

is an optional condition code.

In A32 code, cond is not permitted for MCRR2.

#### coproc

is the name of the coprocessor the instruction is for. The standard name is pn, where n is an integer whose value must be:

- In the range 0-15 in Armv7 and earlier.
- 14 or 15 in Armv8.

#### opcode

is a 4-bit coprocessor-specific opcode.

#### Rt, Rt2

are general-purpose registers. Rt and Rt2 must not be PC.

CRn

is a coprocessor register.

# Usage

The use of these instructions depends on the coprocessor. See the coprocessor documentation for details.

# Architectures

These 32-bit instructions are available in A32 and T32.

There are no 16-bit versions of these instructions in T32.

# **Related references**

# C2.56 MLA

Multiply-Accumulate with signed or unsigned 32-bit operands, giving the least significant 32 bits of the result.

# Syntax

MLA{S}{cond} Rd, Rn, Rm, Ra

where:

cond

is an optional condition code.

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

Rd

is the destination register.

Rn, Rm

are registers holding the values to be multiplied.

Ra

is a register holding the value to be added.

# Operation

The MLA instruction multiplies the values from Rn and Rm, adds the value from Ra, and places the least significant 32 bits of the result in Rd.

# **Register restrictions**

You cannot use PC for any register.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

If S is specified, the MLA instruction:

- Updates the N and Z flags according to the result.
- Does not affect the C or V flag.

# Architectures

This instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# Example

MLA r10, r2, r1, r5

**Related references** C1.9 Condition code suffixes on page C1-92

# C2.57 MLS

Multiply-Subtract, with signed or unsigned 32-bit operands, giving the least significant 32 bits of the result.

# Syntax

MLS{cond} Rd, Rn, Rm, Ra

where:

cond

is an optional condition code.

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

Rd

is the destination register.

Rn, Rm

are registers holding the values to be multiplied.

Ra

is a register holding the value to be subtracted from.

# Operation

The MLS instruction multiplies the values in Rn and Rm, subtracts the result from the value in Ra, and places the least significant 32 bits of the final result in Rd.

# **Register restrictions**

You cannot use PC for any register.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# Architectures

This instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# Example

MLS r4, r5, r6, r7

**Related references** 

# C2.58 MOV

Move.

# Syntax

MOV{S}{cond} Rd, Operand2

MOV{cond} Rd, #imm16

where:

# S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

# Rd

is the destination register.

# Operand2

is a flexible second operand.

imm16

is any value in the range 0-65535.

# Operation

The MOV instruction copies the value of Operand2 into Rd.

In certain circumstances, the assembler can substitute MVN for MOV, or MOV for MVN. Be aware of this when reading disassembly listings.

# Use of PC and SP in 32-bit T32 encodings

You cannot use PC (R15) for *Rd*, or in *Operand2*, in 32-bit T32 MOV instructions. With the following exceptions, you cannot use SP (R13) for *Rd*, or in *Operand2*:

- MOV{cond}.W Rd, SP, where Rd is not SP.
- MOV{cond}.W SP, Rm, where Rm is not SP.

# Use of PC and SP in 16-bit T32 encodings

You can use PC or SP in 16-bit T32 MOV{cond} Rd, Rm instructions but these instructions in which both Rd and Rm are SP or PC are deprecated.

You cannot use PC or SP in any other MOV{S} 16-bit T32 instructions.

# Use of PC and SP in A32 MOV

You cannot use PC for *Rd* or any operand in any data processing instruction that has a register-controlled shift.

In instructions without register-controlled shift, the use of PC is deprecated except for the following cases:

- MOVS PC, LR.
- MOV PC, Rm when Rm is not PC or SP.
- MOV Rd, PC when Rd is not PC or SP.

You can use SP for Rd or Rm. But this is deprecated except for the following cases:

- MOV SP, Rm when Rm is not PC or SP.
- MOV Rd, SP when Rd is not PC or SP.

— Note –

• You cannot use PC for Rd in MOV Rd, #imm16 if the #imm16 value is not a permitted Operand2 value. You can use PC in forms with Operand2 without register-controlled shift.

If you use PC as *Rm*, the value used is the address of the instruction plus 8.

If you use PC as Rd:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, lr instruction.

# **Condition flags**

If S is specified, the instruction:

- Updates the N and Z flags according to the result.
- Can update the C flag during the calculation of *Operand2*.
- Does not affect the V flag.

#### **16-bit instructions**

The following forms of this instruction are available in T32 code, and are 16-bit instructions:

#### MOVS Rd, #imm

Rd must be a Lo register. imm range 0-255. This form can only be used outside an IT block.

MOV{cond} Rd, #imm

Rd must be a Lo register. imm range 0-255. This form can only be used inside an IT block.

MOVS Rd, Rm

Rd and Rm must both be Lo registers. This form can only be used outside an IT block.

#### MOV{cond} Rd, Rm

Rd or Rm can be Lo or Hi registers.

# Availability

These instructions are available in A32 and T32.

In T32, 16-bit and 32-bit versions of these instructions are available.

#### **Related references**

*C2.3 Flexible second operand (Operand2)* on page C2-112 *C2.144 SUBS pc, lr* on page C2-317 *C1.9 Condition code suffixes* on page C1-92

# C2.59 MOVT

Move Top.

# Syntax

MOVT{cond} Rd, #imm16 where: cond is an optional condition code. Rd is the destination register. imm16 is a 16-bit immediate value.

# Usage

MOVT writes *imm16* to *Rd*[31:16], without affecting *Rd*[15:0].

You can generate any 32-bit immediate with a MOV, MOVT instruction pair.

# **Register restrictions**

You cannot use PC in A32 or T32 instructions.

You can use SP for Rd in A32 instructions but this is deprecated.

You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

# Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.60 MRC and MRC2

Move to general-purpose register from Coprocessor. Depending on the coprocessor, you might be able to specify various additional operations.

\_\_\_\_\_ Note \_\_\_\_\_

MRC2 is not supported in Armv8.

### **Syntax**

MRC{cond} coproc, #opcode1, Rt, CRn, CRm{, #opcode2}
MRC2{cond} coproc, #opcode1, Rt, CRn, CRm{, #opcode2}

where: cond

is an optional condition code.

In A32 code, cond is not permitted for MRC2.

#### coproc

is the name of the coprocessor the instruction is for. The standard name is pn, where n is an integer whose value must be:

- In the range 0-15 in Armv7 and earlier.
- 14 or 15 in Armv8.

#### opcode1

is a 3-bit coprocessor-specific opcode.

#### opcode2

is an optional 3-bit coprocessor-specific opcode.

Rt

is the general-purpose register. Rt must not be PC.

*Rt* can be APSR\_nzcv. This means that the coprocessor executes an instruction that changes the value of the condition flags in the APSR.

CRn, CRm

are coprocessor registers.

# Usage

The use of these instructions depends on the coprocessor. See the coprocessor documentation for details.

# Architectures

These 32-bit instructions are available in A32 and T32.

There are no 16-bit versions of these instructions in T32.

#### **Related references**

# C2.61 MRRC and MRRC2

Move to two general-purpose registers from coprocessor. Depending on the coprocessor, you might be able to specify various additional operations.

\_\_\_\_\_ Note \_\_\_\_\_

MRRC2 is not supported in Armv8.

### **Syntax**

MRRC{cond} coproc, #opcode, Rt, Rt2, CRm
MRRC2{cond} coproc, #opcode, Rt, Rt2, CRm

where: cond

is an optional condition code.

In A32 code, cond is not permitted for MRRC2.

#### coproc

is the name of the coprocessor the instruction is for. The standard name is pn, where n is an integer whose value must be:

- In the range 0-15 in Armv7 and earlier.
- 14 or 15 in Armv8.

#### opcode

is a 4-bit coprocessor-specific opcode.

#### Rt, Rt2

are general-purpose registers. Rt and Rt2 must not be PC.

CRm

is a coprocessor register.

# Usage

The use of these instructions depends on the coprocessor. See the coprocessor documentation for details.

# Architectures

These 32-bit instructions are available in A32 and T32.

There are no 16-bit versions of these instructions in T32.

# **Related references**

# C2.62 MRS (PSR to general-purpose register)

Move the contents of a PSR to a general-purpose register.

	Syntax	Syntax		
	MRS{co	RS{cond} Rd, psr		
where:				
	cond			
	is an optional condition code.			
	Rd	is the d	actination register	
	psr	is the d	estimation register.	
		is one of		
		APSK	on any processor, in any mode.	
		CPSR	, , , , , , , , , , , , , , , , , , ,	
			deprecated synonym for APSR and for use in Debug state, on any processor except	
		SPSR	Almv /-Ivi and Almvo-Ivi.	
			on any processor, except Armv6-M, Armv7-M, Armv8-M Baseline, and Armv8-M	
			Mainline, in privileged software execution only.	
		Mpsr	on Army6-M Army7-M Army8-M Baseline and Army8-M Mainline processors only	
	Mpsr		on Annvo-wi, Annv /-wi, Annvo-wi Dasenne, and Annvo-wi Mainine processors only.	
		can be any of: IPSR, EPSR, IEPSR, IAPSR, EAPSR, MSP, PSP, XPSR, PRIMASK, BASEPRI,		
		BASEPRI_MAX, FAULTMASK, or CONTROL.		

# Usage

Use MRS in combination with MSR as part of a read-modify-write sequence for updating a PSR, for example to change processor mode, or to clear the Q flag.

In process swap code, the programmers' model state of the process being swapped out must be saved, including relevant PSR contents. Similarly, the state of the process being swapped in must also be restored. These operations make use of MRS/store and load/MSR instruction sequences.

# SPSR

You must not attempt to access the SPSR when the processor is in User or System mode. This is your responsibility. The assembler cannot warn you about this, because it has no information about the processor mode at execution time.

# CPSR

Arm deprecates reading the CPSR endianness bit (E) with an MRS instruction.

The CPSR execution state bits, other than the E bit, can only be read when the processor is in Debug state, halting debug-mode. Otherwise, the execution state bits in the CPSR read as zero.

The condition flags can be read in any mode on any processor. Use APSR if you are only interested in accessing the condition flags in User mode.

# **Register restrictions**

You cannot use PC for Rd in A32 instructions. You can use SP for Rd in A32 instructions but this is deprecated.

You cannot use PC or SP for Rd in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

# Architectures

This instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# **Related concepts**

A1.13 Current Program Status Register in AArch32 state on page A1-39 **Related references** C2.63 MRS (system coprocessor register to general-purpose register) on page C2-206 C2.64 MSR (general-purpose register to system coprocessor register) on page C2-207 C2.65 MSR (general-purpose register to PSR) on page C2-208 C1.9 Condition code suffixes on page C1-92

#### C2.63 MRS (system coprocessor register to general-purpose register)

Move to general-purpose register from system coprocessor register.

# **Syntax**

```
MRS{cond} Rn, coproc_register
MRS{cond} APSR nzcv, special register
where:
cond
        is an optional condition code.
coproc register
        is the name of the coprocessor register.
special register
        is the name of the coprocessor register that can be written to APSR nzcv. This is only possible
        for the coprocessor register DBGDSCRint.
Rn
```

is the general-purpose register. Rn must not be PC.

#### Usage

You can use this pseudo-instruction to read CP14 or CP15 coprocessor registers, with the exception of write-only registers. A complete list of the applicable coprocessor register names is in the Arm®v7-AR Architecture Reference Manual. For example:

MRS R1, SCTLR ; writes the contents of the CP15 coprocessor ; register SCTLR into R1

# **Architectures**

This pseudo-instruction is available in Armv7-A and Armv7-R in A32 and 32-bit T32 code.

There is no 16-bit version of this pseudo-instruction in T32.

# **Related references**

```
C2.62 MRS (PSR to general-purpose register) on page C2-204
C2.64 MSR (general-purpose register to system coprocessor register) on page C2-207
C2.65 MSR (general-purpose register to PSR) on page C2-208
C1.9 Condition code suffixes on page C1-92
Related information
Arm Architecture Reference Manual
```

# C2.64 MSR (general-purpose register to system coprocessor register)

Move to system coprocessor register from general-purpose register.

# Syntax

```
MSR{cond} coproc_register, Rn
```

where:

cond

is an optional condition code.

coproc\_register

is the name of the coprocessor register.

Rn

is the general-purpose register. Rn must not be PC.

# Usage

You can use this pseudo-instruction to write to any CP14 or CP15 coprocessor writable register. A complete list of the applicable coprocessor register names is in the *Arm Architecture Reference Manual*. For example:

MSR SCTLR, R1 ; writes the contents of R1 into the CP15 ; coprocessor register SCTLR

# Availability

This pseudo-instruction is available in A32 and T32.

This pseudo-instruction is available in Armv7-A and Armv7-R in A32 and 32-bit T32 code.

There is no 16-bit version of this pseudo-instruction in T32.

# **Related references**

C2.62 MRS (PSR to general-purpose register) on page C2-204 C2.63 MRS (system coprocessor register to general-purpose register) on page C2-206 C2.65 MSR (general-purpose register to PSR) on page C2-208 C1.9 Condition code suffixes on page C1-92 C2.153 SYS on page C2-332 **Related information** Arm Architecture Reference Manual

# C2.65 MSR (general-purpose register to PSR)

Load an immediate value, or the contents of a general-purpose register, into the specified fields of a Program Status Register (PSR).

# Syntax

MSR{cond} APSR\_flags, Rm

where:

cond

is an optional condition code.

flags

specifies the APSR flags to be moved. *flags* can be one or more of:

nzcvq

g

ALU flags field mask, PSR[31:27] (User mode)

SIMD GE flags field mask, PSR[19:16] (User mode).

Rm

is the general-purpose register. Rm must not be PC.

# Syntax on architectures other than Armv6-M, Armv7-M, Armv8-M Baseline, and Armv8-M Mainline

MSR{cond}	APSR flags,	#constant

MSR{cond} psr\_fields, #constant

MSR{cond} psr\_fields, Rm

where:

# cond

is an optional condition code.

#### flags

specifies the APSR flags to be moved. *flags* can be one or more of:

# nzcvq

ALU flags field mask, PSR[31:27] (User mode)

g

SIMD GE flags field mask, PSR[19:16] (User mode).

#### constant

is an expression evaluating to a numeric value. The value must correspond to an 8-bit pattern rotated by an even number of bits within a 32-bit word. Not available in T32.

# Rm

is the source register. Rm must not be PC.

# psr

is one of:

# CPSR

for use in Debug state, also deprecated synonym for APSR

SPSR

on any processor, in privileged software execution only.

# fields

specifies the SPSR or CPSR fields to be moved. *fields* can be one or more of:

с

control field mask byte, PSR[7:0] (privileged software execution)

- extension field mask byte, PSR[15:8] (privileged software execution)
- status field mask byte, PSR[23:16] (privileged software execution)
  - flags field mask byte, PSR[31:24] (privileged software execution).

# Syntax on architectures Armv6-M, Armv7-M, Armv8-M Baseline, and Armv8-M Mainline only

MSR{cond} psr, Rm
where:

х

s

f

cond

Rm

is the source register. Rm must not be PC.

is an optional condition code.

psr

can be any of: APSR, IPSR, EPSR, IEPSR, IAPSR, EAPSR, XPSR, MSP, PSP, PRIMASK, BASEPRI, BASEPRI\_MAX, FAULTMASK, or CONTROL.

# Usage

In User mode:

- Use APSR to access the condition flags, Q, or GE bits.
- Writes to unallocated, privileged or execution state bits in the CPSR are ignored. This ensures that User mode programs cannot change to privileged software execution.

Arm deprecates using MSR to change the endianness bit (E) of the CPSR, in any mode.

You must not attempt to access the SPSR when the processor is in User or System mode.

# **Register restrictions**

You cannot use PC in A32 instructions. You can use SP for Rm in A32 instructions but this is deprecated.

You cannot use PC or SP in T32 instructions.

# **Condition flags**

This instruction updates the flags explicitly if the APSR\_nzcvq or CPSR\_f field is specified.

# Architectures

This instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# **Related references**

C2.62 MRS (PSR to general-purpose register) on page C2-204 C2.63 MRS (system coprocessor register to general-purpose register) on page C2-206 C2.64 MSR (general-purpose register to system coprocessor register) on page C2-207 C1.9 Condition code suffixes on page C1-92

# C2.66 MUL

Multiply with signed or unsigned 32-bit operands, giving the least significant 32 bits of the result.

# Syntax

MUL{S}{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

Rd

is the destination register.

Rn, Rm

are registers holding the values to be multiplied.

# Operation

The MUL instruction multiplies the values from Rn and Rm, and places the least significant 32 bits of the result in Rd.

# **Register restrictions**

You cannot use PC for any register.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

If  ${\sf S}$  is specified, the MUL instruction:

- Updates the N and Z flags according to the result.
- Does not affect the C or V flag.

# **16-bit instructions**

The following forms of the MUL instruction are available in T32 code, and are 16-bit instructions:

MULS Rd, Rn, Rd

Rd and Rn must both be Lo registers. This form can only be used outside an IT block.

MUL{cond} Rd, Rn, Rd

Rd and Rn must both be Lo registers. This form can only be used inside an IT block.

There are no other T32 multiply instructions that can update the condition flags.

# Availability

This instruction is available in A32 and T32.

The MULS instruction is available in T32 in a 16-bit encoding.

# Examples

MUL r10, r2, r5 MULS r0, r2, r2 MULLT r2, r3, r2

# **Related references**

# C2.67 MVN

Move Not.

# Syntax

MVN{S}{cond} Rd, Operand2

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

Rd

is the destination register.

Operand2

is a flexible second operand.

# Operation

The MVN instruction takes the value of *Operand2*, performs a bitwise logical NOT operation on the value, and places the result into *Rd*.

In certain circumstances, the assembler can substitute MVN for MOV, or MOV for MVN. Be aware of this when reading disassembly listings.

# Use of PC and SP in 32-bit T32 MVN

You cannot use PC (R15) for *Rd*, or in *Operand2*, in 32-bit T32 MVN instructions. You cannot use SP (R13) for *Rd*, or in *Operand2*.

# Use of PC and SP in 16-bit T32 instructions

You cannot use PC or SP in any MVN{S} 16-bit T32 instructions.

# Use of PC and SP in A32 MVN

You cannot use PC for *Rd* or any operand in any data processing instruction that has a register-controlled shift.

In instructions without register-controlled shift, use of PC is deprecated.

You can use SP for Rd or Rm, but this is deprecated.

—— Note —

• PC and SP in A32 instructions are deprecated.

If you use PC as *Rm*, the value used is the address of the instruction plus 8.

If you use PC as Rd:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, lr instruction.

# Condition flags

If S is specified, the instruction:

- Updates the N and Z flags according to the result.
- Can update the C flag during the calculation of *Operand2*.
- Does not affect the V flag.

# **16-bit instructions**

The following forms of this instruction are available in T32 code, and are 16-bit instructions:

MVNS Rd, Rm

*Rd* and *Rm* must both be Lo registers. This form can only be used outside an IT block.

#### MVN{cond} Rd, Rm

Rd and Rm must both be Lo registers. This form can only be used inside an IT block.

# Architectures

This instruction is available in A32 and T32.

#### **Correct example**

MVNNE r11, #0xF000000B ; A32 only. This immediate value is not ; available in T32.

### Incorrect example

MVN pc,r3,ASR r0

; PC not permitted with ; register-controlled shift

#### **Related references**

C2.3 Flexible second operand (Operand2) on page C2-112 C2.144 SUBS pc, lr on page C2-317 C1.9 Condition code suffixes on page C1-92

# C2.68 NOP

No Operation.

# Syntax

 $NOP{cond}$ 

where:

cond

is an optional condition code.

# Usage

NOP does nothing. If NOP is not implemented as a specific instruction on your target architecture, the assembler treats it as a pseudo-instruction and generates an alternative instruction that does nothing, such as MOV r0, r0 (A32) or MOV r8, r8 (T32).

NOP is not necessarily a time-consuming NOP. The processor might remove it from the pipeline before it reaches the execution stage.

You can use NOP for padding, for example to place the following instruction on a 64-bit boundary in A32, or a 32-bit boundary in T32.

# Architectures

This instruction is available in A32 and T32.

**Related references** 

# C2.69 ORN (T32 only)

Logical OR NOT.

# Syntax

ORN{S}{cond} Rd, Rn, Operand2

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

is the destination register.

Rn

Rd

is the register holding the first operand.

Operand2

is a flexible second operand.

# Operation

The ORN T32 instruction performs an OR operation on the bits in *Rn* with the complements of the corresponding bits in the value of *Operand2*.

In certain circumstances, the assembler can substitute ORN for ORR, or ORR for ORN. Be aware of this when reading disassembly listings.

# Use of PC

You cannot use PC (R15) for Rd or any operand in the ORN instruction.

# **Condition flags**

If S is specified, the ORN instruction:

- Updates the N and Z flags according to the result.
- Can update the C flag during the calculation of *Operand2*.
- Does not affect the V flag.

# Examples

ORN r7, r11, lr, ROR #4 ORNS r7, r11, lr, ASR #32

# Architectures

This 32-bit instruction is available in T32.

There is no A32 or 16-bit T32 ORN instruction.

# **Related references**

*C2.3 Flexible second operand (Operand2)* on page C2-112 *C2.144 SUBS pc, lr* on page C2-317 *C1.9 Condition code suffixes* on page C1-92

# C2.70 ORR

Logical OR.

# Syntax

ORR{S}{cond} Rd, Rn, Operand2

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

is the destination register.

Rn

Rd

is the register holding the first operand.

Operand2

is a flexible second operand.

# Operation

The ORR instruction performs bitwise OR operations on the values in Rn and Operand2.

In certain circumstances, the assembler can substitute ORN for ORR, or ORR for ORN. Be aware of this when reading disassembly listings.

# Use of PC in 32-bit T32 instructions

You cannot use PC (R15) for Rd or any operand with the ORR instruction.

# Use of PC and SP in A32 instructions

You can use PC and SP with the ORR instruction but this is deprecated.

If you use PC as Rn, the value used is the address of the instruction plus 8.

If you use PC as Rd:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, 1r instruction.

You cannot use PC for any operand in any data processing instruction that has a register-controlled shift.

# **Condition flags**

If S is specified, the ORR instruction:

- Updates the N and Z flags according to the result.
- Can update the C flag during the calculation of *Operand2*.
- Does not affect the V flag.

# **16-bit instructions**

The following forms of the ORR instruction are available in T32 code, and are 16-bit instructions:

ORRS Rd, Rd, Rm

*Rd* and *Rm* must both be Lo registers. This form can only be used outside an IT block.

# ORR{cond} Rd, Rd, Rm

*Rd* and *Rm* must both be Lo registers. This form can only be used inside an IT block.

It does not matter if you specify ORR{S} Rd, Rm, Rd. The instruction is the same.

# Example

ORREQ r2,r0,r5

Related references

C2.3 Flexible second operand (Operand2) on page C2-112 C2.144 SUBS pc, lr on page C2-317 C1.9 Condition code suffixes on page C1-92
# C2.71 PKHBT and PKHTB

Halfword Packing instructions that combine a halfword from one register with a halfword from another register. One of the operands can be shifted before extraction of the halfword.

#### Syntax

PKHBT{cond} {Rd}, Rn, Rm{, LSL #Leftshift}
PKHTB{cond} {Rd}, Rn, Rm{, ASR #rightshift}

where:

#### РКНВТ

Combines bits[15:0] of Rn with bits[31:16] of the shifted value from Rm.

#### РКНТВ

Combines bits[31:16] of Rn with bits[15:0] of the shifted value from Rm.

#### cond

is an optional condition code.

#### Rd

is the destination register.

#### Rn

is the register holding the first operand.

#### Rm

is the register holding the first operand.

#### Leftshift

is in the range 0 to 31.

#### rightshift

is in the range 1 to 32.

#### **Register restrictions**

You cannot use PC for any register.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

These instructions do not change the flags.

#### Architectures

These instructions are available in A32.

These 32-bit instructions are available T32. For the Armv7-M architecture, they are only available in an Armv7E-M implementation.

There are no 16-bit versions of these instructions in T32.

#### **Correct examples**

```
PKHBTr0, r3, r5; combine the bottom halfword of R3; with the top halfword of R5PKHBTr0, r3, r5, LSL #16; with the bottom halfword of R3; with the bottom halfword of R5
```

PKHTB r0, r3, r5, ASR #16 ; combine the top halfword of R3 ; with the top halfword of R5  $\,$ 

You can also scale the second operand by using different values of shift.

#### Incorrect example

PKHBTEQ r4, r5, r1, ASR #8 ; ASR not permitted with PKHBT

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.72 PLD, PLDW, and PLI

Preload Data and Preload Instruction allow the processor to signal the memory system that a data or instruction load from an address is likely in the near future.

#### Syntax

PLtype{cond} [Rn {, #offset}]

PLtype{cond} [Rn, ±Rm {, shift}]

PLtype{cond} label

where:

#### type

can be one of:

#### D

Data address.

#### DW

Data address with intention to write.

#### Ι

Instruction address.

type cannot be DW if the syntax specifies LabeL.

#### cond

is an optional condition code.

#### \_\_\_\_\_ Note \_\_\_\_\_

*cond* is permitted only in T32 code, using a preceding IT instruction, but this is deprecated in the Armv8 architecture. This is an unconditional instruction in A32 code and you must not use *cond*.

#### Rn

is the register on which the memory address is based.

#### offset

is an immediate offset. If offset is omitted, the address is the value in Rn.

#### Rm

is a register containing a value to be used as the offset.

#### shift

is an optional shift.

Label

is a PC-relative expression.

#### Range of offsets

The offset is applied to the value in *Rn* before the preload takes place. The result is used as the memory address for the preload. The range of offsets permitted is:

- -4095 to +4095 for A32 instructions.
- -255 to +4095 for T32 instructions, when *Rn* is not PC.
  - -4095 to +4095 for T32 instructions, when Rn is PC.

The assembler calculates the offset from the PC for you. The assembler generates an error if *LabeL* is out of range.

#### Register or shifted register offset

In A32 code, the value in Rm is added to or subtracted from the value in Rn. In T32 code, the value in Rm can only be added to the value in Rn. The result is used as the memory address for the preload.

The range of shifts permitted is:

- LSL #0 to #3 for T32 instructions.
- Any one of the following for A32 instructions:
  - LSL #0 to #31.
  - LSR #1 to #32.
  - ASR #1 to #32.
  - ROR #1 to #31.
  - RRX.

#### Address alignment for preloads

No alignment checking is performed for preload instructions.

#### **Register restrictions**

Rm must not be PC. For T32 instructions Rm must also not be SP.

Rn must not be PC for T32 instructions of the syntax PLtype{cond} [Rn, ±Rm{, #shift}].

#### Architectures

The PLD instruction is available in A32.

The 32-bit encoding of PLD is available in T32.

PLDW is available only in the Armv7 architecture and above that implement the Multiprocessing Extensions.

PLI is available only in the Armv7 architecture and above.

There are no 16-bit encodings of these instructions in T32.

These are hint instructions, and their implementation is optional. If they are not implemented, they execute as NOPs.

#### **Related references**

C1.9 Condition code suffixes on page C1-92

# C2.73 POP

Pop registers off a full descending stack.

#### Syntax

POP{cond} reglist

where:

cond

is an optional condition code.

reglist

is a non-empty list of registers, enclosed in braces. It can contain register ranges. It must be comma separated if it contains more than one register or register range.

#### Operation

POP is a synonym for LDMIA sp! reglist. POP is the preferred mnemonic.

----- Note -----

 ${\tt LDM}$  and  ${\tt LDMFD}$  are synonyms of  ${\tt LDMIA}.$ 

Registers are stored on the stack in numerical order, with the lowest numbered register at the lowest address.

## POP, with reglist including the PC

This instruction causes a branch to the address popped off the stack into the PC. This is usually a return from a subroutine, where the LR was pushed onto the stack at the start of the subroutine.

Also:

- Bits[1:0] must not be 0b10.
- If bit[0] is 1, execution continues in T32 state.
- If bit[0] is 0, execution continues in A32 state.

## **T32 instructions**

A subset of this instruction is available in the T32 instruction set.

The following restriction applies to the 16-bit POP instruction:

• *reglist* can only include the Lo registers and the PC.

The following restrictions apply to the 32-bit POP instruction:

- reglist must not include the SP.
- reglist can include either the LR or the PC, but not both.

#### **Restrictions on reglist in A32 instructions**

The A32 POP instruction cannot have SP but can have PC in the *regList*. The instruction that includes both PC and LR in the *regList* is deprecated.

#### Example

POP {r0,r10,pc} ; no 16-bit version available

*Related references C2.45 LDM* on page C2-177 *C2.74 PUSH* on page C2-222 *C1.9 Condition code suffixes* on page C1-92

# C2.74 PUSH

Push registers onto a full descending stack.

#### Syntax

PUSH{cond} reglist

where:

cond

is an optional condition code.

reglist

is a non-empty list of registers, enclosed in braces. It can contain register ranges. It must be comma separated if it contains more than one register or register range.

#### Operation

PUSH is a synonym for STMDB sp!, reglist. PUSH is the preferred mnemonic.

**\_\_\_\_\_ Note \_\_\_\_\_** STMFD is a synonym of STMDB.

Registers are stored on the stack in numerical order, with the lowest numbered register at the lowest address.

## **T32 instructions**

The following restriction applies to the 16-bit PUSH instruction:

• *regList* can only include the Lo registers and the LR.

The following restrictions apply to the 32-bit PUSH instruction:

- reglist must not include the SP.
- *regList* must not include the PC.

## **Restrictions on reglist in A32 instructions**

The A32 PUSH instruction can have SP and PC in the *regList* but the instruction that includes SP or PC in the *regList* is deprecated.

#### Examples

PUSH {r0,r4-r7} PUSH {r2,lr}

**Related references** 

*C2.45 LDM* on page C2-177 *C2.73 POP* on page C2-221 *C1.9 Condition code suffixes* on page C1-92

# C2.75 QADD

Signed saturating addition.

#### Syntax

QADD{cond} {Rd}, Rm, Rn

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the registers holding the operands.

## Operation

The QADD instruction adds the values in *Rm* and *Rn*. It saturates the result to the signed range  $-2^{31} \le x \le 2^{31}-1$ .

\_\_\_\_\_ Note \_\_\_\_\_

All values are treated as two's complement signed integers by this instruction.

#### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# Q flag

If saturation occurs, this instruction sets the Q flag. To read the state of the Q flag, use an MRS instruction.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## Example

QADD r0, r1, r9

**Related references** 

C2.62 MRS (PSR to general-purpose register) on page C2-204 A1.11 The Q flag in AArch32 state on page A1-37 C1.9 Condition code suffixes on page C1-92

# C2.76 QADD8

Signed saturating parallel byte-wise addition.

#### Syntax

QADD8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction performs four signed integer additions on the corresponding bytes of the operands and writes the results into the corresponding bytes of the destination. It saturates the results to the signed range  $-2^7 \le x \le 2^7 - 1$ . The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.77 QADD16

Signed saturating parallel halfword-wise addition.

#### Syntax

QADD16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction performs two signed integer additions on the corresponding halfwords of the operands and writes the results into the corresponding halfwords of the destination. It saturates the results to the signed range  $-2^{15} \le x \le 2^{15} - 1$ . The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.78 QASX

Signed saturating parallel add and subtract halfwords with exchange.

#### Syntax

QASX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction exchanges the two halfwords of the second operand, then performs an addition on the two top halfwords of the operands and a subtraction on the bottom two halfwords. It writes the results into the corresponding halfwords of the destination. It saturates the results to the signed range  $-2^{15} \le x \le 2^{15}$  -1. The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.79 QDADD

Signed saturating Double and Add.

#### Syntax

QDADD{cond} {Rd}, Rm, Rn

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

## Operation

QDADD calculates SAT(Rm + SAT(Rn \* 2)). It saturates the result to the signed range  $-2^{31} \le x \le 2^{31}-1$ . Saturation can occur on the doubling operation, on the addition, or on both. If saturation occurs on the doubling but not on the addition, the Q flag is set but the final result is unsaturated.

\_\_\_\_\_ Note \_\_\_\_\_

All values are treated as two's complement signed integers by this instruction.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# Q flag

If saturation occurs, this instruction sets the Q flag. To read the state of the Q flag, use an MRS instruction.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

A1.11 The Q flag in AArch32 state on page A1-37 C2.62 MRS (PSR to general-purpose register) on page C2-204 C1.9 Condition code suffixes on page C1-92

# C2.80 QDSUB

Signed saturating Double and Subtract.

#### Syntax

QDSUB{cond} {Rd}, Rm, Rn

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

## Operation

QDSUB calculates SAT(Rm - SAT(Rn \* 2)). It saturates the result to the signed range  $-2^{31} \le x \le 2^{31}-1$ . Saturation can occur on the doubling operation, on the subtraction, or on both. If saturation occurs on the doubling but not on the subtraction, the Q flag is set but the final result is unsaturated.

\_\_\_\_\_ Note \_\_\_\_\_

All values are treated as two's complement signed integers by this instruction.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# Q flag

If saturation occurs, this instruction sets the Q flag. To read the state of the Q flag, use an MRS instruction.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## Example

QDSUBLT r9, r0, r1

#### **Related references**

A1.11 The Q flag in AArch32 state on page A1-37 C2.62 MRS (PSR to general-purpose register) on page C2-204 C1.9 Condition code suffixes on page C1-92

# C2.81 QSAX

Signed saturating parallel subtract and add halfwords with exchange.

#### Syntax

QSAX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction exchanges the two halfwords of the second operand, then performs a subtraction on the two top halfwords of the operands and an addition on the bottom two halfwords. It writes the results into the corresponding halfwords of the destination. It saturates the results to the signed range  $-2^{15} \le x \le 2^{15}$ -1. The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.82 QSUB

Signed saturating Subtract.

#### Syntax

QSUB{cond} {Rd}, Rm, Rn

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

The QSUB instruction subtracts the value in *Rn* from the value in *Rm*. It saturates the result to the signed range  $-2^{31} \le x \le 2^{31}-1$ .

\_\_\_\_\_ Note \_\_\_\_\_

All values are treated as two's complement signed integers by this instruction.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# Q flag

If saturation occurs, this instruction sets the Q flag. To read the state of the Q flag, use an MRS instruction.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

A1.11 The Q flag in AArch32 state on page A1-37 C2.62 MRS (PSR to general-purpose register) on page C2-204 C1.9 Condition code suffixes on page C1-92

# C2.83 QSUB8

Signed saturating parallel byte-wise subtraction.

#### Syntax

QSUB8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction subtracts each byte of the second operand from the corresponding byte of the first operand and writes the results into the corresponding bytes of the destination. It saturates the results to the signed range  $-2^7 \le x \le 2^7$  -1. The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.84 QSUB16

Signed saturating parallel halfword-wise subtraction.

#### Syntax

QSUB16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

## Operation

This instruction subtracts each halfword of the second operand from the corresponding halfword of the first operand and writes the results into the corresponding halfwords of the destination. It saturates the results to the signed range  $-2^{15} \le x \le 2^{15} - 1$ . The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.85 RBIT

Reverse the bit order in a 32-bit word.

#### Syntax

RBIT{cond} Rd, Rn

where:

cond

is an optional condition code.

Rd

is the destination register.

Rn

is the register holding the operand.

## **Register restrictions**

You cannot use PC for any register.

You can use SP in the A32 instruction but this is deprecated. You cannot use SP in the T32 instruction.

## **Condition flags**

This instruction does not change the flags.

## Architectures

This instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

## Example

RBIT r7, r8

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.86 REV

Reverse the byte order in a word.

#### Syntax

REV{cond} Rd, Rn

where:

cond

is an optional condition code.

Rd

is the destination register.

Rn

is the register holding the operand.

## Usage

You can use this instruction to change endianness. REV converts 32-bit big-endian data into little-endian data or 32-bit little-endian data into big-endian data.

# **Register restrictions**

You cannot use PC for any register.

You can use SP in the A32 instruction but this is deprecated. You cannot use SP in the T32 instruction.

## **Condition flags**

This instruction does not change the flags.

## **16-bit instructions**

The following form of this instruction is available in T32 code, and is a 16-bit instruction:

REV Rd, Rm

Rd and Rm must both be Lo registers.

## Architectures

This instruction is available in A32 and T32.

## Example

REV r3, r7

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.87 REV16

Reverse the byte order in each halfword independently.

#### Syntax

REV16{cond} Rd, Rn

where:

cond

is an optional condition code.

Rd

is the destination register.

Rn

is the register holding the operand.

#### Usage

You can use this instruction to change endianness. REV16 converts 16-bit big-endian data into littleendian data or 16-bit little-endian data into big-endian data.

#### **Register restrictions**

You cannot use PC for any register.

You can use SP in the A32 instruction but this is deprecated. You cannot use SP in the T32 instruction.

#### **Condition flags**

This instruction does not change the flags.

#### **16-bit instructions**

The following form of this instruction is available in T32 code, and is a 16-bit instruction:

REV16 Rd, Rm

Rd and Rm must both be Lo registers.

#### Architectures

This instruction is available in A32 and T32.

#### Example

REV16 r0, r0

```
Related references
```

C1.9 Condition code suffixes on page C1-92

# C2.88 REVSH

Reverse the byte order in the bottom halfword, and sign extend to 32 bits.

#### Syntax

REVSH{cond} Rd, Rn

where:

cond

is an optional condition code.

Rd

is the destination register.

Rn

is the register holding the operand.

## Usage

You can use this instruction to change endianness. REVSH converts either:

- 16-bit signed big-endian data into 32-bit signed little-endian data.
- 16-bit signed little-endian data into 32-bit signed big-endian data.

## **Register restrictions**

You cannot use PC for any register.

You can use SP in the A32 instruction but this is deprecated. You cannot use SP in the T32 instruction.

## **Condition flags**

This instruction does not change the flags.

## **16-bit instructions**

The following form of this instruction is available in T32 code, and is a 16-bit instruction:

#### REVSH Rd, Rm

Rd and Rm must both be Lo registers.

## Architectures

This instruction is available in A32 and T32.

## Example

REVSH r0, r5 ; Reverse Signed Halfword

**Related references** 

C1.9 Condition code suffixes on page C1-92

# C2.89 RFE

Return From Exception.

## Syntax

RFE{addr\_mode}{cond} Rn{!}

where:

addr\_mode

is any one of the following:

IA	
	Increment address After each transfer (Full Descending stack)
IB	In anomant address Defens such transfer (A22 or h)
DA	Increment address Before each transfer (A32 only)
2.11	Decrement address After each transfer (A32 only)
DB	
	Decrement address Before each transfer.
If <i>addr_mode</i> is omitted, it defaults to Increment After.	

cond

is an optional condition code.

\_\_\_\_\_ Note \_\_\_\_\_

*cond* is permitted only in T32 code, using a preceding IT instruction, but this is deprecated in Armv8. This is an unconditional instruction in A32 code.

#### Rn

specifies the base register. Rn must not be PC.

I

is an optional suffix. If ! is present, the final address is written back into Rn.

## Usage

You can use RFE to return from an exception if you previously saved the return state using the SRS instruction. *Rn* is usually the SP where the return state information was saved.

## Operation

Loads the PC and the CPSR from the address contained in *Rn*, and the following address. Optionally updates *Rn*.

## Notes

RFE writes an address to the PC. The alignment of this address must be correct for the instruction set in use after the exception return:

- For a return to A32, the address written to the PC must be word-aligned.
- For a return to T32, the address written to the PC must be halfword-aligned.
- For a return to Jazelle, there are no alignment restrictions on the address written to the PC.

No special precautions are required in software to follow these rules, if you use the instruction to return after a valid exception entry mechanism.

Where addresses are not word-aligned, RFE ignores the least significant two bits of Rn.

The time order of the accesses to individual words of memory generated by RFE is not architecturally defined. Do not use this instruction on memory-mapped I/O locations where access order matters.

Do not use RFE in unprivileged software execution.

#### Architectures

This instruction is available in A32.

This 32-bit T32 instruction is available, except in the Armv7-M and Armv8-M Mainline architectures.

There is no 16-bit version of this instruction.

# Example

RFE sp!

Related concepts A1.3 Processor modes, and privileged and unprivileged software execution on page A1-28 Related references C2.129 SRS on page C2-289 C1.9 Condition code suffixes on page C1-92

# C2.90 ROR

Rotate Right. This instruction is a preferred synonym for MOV instructions with shifted register operands.

#### Syntax

ROR{S}{cond} Rd, Rm, Rs
ROR{S}{cond} Rd, Rm, #sh
where:

s

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

Rd

is the destination register.

```
Rm
```

is the register holding the first operand. This operand is shifted right.

Rs

is a register holding a shift value to apply to the value in Rm. Only the least significant byte is used.

sh

is a constant shift. The range of values is 1-31.

#### Operation

ROR provides the value of the contents of a register rotated by a value. The bits that are rotated off the right end are inserted into the vacated bit positions on the left.

## **Restrictions in T32 code**

T32 instructions must not use PC or SP.

#### Use of SP and PC in A32 instructions

You can use SP in these A32 instructions but this is deprecated.

You cannot use PC in instructions with the  $ROR{S}{cond} Rd$ , Rm, Rs syntax. You can use PC for Rd and Rm in the other syntax, but this is deprecated.

If you use PC as *Rm*, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, the SPSR of the current mode is copied to the CPSR. You can use this to return from exceptions.

– Note

The A32 instruction RORS{*cond*} pc,Rm,#sh always disassembles to the preferred form MOVS{*cond*} pc,Rm{,shift}.

#### —— Caution –

Do not use the S suffix when using PC as *Rd* in User mode or System mode. The assembler cannot warn you about this because it has no information about what the processor mode is likely to be at execution time.

You cannot use PC for Rd or any operand in this instruction if it has a register-controlled shift.

#### **Condition flags**

If S is specified, the instruction updates the N and Z flags according to the result.

The C flag is unaffected if the shift value is 0. Otherwise, the C flag is updated to the last bit shifted out.

#### **16-bit instructions**

The following forms of this instruction are available in T32 code, and are 16-bit instructions:

RORS Rd, Rd, Rs

*Rd* and *Rs* must both be Lo registers. This form can only be used outside an IT block.

#### ROR{cond} Rd, Rd, Rs

*Rd* and *Rs* must both be Lo registers. This form can only be used inside an IT block.

#### Architectures

This instruction is available in A32 and T32.

#### Example

ROR r4, r5, r6

#### **Related references**

C2.58 MOV on page C2-199 C1.9 Condition code suffixes on page C1-92

# C2.91 RRX

Rotate Right with Extend. This instruction is a preferred synonym for MOV instructions with shifted register operands.

## Syntax

RRX{S}{cond} Rd, Rm

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

Rd

is the destination register.

Rm

is the register holding the first operand. This operand is shifted right.

## Operation

RRX provides the value of the contents of a register shifted right one bit. The old carry flag is shifted into bit[31]. If the S suffix is present, the old bit[0] is placed in the carry flag.

## **Restrictions in T32 code**

T32 instructions must not use PC or SP.

# Use of SP and PC in A32 instructions

You can use SP in this A32 instruction but this is deprecated.

If you use PC as *Rm*, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, the SPSR of the current mode is copied to the CPSR. You can use this to return from exceptions.

— Note —

The A32 instruction RRXS{cond} pc,Rm always disassembles to the preferred form MOVS{*cond*} pc,Rm{,shift}.

— Caution –

Do not use the S suffix when using PC as *Rd* in User mode or System mode. The assembler cannot warn you about this because it has no information about what the processor mode is likely to be at execution time.

You cannot use PC for Rd or any operand in this instruction if it has a register-controlled shift.

# **Condition flags**

If S is specified, the instruction updates the N and Z flags according to the result.

The C flag is unaffected if the shift value is 0. Otherwise, the C flag is updated to the last bit shifted out.

## Architectures

The 32-bit instruction is available in A32 and T32.

There is no 16-bit instruction in T32.

*Related references C2.58 MOV* on page C2-199

C1.9 Condition code suffixes on page C1-92

# C2.92 RSB

Reverse Subtract without carry.

# Syntax

RSB{S}{cond} {Rd}, Rn, Operand2

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

Rd

is the destination register.

Rn

is the register holding the first operand.

## Operand2

is a flexible second operand.

# Operation

The RSB instruction subtracts the value in *Rn* from the value of *Operand2*. This is useful because of the wide range of options for *Operand2*.

In certain circumstances, the assembler can substitute one instruction for another. Be aware of this when reading disassembly listings.

# Use of PC and SP in T32 instructions

You cannot use PC (R15) for *Rd* or any operand.

You cannot use SP (R13) for *Rd* or any operand.

# Use of PC and SP in A32 instructions

You cannot use PC for Rd or any operand in an RSB instruction that has a register-controlled shift.

Use of PC for any operand, in instructions without register-controlled shift, is deprecated.

If you use PC (R15) as Rn or Rm, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc,lr instruction.

Use of SP and PC in A32 instructions is deprecated.

## **Condition flags**

If S is specified, the RSB instruction updates the N, Z, C and V flags according to the result.

# **16-bit instructions**

The following forms of this instruction are available in T32 code, and are 16-bit instructions:

# RSBS Rd, Rn, #0

Rd and Rn must both be Lo registers. This form can only be used outside an IT block.

#### RSB{cond} Rd, Rn, #0

*Rd* and *Rn* must both be Lo registers. This form can only be used inside an IT block.

#### Example

RSB r4, r4, #1280 ; subtracts contents of R4 from 1280

#### **Related references**

*C2.3 Flexible second operand (Operand2)* on page C2-112 *C1.9 Condition code suffixes* on page C1-92

# C2.93 RSC

Reverse Subtract with Carry.

## Syntax

RSC{S}{cond} {Rd}, Rn, Operand2

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

Rd

is the destination register.

Rn

is the register holding the first operand.

#### Operand2

is a flexible second operand.

# Usage

The RSC instruction subtracts the value in *Rn* from the value of *Operand2*. If the carry flag is clear, the result is reduced by one.

You can use RSC to synthesize multiword arithmetic.

In certain circumstances, the assembler can substitute one instruction for another. Be aware of this when reading disassembly listings.

RSC is not available in T32 code.

# Use of PC and SP

Use of PC and SP is deprecated.

You cannot use PC for Rd or any operand in an RSC instruction that has a register-controlled shift.

If you use PC (R15) as Rn or Rm, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, 1r instruction.

# **Condition flags**

If S is specified, the RSC instruction updates the N, Z, C and V flags according to the result.

## **Correct example**

RSCSLE r0,r5,r0,LSL r4 ; conditional, flags set

#### Incorrect example

RSCSLE r0,pc,r0,LSL r4 ; PC not permitted with register ; controlled shift

**Related references** C2.3 Flexible second operand (Operand2) on page C2-112 C1.9 Condition code suffixes on page C1-92

# C2.94 SADD8

Signed parallel byte-wise addition.

#### Syntax

SADD8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction performs four signed integer additions on the corresponding bytes of the operands and writes the results into the corresponding bytes of the destination. The results are modulo  $2^8$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# GE flags

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

## GE[0]

for bits[7:0] of the result.

# GE[1]

for bits[15:8] of the result.

#### GE[2]

for bits[23:16] of the result.

```
GE[3]
```

for bits[31:24] of the result.

It sets a GE flag to 1 to indicate that the corresponding result is greater than or equal to zero. This is equivalent to an ADDS instruction setting the N and V condition flags to the same value, so that the GE condition passes.

You can use these flags to control a following SEL instruction.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

Related references C2.100 SEL on page C2-257 C1.9 Condition code suffixes on page C1-92

# C2.95 SADD16

Signed parallel halfword-wise addition.

#### Syntax

SADD16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction performs two signed integer additions on the corresponding halfwords of the operands and writes the results into the corresponding halfwords of the destination. The results are modulo  $2^{16}$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# GE flags

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

## GE[1:0]

for bits[15:0] of the result.

## GE[3:2]

for bits[31:16] of the result.

It sets a pair of GE flags to 1 to indicate that the corresponding result is greater than or equal to zero. This is equivalent to an ADDS instruction setting the N and V condition flags to the same value, so that the GE condition passes.

You can use these flags to control a following SEL instruction.

—— Note —

GE[1:0] are set or cleared together, and GE[3:2] are set or cleared together.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

**Related references** C2.100 SEL on page C2-257 C1.9 Condition code suffixes on page C1-92

# C2.96 SASX

Signed parallel add and subtract halfwords with exchange.

#### Syntax

SASX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction exchanges the two halfwords of the second operand, then performs an addition on the two top halfwords of the operands and a subtraction on the bottom two halfwords. It writes the results into the corresponding halfwords of the destination. The results are modulo  $2^{16}$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# GE flags

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

## GE[1:0]

for bits[15:0] of the result.

## GE[3:2]

for bits[31:16] of the result.

It sets a pair of GE flags to 1 to indicate that the corresponding result is greater than or equal to zero. This is equivalent to an ADDS or SUBS instruction setting the N and V condition flags to the same value, so that the GE condition passes.

You can use these flags to control a following SEL instruction.

\_\_\_\_\_ Note \_\_\_\_

GE[1:0] are set or cleared together, and GE[3:2] are set or cleared together.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

**Related references** C2.100 SEL on page C2-257 C1.9 Condition code suffixes on page C1-92
# C2.97 SBC

Subtract with Carry.

## Syntax

SBC{S}{cond} {Rd}, Rn, Operand2

where:

S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

```
cond
```

is an optional condition code.

Rd

is the destination register.

Rn

is the register holding the first operand.

## Operand2

is a flexible second operand.

## Usage

The SBC (Subtract with Carry) instruction subtracts the value of *Operand2* from the value in *Rn*. If the carry flag is clear, the result is reduced by one.

You can use SBC to synthesize multiword arithmetic.

In certain circumstances, the assembler can substitute one instruction for another. Be aware of this when reading disassembly listings.

## Use of PC and SP in T32 instructions

You cannot use PC (R15) for Rd, or any operand.

You cannot use SP (R13) for *Rd*, or any operand.

## Use of PC and SP in A32 instructions

You cannot use PC for Rd or any operand in an SBC instruction that has a register-controlled shift.

Use of PC for any operand in instructions without register-controlled shift, is deprecated.

If you use PC (R15) as Rn or Rm, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, 1r instruction.

Use of SP and PC in SBC A32 instructions is deprecated.

## **Condition flags**

If S is specified, the SBC instruction updates the N, Z, C and V flags according to the result.

## **16-bit instructions**

The following forms of this instruction are available in T32 code, and are 16-bit instructions:

SBCS Rd, Rd, Rm

Rd and Rm must both be Lo registers. This form can only be used outside an IT block.

SBC{cond} Rd, Rd, Rm

Rd and Rm must both be Lo registers. This form can only be used inside an IT block.

#### **Multiword arithmetic examples**

These instructions subtract one 96-bit integer contained in R9, R10, and R11 from another 96-bit integer contained in R6, R7, and R8, and place the result in R3, R4, and R5:

SUBSr3, r6, r9SBCSr4, r7, r10SBCr5, r8, r11

For clarity, the above examples use consecutive registers for multiword values. There is no requirement to do this. The following, for example, is perfectly valid:

 SUBS
 r6, r6, r9

 SBCS
 r9, r2, r1

 SBC
 r2, r8, r11

## **Related references**

*C2.3 Flexible second operand (Operand2)* on page C2-112 *C1.9 Condition code suffixes* on page C1-92

# C2.98 SBFX

Signed Bit Field Extract.

### Syntax

SBFX{cond} Rd, Rn, #Lsb, #width
where:

### cond

is an optional condition code.

#### Rd

is the destination register.

### Rn

is the source register.

### Lsb

is the bit number of the least significant bit in the bitfield, in the range 0 to 31.

#### width

is the width of the bitfield, in the range 1 to (32–Lsb).

## Operation

Copies adjacent bits from one register into the least significant bits of a second register, and sign extends to 32 bits.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not alter any flags.

## Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.99 SDIV

Signed Divide.

Syntax
<pre>SDIV{cond} {Rd}, Rn, Rm</pre>
where:
cond
is an optional condition code.
₹d
is the destination register.
{n
is the register holding the value to be divided.
<i>?m</i>
is a register holding the divisor.

## **Register restrictions**

 $PC \mbox{ or } SP \mbox{ cannot be used for Rd, Rn, or Rm.}$ 

## Architectures

This 32-bit T32 instruction is available in Armv7-R, Armv7-M, and Armv8-M Mainline.

This 32-bit A32 instruction is optional in Armv7-R.

This 32-bit A32 and T32 instruction is available in Armv7-A if Virtualization Extensions are implemented, and optional if not.

There is no 16-bit T32 SDIV instruction.

## **Related references**

# C2.100 SEL

Select bytes from each operand according to the state of the APSR GE flags.

### Syntax

SEL{cond} {Rd}, Rn, Rm

where:

### cond

is an optional condition code.

### Rd

is the destination register.

### Rn

is the register holding the first operand.

### Rm

is the register holding the second operand.

## Operation

The SEL instruction selects bytes from Rn or Rm according to the APSR GE flags:

- If GE[0] is set, Rd[7:0] come from Rn[7:0], otherwise from Rm[7:0].
- If GE[1] is set, Rd[15:8] come from Rn[15:8], otherwise from Rm[15:8].
- If GE[2] is set, Rd[23:16] come from Rn[23:16], otherwise from Rm[23:16].
- If GE[3] is set, Rd[31:24] come from Rn[31:24], otherwise from Rm[31:24].

## Usage

Use the SEL instruction after one of the signed parallel instructions. You can use this to select maximum or minimum values in multiple byte or halfword data.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not change the flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## Examples

SEL r0, r4, r5 SELLT r4, r0, r4

The following instruction sequence sets each byte in R4 equal to the unsigned minimum of the corresponding bytes of R1 and R2:

USUB8 r4, r1, r2 SEL r4, r2, r1 **Related concepts** A1.12 Application Program Status Register on page A1-38 **Related references** C1.9 Condition code suffixes on page C1-92

# C2.101 SETEND

Set the endianness bit in the CPSR, without affecting any other bits in the CPSR.

\_\_\_\_\_ Note \_\_\_\_\_

This instruction is deprecated in Armv8.

## Syntax

SETEND specifier

where:

specifier

is one of:

BE

Big-endian.

LE

Little-endian.

### Usage

Use SETEND to access data of different endianness, for example, to access several big-endian DMA-formatted data fields from an otherwise little-endian application.

SETEND cannot be conditional, and is not permitted in an IT block.

#### Architectures

This instruction is available in A32 and 16-bit T32.

This 16-bit instruction is available in T32, except in the Armv6-M and Armv7-M architectures.

There is no 32-bit version of this instruction in T32.

#### Example

SETENDBE; Set the CPSR E bit for big-endian accessesLDRr0, [r2, #header]LDRr1, [r2, #CRC32]SETENDle; Set the CPSR E bit for little-endian accesses; for the rest of the application

# C2.102 SETPAN

Set Privileged Access Never.

## Syntax

```
SETPAN{q} #imm ; A1 general registers (A32)
SETPAN{q} #imm ; T1 general registers (T32)
Where:
```

q

Is an optional instruction width specifier. See *C2.2 Instruction width specifiers* on page C2-111.

Is the unsigned immediate 0 or 1.

## Architectures supported

Supported in Armv8.1 and later.

## Usage

Set Privileged Access Never writes a new value to PSTATE.PAN.

This instruction is available only in privileged mode and it is a NOP when executed in User mode.

## **Related references**

C2.1 A32 and T32 instruction summary on page C2-106

# C2.103 SEV

Set Event.

## Syntax

SEV{cond}

where:

cond

is an optional condition code.

## Operation

This is a hint instruction. It is optional whether it is implemented or not. If it is not implemented, it executes as a NOP. The assembler produces a diagnostic message if the instruction executes as a NOP on the target.

SEV causes an event to be signaled to all cores within a multiprocessor system. If SEV is implemented, WFE must also be implemented.

## Availability

This instruction is available in A32 and T32.

### **Related references**

*C2.104 SEVL* on page C2-262 *C2.68 NOP* on page C2-213 *C1.9 Condition code suffixes* on page C1-92

# C2.104 SEVL

Set Event Locally.

—— Note —

This instruction is supported only in Armv8.

### Syntax

SEVL{cond}

where:

cond

is an optional condition code.

### Operation

This is a hint instruction. It is optional whether it is implemented or not. If it is not implemented, it executes as a NOP. armasm produces a diagnostic message if the instruction executes as a NOP on the target.

SEVL causes an event to be signaled to all cores the current processor. SEVL is not required to affect other processors although it is permitted to do so.

### Availability

This instruction is available in A32 and T32.

**Related references** 

C2.103 SEV on page C2-261 C2.68 NOP on page C2-213 C1.9 Condition code suffixes on page C1-92

# C2.105 SG

Secure Gateway.

## Syntax

SG

## Usage

Secure Gateway marks a valid branch target for branches from Non-secure code that wants to call Secure code.

# C2.106 SHADD8

Signed halving parallel byte-wise addition.

### Syntax

SHADD8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

## Operation

This instruction performs four signed integer additions on the corresponding bytes of the operands, halves the results, and writes the results into the corresponding bytes of the destination. This cannot cause overflow.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.107 SHADD16

Signed halving parallel halfword-wise addition.

#### Syntax

SHADD16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

## Operation

This instruction performs two signed integer additions on the corresponding halfwords of the operands, halves the results, and writes the results into the corresponding halfwords of the destination. This cannot cause overflow.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.108 SHASX

Signed halving parallel add and subtract halfwords with exchange.

#### Syntax

SHASX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

## Operation

This instruction exchanges the two halfwords of the second operand, then performs an addition on the two top halfwords of the operands and a subtraction on the bottom two halfwords. It halves the results and writes them into the corresponding halfwords of the destination. This cannot cause overflow.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

## C2.109 SHSAX

Signed halving parallel subtract and add halfwords with exchange.

### Syntax

SHSAX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

## Operation

This instruction exchanges the two halfwords of the second operand, then performs a subtraction on the two top halfwords of the operands and an addition on the bottom two halfwords. It halves the results and writes them into the corresponding halfwords of the destination. This cannot cause overflow.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.110 SHSUB8

Signed halving parallel byte-wise subtraction.

#### Syntax

SHSUB8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

## Operation

This instruction subtracts each byte of the second operand from the corresponding byte of the first operand, halves the results, and writes the results into the corresponding bytes of the destination. This cannot cause overflow.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.111 SHSUB16

Signed halving parallel halfword-wise subtraction.

#### Syntax

SHSUB16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

## Operation

This instruction subtracts each halfword of the second operand from the corresponding halfword of the first operand, halves the results, and writes the results into the corresponding halfwords of the destination. This cannot cause overflow.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.112 SMC

Secure Monitor Call.

### Syntax

SMC{cond} #imm4

where:

cond

is an optional condition code.

imm4

is a 4-bit immediate value. This is ignored by the Arm processor, but can be used by the SMC exception handler to determine what service is being requested.

— Note —

SMC was called SMI in earlier versions of the A32 assembly language. SMI instructions disassemble to SMC, with a comment to say that this was formerly SMI.

## Architectures

This 32-bit instruction is available in A32 and T32, if the Arm architecture has the Security Extensions.

There is no 16-bit version of this instruction in T32.

**Related references** C1.9 Condition code suffixes on page C1-92 **Related information** Arm Architecture Reference Manual

## C2.113 SMLAxy

Signed Multiply Accumulate, with 16-bit operands and a 32-bit result and accumulator.

#### Syntax

SMLA<x><y>{cond} Rd, Rn, Rm, Ra

where:

<*x>* 

is either B or T. B means use the bottom half (bits [15:0]) of *Rn*, T means use the top half (bits [31:16]) of *Rn*.

<y>

is either B or T. B means use the bottom half (bits [15:0]) of *Rm*, T means use the top half (bits [31:16]) of *Rm*.

#### cond

is an optional condition code.

#### Rd

is the destination register.

Rn, Rm

are the registers holding the values to be multiplied.

Ra

is the register holding the value to be added.

## Operation

SMLAxy multiplies the 16-bit signed integers from the selected halves of *Rn* and *Rm*, adds the 32-bit result to the 32-bit value in *Ra*, and places the result in *Rd*.

#### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not affect the N, Z, C, or V flags.

If overflow occurs in the accumulation, SMLAxy sets the Q flag. To read the state of the Q flag, use an MRS instruction.

----- Note ------

SMLAxy never clears the  $\boldsymbol{Q}$  flag. To clear the  $\boldsymbol{Q}$  flag, use an MSR instruction.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

### Examples

SMLABBNE	r0,	r2,	r1,	r10
SMLABT	r0,	r0,	r3,	r5

## **Related references**

C2.62 MRS (PSR to general-purpose register) on page C2-204 C2.65 MSR (general-purpose register to PSR) on page C2-208 C1.9 Condition code suffixes on page C1-92

# C2.114 SMLAD

Dual 16-bit Signed Multiply with Addition of products and 32-bit accumulation.

### Syntax

SMLAD{X}{cond} Rd, Rn, Rm, Ra

where:

cond

is an optional condition code.

### Х

is an optional parameter. If X is present, the most and least significant halfwords of the second operand are exchanged before the multiplications occur.

#### Rd

is the destination register.

#### Rn, Rm

are the registers holding the operands.

#### Ra

is the register holding the accumulate operand.

### Operation

SMLAD multiplies the bottom halfword of Rn with the bottom halfword of Rm, and the top halfword of Rn with the top halfword of Rm. It then adds both products to the value in Ra and stores the sum to Rd.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not change the flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

#### Example

SMLADLT r1, r2, r4, r1

Related references

# C2.115 SMLAL

Signed Long Multiply, with optional Accumulate, with 32-bit operands, and 64-bit result and accumulator.

#### Syntax

SMLAL{S}{cond} RdLo, RdHi, Rn, Rm

where:

## S

is an optional suffix available in A32 state only. If S is specified, the condition flags are updated on the result of the operation.

cond

is an optional condition code.

#### RdLo, RdHi

are the destination registers. They also hold the accumulating value. RdLo and RdHi must be different registers

Rn, Rm

are general-purpose registers holding the operands.

### Operation

The SMLAL instruction interprets the values from *Rn* and *Rm* as two's complement signed integers. It multiplies these integers, and adds the 64-bit result to the 64-bit signed integer contained in *RdHi* and *RdLo*.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

If S is specified, this instruction:

- Updates the N and Z flags according to the result.
- Does not affect the C or V flags.

#### Architectures

This instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

**Related references** 

## C2.116 SMLALD

Dual 16-bit Signed Multiply with Addition of products and 64-bit Accumulation.

#### Syntax

SMLALD{X}{cond} RdLo, RdHi, Rn, Rm

where:

Х

is an optional parameter. If X is present, the most and least significant halfwords of the second operand are exchanged before the multiplications occur.

#### cond

is an optional condition code.

#### RdLo, RdHi

are the destination registers for the 64-bit result. They also hold the 64-bit accumulate operand. *RdHi* and *RdLo* must be different registers.

Rn, Rm

are the general-purpose registers holding the operands.

#### Operation

SMLALD multiplies the bottom halfword of *Rn* with the bottom halfword of *Rm*, and the top halfword of *Rn* with the top halfword of *Rm*. It then adds both products to the value in *RdLo*, *RdHi* and stores the sum to *RdLo*, *RdHi*.

#### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

#### **Condition flags**

This instruction does not change the flags.

#### Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

#### Example

SMLALD r10, r11, r5, r1

*Related references C1.9 Condition code suffixes* on page C1-92

## C2.117 SMLALxy

Signed Multiply-Accumulate with 16-bit operands and a 64-bit accumulator.

#### Syntax

SMLAL<x><y>{cond} RdLo, RdHi, Rn, Rm

where:

<*x>* 

is either B or T. B means use the bottom half (bits [15:0]) of *Rn*, T means use the top half (bits [31:16]) of *Rn*.

<y>

is either B or T. B means use the bottom half (bits [15:0]) of *Rm*, T means use the top half (bits [31:16]) of *Rm*.

cond

is an optional condition code.

#### RdLo, RdHi

are the destination registers. They also hold the accumulate value. *RdHi* and *RdLo* must be different registers.

Rn, Rm

are the general-purpose registers holding the values to be multiplied.

#### Operation

SMLALxy multiplies the signed integer from the selected half of *Rm* by the signed integer from the selected half of *Rn*, and adds the 32-bit result to the 64-bit value in *RdHi* and *RdLo*.

#### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

#### **Condition flags**

This instruction does not change the flags.

\_\_\_\_\_ Note \_\_\_\_\_

SMLALxy cannot raise an exception. If overflow occurs on this instruction, the result wraps round without any warning.

#### Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

#### Examples

 SMLALTB
 r2, r3, r7, r1

 SMLALBTVS
 r0, r1, r9, r2

*Related references C1.9 Condition code suffixes* on page C1-92

## C2.118 SMLAWy

Signed Multiply-Accumulate Wide, with one 32-bit and one 16-bit operand, and a 32-bit accumulate value, providing the top 32 bits of the result.

#### Syntax

SMLAW<y>{cond} Rd, Rn, Rm, Ra

where:

<y>

is either B or T. B means use the bottom half (bits [15:0]) of *Rm*, T means use the top half (bits [31:16]) of *Rm*.

cond

is an optional condition code.

#### Rd

is the destination register.

#### Rn, Rm

are the registers holding the values to be multiplied.

Ra

is the register holding the value to be added.

### Operation

SMLAWy multiplies the signed 16-bit integer from the selected half of Rm by the signed 32-bit integer from Rn, adds the top 32 bits of the 48-bit result to the 32-bit value in Ra, and places the result in Rd.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

#### **Condition flags**

This instruction does not affect the N, Z, C, or V flags.

If overflow occurs in the accumulation, SMLAWy sets the  $\boldsymbol{Q}$  flag.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

#### **Related references**

*C2.62 MRS (PSR to general-purpose register)* on page C2-204 *C1.9 Condition code suffixes* on page C1-92

# C2.119 SMLSD

Dual 16-bit Signed Multiply with Subtraction of products and 32-bit accumulation.

### Syntax

SMLSD{X}{cond} Rd, Rn, Rm, Ra

where:

#### cond

is an optional condition code.

### Х

is an optional parameter. If X is present, the most and least significant halfwords of the second operand are exchanged before the multiplications occur.

#### Rd

is the destination register.

#### Rn, Rm

are the registers holding the operands.

Ra

is the register holding the accumulate operand.

## Operation

SMLSD multiplies the bottom halfword of Rn with the bottom halfword of Rm, and the top halfword of Rn with the top halfword of Rm. It then subtracts the second product from the first, adds the difference to the value in Ra, and stores the result to Rd.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not change the flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## Examples

 SMLSD
 r1, r2, r0, r7

 SMLSDX
 r11, r10, r2, r3

## **Related references**

# C2.120 SMLSLD

Dual 16-bit Signed Multiply with Subtraction of products and 64-bit accumulation.

#### Syntax

SMLSD{X}{cond} RdLo, RdHi, Rn, Rm

where:

#### Х

is an optional parameter. If X is present, the most and least significant halfwords of the second operand are exchanged before the multiplications occur.

#### cond

is an optional condition code.

#### RdLo, RdHi

are the destination registers for the 64-bit result. They also hold the 64-bit accumulate operand. *RdHi* and *RdLo* must be different registers.

Rn, Rm

are the general-purpose registers holding the operands.

#### Operation

SMLSLD multiplies the bottom halfword of *Rn* with the bottom halfword of *Rm*, and the top halfword of *Rn* with the top halfword of *Rm*. It then subtracts the second product from the first, adds the difference to the value in *RdLo*, *RdHi*, and stores the result to *RdLo*, *RdHi*.

#### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

#### **Condition flags**

This instruction does not change the flags.

#### Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

#### Example

SMLSLD r3, r0, r5, r1

**Related references** 

# C2.121 SMMLA

Signed Most significant word Multiply with Accumulation.

### Syntax

SMMLA{R}{cond} Rd, Rn, Rm, Ra

where:

## R

is an optional parameter. If R is present, the result is rounded, otherwise it is truncated.

cond

is an optional condition code.

#### Rd

is the destination register.

### Rn, Rm

are the registers holding the operands.

#### Ra

is a register holding the value to be added or subtracted from.

## Operation

SMMLA multiplies the values from *Rn* and *Rm*, adds the value in *Ra* to the most significant 32 bits of the product, and stores the result in *Rd*.

If the optional R parameter is specified,  $0 \times 80000000$  is added before extracting the most significant 32 bits. This has the effect of rounding the result.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not change the flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.122 SMMLS

Signed Most significant word Multiply with Subtraction.

#### Syntax

SMMLS{R}{cond} Rd, Rn, Rm, Ra

where:

### R

is an optional parameter. If R is present, the result is rounded, otherwise it is truncated.

cond

is an optional condition code.

#### Rd

is the destination register.

#### Rn, Rm

are the registers holding the operands.

#### Ra

is a register holding the value to be added or subtracted from.

### Operation

SMMLS multiplies the values from *Rn* and *Rm*, subtracts the product from the value in *Ra* shifted left by 32 bits, and stores the most significant 32 bits of the result in *Rd*.

If the optional R parameter is specified,  $0 \times 80000000$  is added before extracting the most significant 32 bits. This has the effect of rounding the result.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not change the flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## **Related references**

# C2.123 SMMUL

Signed Most significant word Multiply.

#### Syntax

SMMUL{R}{cond} {Rd}, Rn, Rm

where:

### R

is an optional parameter. If R is present, the result is rounded, otherwise it is truncated.

cond

is an optional condition code.

#### Rd

is the destination register.

#### Rn, Rm

are the registers holding the operands.

#### Ra

is a register holding the value to be added or subtracted from.

## Operation

SMMUL multiplies the 32-bit values from Rn and Rm, and stores the most significant 32 bits of the 64-bit result to Rd.

If the optional R parameter is specified,  $0 \times 80000000$  is added before extracting the most significant 32 bits. This has the effect of rounding the result.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not change the flags.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

#### Examples

SMMULGE r6, r4, r3 SMMULR r2, r2, r2

## **Related references**

# C2.124 SMUAD

Dual 16-bit Signed Multiply with Addition of products, and optional exchange of operand halves.

#### Syntax

SMUAD{X}{cond} {Rd}, Rn, Rm

where:

Х

is an optional parameter. If X is present, the most and least significant halfwords of the second operand are exchanged before the multiplications occur.

#### cond

is an optional condition code.

#### Rd

is the destination register.

### Rn, Rm

are the registers holding the operands.

## Operation

SMUAD multiplies the bottom halfword of Rn with the bottom halfword of Rm, and the top halfword of Rn with the top halfword of Rm. It then adds the products and stores the sum to Rd.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## Q flag

The SMUAD instruction sets the  $\boldsymbol{Q}$  flag if the addition overflows.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## Examples

SMUAD r2, r3, r2

*Related references C1.9 Condition code suffixes* on page C1-92

## C2.125 SMULxy

Signed Multiply, with 16-bit operands and a 32-bit result.

#### Syntax

SMUL<x><y>{cond} {Rd}, Rn, Rm

where:

<*x>* 

is either B or T. B means use the bottom half (bits [15:0]) of *Rn*, T means use the top half (bits [31:16]) of *Rn*.

<y>

is either B or T. B means use the bottom half (bits [15:0]) of *Rm*, T means use the top half (bits [31:16]) of *Rm*.

#### cond

is an optional condition code.

#### Rd

is the destination register.

Rn, Rm

are the registers holding the values to be multiplied.

#### Operation

SMULxy multiplies the 16-bit signed integers from the selected halves of Rn and Rm, and places the 32-bit result in Rd.

#### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

#### **Condition flags**

These instructions do not affect the N, Z, C, or V flags.

#### Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

#### Examples

SMULTBEQ r8, r7, r9

**Related references** 

C2.62 MRS (PSR to general-purpose register) on page C2-204 C2.65 MSR (general-purpose register to PSR) on page C2-208 C1.9 Condition code suffixes on page C1-92

# C2.126 SMULL

Signed Long Multiply, with 32-bit operands and 64-bit result.

### Syntax

SMULL{S}{cond} RdLo, RdHi, Rn, Rm

where:

### S

is an optional suffix available in A32 state only. If S is specified, the condition flags are updated on the result of the operation.

#### cond

is an optional condition code.

#### RdLo, RdHi

are the destination registers. RdLo and RdHi must be different registers

Rn, Rm

are general-purpose registers holding the operands.

### Operation

The SMULL instruction interprets the values from Rn and Rm as two's complement signed integers. It multiplies these integers and places the least significant 32 bits of the result in RdLo, and the most significant 32 bits of the result in RdHi.

### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

If S is specified, this instruction:

- Updates the N and Z flags according to the result.
- Does not affect the C or V flags.

#### Architectures

This instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

**Related references** 

## C2.127 SMULWy

Signed Multiply Wide, with one 32-bit and one 16-bit operand, providing the top 32 bits of the result.

#### Syntax

SMULW<y>{cond} {Rd}, Rn, Rm

where:

<*y*>

is either B or T. B means use the bottom half (bits [15:0]) of *Rm*, T means use the top half (bits [31:16]) of *Rm*.

```
cond
```

is an optional condition code.

Rd

is the destination register.

#### Rn, Rm

are the registers holding the values to be multiplied.

#### Operation

SMULWy multiplies the signed integer from the selected half of Rm by the signed integer from Rn, and places the upper 32-bits of the 48-bit result in Rd.

### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## **Condition flags**

This instruction does not affect the N, Z, C, or V flags.

#### Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

#### **Related references**

*C2.62 MRS (PSR to general-purpose register)* on page C2-204 *C1.9 Condition code suffixes* on page C1-92

# C2.128 SMUSD

Dual 16-bit Signed Multiply with Subtraction of products, and optional exchange of operand halves.

#### Syntax

```
SMUSD{X}{cond} {Rd}, Rn, Rm
```

where:

Х

is an optional parameter. If X is present, the most and least significant halfwords of the second operand are exchanged before the multiplications occur.

#### cond

is an optional condition code.

Rd

is the destination register.

#### Rn, Rm

are the registers holding the operands.

## Operation

SMUSD multiplies the bottom halfword of *Rn* with the bottom halfword of *Rm*, and the top halfword of *Rn* with the top halfword of *Rm*. It then subtracts the second product from the first, and stores the difference to *Rd*.

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

## Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## Example

SMUSDXNE r0, r1, r2

**Related references** C1.9 Condition code suffixes on page C1-92
# C2.129 SRS

Store Return State onto a stack.

## Syntax

SRS{addr\_mode}{cond} sp{!}, #modenum

SRS{addr\_mode}{cond} #modenum{!}; This is pre-UAL syntax

where:

addr\_mode

is any one of the following:

IA

Increment address After each transfer

## ΙB

Increment address Before each transfer (A32 only)

## DA

Decrement address After each transfer (A32 only)

DB

Decrement address Before each transfer (Full Descending stack).

If *addr\_mode* is omitted, it defaults to Increment After. You can also use stack oriented addressing mode suffixes, for example, when implementing stacks.

#### cond

is an optional condition code.

----- Note --

*cond* is permitted only in T32 code, using a preceding IT instruction, but this is deprecated in the Armv8 architecture. This is an unconditional instruction in A32.

#### !

is an optional suffix. If ! is present, the final address is written back into the SP of the mode specified by *modenum*.

#### modenum

specifies the number of the mode whose banked SP is used as the base register. You must use only the defined mode numbers.

### Operation

SRS stores the LR and the SPSR of the current mode, at the address contained in SP of the mode specified by *modenum*, and the following word respectively. Optionally updates SP of the mode specified by *modenum*. This is compatible with the normal use of the STM instruction for stack accesses.

\_\_\_\_\_ Note \_\_\_\_

For full descending stack, you must use SRSFD or SRSDB.

# Usage

You can use SRS to store return state for an exception handler on a different stack from the one automatically selected.

## Notes

Where addresses are not word-aligned, SRS ignores the least significant two bits of the specified address.

The time order of the accesses to individual words of memory generated by SRS is not architecturally defined. Do not use this instruction on memory-mapped I/O locations where access order matters.

Do not use SRS in User and System modes because these modes do not have a SPSR.

SRS is not permitted in a non-secure state if modenum specifies monitor mode.

#### Availability

This 32-bit instruction is available in A32 and T32.

The 32-bit T32 instruction is not available in the Armv7-M architecture.

There is no 16-bit version of this instruction in T32.

### Example

R13\_usr EQU 16 SRSFD sp,#R13\_usr

## **Related concepts**

A1.3 Processor modes, and privileged and unprivileged software execution on page A1-28 **Related references** C2.45 LDM on page C2-177 C1.9 Condition code suffixes on page C1-92

# C2.130 SSAT

Signed Saturate to any bit position, with optional shift before saturating.

## Syntax

```
SSAT{cond} Rd, #sat, Rm{, shift}
```

where:

#### cond

is an optional condition code.

## Rd

is the destination register.

#### sat

specifies the bit position to saturate to, in the range 1 to 32.

#### Rm

is the register containing the operand.

## shift

is an optional shift. It must be one of the following:

#### ASR #n

where *n* is in the range 1-32 (A32) or 1-31 (T32)

### LSL #n

where *n* is in the range 0-31.

# Operation

The SSAT instruction applies the specified shift, then saturates a signed value to the signed range  $-2^{\text{sat-1}} \le x \le 2^{\text{sat-1}} - 1$ .

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# Q flag

If saturation occurs, this instruction sets the Q flag. To read the state of the Q flag, use an MRS instruction.

### Architectures

This instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# Example

SSAT r7, #16, r7, LSL #4

# **Related references** C2.131 SSAT16 on page C2-292 C2.62 MRS (PSR to general-purpose register) on page C2-204

# C2.131 SSAT16

Parallel halfword Saturate.

## Syntax

SSAT16{cond} Rd, #sat, Rn

where:

cond

is an optional condition code.

### Rd

is the destination register.

### sat

specifies the bit position to saturate to, in the range 1 to 16.

### Rn

is the register holding the operand.

# Operation

Halfword-wise signed saturation to any bit position.

The SSAT16 instruction saturates each signed halfword to the signed range  $-2^{\text{sat-1}} \le x \le 2^{\text{sat-1}} - 1$ .

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# Q flag

If saturation occurs on either halfword, this instruction sets the Q flag. To read the state of the Q flag, use an MRS instruction.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Correct example**

SSAT16 r7, #12, r7

# Incorrect example

SSAT16 r1, #16, r2, LSL #4 ; shifts not permitted with halfword ; saturations

# **Related references**

*C2.62 MRS (PSR to general-purpose register)* on page C2-204 *C1.9 Condition code suffixes* on page C1-92

# C2.132 SSAX

Signed parallel subtract and add halfwords with exchange.

### Syntax

SSAX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

### Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction exchanges the two halfwords of the second operand, then performs a subtraction on the two top halfwords of the operands and an addition on the bottom two halfwords. It writes the results into the corresponding halfwords of the destination. The results are modulo  $2^{16}$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **GE flags**

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

# GE[1:0]

for bits[15:0] of the result.

# GE[3:2]

for bits[31:16] of the result.

It sets a pair of GE flags to 1 to indicate that the corresponding result is greater than or equal to zero. This is equivalent to an ADDS or SUBS instruction setting the N and V condition flags to the same value, so that the GE condition passes.

You can use these flags to control a following SEL instruction.

——Note —

GE[1:0] are set or cleared together, and GE[3:2] are set or cleared together.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

**Related references** C2.100 SEL on page C2-257 C1.9 Condition code suffixes on page C1-92

# C2.133 SSUB8

Signed parallel byte-wise subtraction.

## Syntax

SSUB8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction subtracts each byte of the second operand from the corresponding byte of the first operand and writes the results into the corresponding bytes of the destination. The results are modulo  $2^8$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# GE flags

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

# GE[0]

for bits[7:0] of the result.

# GE[1]

for bits[15:8] of the result.

### GE[2]

for bits[23:16] of the result.

```
GE[3]
```

for bits[31:24] of the result.

It sets a GE flag to 1 to indicate that the corresponding result is greater than or equal to zero. This is equivalent to a SUBS instruction setting the N and V condition flags to the same value, so that the GE condition passes.

You can use these flags to control a following SEL instruction.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

Related references C2.100 SEL on page C2-257 C1.9 Condition code suffixes on page C1-92

# C2.134 SSUB16

Signed parallel halfword-wise subtraction.

## Syntax

SSUB16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction subtracts each halfword of the second operand from the corresponding halfword of the first operand and writes the results into the corresponding halfwords of the destination. The results are modulo  $2^{16}$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **GE flags**

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

# GE[1:0]

for bits[15:0] of the result.

# GE[3:2]

for bits[31:16] of the result.

It sets a pair of GE flags to 1 to indicate that the corresponding result is greater than or equal to zero. This is equivalent to a SUBS instruction setting the N and V condition flags to the same value, so that the GE condition passes.

You can use these flags to control a following SEL instruction.

—— Note —

GE[1:0] are set or cleared together, and GE[3:2] are set or cleared together.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

**Related references** C2.100 SEL on page C2-257 C1.9 Condition code suffixes on page C1-92

# C2.135 STC and STC2

Transfer Data between memory and Coprocessor.

**\_\_\_\_\_** Note \_\_\_\_\_ STC2 is not supported in Armv8.

## Syntax

```
op{L}{cond} coproc, CRd, [Rn]
op{L}{cond} coproc, CRd, [Rn, #{-}offset] ; offset addressing
op{L}{cond} coproc, CRd, [Rn, #{-}offset]! ; pre-index addressing
op{L}{cond} coproc, CRd, [Rn], #{-}offset ; post-index addressing
op{L}{cond} coproc, CRd, [Rn], #{option}
where:
```

# ор

is one of STC or STC2.

#### cond

is an optional condition code.

In A32 code, cond is not permitted for STC2.

#### L

is an optional suffix specifying a long transfer.

#### coproc

is the name of the coprocessor the instruction is for. The standard name is pn, where n is an integer whose value must be:

- In the range 0-15 in Armv7 and earlier.
- 14 in Armv8.

#### CRd

is the coprocessor register to store.

#### Rn

is the register on which the memory address is based. If PC is specified, the value used is the address of the current instruction plus eight.

-

is an optional minus sign. If - is present, the offset is subtracted from Rn. Otherwise, the offset is added to Rn.

offset

is an expression evaluating to a multiple of 4, in the range 0 to 1020.

#### !

is an optional suffix. If ! is present, the address including the offset is written back into Rn.

#### option

is a coprocessor option in the range 0-255, enclosed in braces.

## Usage

The use of these instructions depends on the coprocessor. See the coprocessor documentation for details.

### Architectures

These 32-bit instructions are available in A32 and T32.

There are no 16-bit versions of these instructions in T32.

## **Register restrictions**

You cannot use PC for Rn in the pre-index and post-index instructions. These are the forms that write back to Rn.

You cannot use PC for Rn in T32 STC and STC2 instructions.

A32 STC and STC2 instructions where Rn is PC, are deprecated.

# **Related references**

# C2.136 STL

Store-Release Register.

—— Note —

This instruction is supported only in Armv8.

# Syntax

STL{cond} Rt, [Rn]
STLB{cond} Rt, [Rn]
STLH{cond} Rt, [Rn]
where:
cond
 is an optional condition code.
Rt
 is the register to store.
Rn

is the register on which the memory address is based.

## Operation

STL stores data to memory. If any loads or stores appear before a store-release in program order, then all observers are guaranteed to observe the loads and stores before observing the store-release. Loads and stores appearing after a store-release are unaffected.

If a store-release follows a load-acquire, each observer is guaranteed to observe them in program order.

There is no requirement that a store-release be paired with a load-acquire.

All store-release operations are multi-copy atomic, meaning that in a multiprocessing system, if one observer observes a write to memory because of a store-release operation, then all observers observe it. Also, all observers observe all such writes to the same location in the same order.

# Restrictions

The address specified must be naturally aligned, or an alignment fault is generated.

The PC must not be used for Rt or Rn.

# Availability

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction.

# **Related references**

C2.43 LDAEX on page C2-173 C2.42 LDA on page C2-172 C2.137 STLEX on page C2-302 C1.9 Condition code suffixes on page C1-92

# C2.137 STLEX

Store-Release Register Exclusive.

# Syntax

STLEX{cond} Rd, Rt, [Rn]
STLEXB{cond} Rd, Rt, [Rn]
STLEXH{cond} Rd, Rt, [Rn]
STLEXD{cond} Rd, Rt, Rt2, [Rn]

where:

cond

Rd

Rt

is an optional condition code.

is the destination register for the returned status.

is the register to load or store.

Rt2

is the second register for doubleword loads or stores.

Rn

is the register on which the memory address is based.

# Operation

STLEX performs a conditional store to memory. The conditions are as follows:

- If the physical address does not have the Shared TLB attribute, and the executing processor has an outstanding tagged physical address, the store takes place, the tag is cleared, and the value 0 is returned in *Rd*.
- If the physical address does not have the Shared TLB attribute, and the executing processor does not have an outstanding tagged physical address, the store does not take place, and the value 1 is returned in *Rd*.
- If the physical address has the Shared TLB attribute, and the physical address is tagged as exclusive access for the executing processor, the store takes place, the tag is cleared, and the value 0 is returned in *Rd*.
- If the physical address has the Shared TLB attribute, and the physical address is not tagged as exclusive access for the executing processor, the store does not take place, and the value 1 is returned in *Rd*.

If any loads or stores appear before STLEX in program order, then all observers are guaranteed to observe the loads and stores before observing the store-release. Loads and stores appearing after STLEX are unaffected.

All store-release operations are multi-copy atomic.

# Restrictions

The PC must not be used for any of Rd, Rt, Rt2, or Rn.

For STLEX, Rd must not be the same register as Rt, Rt2, or Rn.

For A32 instructions:

- SP can be used but use of SP for any of Rd, Rt, or Rt2 is deprecated.
- For STLEXD, *Rt* must be an even numbered register, and not LR.
- *Rt2* must be *R(t+1)*.

For T32 instructions, SP can be used for Rn, but must not be used for any of Rd, Rt, or Rt2.

### Usage

Use LDAEX and STLEX to implement interprocess communication in multiple-processor and sharedmemory systems.

For reasons of performance, keep the number of instructions between corresponding LDAEX and STLEX instructions to a minimum.

\_\_\_\_\_ Note \_\_\_\_\_

The address used in a STLEX instruction must be the same as the address in the most recently executed LDAEX instruction.

## Availability

These 32-bit instructions are available in A32 and T32.

There are no 16-bit versions of these instructions.

#### **Related references**

C2.43 LDAEX on page C2-173 C2.136 STL on page C2-301 C2.42 LDA on page C2-172 C1.9 Condition code suffixes on page C1-92

# C2.138 STM

Store Multiple registers.

# Syntax

```
STM{addr_mode}{cond} Rn{!}, reglist{^}
```

where:

### addr\_mode

is any one of the following:

### IA

Increment address After each transfer. This is the default, and can be omitted.

## IB

Increment address Before each transfer (A32 only).

## DA

Decrement address After each transfer (A32 only).

### DB

Decrement address Before each transfer.

You can also use the stack-oriented addressing mode suffixes, for example when implementing stacks.

#### cond

is an optional condition code.

#### Rn

is the *base register*, the general-purpose register holding the initial address for the transfer. *Rn* must not be PC.

!

is an optional suffix. If ! is present, the final address is written back into Rn.

### reglist

is a list of one or more registers to be stored, enclosed in braces. It can contain register ranges. It must be comma-separated if it contains more than one register or register range. Any combination of registers R0 to R15 (PC) can be transferred in A32 state, but there are some restrictions in T32 state.

^

is an optional suffix, available in A32 state only. You must not use it in User mode or System mode. Data is transferred into or out of the User mode registers instead of the current mode registers.

# Restrictions on reglist in 32-bit T32 instructions

In 32-bit T32 instructions:

- The SP cannot be in the list.
- The PC cannot be in the list.
- There must be two or more registers in the list.

If you write an STM instruction with only one register in *regList*, the assembler automatically substitutes the equivalent STR instruction. Be aware of this when comparing disassembly listings with source code.

# **Restrictions on reglist in A32 instructions**

A32 store instructions can have SP and PC in the *regList* but these instructions that include SP or PC in the *regList* are deprecated.

#### 16-bit instruction

A 16-bit version of this instruction is available in T32 code.

The following restrictions apply to the 16-bit instruction:

- All registers in *regList* must be Lo registers.
- *Rn* must be a Lo register.
- *addr\_mode* must be omitted (or IA), meaning increment address after each transfer.
- Writeback must be specified for STM instructions.

#### —— Note —

16-bit T32 STM instructions with writeback that specify *Rn* as the lowest register in the *regList* are deprecated.

In addition, the PUSH and POP instructions are subsets of the STM and LDM instructions and can therefore be expressed using the STM and LDM instructions. Some forms of PUSH and POP are also 16-bit instructions.

#### Storing the base register, with writeback

In A32 or 16-bit T32 instructions, if *Rn* is in *regList*, and writeback is specified with the ! suffix:

- If the instruction is STM{addr\_mode}{cond} and Rn is the lowest-numbered register in regList, the initial value of Rn is stored. These instructions are deprecated.
- Otherwise, the stored value of Rn cannot be relied on, so these instructions are not permitted.

32-bit T32 instructions are not permitted if Rn is in regList, and writeback is specified with the ! suffix.

### **Correct example**

STMDB r1!,{r3-r6,r11,r12}

### Incorrect example

STM r5!,{r5,r4,r9} ; value stored for R5 unknown

**Related references** 

*C2.73 POP* on page C2-221

# C2.139 STR (immediate offset)

Store with immediate offset, pre-indexed immediate offset, or post-indexed immediate offset.

## Syntax

В

Byte

#### н

Halfword

-

omitted, for Word.

#### cond

is an optional condition code.

#### Rt

is the general-purpose register to store.

#### Rn

is the general-purpose register on which the memory address is based.

#### offset

is an offset. If offset is omitted, the address is the contents of Rn.

## Rt2

is the additional register to store for doubleword operations.

Not all options are available in every instruction set and architecture.

## Offset ranges and architectures

The following table shows the ranges of offsets and availability of this instruction:

#### Table C2-15 Offsets and architectures, STR, word, halfword, and byte

Instruction	Immediate offset	Pre-indexed	Post-indexed
A32, word or byte	-4095 to 4095	-4095 to 4095	-4095 to 4095
A32, halfword	-255 to 255	-255 to 255	-255 to 255

Instruction	Immediate offset	Pre-indexed	Post-indexed
A32, doubleword	-255 to 255	-255 to 255	-255 to 255
T32 32-bit encoding, word, halfword, or byte	-255 to 4095	-255 to 255	-255 to 255
T32 32-bit encoding, doubleword	-1020 to 1020 <sup>z</sup>	-1020 to 1020 <sup>z</sup>	-1020 to 1020 <sup>z</sup>
T32 16-bit encoding, word <sup>aa</sup>	0 to 124 <sup>z</sup>	Not available	Not available
T32 16-bit encoding, halfword aa	0 to 62 ac	Not available	Not available
T32 16-bit encoding, byte aa	0 to 31	Not available	Not available
T32 16-bit encoding, word, Rn is SP <sup>ab</sup>	0 to 1020 <sup>z</sup>	Not available	Not available

#### Table C2-15 Offsets and architectures, STR, word, halfword, and byte (continued)

#### **Register restrictions**

Rn must be different from Rt in the pre-index and post-index forms.

#### **Doubleword register restrictions**

Rn must be different from Rt2 in the pre-index and post-index forms.

For T32 instructions, you must not specify SP or PC for either Rt or Rt2.

For A32 instructions:

- *Rt* must be an even-numbered register.
- *Rt* must not be LR.
- Arm strongly recommends that you do not use R12 for Rt.
- Rt2 must be R(t + 1).

#### Use of PC

In A32 instructions you can use PC for Rt in STR word instructions and PC for Rn in STR instructions with immediate offset syntax (that is the forms that do not writeback to the Rn). However, this is deprecated.

Other uses of PC are not permitted in these A32 instructions.

In T32 code, using PC in STR instructions is not permitted.

#### Use of SP

You can use SP for Rn.

In A32 code, you can use SP for Rt in word instructions. You can use SP for Rt in non-word instructions in A32 code but this is deprecated.

In T32 code, you can use SP for Rt in word instructions only. All other use of SP for Rt in this instruction is not permitted in T32 code.

#### Example

STR	r2,[r9,#consta-struc]	; consta-struc is an expression ; evaluating to a constant in
		; the range 0-4095.

# **Related references**

Z Must be divisible by 4.

aa Rt and Rn must be in the range R0-R7.

ab Rt must be in the range R0-R7.

ac Must be divisible by 2.

# C2.140 STR (register offset)

Store with register offset, pre-indexed register offset, or post-indexed register offset.

## Syntax

STR{type}{cond} Rt, [Rn, ±R	<pre>m {, shift}] ; register offset</pre>
STR{type}{cond} Rt, [Rn, ±R	<pre>m {, shift}]! ; pre-indexed ; A32 only</pre>
STR{type}{cond} Rt, [Rn], ±	Rm {, shift} ; post-indexed ; A32 only
STRD{cond} Rt, Rt2, [Rn, ±R	m] ; register offset, doubleword ; A32 only
STRD{cond} Rt, Rt2, [Rn, ±R	<pre>m]! ; pre-indexed, doubleword ; A32 only</pre>
STRD{cond} Rt, Rt2, [Rn], ±	Rm ; post-indexed, doubleword ; A32 only
where:	
type	
can be any one of:	

В

	Byte
н	

- Halfword
  - omitted, for Word.

cond

Rt

Rn

- is an optional condition code.
- is the general-purpose register to store.
- is the general-purpose register on which the memory address is based.
- Rm

is a general-purpose register containing a value to be used as the offset. -Rm is not permitted in T32 code.

shift

is an optional shift.

Rt2

is the additional register to store for doubleword operations.

Not all options are available in every instruction set and architecture.

## Offset register and shift options

The following table shows the ranges of offsets and availability of this instruction:

#### Table C2-16 Options and architectures, STR (register offsets)

Instruction	±Rm <sup>ad</sup>	shift			
A32, word or byte	±Rm	LSL #0-31	LSR	#1-32	
		ASR #1-32	ROR	#1-31	RRX
A32, halfword	±Rm	Not available	•		
A32, doubleword	±Rm	Not available	;		

ad Where ±Rm is shown, you can use -Rm, +Rm, or Rm. Where +Rm is shown, you cannot use -Rm.

ae Rt, Rn, and Rm must all be in the range R0-R7.

### Table C2-16 Options and architectures, STR (register offsets) (continued)

Instruction	±Rm <sup>ad</sup>	shift	
T32 32-bit encoding, word, halfword, or byte	+Rm	LSL #0-3	
T32 16-bit encoding, all except doubleword ae	+Rm	Not available	

## **Register restrictions**

In the pre-index and post-index forms, Rn must be different from Rt.

## **Doubleword register restrictions**

For A32 instructions:

- *Rt* must be an even-numbered register.
- *Rt* must not be LR.
- Arm strongly recommends that you do not use R12 for Rt.
- Rt2 must be R(t + 1).
- Rn must be different from Rt2 in the pre-index and post-index forms.

## Use of PC

In A32 instructions you can use PC for Rt in STR word instructions, and you can use PC for Rn in STR instructions with register offset syntax (that is, the forms that do not writeback to the Rn). However, this is deprecated.

Other uses of PC are not permitted in A32 instructions.

Use of PC in STR T32 instructions is not permitted.

## Use of SP

You can use SP for Rn.

In A32 code, you can use SP for Rt in word instructions. You can use SP for Rt in non-word A32 instructions but this is deprecated.

You can use SP for Rm in A32 instructions but this is deprecated.

In T32 code, you can use SP for Rt in word instructions only. All other use of SP for Rt in this instruction is not permitted in T32 code.

Use of SP for Rm is not permitted in T32 state.

### **Related references**

# C2.141 STR, unprivileged

Unprivileged Store, byte, halfword, or word.

# Syntax

```
STR{type}T{cond} Rt, [Rn {, #offset}] ; immediate offset (T32, 32-bit encoding only)
STR{type}T{cond} Rt, [Rn] {, #offset} ; post-indexed (A32 only)
STR{type}T{cond} Rt, [Rn], ±Rm {, shift} ; post-indexed (register) (A32 only)
where:
type
```

can be any one of:

В	
	Byte
н	
	Halfword

omitted, for Word.

#### cond

is an optional condition code.

#### Rt

is the register to load or store.

#### Rn

is the register on which the memory address is based.

### offset

is an offset. If offset is omitted, the address is the value in Rn.

### Rm

is a register containing a value to be used as the offset. Rm must not be PC.

shift

is an optional shift.

### Operation

When these instructions are executed by privileged software, they access memory with the same restrictions as they would have if they were executed by unprivileged software.

When executed by unprivileged software, these instructions behave in exactly the same way as the corresponding store instruction, for example STRBT behaves in the same way as STRB.

### Offset ranges and architectures

The following table shows the ranges of offsets and availability of this instruction:

## Table C2-17 Offsets and architectures, STR (User mode)

Instruction	Immediate offset	Post-indexed	+/—Rm <sup>af</sup>	shift
A32, word or byte	Not available	-4095 to 4095	+/- <b>R</b> m	LSL #0-31
				LSR #1-32
				ASR #1-32
				ROR #1-31
				RRX
A32, halfword	Not available	-255 to 255	+/- <b>R</b> m	Not available
T32 32-bit encoding, word, halfword, or byte	0 to 255	Not available	Not avail	able

# **Related references**

af You can use –Rm, +Rm, or Rm.

# C2.142 STREX

Store Register Exclusive.

## Syntax

STREX{cond} Rd, Rt, [Rn {, #offset}]

STREXB{cond} Rd, Rt, [Rn]

STREXH{cond} Rd, Rt, [Rn]

STREXD{cond} Rd, Rt, Rt2, [Rn]

where:

cond

is an optional condition code.

### Rd

is the destination register for the returned status.

### Rt

is the register to store.

### Rt2

is the second register for doubleword stores.

Rn

is the register on which the memory address is based.

offset

is an optional offset applied to the value in *Rn. offset* is permitted only in T32 instructions. If *offset* is omitted, an offset of 0 is assumed.

# Operation

STREX performs a conditional store to memory. The conditions are as follows:

- If the physical address does not have the Shared TLB attribute, and the executing processor has an outstanding tagged physical address, the store takes place, the tag is cleared, and the value 0 is returned in *Rd*.
- If the physical address does not have the Shared TLB attribute, and the executing processor does not have an outstanding tagged physical address, the store does not take place, and the value 1 is returned in *Rd*.
- If the physical address has the Shared TLB attribute, and the physical address is tagged as exclusive access for the executing processor, the store takes place, the tag is cleared, and the value 0 is returned in *Rd*.
- If the physical address has the Shared TLB attribute, and the physical address is not tagged as exclusive access for the executing processor, the store does not take place, and the value 1 is returned in *Rd*.

# Restrictions

PC must not be used for any of Rd, Rt, Rt2, or Rn.

For STREX, Rd must not be the same register as Rt, Rt2, or Rn.

For A32 instructions:

- SP can be used but use of SP for any of Rd, Rt, or Rt2 is deprecated.
- For STREXD, *Rt* must be an even numbered register, and not LR.

- Rt2 must be R(t+1).
- *offset* is not permitted.

For T32 instructions:

- SP can be used for Rn, but must not be used for any of Rd, Rt, or Rt2.
- The value of *offset* can be any multiple of four in the range 0-1020.

#### Usage

Use LDREX and STREX to implement interprocess communication in multiple-processor and sharedmemory systems.

For reasons of performance, keep the number of instructions between corresponding LDREX and STREX instructions to a minimum.

----- Note -----

The address used in a STREX instruction must be the same as the address in the most recently executed LDREX instruction.

### Availability

All these 32-bit instructions are available in A32 and T32.

There are no 16-bit versions of these instructions.

#### Examples

	MOV r1, #0x1	; load the 'lock taken' value
tr	Y LDREX r0, [LockAddr] CMP r0, #0 STREXEQ r0, r1, [LockAddr] CMPEO r0 #0	; load the lock taken value ; is the lock free? ; try and claim the lock did this succeed?
	BNE try	; no – try again
		; yes – we have the lock

# **Related references**

# C2.143 SUB

Subtract without carry.

# Syntax

SUB{S}{cond} {Rd}, Rn, Operand2

SUB{cond} {Rd}, Rn, #imm12 ; T32, 32-bit encoding only

where:

## S

is an optional suffix. If S is specified, the condition flags are updated on the result of the operation.

#### cond

is an optional condition code.

## Rd

is the destination register.

#### Rn

is the register holding the first operand.

### Operand2

is a flexible second operand.

#### imm12

is any value in the range 0-4095.

# Operation

The SUB instruction subtracts the value of Operand2 or imm12 from the value in Rn.

In certain circumstances, the assembler can substitute one instruction for another. Be aware of this when reading disassembly listings.

### Use of PC and SP in T32 instructions

In general, you cannot use PC (R15) for *Rd*, or any operand. The exception is you can use PC for *Rn* in 32-bit T32 SUB instructions, with a constant *Operand2* value in the range 0-4095, and no S suffix. These instructions are useful for generating PC-relative addresses. Bit[1] of the PC value reads as 0 in this case, so that the base address for the calculation is always word-aligned.

Generally, you cannot use SP (R13) for Rd, or any operand, except that you can use SP for Rn.

# Use of PC and SP in A32 instructions

You cannot use PC for Rd or any operand in a SUB instruction that has a register-controlled shift.

In SUB instructions without register-controlled shift, use of PC is deprecated except for the following cases:

- Use of PC for Rd.
- Use of PC for Rn in the instruction SUB{cond} Rd, Rn, #Constant.

If you use PC (R15) as Rn or Rm, the value used is the address of the instruction plus 8.

If you use PC as *Rd*:

- Execution branches to the address corresponding to the result.
- If you use the S suffix, see the SUBS pc, lr instruction.

You can use SP for Rn in SUB instructions, however, SUBS PC, SP, #Constant is deprecated.

You can use SP in SUB (register) if Rn is SP and shift is omitted or LSL #1, LSL #2, or LSL #3.

Other uses of SP in A32 SUB instructions are deprecated.

----- Note -

Use of SP and PC is deprecated in A32 instructions.

#### **Condition flags**

If S is specified, the SUB instruction updates the N, Z, C and V flags according to the result.

#### **16-bit instructions**

The following forms of this instruction are available in T32 code, and are 16-bit instructions:

SUBS Rd, Rn, Rm

Rd, Rn and Rm must all be Lo registers. This form can only be used outside an IT block.

SUB{cond} Rd, Rn, Rm

Rd, Rn and Rm must all be Lo registers. This form can only be used inside an IT block.

SUBS Rd, Rn, #imm

*imm* range 0-7. *Rd* and *Rn* must both be Lo registers. This form can only be used outside an IT block.

#### SUB{cond} Rd, Rn, #imm

*imm* range 0-7. *Rd* and *Rn* must both be Lo registers. This form can only be used inside an IT block.

#### SUBS Rd, Rd, #imm

*imm* range 0-255. *Rd* must be a Lo register. This form can only be used outside an IT block.

SUB{cond} Rd, Rd, #imm

imm range 0-255. Rd must be a Lo register. This form can only be used inside an IT block.

#### SUB{cond} SP, SP, #imm

imm range 0-508, word aligned.

#### Example

SUBS r8, r6, #240 ; sets the flags based on the result

#### Multiword arithmetic examples

These instructions subtract one 96-bit integer contained in R9, R10, and R11 from another 96-bit integer contained in R6, R7, and R8, and place the result in R3, R4, and R5:

SUBS	r3,	r6,	r9
SBCS	r4,	r7,	r10
SBC	r5,	r8,	r11

For clarity, the above examples use consecutive registers for multiword values. There is no requirement to do this. The following, for example, is perfectly valid:

# **Related references**

C2.3 Flexible second operand (Operand2) on page C2-112 C2.144 SUBS pc, lr on page C2-317 C1.9 Condition code suffixes on page C1-92

# C2.144 SUBS pc, lr

Exception return, without popping anything from the stack.

### Syntax

```
SUBS{cond} pc, lr, #imm ; A32 and T32 code
MOVS{cond} pc, lr; A32 and T32 code
op1S{cond} pc, Rn, #imm ; A32 code only and is deprecated
op1S{cond} pc, Rn, Rm {, shift} ; A32 code only and is deprecated
op2S{cond} pc, #imm ; A32 code only and is deprecated
op2S{cond} pc, Rm {, shift} ; A32 code only and is deprecated
where:
op1
        is one of ADC, ADD, AND, BIC, EOR, ORN, ORR, RSB, RSC, SBC, and SUB.
op2
        is one of MOV and MVN.
cond
        is an optional condition code.
imm
        is an immediate value. In T32 code, it is limited to the range 0-255. In A32 code, it is a flexible
        second operand.
Rn
        is the first general-purpose source register. Arm deprecates the use of any register except LR.
Rm
        is the optionally shifted second or only general-purpose register.
shift
        is an optional condition code.
Usage
```

SUBS pc, 1r, #*imm* subtracts a value from the link register and loads the PC with the result, then copies the SPSR to the CPSR.

You can use SUBS pc, lr, #*imm* to return from an exception if there is no return state on the stack. The value of *#imm* depends on the exception to return from.

### Notes

SUBS pc, lr, #*imm* writes an address to the PC. The alignment of this address must be correct for the instruction set in use after the exception return:

- For a return to A32, the address written to the PC must be word-aligned.
- For a return to T32, the address written to the PC must be halfword-aligned.
- For a return to Jazelle, there are no alignment restrictions on the address written to the PC.

No special precautions are required in software to follow these rules, if you use the instruction to return after a valid exception entry mechanism.

In T32, only SUBS{*cond*} pc, lr, *#imm* is a valid instruction. MOVS pc, lr is a synonym of SUBS pc, lr, *#0*. Other instructions are undefined.

In A32, only SUBS{*cond*} pc, lr, *#imm* and MOVS{*cond*} pc, lr are valid instructions. Other instructions are deprecated.

—— Caution ——

Do not use these instructions in User mode or System mode. The assembler cannot warn you about this.

### **Availability**

This 32-bit instruction is available in A32 and T32.

The 32-bit T32 instruction is not available in the Armv7-M architecture.

There is no 16-bit version of this instruction in T32.

**Related references** 

C2.12 AND on page C2-128 C2.58 MOV on page C2-199 C2.3 Flexible second operand (Operand2) on page C2-112 C2.9 ADD on page C2-121 C1.9 Condition code suffixes on page C1-92

# C2.145 SVC

SuperVisor Call.

# Syntax

SVC{cond} #imm

where:

cond

is an optional condition code.

imm

is an expression evaluating to an integer in the range:

- 0 to 2<sup>24</sup>-1 (a 24-bit value) in an A32 instruction.
- 0-255 (an 8-bit value) in a T32 instruction.

# Operation

The SVC instruction causes an exception. This means that the processor mode changes to Supervisor, the CPSR is saved to the Supervisor mode SPSR, and execution branches to the SVC vector.

*imm* is ignored by the processor. However, it can be retrieved by the exception handler to determine what service is being requested.

——— Note —

SVC was called SWI in earlier versions of the A32 assembly language. SWI instructions disassemble to SVC, with a comment to say that this was formerly SWI.

# **Condition flags**

This instruction does not change the flags.

# Availability

This instruction is available in A32 and 16-bit T32 and in the Armv7 architectures.

There is no 32-bit version of this instruction in T32.

# **Related references**

# C2.146 SWP and SWPB

Swap data between registers and memory.

——— Note —

These instruction are not supported in Armv8.

### Syntax

SWP{B}{cond} Rt, Rt2, [Rn]

where:

cond

is an optional condition code.

#### В

is an optional suffix. If B is present, a byte is swapped. Otherwise, a 32-bit word is swapped.

#### Rt

is the destination register. Rt must not be PC.

#### Rt2

is the source register. Rt2 can be the same register as Rt. Rt2 must not be PC.

#### Rn

contains the address in memory. *Rn* must be a different register from both *Rt* and *Rt2*. *Rn* must not be PC.

#### Usage

You can use SWP and SWPB to implement semaphores:

- Data from memory is loaded into *Rt*.
- The contents of *Rt2* are saved to memory.
- If *Rt2* is the same register as *Rt*, the contents of the register are swapped with the contents of the memory location.

## Note

The use of SWP and SWPB is deprecated. You can use LDREX and STREX instructions to implement more sophisticated semaphores.

#### Availability

These instructions are available in A32.

There are no T32 SWP or SWPB instructions.

Related references C2.51 LDREX on page C2-189 C1.9 Condition code suffixes on page C1-92

# C2.147 SXTAB

Sign extend Byte with Add, to extend an 8-bit value to a 32-bit value.

### Syntax

SXTAB{cond} {Rd}, Rn, Rm {,rotation}

where:

#### cond

is an optional condition code.

## Rd

is the destination register.

# Rn

is the register holding the number to add.

### Rm

is the register holding the value to extend.

## rotation

is one of:

## ROR #8

Value from *Rm* is rotated right 8 bits.

# ROR #16

Value from *Rm* is rotated right 16 bits.

### ROR #24

Value from *Rm* is rotated right 24 bits.

If *rotation* is omitted, no rotation is performed.

# Operation

This instruction does the following:

- 1. Rotate the value from *Rm* right by 0, 8, 16 or 24 bits.
- 2. Extract bits[7:0] from the value obtained.
- 3. Sign extend to 32 bits.
- 4. Add the value from *Rn*.

### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

### **Condition flags**

This instruction does not change the flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.148 SXTAB16

Sign extend two Bytes with Add, to extend two 8-bit values to two 16-bit values.

### Syntax

SXTAB16{cond} {Rd}, Rn, Rm {,rotation}

where:

#### cond

is an optional condition code.

## Rd

is the destination register.

# Rn

is the register holding the number to add.

### Rm

is the register holding the value to extend.

### rotation

is one of:

#### ROR #8

Value from *Rm* is rotated right 8 bits.

# ROR #16

Value from *Rm* is rotated right 16 bits.

#### ROR #24

Value from *Rm* is rotated right 24 bits.

If rotation is omitted, no rotation is performed.

# Operation

This instruction does the following:

- 1. Rotate the value from *Rm* right by 0, 8, 16 or 24 bits.
- 2. Extract bits[23:16] and bits[7:0] from the value obtained.
- 3. Sign extend to 16 bits.
- 4. Add them to bits[31:16] and bits[15:0] respectively of *Rn* to form bits[31:16] and bits[15:0] of the result.

### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

*Related references C1.9 Condition code suffixes* on page C1-92
# C2.149 SXTAH

Sign extend Halfword with Add, to extend a 16-bit value to a 32-bit value.

### Syntax

SXTAH{cond} {Rd}, Rn, Rm {,rotation}

where:

#### cond

is an optional condition code.

### Rd

is the destination register.

### Rn

is the register holding the number to add.

### Rm

is the register holding the value to extend.

### rotation

is one of:

### ROR #8

Value from *Rm* is rotated right 8 bits.

### ROR #16

Value from *Rm* is rotated right 16 bits.

### ROR #24

Value from *Rm* is rotated right 24 bits.

If *rotation* is omitted, no rotation is performed.

### Operation

This instruction does the following:

- 1. Rotate the value from *Rm* right by 0, 8, 16 or 24 bits.
- 2. Extract bits[15:0] from the value obtained.
- 3. Sign extend to 32 bits.
- 4. Add the value from *Rn*.

### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

### **Condition flags**

This instruction does not change the flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.150 SXTB

Sign extend Byte, to extend an 8-bit value to a 32-bit value.

### Syntax

SXTB{cond} {Rd}, Rm {,rotation}

where:

#### cond

is an optional condition code.

### Rd

is the destination register.

#### Rm

is the register holding the value to extend.

### rotation

is one of:

# ROR #8

Value from *Rm* is rotated right 8 bits.

#### ROR #16

Value from *Rm* is rotated right 16 bits.

### ROR #24

Value from *Rm* is rotated right 24 bits.

If *rotation* is omitted, no rotation is performed.

# Operation

This instruction does the following:

- 1. Rotates the value from *Rm* right by 0, 8, 16 or 24 bits.
- 2. Extracts bits[7:0] from the value obtained.
- 3. Sign extends to 32 bits.

### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

### **16-bit instructions**

The following form of this instruction is available in T32 code, and is a 16-bit instruction:

SXTB Rd, Rm

Rd and Rm must both be Lo registers.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

The 16-bit instruction is available in T32.

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.151 SXTB16

Sign extend two bytes.

### Syntax

SXTB16{cond} {Rd}, Rm {,rotation}

where:

cond

is an optional condition code.

### Rd

is the destination register.

### Rm

is the register holding the value to extend.

### rotation

is one of:

### ROR #8

Value from *Rm* is rotated right 8 bits.

### ROR #16

Value from *Rm* is rotated right 16 bits.

### ROR #24

Value from *Rm* is rotated right 24 bits.

If rotation is omitted, no rotation is performed.

# Operation

SXTB16 extends two 8-bit values to two 16-bit values. It does this by:

- 1. Rotating the value from *Rm* right by 0, 8, 16 or 24 bits.
- 2. Extracting bits[23:16] and bits[7:0] from the value obtained.
- 3. Sign extending to 16 bits each.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.152 SXTH

Sign extend Halfword.

### Syntax

SXTH{cond} {Rd}, Rm {,rotation}

where:

cond

is an optional condition code.

### Rd

is the destination register.

#### Rm

is the register holding the value to extend.

### rotation

is one of:

# ROR #8

Value from *Rm* is rotated right 8 bits.

#### ROR #16

Value from *Rm* is rotated right 16 bits.

### ROR #24

Value from *Rm* is rotated right 24 bits.

If *rotation* is omitted, no rotation is performed.

# Operation

SXTH extends a 16-bit value to a 32-bit value. It does this by:

- 1. Rotating the value from *Rm* right by 0, 8, 16 or 24 bits.
- 2. Extracting bits[15:0] from the value obtained.
- 3. Sign extending to 32 bits.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

### **16-bit instructions**

The following form of this instruction is available in T32 code, and is a 16-bit instruction:

SXTH Rd, Rm

Rd and Rm must both be Lo registers.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

The 16-bit instruction is available in T32.

### Example

SXTH r3, r9

# Incorrect example

SXTH r3, r9, ROR #12 ; rotation must be 0, 8, 16, or 24.

**Related references** 

# C2.153 SYS

Execute system coprocessor instruction.

### Syntax

SYS{cond} instruction{, Rn}

where:

cond

is an optional condition code.

instruction

is the coprocessor instruction to execute.

Rn

is an operand to the instruction. For instructions that take an argument, *Rn* is compulsory. For instructions that do not take an argument, *Rn* is optional and if it is not specified, R0 is used. *Rn* must not be PC.

### Usage

You can use this pseudo-instruction to execute special coprocessor instructions such as cache, branch predictor, and TLB operations. The instructions operate by writing to special write-only coprocessor registers. The instruction names are the same as the write-only coprocessor register names and are listed in the *Arm*<sup>®</sup> *Architecture Reference Manual*. For example:

SYS ICIALLUIS ; invalidates all instruction caches Inner Shareable ; to Point of Unification and also flushes branch ; target cache.

# Availability

This 32-bit instruction is available in A32 and T32.

The 32-bit T32 instruction is not available in the Armv7-M architecture.

There is no 16-bit version of this instruction in T32.

**Related references** C1.9 Condition code suffixes on page C1-92 **Related information** Arm Architecture Reference Manual

# C2.154 TBB and TBH

Table Branch Byte and Table Branch Halfword.

### Syntax

```
TBB [Rn, Rm]
TBH [Rn, Rm, LSL #1]
where:
```

Rn

is the base register. This contains the address of the table of branch lengths. Rn must not be SP.

If PC is specified for *Rn*, the value used is the address of the instruction plus 4.

Rm

is the index register. This contains an index into the table.

*Rm* must not be PC or SP.

# Operation

These instructions cause a PC-relative forward branch using a table of single byte offsets (TBB) or halfword offsets (TBH). *Rn* provides a pointer to the table, and *Rm* supplies an index into the table. The branch length is twice the value of the byte (TBB) or the halfword (TBH) returned from the table. The target of the branch table must be in the same execution state.

# Architectures

These 32-bit T32 instructions are available.

There are no versions of these instructions in A32 or in 16-bit T32 encodings.

# C2.155 TEQ

Test Equivalence.

### Syntax

TEQ{cond} Rn, Operand2

where:

cond

is an optional condition code.

Rn

is the general-purpose register holding the first operand.

Operand2

is a flexible second operand.

### Usage

This instruction tests the value in a register against *Operand2*. It updates the condition flags on the result, but does not place the result in any register.

The TEQ instruction performs a bitwise Exclusive OR operation on the value in *Rn* and the value of *Operand2*. This is the same as an EORS instruction, except that the result is discarded.

Use the TEQ instruction to test if two values are equal, without affecting the V or C flags (as CMP does).

TEQ is also useful for testing the sign of a value. After the comparison, the N flag is the logical Exclusive OR of the sign bits of the two operands.

### **Register restrictions**

In this T32 instruction, you cannot use SP or PC for Rn or Operand2.

In this A32 instruction, use of SP or PC is deprecated.

For A32 instructions:

- If you use PC (R15) as Rn, the value used is the address of the instruction plus 8.
- You cannot use PC for any operand in any data processing instruction that has a register-controlled shift.

### **Condition flags**

This instruction:

- Updates the N and Z flags according to the result.
- Can update the C flag during the calculation of *Operand2*.
- Does not affect the V flag.

### Architectures

This instruction is available in A32 and T32.

### **Correct example**

TEQEQ r10, r9

### Incorrect example

TEQ pc, r1, ROR r0

; PC not permitted with register ; controlled shift

**Related references** C2.3 Flexible second operand (Operand2) on page C2-112 C1.9 Condition code suffixes on page C1-92

# C2.156 TST

Test bits.

### Syntax

TST{cond} Rn, Operand2

where:

cond

is an optional condition code.

Rn

is the general-purpose register holding the first operand.

Operand2

is a flexible second operand.

# Operation

This instruction tests the value in a register against *Operand2*. It updates the condition flags on the result, but does not place the result in any register.

The TST instruction performs a bitwise AND operation on the value in *Rn* and the value of *Operand2*. This is the same as an ANDS instruction, except that the result is discarded.

# **Register restrictions**

In this T32 instruction, you cannot use SP or PC for Rn or Operand2.

In this A32 instruction, use of SP or PC is deprecated.

For A32 instructions:

- If you use PC (R15) as Rn, the value used is the address of the instruction plus 8.
- You cannot use PC for any operand in any data processing instruction that has a register-controlled shift.

# **Condition flags**

This instruction:

- Updates the N and Z flags according to the result.
- Can update the C flag during the calculation of *Operand2*.
- Does not affect the V flag.

# **16-bit instructions**

The following form of the TST instruction is available in T32 code, and is a 16-bit instruction:

TST Rn, Rm

Rn and Rm must both be Lo registers.

# Architectures

This instruction is available A32 and T32.

# Examples

TST r0, #0x3F8 TSTNE r1, r5, ASR r1

**Related references** C2.3 Flexible second operand (Operand2) on page C2-112

# C2.157 TT, TTT, TTA, TTAT

Test Target (Alternate Domain, Unprivileged).

# Syntax

```
TT{cond}{q} Rd, Rn ; T1 TT general registers (T32)
TTA{cond}{q} Rd, Rn ; T1 TTA general registers (T32)
TTAT{cond}{q} Rd, Rn ; T1 TTAT general registers (T32)
TTT{cond}{q} Rd, Rn ; T1 TTT general registers (T32)
Where:
```

cond

Is an optional condition code. It specifies the condition under which the instruction is executed. If cond is omitted, it defaults to *always* (AL). See *Chapter C1 Condition Codes* on page C1-83.

q

Rn

Is an optional instruction width specifier. See *C2.2 Instruction width specifiers* on page C2-111. *Rd* 

Is the destination general-purpose register into which the status result of the target test is written.

Is the general-purpose base register.

### Usage

Test Target (TT) queries the security state and access permissions of a memory location.

Test Target Unprivileged (TTT) queries the security state and access permissions of a memory location for an unprivileged access to that location.

Test Target Alternate Domain (TTA) and Test Target Alternate Domain Unprivileged (TTAT) query the security state and access permissions of a memory location for a Non-secure access to that location. These instructions are only valid when executing in Secure state, and are UNDEFINED if used from Non-secure state.

These instructions return the security state and access permissions in the destination register, the contents of which are as follows:

Bits	Name	Description
[7:0]	MREGION	The MPU region that the address maps to. This field is 0 if MRVALID is 0.
[15:8]	SREGION	The SAU region that the address maps to. This field is only valid if the instruction is executed from Secure state. This field is 0 if SRVALID is 0.
[16]	MRVALID	Set to 1 if the MREGION content is valid. Set to 0 if the MREGION content is invalid.
[17]	SRVALID	Set to 1 if the SREGION content is valid. Set to 0 if the SREGION content is invalid.
[18]	R	Read accessibility. Set to 1 if the memory location can be read according to the permissions of the selected MPU when operating in the current mode. For TTT and TTAT, this bit returns the permissions for unprivileged access, regardless of whether the current mode is privileged or unprivileged.
[19]	RW	Read/write accessibility. Set to 1 if the memory location can be read and written according to the permissions of the selected MPU when operating in the current mode. For TTT and TTAT, this bit returns the permissions for unprivileged access, regardless of whether the current mode is privileged or unprivileged.
[20]	NSR	Equal to R AND NOT S. Can be used in combination with the LSLS (immediate) instruction to check both the MPU and SAU/IDAU permissions. This bit is only valid if the instruction is executed from Secure state and the R field is valid.

#### (continued)

Bits	Name	Description
[21]	NSRW	Equal to RW AND NOT S. Can be used in combination with the LSLS (immediate) instruction to check both the MPU and SAU/IDAU permissions. This bit is only valid if the instruction is executed from Secure state and the RW field is valid.
[22]	S	Security. A value of 1 indicates the memory location is Secure, and a value of 0 indicates the memory location is Non-secure. This bit is only valid if the instruction is executed from Secure state.
[23]	IRVALID	IREGION valid flag. For a Secure request, indicates the validity of the IREGION field. Set to 1 if the IREGION content is valid. Set to 0 if the IREGION content is invalid. This bit is always 0 if the IDAU cannot provide a region number, the address is exempt from security attribution, or if the requesting TT instruction is executed from the Non-secure state.
[31:24]	IREGION	IDAU region number. Indicates the IDAU region number containing the target address. This field is 0 if IRVALID is0.

Invalid fields are 0.

The MREGION field is invalid and 0 if any of the following conditions are true:

- The MPU is not present or MPU\_CTRL.ENABLE is 0.
- The address did not match any enabled MPU regions.
- The address matched multiple MPU regions.
- TT or TTT was executed from an unprivileged mode.

The SREGION field is invalid and 0 if any of the following conditions are true:

- SAU\_CTRL.ENABLE is set to 0.
- The address did not match any enabled SAU regions.
- The address matched multiple SAU regions.
- The SAU attributes were overridden by the IDAU.
- The instruction is executed from Non-secure state, or is executed on a processor that does not implement the Armv8-M Security Extensions.

The R and RW bits are invalid and 0 if any of the following conditions are true:

- The address matched multiple MPU regions.
- TT or TTT is executed from an unprivileged mode.

#### **Related references**

*C1.9 Condition code suffixes* on page C1-92

C2.2 Instruction width specifiers on page C2-111

# C2.158 UADD8

Unsigned parallel byte-wise addition.

### Syntax

UADD8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction performs four unsigned integer additions on the corresponding bytes of the operands and writes the results into the corresponding bytes of the destination. The results are modulo  $2^8$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **GE flags**

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

# GE[0]

for bits[7:0] of the result.

# GE[1]

for bits[15:8] of the result.

### GE[2]

for bits[23:16] of the result.

```
GE[3]
```

for bits[31:24] of the result.

It sets a GE flag to 1 to indicate that the corresponding result overflowed, generating a carry. This is equivalent to an ADDS instruction setting the C condition flag to 1.

You can use these flags to control a following SEL instruction.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

**Related references** C2.100 SEL on page C2-257 C1.9 Condition code suffixes on page C1-92

# C2.159 UADD16

Unsigned parallel halfword-wise addition.

### Syntax

UADD16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction performs two unsigned integer additions on the corresponding halfwords of the operands and writes the results into the corresponding halfwords of the destination. The results are modulo  $2^{16}$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **GE flags**

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

### GE[1:0]

for bits[15:0] of the result.

# GE[3:2]

for bits[31:16] of the result.

It sets a pair of GE flags to 1 to indicate that the corresponding result overflowed, generating a carry. This is equivalent to an ADDS instruction setting the C condition flag to 1.

You can use these flags to control a following SEL instruction.

— Note –

GE[1:0] are set or cleared together, and GE[3:2] are set or cleared together.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

**Related references** C2.100 SEL on page C2-257 C1.9 Condition code suffixes on page C1-92

# C2.160 UASX

Unsigned parallel add and subtract halfwords with exchange.

### Syntax

UASX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction exchanges the two halfwords of the second operand, then performs an addition on the two top halfwords of the operands and a subtraction on the bottom two halfwords. It writes the results into the corresponding halfwords of the destination. The results are modulo  $2^{16}$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# GE flags

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

# GE[1:0]

for bits[15:0] of the result.

# GE[3:2]

for bits[31:16] of the result.

It sets GE[1:0] to 1 to indicate that the subtraction gave a result greater than or equal to zero, meaning a borrow did not occur. This is equivalent to a SUBS instruction setting the C condition flag to 1.

It sets GE[3:2] to 1 to indicate that the addition overflowed, generating a carry. This is equivalent to an ADDS instruction setting the C condition flag to 1.

You can use these flags to control a following SEL instruction.

—— Note –

GE[1:0] are set or cleared together, and GE[3:2] are set or cleared together.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

*Related references C2.100 SEL* on page C2-257 *C1.9 Condition code suffixes* on page C1-92

# C2.161 UBFX

Unsigned Bit Field Extract.

### Syntax

UBFX{cond} Rd, Rn, #Lsb, #width
where:

### cond

is an optional condition code.

### Rd

is the destination register.

### Rn

is the source register.

### Lsb

is the bit number of the least significant bit in the bitfield, in the range 0 to 31.

### width

is the width of the bitfield, in the range 1 to (32–Lsb).

# Operation

Copies adjacent bits from one register into the least significant bits of a second register, and zero extends to 32 bits.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not alter any flags.

# Architectures

This instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.162 UDF

Permanently Undefined.

# Syntax

```
UDF{c}{q} {#}imm ; A1 general registers (A32)
UDF{c}{q} {#}imm ; T1 general registers (T32)
```

```
UDF{c}.W {#}imm ; T2 general registers (T32)
```

Where:

# wnei

imm

The value depends on the instruction variant:

### A1 general registers

For A32, a 16-bit unsigned immediate, in the range 0 to 65535.

### T1 general registers

For T32, an 8-bit unsigned immediate, in the range 0 to 255.

# T2 general registers

– Note –

For T32, a 16-bit unsigned immediate, in the range 0 to 65535.

The PE ignores the value of this constant.

с

Is an optional condition code. See *Chapter C1 Condition Codes* on page C1-83. Arm deprecates using any *c* value other than AL.

q

Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.

# Usage

Permanently Undefined generates an Undefined Instruction exception.

The encodings for UDF used in this section are defined as permanently UNDEFINED in the Armv8-A architecture. However:

- With the T32 instruction set, Arm deprecates using the UDF instruction in an IT block.
- In the A32 instruction set, UDF is not conditional.

# **Related references**

C2.1 A32 and T32 instruction summary on page C2-106

# C2.163 UDIV

Unsigned Divide.

Syntax	
UDIV{cond} {Rd}, Rn, Rm	
where:	
cond	
is an optional condition code.	
<i>Rd</i> is the destination register.	
Rn	
is the register holding the value to be divide	d.
Rm	
is a register notating the divisor.	

# **Register restrictions**

PC or SP cannot be used for Rd, Rn, or Rm.

### Architectures

This 32-bit T32 instruction is available in Armv7-R, Armv7-M and Armv8-M Mainline.

This 32-bit A32 instruction is optional in Armv7-R.

This 32-bit A32 and T32 instruction is available in Armv7-A if Virtualization Extensions are implemented, and optional if not.

There is no 16-bit T32 UDIV instruction.

### **Related references**

# C2.164 UHADD8

Unsigned halving parallel byte-wise addition.

### Syntax

UHADD8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction performs four unsigned integer additions on the corresponding bytes of the operands, halves the results, and writes the results into the corresponding bytes of the destination. This cannot cause overflow.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.165 UHADD16

Unsigned halving parallel halfword-wise addition.

### Syntax

UHADD16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction performs two unsigned integer additions on the corresponding halfwords of the operands, halves the results, and writes the results into the corresponding halfwords of the destination. This cannot cause overflow.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.166 UHASX

Unsigned halving parallel add and subtract halfwords with exchange.

### Syntax

UHASX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction exchanges the two halfwords of the second operand, then performs an addition on the two top halfwords of the operands and a subtraction on the bottom two halfwords. It halves the results and writes them into the corresponding halfwords of the destination. This cannot cause overflow.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.167 UHSAX

Unsigned halving parallel subtract and add halfwords with exchange.

### Syntax

UHSAX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction exchanges the two halfwords of the second operand, then performs a subtraction on the two top halfwords of the operands and an addition on the bottom two halfwords. It halves the results and writes them into the corresponding halfwords of the destination. This cannot cause overflow.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.168 UHSUB8

Unsigned halving parallel byte-wise subtraction.

### Syntax

UHSUB8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction subtracts each byte of the second operand from the corresponding byte of the first operand, halves the results, and writes the results into the corresponding bytes of the destination. This cannot cause overflow.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.169 UHSUB16

Unsigned halving parallel halfword-wise subtraction.

### Syntax

UHSUB16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

### Operation

This instruction subtracts each halfword of the second operand from the corresponding halfword of the first operand, halves the results, and writes the results into the corresponding halfwords of the destination. This cannot cause overflow.

### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

### **Related references**

# C2.170 UMAAL

Unsigned Multiply Accumulate Accumulate Long.

### Syntax

UMAAL{cond} RdLo, RdHi, Rn, Rm

where:

cond

is an optional condition code.

RdLo, RdHi

are the destination registers for the 64-bit result. They also hold the two 32-bit accumulate operands. *RdLo* and *RdHi* must be different registers.

Rn, Rm

are the general-purpose registers holding the multiply operands.

### Operation

The UMAAL instruction multiplies the 32-bit values in *Rn* and *Rm*, adds the two 32-bit values in *RdHi* and *RdLo*, and stores the 64-bit result to *RdLo*, *RdHi*.

### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

### **Condition flags**

This instruction does not change the flags.

### Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

### Examples

UMAAL r8, r9, r2, r3 UMAALGE r2, r0, r5, r3

**Related references** 

# C2.171 UMLAL

Unsigned Long Multiply, with optional Accumulate, with 32-bit operands and 64-bit result and accumulator.

### Syntax

UMLAL{S}{cond} RdLo, RdHi, Rn, Rm

where:

### S

is an optional suffix available in A32 state only. If S is specified, the condition flags are updated based on the result of the operation.

cond

is an optional condition code.

#### RdLo, RdHi

are the destination registers. They also hold the accumulating value. *RdLo* and *RdHi* must be different registers.

Rn, Rm

are general-purpose registers holding the operands.

### Operation

The UMLAL instruction interprets the values from *Rn* and *Rm* as unsigned integers. It multiplies these integers, and adds the 64-bit result to the 64-bit unsigned integer contained in *RdHi* and *RdLo*.

### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

### **Condition flags**

If S is specified, this instruction:

- Updates the N and Z flags according to the result.
- Does not affect the C or V flags.

# Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# Example

UMLALS r4, r5, r3, r8

**Related references** 

# C2.172 UMULL

Unsigned Long Multiply, with 32-bit operands, and 64-bit result.

### Syntax

UMULL{S}{cond} RdLo, RdHi, Rn, Rm

where:

### S

is an optional suffix available in A32 state only. If S is specified, the condition flags are updated based on the result of the operation.

#### cond

is an optional condition code.

### RdLo, RdHi

are the destination general-purpose registers. RdLo and RdHi must be different registers.

Rn, Rm

are general-purpose registers holding the operands.

### Operation

The UMULL instruction interprets the values from Rn and Rm as unsigned integers. It multiplies these integers and places the least significant 32 bits of the result in RdLo, and the most significant 32 bits of the result in RdHi.

### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

If S is specified, this instruction:

- Updates the N and Z flags according to the result.
- Does not affect the C or V flags.

### Architectures

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

### Example

UMULL r0, r4, r5, r6

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.173 UQADD8

Unsigned saturating parallel byte-wise addition.

# Syntax

UQADD8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction performs four unsigned integer additions on the corresponding bytes of the operands and writes the results into the corresponding bytes of the destination. It saturates the results to the unsigned range  $0 \le x \le 2^8$  -1. The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.174 UQADD16

Unsigned saturating parallel halfword-wise addition.

### Syntax

UQADD16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction performs two unsigned integer additions on the corresponding halfwords of the operands and writes the results into the corresponding halfwords of the destination. It saturates the results to the unsigned range  $0 \le x \le 2^{16}$  -1. The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.175 UQASX

Unsigned saturating parallel add and subtract halfwords with exchange.

### Syntax

UQASX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction exchanges the two halfwords of the second operand, then performs an addition on the two top halfwords of the operands and a subtraction on the bottom two halfwords. It writes the results into the corresponding halfwords of the destination. It saturates the results to the unsigned range  $0 \le x \le 2^{16}$ -1. The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**
# C2.176 UQSAX

Unsigned saturating parallel subtract and add halfwords with exchange.

#### Syntax

UQSAX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction exchanges the two halfwords of the second operand, then performs a subtraction on the two top halfwords of the operands and an addition on the bottom two halfwords. It writes the results into the corresponding halfwords of the destination. It saturates the results to the unsigned range  $0 \le x \le 2^{16}$ -1. The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.177 UQSUB8

Unsigned saturating parallel byte-wise subtraction.

# Syntax

UQSUB8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction subtracts each byte of the second operand from the corresponding byte of the first operand and writes the results into the corresponding bytes of the destination. It saturates the results to the unsigned range  $0 \le x \le 2^8$  -1. The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.178 UQSUB16

Unsigned saturating parallel halfword-wise subtraction.

#### Syntax

UQSUB16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction subtracts each halfword of the second operand from the corresponding halfword of the first operand and writes the results into the corresponding halfwords of the destination. It saturates the results to the unsigned range  $0 \le x \le 2^{16}$  -1. The Q flag is not affected even if this operation saturates.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, Q, or GE flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.179 USAD8

Unsigned Sum of Absolute Differences.

## Syntax

USAD8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination register.

Rn

is the register holding the first operand.

#### Rm

is the register holding the second operand.

# Operation

The USAD8 instruction finds the four differences between the unsigned values in corresponding bytes of Rn and Rm. It adds the absolute values of the four differences, and saves the result to Rd.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not alter any flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

#### Example

USAD8 r2, r4, r6

**Related references** C1.9 Condition code suffixes on page C1-92

# C2.180 USADA8

Unsigned Sum of Absolute Differences and Accumulate.

#### Syntax

USADA8{cond} Rd, Rn, Rm, Ra

where:

## cond

is an optional condition code.

#### Rd

is the destination register.

# Rn

is the register holding the first operand.

#### Rm

is the register holding the second operand.

#### Ra

is the register holding the accumulate operand.

# Operation

The USADA8 instruction adds the absolute values of the four differences to the value in Ra, and saves the result to Rd.

#### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not alter any flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

#### **Correct examples**

USADA8 r0, r3, r5, r2 USADA8VS r0, r4, r0, r1

## **Incorrect examples**

USADA8 r2, r4, r6 ; USADA8 requires four registers USADA16 r0, r4, r0, r1 ; no such instruction

#### **Related references**

# C2.181 USAT

Unsigned Saturate to any bit position, with optional shift before saturating.

#### Syntax

```
USAT{cond} Rd, #sat, Rm{, shift}
```

where:

#### cond

is an optional condition code.

#### Rd

is the destination register.

#### sat

specifies the bit position to saturate to, in the range 0 to 31.

#### Rm

is the register containing the operand.

#### shift

is an optional shift. It must be one of the following:

#### ASR #n

where *n* is in the range 1-32 (A32) or 1-31 (T32).

#### LSL #n

where *n* is in the range 0-31.

# Operation

The USAT instruction applies the specified shift to a signed value, then saturates to the unsigned range  $0 \le x \le 2^{\text{sat}} - 1$ .

#### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# Q flag

If saturation occurs, this instruction sets the Q flag. To read the state of the Q flag, use an MRS instruction.

#### Architectures

This instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# Example

USATNE r0, #7, r5

**Related references** C2.131 SSAT16 on page C2-292 C2.62 MRS (PSR to general-purpose register) on page C2-204 C1.9 Condition code suffixes on page C1-92

# C2.182 USAT16

Parallel halfword Saturate.

#### Syntax

USAT16{cond} Rd, #sat, Rn

where:

cond

is an optional condition code.

#### Rd

is the destination register.

#### sat

specifies the bit position to saturate to, in the range 0 to 15.

#### Rn

is the register holding the operand.

# Operation

Halfword-wise unsigned saturation to any bit position.

The USAT16 instruction saturates each signed halfword to the unsigned range  $0 \le x \le 2^{\text{sat}} - 1$ .

## **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# Q flag

If saturation occurs on either halfword, this instruction sets the Q flag. To read the state of the Q flag, use an MRS instruction.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# Example

USAT16 r0, #7, r5

#### **Related references**

*C2.62 MRS (PSR to general-purpose register)* on page C2-204 *C1.9 Condition code suffixes* on page C1-92

# C2.183 USAX

Unsigned parallel subtract and add halfwords with exchange.

#### Syntax

USAX{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction exchanges the two halfwords of the second operand, then performs a subtraction on the two top halfwords of the operands and an addition on the bottom two halfwords. It writes the results into the corresponding halfwords of the destination. The results are modulo  $2^{16}$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **GE flags**

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

#### GE[1:0]

for bits[15:0] of the result.

#### GE[3:2]

for bits[31:16] of the result.

It sets GE[1:0] to 1 to indicate that the addition overflowed, generating a carry. This is equivalent to an ADDS instruction setting the C condition flag to 1.

It sets GE[3:2] to 1 to indicate that the subtraction gave a result greater than or equal to zero, meaning a borrow did not occur. This is equivalent to a SUBS instruction setting the C condition flag to 1.

You can use these flags to control a following SEL instruction.

\_\_\_\_\_ Note \_\_\_\_

GE[1:0] are set or cleared together, and GE[3:2] are set or cleared together.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

**Related references** C2.100 SEL on page C2-257 C1.9 Condition code suffixes on page C1-92

# C2.184 USUB8

Unsigned parallel byte-wise subtraction.

## Syntax

USUB8{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction subtracts each byte of the second operand from the corresponding byte of the first operand and writes the results into the corresponding bytes of the destination. The results are modulo  $2^8$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **GE flags**

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

# GE[0]

for bits[7:0] of the result.

# GE[1]

for bits[15:8] of the result.

#### GE[2]

for bits[23:16] of the result.

```
GE[3]
```

for bits[31:24] of the result.

It sets a GE flag to 1 to indicate that the corresponding result is greater than or equal to zero, meaning a borrow did not occur. This is equivalent to a SUBS instruction setting the C condition flag to 1.

You can use these flags to control a following SEL instruction.

# Availability

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

**Related references** C2.100 SEL on page C2-257

# C2.185 USUB16

Unsigned parallel halfword-wise subtraction.

#### Syntax

USUB16{cond} {Rd}, Rn, Rm

where:

cond

is an optional condition code.

Rd

is the destination general-purpose register.

Rm, Rn

are the general-purpose registers holding the operands.

# Operation

This instruction subtracts each halfword of the second operand from the corresponding halfword of the first operand and writes the results into the corresponding halfwords of the destination. The results are modulo  $2^{16}$ . It sets the APSR GE flags.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not affect the N, Z, C, V, or Q flags.

It sets the GE flags in the APSR as follows:

# GE[1:0]

for bits[15:0] of the result.

# GE[3:2]

for bits[31:16] of the result.

It sets a pair of GE flags to 1 to indicate that the corresponding result is greater than or equal to zero, meaning a borrow did not occur. This is equivalent to a SUBS instruction setting the C condition flag to 1.

You can use these flags to control a following SEL instruction.

— Note –

GE[1:0] are set or cleared together, and GE[3:2] are set or cleared together.

# Availability

This 32-bit instruction is available in A32 and T32.

There is no 16-bit version of this instruction in T32.

# **Related references**

C2.100 SEL on page C2-257 C1.9 Condition code suffixes on page C1-92

# C2.186 UXTAB

Zero extend Byte and Add.

## Syntax

UXTAB{cond} {Rd}, Rn, Rm {,rotation}

where:

cond

is an optional condition code.

# Rd

is the destination register.

# Rn

is the register holding the number to add.

## Rm

is the register holding the value to extend.

## rotation

is one of:

#### ROR #8

Value from *Rm* is rotated right 8 bits.

# ROR #16

Value from *Rm* is rotated right 16 bits.

#### ROR #24

Value from *Rm* is rotated right 24 bits.

If *rotation* is omitted, no rotation is performed.

# Operation

UXTAB extends an 8-bit value to a 32-bit value. It does this by:

- 1. Rotating the value from *Rm* right by 0, 8, 16 or 24 bits.
- 2. Extracting bits[7:0] from the value obtained.
- 3. Zero extending to 32 bits.
- 4. Adding the value from *Rn*.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.187 UXTAB16

Zero extend two Bytes and Add.

## Syntax

UXTAB16{cond} {Rd}, Rn, Rm {,rotation}

where:

#### cond

is an optional condition code.

## Rd

is the destination register.

# Rn

is the register holding the number to add.

## Rm

is the register holding the value to extend.

## rotation

is one of:

## ROR #8

Value from *Rm* is rotated right 8 bits.

# ROR #16

Value from *Rm* is rotated right 16 bits.

#### ROR #24

Value from *Rm* is rotated right 24 bits.

If *rotation* is omitted, no rotation is performed.

# Operation

UXTAB16 extends two 8-bit values to two 16-bit values. It does this by:

- 1. Rotating the value from *Rm* right by 0, 8, 16 or 24 bits.
- 2. Extracting bits[23:16] and bits[7:0] from the value obtained.
- 3. Zero extending them to 16 bits.
- 4. Adding them to bits[31:16] and bits[15:0] respectively of *Rn* to form bits[31:16] and bits[15:0] of the result.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

## Example

UXTAB16EQ r0, r0, r4, ROR #16

**Related references** 

# C2.188 UXTAH

Zero extend Halfword and Add.

# Syntax

UXTAH{cond} {Rd}, Rn, Rm {,rotation}

where:

#### cond

is an optional condition code.

# Rd

is the destination register.

# Rn

is the register holding the number to add.

## Rm

is the register holding the value to extend.

## rotation

is one of:

## ROR #8

Value from *Rm* is rotated right 8 bits.

# ROR #16

Value from *Rm* is rotated right 16 bits.

#### ROR #24

Value from *Rm* is rotated right 24 bits.

If *rotation* is omitted, no rotation is performed.

# Operation

UXTAH extends a 16-bit value to a 32-bit value. It does this by:

- 1. Rotating the value from *Rm* right by 0, 8, 16 or 24 bits.
- 2. Extracting bits[15:0] from the value obtained.
- 3. Zero extending to 32 bits.
- 4. Adding the value from *Rn*.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.189 UXTB

Zero extend Byte.

## Syntax

UXTB{cond} {Rd}, Rm {,rotation}

where:

cond

is an optional condition code.

#### Rd

is the destination register.

#### Rm

is the register holding the value to extend.

#### rotation

is one of:

# ROR #8

Value from *Rm* is rotated right 8 bits.

#### ROR #16

Value from *Rm* is rotated right 16 bits.

#### ROR #24

Value from *Rm* is rotated right 24 bits.

If *rotation* is omitted, no rotation is performed.

# Operation

UXTB extends an 8-bit value to a 32-bit value. It does this by:

- 1. Rotating the value from *Rm* right by 0, 8, 16, or 24 bits.
- 2. Extracting bits[7:0] from the value obtained.
- 3. Zero extending to 32 bits.

#### **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

#### **16-bit instruction**

The following form of this instruction is available in T32 code, and is a 16-bit instruction:

UXTB Rd, Rm

Rd and Rm must both be Lo registers.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

The 16-bit instruction is available in T32.

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.190 UXTB16

Zero extend two Bytes.

#### Syntax

UXTB16{cond} {Rd}, Rm {,rotation}

where:

cond

is an optional condition code.

#### Rd

is the destination register.

#### Rm

is the register holding the value to extend.

#### rotation

is one of:

#### ROR #8

Value from *Rm* is rotated right 8 bits.

#### ROR #16

Value from *Rm* is rotated right 16 bits.

#### ROR #24

Value from *Rm* is rotated right 24 bits.

If *rotation* is omitted, no rotation is performed.

# Operation

UXTB16 extends two 8-bit values to two 16-bit values. It does this by:

- 1. Rotating the value from *Rm* right by 0, 8, 16 or 24 bits.
- 2. Extracting bits[23:16] and bits[7:0] from the value obtained.
- 3. Zero extending each to 16 bits.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

There is no 16-bit version of this instruction in T32.

# **Related references**

# C2.191 UXTH

Zero extend Halfword.

# Syntax

UXTH{cond} {Rd}, Rm {,rotation}

where:

cond

is an optional condition code.

## Rd

is the destination register.

#### Rm

is the register holding the value to extend.

## rotation

is one of:

# ROR #8

Value from *Rm* is rotated right 8 bits.

#### ROR #16

Value from *Rm* is rotated right 16 bits.

## ROR #24

Value from *Rm* is rotated right 24 bits.

If *rotation* is omitted, no rotation is performed.

# Operation

UXTH extends a 16-bit value to a 32-bit value. It does this by:

- 1. Rotating the value from *Rm* right by 0, 8, 16, or 24 bits.
- 2. Extracting bits[15:0] from the value obtained.
- 3. Zero extending to 32 bits.

# **Register restrictions**

You cannot use PC for any operand.

You can use SP in A32 instructions but this is deprecated. You cannot use SP in T32 instructions.

# **Condition flags**

This instruction does not change the flags.

# **16-bit instructions**

The following form of this instruction is available in T32 code, and is a 16-bit instruction:

UXTH Rd, Rm

*Rd* and *Rm* must both be Lo registers.

# Availability

The 32-bit instruction is available in A32 and T32.

For the Armv7-M architecture, the 32-bit T32 instruction is only available in an Armv7E-M implementation.

The 16-bit instruction is available in T32.

*Related references C1.9 Condition code suffixes* on page C1-92

# C2.192 WFE

Wait For Event.

Syntax

WFE{cond}

where:

cond

is an optional condition code.

## Operation

This is a hint instruction. It is optional whether this instruction is implemented or not. If this instruction is not implemented, it executes as a NOP. The assembler produces a diagnostic message if the instruction executes as a NOP on the target.

If the Event Register is not set, WFE suspends execution until one of the following events occurs:

- An IRQ interrupt, unless masked by the CPSR I-bit.
- An FIQ interrupt, unless masked by the CPSR F-bit.
- An Imprecise Data abort, unless masked by the CPSR A-bit.
- A Debug Entry request, if Debug is enabled.
- An Event signaled by another processor using the SEV instruction, or by the current processor using the SEVL instruction.

If the Event Register is set, WFE clears it and returns immediately.

If WFE is implemented, SEV must also be implemented.

# Availability

This instruction is available in A32 and T32.

#### **Related references**

*C2.68 NOP* on page C2-213 *C1.9 Condition code suffixes* on page C1-92 *C2.103 SEV* on page C2-261 *C2.104 SEVL* on page C2-262 *C2.193 WFI* on page C2-385

# C2.193 WFI

Wait for Interrupt.

#### Syntax

WFI{cond}

where:

cond

is an optional condition code.

# Operation

This is a hint instruction. It is optional whether this instruction is implemented or not. If this instruction is not implemented, it executes as a NOP. The assembler produces a diagnostic message if the instruction executes as a NOP on the target.

WFI suspends execution until one of the following events occurs:

- An IRQ interrupt, regardless of the CPSR I-bit.
- An FIQ interrupt, regardless of the CPSR F-bit.
- An Imprecise Data abort, unless masked by the CPSR A-bit.
- A Debug Entry request, regardless of whether Debug is enabled.

# Availability

This instruction is available in A32 and T32.

**Related references** 

*C2.68 NOP* on page C2-213 *C1.9 Condition code suffixes* on page C1-92 *C2.192 WFE* on page C2-384

# C2.194 YIELD

Yield.

Syntax

YIELD{cond}

where:

cond

is an optional condition code.

## Operation

This is a hint instruction. It is optional whether this instruction is implemented or not. If this instruction is not implemented, it executes as a NOP. The assembler produces a diagnostic message if the instruction executes as a NOP on the target.

YIELD indicates to the hardware that the current thread is performing a task, for example a spinlock, that can be swapped out. Hardware can use this hint to suspend and resume threads in a multithreading system.

# Availability

This instruction is available in A32 and T32.

Related references C2.68 NOP on page C2-213 C1.9 Condition code suffixes on page C1-92

# Chapter C3 Advanced SIMD Instructions (32-bit)

Describes Advanced SIMD assembly language instructions.

It contains the following sections:

- C3.1 Summary of Advanced SIMD instructions on page C3-391.
- C3.2 Summary of shared Advanced SIMD and floating-point instructions on page C3-394.
- C3.3 Interleaving provided by load and store element and structure instructions on page C3-395.
- C3.4 Alignment restrictions in load and store element and structure instructions on page C3-396.
- *C3.5 FLDMDBX, FLDMIAX* on page C3-397.
- C3.6 FSTMDBX, FSTMIAX on page C3-398.
- C3.7 VABA and VABAL on page C3-399.
- C3.8 VABD and VABDL on page C3-400.
- C3.9 VABS on page C3-401.
- C3.10 VACLE, VACLT, VACGE and VACGT on page C3-402.
- *C3.11 VADD* on page C3-403.
- *C3.12 VADDHN* on page C3-404.
- C3.13 VADDL and VADDW on page C3-405.
- C3.14 VAND (immediate) on page C3-406.
- C3.15 VAND (register) on page C3-407.
- C3.16 VBIC (immediate) on page C3-408.
- C3.17 VBIC (register) on page C3-409.
- C3.18 VBIF on page C3-410.
- C3.19 VBIT on page C3-411.
- C3.20 VBSL on page C3-412.
- *C3.21 VCADD* on page C3-413.
- *C3.22 VCEQ (immediate #0)* on page C3-414.
- C3.23 VCEQ (register) on page C3-415.

- C3.24 VCGE (immediate #0) on page C3-416.
- C3.25 VCGE (register) on page C3-417.
- *C3.26 VCGT (immediate #0)* on page C3-418.
- C3.27 VCGT (register) on page C3-419.
- C3.28 VCLE (immediate #0) on page C3-420.
- C3.29 VCLS on page C3-421.
- C3.30 VCLE (register) on page C3-422.
- *C3.31 VCLT (immediate #0)* on page C3-423.
- C3.32 VCLT (register) on page C3-424.
- C3.33 VCLZ on page C3-425.
- C3.34 VCMLA on page C3-426.
- C3.35 VCMLA (by element) on page C3-427.
- *C3.36 VCNT* on page C3-428.
- C3.37 VCVT (between fixed-point or integer, and floating-point) on page C3-429.
- C3.38 VCVT (between half-precision and single-precision floating-point) on page C3-430.
- C3.39 VCVT (from floating-point to integer with directed rounding modes) on page C3-431.
- C3.40 VCVTB, VCVTT (between half-precision and double-precision) on page C3-432.
- *C3.41 VDUP* on page C3-433.
- *C3.42 VEOR* on page C3-434.
- *C3.43 VEXT* on page C3-435.
- *C3.44 VFMA*, *VFMS* on page C3-436.
- C3.45 VFMAL (by scalar) on page C3-437.
- C3.46 VFMAL (vector) on page C3-438.
- C3.47 VFMSL (by scalar) on page C3-439.
- C3.48 VFMSL (vector) on page C3-440.
- *C3.49 VHADD* on page C3-441.
- C3.50 VHSUB on page C3-442.
- C3.51 VLDn (single n-element structure to one lane) on page C3-443.
- C3.52 VLDn (single n-element structure to all lanes) on page C3-445.
- C3.53 VLDn (multiple n-element structures) on page C3-447.
- *C3.54 VLDM* on page C3-449.
- *C3.55 VLDR* on page C3-450.
- C3.56 VLDR (post-increment and pre-decrement) on page C3-451.
- *C3.57 VLDR pseudo-instruction* on page C3-452.
- C3.58 VMAX and VMIN on page C3-453.
- C3.59 VMAXNM, VMINNM on page C3-454.
- C3.60 VMLA on page C3-455.
- C3.61 VMLA (by scalar) on page C3-456.
- C3.62 VMLAL (by scalar) on page C3-457.
- C3.63 VMLAL on page C3-458.
- C3.64 VMLS (by scalar) on page C3-459.
- *C3.65 VMLS* on page C3-460.
- *C3.66 VMLSL* on page C3-461.
- *C3.67 VMLSL (by scalar)* on page C3-462.
- C3.68 VMOV (immediate) on page C3-463.
- C3.69 VMOV (register) on page C3-464.
- *C3.70 VMOV (between two general-purpose registers and a 64-bit extension register)* on page C3-465.
- C3.71 VMOV (between a general-purpose register and an Advanced SIMD scalar) on page C3-466.
- C3.72 VMOVL on page C3-467.
- C3.73 VMOVN on page C3-468.
- *C3.74 VMOV2* on page C3-469.
- C3.75 VMRS on page C3-470.
- *C3.76 VMSR* on page C3-471.
- *C3.77 VMUL* on page C3-472.
- C3.78 VMUL (by scalar) on page C3-473.

- C3.79 VMULL on page C3-474.
- C3.80 VMULL (by scalar) on page C3-475.
- C3.81 VMVN (register) on page C3-476.
- C3.82 VMVN (immediate) on page C3-477.
- *C3.83 VNEG* on page C3-478.
- C3.84 VORN (register) on page C3-479.
- C3.85 VORN (immediate) on page C3-480.
- C3.86 VORR (register) on page C3-481.
- C3.87 VORR (immediate) on page C3-482.
- *C3.88 VPADAL* on page C3-483.
- *C3.89 VPADD* on page C3-484.
- *C3.90 VPADDL* on page C3-485.
- C3.91 VPMAX and VPMIN on page C3-486.
- *C3.92 VPOP* on page C3-487.
- *C3.93 VPUSH* on page C3-488.
- *C3.94 VQABS* on page C3-489.
- C3.95 VQADD on page C3-490.
- C3.96 VQDMLAL and VQDMLSL (by vector or by scalar) on page C3-491.
- C3.97 VQDMULH (by vector or by scalar) on page C3-492.
- C3.98 VODMULL (by vector or by scalar) on page C3-493.
- C3.99 VQMOVN and VQMOVUN on page C3-494.
- C3.100 VQNEG on page C3-495.
- C3.101 VQRDMULH (by vector or by scalar) on page C3-496.
- C3.102 VQRSHL (by signed variable) on page C3-497.
- C3.103 VQRSHRN and VQRSHRUN (by immediate) on page C3-498.
- C3.104 VQSHL (by signed variable) on page C3-499.
- C3.105 VQSHL and VQSHLU (by immediate) on page C3-500.
- C3.106 VQSHRN and VQSHRUN (by immediate) on page C3-501.
- *C3.107 VQSUB* on page C3-502.
- C3.108 VRADDHN on page C3-503.
- *C3.109 VRECPE* on page C3-504.
- C3.110 VRECPS on page C3-505.
- C3.111 VREV16, VREV32, and VREV64 on page C3-506.
- C3.112 VRHADD on page C3-507.
- C3.113 VRSHL (by signed variable) on page C3-508.
- C3.114 VRSHR (by immediate) on page C3-509.
- C3.115 VRSHRN (by immediate) on page C3-510.
- C3.116 VRINT on page C3-511.
- C3.117 VRSQRTE on page C3-512.
- C3.118 VRSQRTS on page C3-513.
- C3.119 VRSRA (by immediate) on page C3-514.
- C3.120 VRSUBHN on page C3-515.
- C3.121 VSDOT (vector) on page C3-516.
- C3.122 VSDOT (by element) on page C3-517.
- C3.123 VSHL (by immediate) on page C3-518.
- C3.124 VSHL (by signed variable) on page C3-519.
- C3.125 VSHLL (by immediate) on page C3-520.
- C3.126 VSHR (by immediate) on page C3-521.
- C3.127 VSHRN (by immediate) on page C3-522.
- *C3.128 VSLI* on page C3-523.
- C3.129 VSRA (by immediate) on page C3-524.
- *C3.130 VSRI* on page C3-525.
- *C3.131 VSTM* on page C3-526.
- C3.132 VSTn (multiple n-element structures) on page C3-527.
- C3.133 VSTn (single n-element structure to one lane) on page C3-529.
- *C3.134 VSTR* on page C3-531.

- C3.135 VSTR (post-increment and pre-decrement) on page C3-532.
- *C3.136 VSUB* on page C3-533.
- *C3.137 VSUBHN* on page C3-534.
- C3.138 VSUBL and VSUBW on page C3-535.
- C3.139 VSWP on page C3-536.
- C3.140 VTBL and VTBX on page C3-537.
- *C3.141 VTRN* on page C3-538.
- *C3.142 VTST* on page C3-539.
- *C3.143 VUDOT (vector)* on page C3-540.
- C3.144 VUDOT (by element) on page C3-541.
- *C3.145 VUZP* on page C3-542.
- *C3.146 VZIP* on page C3-543.

# C3.1 Summary of Advanced SIMD instructions

Most Advanced SIMD instructions are not available in floating-point.

The following table shows a summary of Advanced SIMD instructions that are not available as floatingpoint instructions:

Mnemonic	Brief description
FLDMDBX, FLDMIAX	FLDMX
FSTMDBX, FSTMIAX	FSTMX
VABA, VABD	Absolute difference and Accumulate, Absolute Difference
VABS	Absolute value
VACGE, VACGT	Absolute Compare Greater than or Equal, Greater Than
VACLE, VACLT	Absolute Compare Less than or Equal, Less Than (pseudo-instructions)
VADD	Add
VADDHN	Add, select High half
VAND	Bitwise AND
VAND	Bitwise AND (pseudo-instruction)
VBIC	Bitwise Bit Clear (register)
VBIC	Bitwise Bit Clear (immediate)
VBIF, VBIT, VBSL	Bitwise Insert if False, Insert if True, Select
VCADD	Vector Complex Add
VCEQ, VCLE, VCLT	Compare Equal, Less than or Equal, Compare Less Than
VCGE, VCGT	Compare Greater than or Equal, Greater Than
VCLE, VCLT	Compare Less than or Equal, Compare Less Than (pseudo-instruction)
VCLS, VCLZ, VCNT	Count Leading Sign bits, Count Leading Zeros, and Count set bits
VCMLA	Vector Complex Multiply Accumulate
VCMLA (by element)	Vector Complex Multiply Accumulate (by element)
VCVT	Convert fixed-point or integer to floating-point, floating-point to integer or fixed-point
VCVT	Convert floating-point to integer with directed rounding modes
VCVT	Convert between half-precision and single-precision floating-point numbers
VDUP	Duplicate scalar to all lanes of vector
VEOR	Bitwise Exclusive OR
VEXT	Extract
VFMA, VFMS	Fused Multiply Accumulate, Fused Multiply Subtract
VFMAL, VFMSL	Vector Floating-point Multiply-Add Long to accumulator (by scalar)
VFMAL, VFMSL	Vector Floating-point Multiply-Add Long to accumulator (vector)
VHADD, VHSUB	Halving Add, Halving Subtract

## Table C3-1 Summary of Advanced SIMD instructions

## Table C3-1 Summary of Advanced SIMD instructions (continued)

Mnemonic	Brief description
VLD	Vector Load
VMAX, VMIN	Maximum, Minimum
VMAXNM, VMINNM	Maximum, Minimum, consistent with IEEE 754-2008
VMLA, VMLS	Multiply Accumulate, Multiply Subtract (vector)
VMLA, VMLS	Multiply Accumulate, Multiply Subtract (by scalar)
VMOV	Move (immediate)
VMOV	Move (register)
VMOVL, VMOV{U}N	Move Long, Move Narrow (register)
VMUL	Multiply (vector)
VMUL	Multiply (by scalar)
VMVN	Move Negative (immediate)
VNEG	Negate
VORN	Bitwise OR NOT
VORN	Bitwise OR NOT (pseudo-instruction)
VORR	Bitwise OR (register)
VORR	Bitwise OR (immediate)
VPADD, VPADAL	Pairwise Add, Pairwise Add and Accumulate
VPMAX, VPMIN	Pairwise Maximum, Pairwise Minimum
VQABS	Absolute value, saturate
VQADD	Add, saturate
VQDMLAL, VQDMLSL	Saturating Doubling Multiply Accumulate, and Multiply Subtract
VQDMULL	Saturating Doubling Multiply
VQDMULH	Saturating Doubling Multiply returning High half
VQMOV{U}N	Saturating Move (register)
VQNEG	Negate, saturate
VQRDMULH	Saturating Doubling Multiply returning High half
VQRSHL	Shift Left, Round, saturate (by signed variable)
VQRSHR{U}N	Shift Right, Round, saturate (by immediate)
VQSHL	Shift Left, saturate (by immediate)
VQSHL	Shift Left, saturate (by signed variable)
VQSHR{U}N	Shift Right, saturate (by immediate)
VQSUB	Subtract, saturate
VRADDHN	Add, select High half, Round
VRECPE	Reciprocal Estimate

## Table C3-1 Summary of Advanced SIMD instructions (continued)

Mnemonic	Brief description
VRECPS	Reciprocal Step
VREV	Reverse elements
VRHADD	Halving Add, Round
VRINT	Round to integer
VRSHR	Shift Right and Round (by immediate)
VRSHRN	Shift Right, Round, Narrow (by immediate)
VRSQRTE	Reciprocal Square Root Estimate
VRSQRTS	Reciprocal Square Root Step
VRSRA	Shift Right, Round, and Accumulate (by immediate)
VRSUBHN	Subtract, select High half, Round
VSDOT (vector)	Dot Product vector form with signed integers
VSDOT (by element)	Dot Product index form with signed integers
VSHL	Shift Left (by immediate)
VSHR	Shift Right (by immediate)
VSHRN	Shift Right, Narrow (by immediate)
VSLI	Shift Left and Insert
VSRA	Shift Right, Accumulate (by immediate)
VSRI	Shift Right and Insert
VST	Vector Store
VSUB	Subtract
VSUBHN	Subtract, select High half
VSWP	Swap vectors
VTBL, VTBX	Vector table look-up
VTRN	Vector transpose
VTST	Test bits
VUDOT (vector)	Dot Product vector form with unsigned integers
VUDOT (by element)	Dot Product index form with unsigned integers
VUZP, VZIP	Vector interleave and de-interleave
VZIP	Vector Zip

# C3.2 Summary of shared Advanced SIMD and floating-point instructions

Some instructions are common to Advanced SIMD and floating-point.

The following table shows a summary of instructions that are common to the Advanced SIMD and floating-point instruction sets.

Mnemonic	Brief description
VLDM	Load multiple
VLDR	Load
	Load (post-increment and pre-decrement)
VMOV	Transfer from one general-purpose register to a scalar
	Transfer from two general-purpose registers to either one double-precision or two single-precision registers
	Transfer from a scalar to a general-purpose register
	Transfer from either one double-precision or two single-precision registers to two general-purpose registers
VMRS	Transfer from a SIMD and floating-point system register to a general-purpose register
VMSR	Transfer from a general-purpose register to a SIMD and floating-point system register
VPOP	Pop floating-point or SIMD registers from full-descending stack
VPUSH	Push floating-point or SIMD registers to full-descending stack
VSTM	Store multiple
VSTR	Store
	Store (post-increment and pre-decrement)

#### Table C3-2 Summary of shared Advanced SIMD and floating-point instructions

#### **Related references**

C3.54 VLDM on page C3-449 C3.55 VLDR on page C3-450 C3.56 VLDR (post-increment and pre-decrement) on page C3-451 C3.57 VLDR pseudo-instruction on page C3-452 C3.70 VMOV (between two general-purpose registers and a 64-bit extension register) on page C3-465 C3.71 VMOV (between a general-purpose register and an Advanced SIMD scalar) on page C3-466 C3.75 VMRS on page C3-470 C3.76 VMSR on page C3-471 C3.92 VPOP on page C3-487 C3.93 VPUSH on page C3-488 C3.131 VSTM on page C3-526 C3.134 VSTR on page C3-531 C3.135 VSTR (post-increment and pre-decrement) on page C3-532

# C3.3 Interleaving provided by load and store element and structure instructions

Many instructions in this group provide interleaving when structures are stored to memory, and deinterleaving when structures are loaded from memory.

The following figure shows an example of de-interleaving. Interleaving is the inverse process.



Figure C3-1 De-interleaving an array of 3-element structures

# **Related concepts**

*C3.4 Alignment restrictions in load and store element and structure instructions* on page C3-396 *Related references* 

C3.51 VLDn (single n-element structure to one lane) on page C3-443

C3.52 VLDn (single n-element structure to all lanes) on page C3-445

C3.53 VLDn (multiple n-element structures) on page C3-447

C3.132 VSTn (multiple n-element structures) on page C3-527

C3.133 VSTn (single n-element structure to one lane) on page C3-529

# **Related information**

Arm Architecture Reference Manual

# C3.4 Alignment restrictions in load and store element and structure instructions

Many of these instructions allow you to specify memory alignment restrictions.

When the alignment is not specified in the instruction, the alignment restriction is controlled by the A bit (SCTLR bit[1]):

- If the A bit is 0, there are no alignment restrictions (except for strongly-ordered or device memory, where accesses must be element-aligned).
- If the A bit is 1, accesses must be element-aligned.

If an address is not correctly aligned, an alignment fault occurs.

## **Related concepts**

*C3.3 Interleaving provided by load and store element and structure instructions* on page C3-395 *Related references* 

C3.51 VLDn (single n-element structure to one lane) on page C3-443

C3.52 VLDn (single n-element structure to all lanes) on page C3-445

C3.53 VLDn (multiple n-element structures) on page C3-447

C3.132 VSTn (multiple n-element structures) on page C3-527

C3.133 VSTn (single n-element structure to one lane) on page C3-529

# **Related information**

Arm Architecture Reference Manual
# C3.5 FLDMDBX, FLDMIAX

FLDMX.

## Syntax

```
FLDMDBX{c}{q} Rn!, dregList ; A1 Decrement Before FP/SIMD registers (A32)
FLDMIAX{c}{q} Rn{!}, dregList ; A1 Increment After FP/SIMD registers (A32)
FLDMDBX{c}{q} Rn!, dregList ; T1 Decrement Before FP/SIMD registers (T32)
FLDMIAX{c}{q} Rn{!}, dregList ; T1 Increment After FP/SIMD registers (T32)
Where:
```

С

а

Is an optional condition code. See *Chapter C1 Condition Codes* on page C1-83.

Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.

Rn

L

Is the general-purpose base register. If writeback is not specified, the PC can be used.

Specifies base register writeback.

dreglist

Is the list of consecutively numbered 64-bit SIMD and FP registers to be transferred. The list must contain at least one register, all registers must be in the range D0-D15, and must not contain more than 16 registers.

#### Usage

FLDMX loads multiple SIMD and FP registers from consecutive locations in the Advanced SIMD and floating-point register file using an address from a general-purpose register.

Arm deprecates use of FLDMDBX and FLDMIAX, except for disassembly purposes, and reassembly of disassembled code.

Depending on settings in the *CPACR*, *NSACR*, and *HCPTR* registers, and the security state and mode in which the instruction is executed, an attempt to execute the instruction might be UNDEFINED, or trapped to Hyp mode. For more information see *Enabling Advanced SIMD and floating-point support* in the *Arm*<sup>®</sup> *Architecture Reference Manual Arm*<sup>®</sup>v8, for *Arm*<sup>®</sup>v8-A architecture profile.

— Note -

For more information about the CONSTRAINED UNPREDICTABLE behavior of this instruction, see Architectural Constraints on UNPREDICTABLE behaviors in the Arm<sup>®</sup> Architecture Reference Manual Arm<sup>®</sup>v8, for Arm<sup>®</sup>v8-A architecture profile.

## **Related references**

C3.1 Summary of Advanced SIMD instructions on page C3-391

# C3.6 FSTMDBX, FSTMIAX

FSTMX.

## Syntax

```
FSTMDBX{c}{q} Rn!, dreglist ; A1 Decrement Before FP/SIMD registers (A32)
FSTMIAX{c}{q} Rn{!}, dreglist ; A1 Increment After FP/SIMD registers (A32)
FSTMDBX{c}{q} Rn!, dreglist ; T1 Decrement Before FP/SIMD registers (T32)
FSTMIAX{c}{q} Rn{!}, dreglist ; T1 Increment After FP/SIMD registers (T32)
Where:
```

```
с
```

Is an optional condition code. See *Chapter C1 Condition Codes* on page C1-83.

Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.

Rn

а

Is the general-purpose base register. If writeback is not specified, the PC can be used. However, Arm deprecates use of the PC.

!

Specifies base register writeback.

dreglist

Is the list of consecutively numbered 64-bit SIMD and FP registers to be transferred. The list must contain at least one register, all registers must be in the range D0-D15, and must not contain more than 16 registers.

## Usage

FSTMX stores multiple SIMD and FP registers from the Advanced SIMD and floating-point register file to consecutive locations in using an address from a general-purpose register.

Arm deprecates use of FLDMDBX and FLDMIAX, except for disassembly purposes, and reassembly of disassembled code.

Depending on settings in the *CPACR*, *NSACR*, *HCPTR*, and *FPEXC* registers, and the security state and mode in which the instruction is executed, an attempt to execute the instruction might be UNDEFINED, or trapped to Hyp mode. For more information see *Enabling Advanced SIMD and floating-point support* in the *Arm*<sup>®</sup> *Architecture Reference Manual Arm*<sup>®</sup> v8, for *Arm*<sup>®</sup> v8-A architecture profile.

------ Note -

For more information about the CONSTRAINED UNPREDICTABLE behavior of this instruction, see Architectural Constraints on UNPREDICTABLE behaviors in the Arm® Architecture Reference Manual Arm®v8, for Arm®v8-A architecture profile.

*Related references C3.1 Summary of Advanced SIMD instructions* on page C3-391

# C3.7 VABA and VABAL

Vector Absolute Difference and Accumulate.

#### Syntax

```
VABA{cond}.datatype {Qd}, Qn, Qm
```

VABA{cond}.datatype {Dd}, Dn, Dm

VABAL{cond}.datatype Qd, Dn, Dm

where:

cond

is an optional condition code.

#### datatype

must be one of \$8, \$16, \$32, U8, U16, or U32.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

Qd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a long operation.

# Operation

VABA subtracts the elements of one vector from the corresponding elements of another vector, and accumulates the absolute values of the results into the elements of the destination vector.

VABAL is the long version of the VABA instruction.

**Related references** 

# C3.8 VABD and VABDL

Vector Absolute Difference.

#### Syntax

```
VABD{cond}.datatype {Qd}, Qn, Qm
```

VABD{cond}.datatype {Dd}, Dn, Dm

VABDL{cond}.datatype Qd, Dn, Dm

where:

cond

is an optional condition code.

#### datatype

must be one of:

- S8, S16, S32, U8, U16, or U32 for VABDL.
- S8, S16, S32, U8, U16, U32 or F32 for VABD.
- Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

Qd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a long operation.

## Operation

VABD subtracts the elements of one vector from the corresponding elements of another vector, and places the absolute values of the results into the elements of the destination vector.

VABDL is the long version of the VABD instruction.

**Related references** 

# C3.9 VABS

Vector Absolute

## Syntax

VABS{cond}.datatype Qd, Qm

VABS{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

## datatype

must be one of \$8, \$16, \$32, or \$32.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

#### Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

## Operation

VABS takes the absolute value of each element in a vector, and places the results in a second vector. (The floating-point version only clears the sign bit.)

#### **Related references**

C3.94 VQABS on page C3-489 C1.9 Condition code suffixes on page C1-92

# C3.10 VACLE, VACLT, VACGE and VACGT

Vector Absolute Compare.

## Syntax

- VACop{cond}.F32 {Qd}, Qn, Qm
- VACop{cond}.F32 {Dd}, Dn, Dm

where:

#### ор

must be one of:

#### GE

Absolute Greater than or Equal.

#### GT

Absolute Greater Than.

#### LE

Absolute Less than or Equal.

LT

Absolute Less Than.

#### cond

is an optional condition code.

## Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

The result datatype is I32.

## Operation

These instructions take the absolute value of each element in a vector, and compare it with the absolute value of the corresponding element of a second vector. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

—— Note -

On disassembly, the VACLE and VACLT pseudo-instructions are disassembled to the corresponding VACGE and VACGT instructions, with the operands reversed.

# Related references

# C3.11 VADD

Vector Add.

## Syntax

VADD{cond}.datatype {Qd}, Qn, Qm

VADD{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## datatype

must be one of 18, 116, 132, 164, or F32

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

# Operation

VADD adds corresponding elements in two vectors, and places the results in the destination vector.

## **Related references**

*C3.13 VADDL and VADDW* on page C3-405 *C3.95 VQADD* on page C3-490 *C1.9 Condition code suffixes* on page C1-92

# C3.12 VADDHN

Vector Add and Narrow, selecting High half.

## Syntax

VADDHN{cond}.datatype Dd, Qn, Qm

where:

cond

is an optional condition code.

datatype

must be one of 116, 132, or 164.

Dd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector.

## Operation

VADDHN adds corresponding elements in two vectors, selects the most significant halves of the results, and places the final results in the destination vector. Results are truncated.

#### **Related references**

*C3.108 VRADDHN* on page C3-503 *C1.9 Condition code suffixes* on page C1-92

# C3.13 VADDL and VADDW

Vector Add Long, Vector Add Wide.

## Syntax

VADDL{cond}.datatype Qd, Dn, Dm ; Long operation

VADDW{cond}.datatype {Qd,} Qn, Dm ; Wide operation

where:

cond

is an optional condition code.

#### datatype

must be one of S8, S16, S32, U8, U16, or U32.

Qd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a long operation.

Qd, Qn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a wide operation.

## Operation

VADDL adds corresponding elements in two doubleword vectors, and places the results in the destination quadword vector.

VADDW adds corresponding elements in one quadword and one doubleword vector, and places the results in the destination quadword vector.

## **Related references**

*C3.11 VADD* on page C3-403 *C1.9 Condition code suffixes* on page C1-92

# C3.14 VAND (immediate)

Vector bitwise AND immediate pseudo-instruction.

#### Syntax

VAND{cond}.datatype Qd, #imm

VAND{cond}.datatype Dd, #imm

where:

cond

is an optional condition code.

#### datatype

must be either 18, 116, 132, or 164.

#### Qd or Dd

is the Advanced SIMD register for the result.

#### imm

is the immediate value.

## Operation

VAND takes each element of the destination vector, performs a bitwise AND with an immediate value, and returns the result into the destination vector.

—— Note —

On disassembly, this pseudo-instruction is disassembled to a corresponding VBIC instruction, with the complementary immediate value.

#### Immediate values

If *datatype* is **I16**, the immediate value must have one of the following forms:

- ØxFFXY.
- ØxXYFF.

If *datatype* is I32, the immediate value must have one of the following forms:

- 0xFFFFFFXY.
- 0xFFFFXYFF.
- 0xFFXYFFFF.
- 0xXYFFFFFF.

#### **Related references**

*C3.16 VBIC (immediate)* on page C3-408 *C1.9 Condition code suffixes* on page C1-92

# C3.15 VAND (register)

Vector bitwise AND.

## Syntax

VAND{cond}{.datatype} {Qd}, Qn, Qm

VAND{cond}{.datatype} {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## datatype

is an optional data type. The assembler ignores datatype.

Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VAND performs a bitwise logical AND between two registers, and places the result in the destination register.

# **Related references**

# C3.16 VBIC (immediate)

Vector Bit Clear immediate.

#### Syntax

VBIC{cond}.datatype Qd, #imm

VBIC{cond}.datatype Dd, #imm

where:

cond

is an optional condition code.

#### datatype

must be either 18, 116, 132, or 164.

#### Qd or Dd

is the Advanced SIMD register for the source and result.

imm

is the immediate value.

## Operation

VBIC takes each element of the destination vector, performs a bitwise AND complement with an immediate value, and returns the result in the destination vector.

#### Immediate values

You can either specify *imm* as a pattern which the assembler repeats to fill the destination register, or you can directly specify the immediate value (that conforms to the pattern) in full. The pattern for *imm* depends on *datatype* as shown in the following table:

#### Table C3-3 Patterns for immediate value in VBIC (immediate)

116	132
0x00XY	0x000000XY
0xXY00	0x0000XY00
	0x00XY0000
	0xXY000000

If you use the **I8** or **I64** datatypes, the assembler converts it to either the **I16** or **I32** instruction to match the pattern of *imm*. If the immediate value does not match any of the patterns in the preceding table, the assembler generates an error.

## *Related references C3.14 VAND (immediate)* on page C3-406 *C1.9 Condition code suffixes* on page C1-92

# C3.17 VBIC (register)

Vector Bit Clear.

## Syntax

VBIC{cond}{.datatype} {Qd}, Qn, Qm

VBIC{cond}{.datatype} {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## datatype

is an optional data type. The assembler ignores datatype.

Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VBIC performs a bitwise logical AND complement between two registers, and places the result in the destination register.

# **Related references**

# C3.18 VBIF

Vector Bitwise Insert if False.

## Syntax

VBIF{cond}{.datatype} {Qd}, Qn, Qm

VBIF{cond}{.datatype} {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## datatype

is an optional datatype. The assembler ignores datatype.

Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VBIF inserts each bit from the first operand into the destination if the corresponding bit of the second operand is 0, otherwise it leaves the destination bit unchanged.

# **Related references**

# C3.19 VBIT

Vector Bitwise Insert if True.

## Syntax

VBIT{cond}{.datatype} {Qd}, Qn, Qm

VBIT{cond}{.datatype} {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## datatype

is an optional datatype. The assembler ignores datatype.

Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VBIT inserts each bit from the first operand into the destination if the corresponding bit of the second operand is 1, otherwise it leaves the destination bit unchanged.

# **Related references**

# C3.20 VBSL

Vector Bitwise Select.

## Syntax

VBSL{cond}{.datatype} {Qd}, Qn, Qm

VBSL{cond}{.datatype} {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## datatype

is an optional datatype. The assembler ignores datatype.

Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VBSL selects each bit for the destination from the first operand if the corresponding bit of the destination is 1, or from the second operand if the corresponding bit of the destination is 0.

# **Related references**

# C3.21 VCADD

Vector Complex Add.

## Syntax

VCADD{q}.dt {Dd,} Dn, Dm, #rotate ; A1 64-bit SIMD vector FP/SIMD registers (A32)
VCADD{q}.dt {Qd,} Qn, Qm, #rotate ; A1 128-bit SIMD vector FP/SIMD registers (A32)
Where:

Dd

Dn

Dm

0d

Qn

Qm

q

dt

Is the 64-bit name of the SIMD and FP destination register.

Is the 64-bit name of the first SIMD and FP source register.

Is the 64-bit name of the second SIMD and FP source register.

Is the 128-bit name of the SIMD and FP destination register.

Is the 128-bit name of the first SIMD and FP source register.

Is the 128-bit name of the second SIMD and FP source register.

Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.

Is the data type for the elements of the vectors, and can be either F16 or F32.

rotate

Is the rotation to be applied to elements in the second SIMD and FP source register, and can be either 90 or 270.

## Architectures supported

Supported in the Armv8.3-A architecture and later.

# Usage

Depending on settings in the *CPACR*, *NSACR*, and *HCPTR* registers, and the security state and mode in which the instruction is executed, an attempt to execute the instruction might be UNDEFINED, or trapped to Hyp mode. For more information see *Enabling Advanced SIMD and floating-point support* in the *Arm*<sup>®</sup> *Architecture Reference Manual Arm*<sup>®</sup>v8, for *Arm*<sup>®</sup>v8-A architecture profile.

## **Related references**

C3.1 Summary of Advanced SIMD instructions on page C3-391

# C3.22 VCEQ (immediate #0)

Vector Compare Equal to zero.

#### Syntax

VCEQ{cond}.datatype {Qd}, Qn, #0

VCEQ{cond}.datatype {Dd}, Dn, #0

where:

cond

is an optional condition code.

#### datatype

must be one of 18, 116, 132, or F32.

The result datatype is:

- I32 for operand datatypes I32 or F32.
- I16 for operand datatype I16.
- 18 for operand datatype 18.
- Qd, Qn, Qm

specifies the destination register and the operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register and the operand register, for a doubleword operation.

#0

specifies a comparison with zero.

## Operation

VCEQ takes the value of each element in a vector, and compares it with zero. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

## **Related references**

# C3.23 VCEQ (register)

Vector Compare Equal.

## Syntax

VCEQ{cond}.datatype {Qd}, Qn, Qm

VCEQ{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

#### datatype

must be one of 18, 116, 132, or F32.

The result datatype is:

- I32 for operand datatypes I32 or F32.
- I16 for operand datatype I16.
- 18 for operand datatype 18.
- Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VCEQ takes the value of each element in a vector, and compares it with the value of the corresponding element of a second vector. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

## **Related references**

# C3.24 VCGE (immediate #0)

Vector Compare Greater than or Equal to zero.

#### Syntax

VCGE{cond}.datatype {Qd}, Qn, #0

VCGE{cond}.datatype {Dd}, Dn, #0

where:

cond

is an optional condition code.

#### datatype

must be one of \$8, \$16, \$32, or \$32.

The result datatype is:

- I32 for operand datatypes S32 or F32.
- I16 for operand datatype S16.
- 18 for operand datatype S8.
- Qd, Qn, Qm

specifies the destination register and the operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register and the operand register, for a doubleword operation.

#0

specifies a comparison with zero.

## Operation

VCGE takes the value of each element in a vector, and compares it with zero. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

#### **Related references**

# C3.25 VCGE (register)

Vector Compare Greater than or Equal.

## Syntax

VCGE{cond}.datatype {Qd}, Qn, Qm

VCGE{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

#### datatype

must be one of \$8, \$16, \$32, U8, U16, U32, or F32.

The result datatype is:

- I32 for operand datatypes S32, U32, or F32.
- I16 for operand datatypes S16 or U16.
- 18 for operand datatypes S8 or U8.
- Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VCGE takes the value of each element in a vector, and compares it with the value of the corresponding element of a second vector. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

## **Related references**

# C3.26 VCGT (immediate #0)

Vector Compare Greater Than zero.

## Syntax

VCGT{cond}.datatype {Qd}, Qn, #0

VCGT{cond}.datatype {Dd}, Dn, #0

where:

cond

is an optional condition code.

#### datatype

must be one of \$8, \$16, \$32, or \$32.

The result datatype is:

- I32 for operand datatypes S32 or F32.
- I16 for operand datatype S16.
- 18 for operand datatype S8.
- Qd, Qn, Qm

specifies the destination register and the operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register and the operand register, for a doubleword operation.

## Operation

VCGT takes the value of each element in a vector, and compares it with zero. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

# **Related references**

# C3.27 VCGT (register)

Vector Compare Greater Than.

## Syntax

VCGT{cond}.datatype {Qd}, Qn, Qm

VCGT{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## datatype

must be one of \$8, \$16, \$32, U8, U16, U32, or F32.

The result datatype is:

- I32 for operand datatypes S32, U32, or F32.
- I16 for operand datatypes S16 or U16.
- 18 for operand datatypes S8 or U8.
- Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VCGT takes the value of each element in a vector, and compares it with the value of the corresponding element of a second vector. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

## **Related references**

# C3.28 VCLE (immediate #0)

Vector Compare Less than or Equal to zero.

#### Syntax

VCLE{cond}.datatype {Qd}, Qn, #0

VCLE{cond}.datatype {Dd}, Dn, #0

where:

cond

is an optional condition code.

#### datatype

must be one of \$8, \$16, \$32, or \$32.

The result datatype is:

- I32 for operand datatypes S32 or F32.
- I16 for operand datatype S16.
- 18 for operand datatype S8.
- Qd, Qn, Qm

specifies the destination register and the operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register and the operand register, for a doubleword operation.

#0

specifies a comparison with zero.

## Operation

VCLE takes the value of each element in a vector, and compares it with zero. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

#### **Related references**

# C3.29 VCLS

Vector Count Leading Sign bits.

## Syntax

VCLS{cond}.datatype Qd, Qm

VCLS{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

## datatype

must be one of \$8, \$16, or \$32.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

## Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

# Operation

VCLS counts the number of consecutive bits following the topmost bit, that are the same as the topmost bit, in each element in a vector, and places the results in a second vector.

## **Related references**

# C3.30 VCLE (register)

Vector Compare Less than or Equal pseudo-instruction.

## Syntax

VCLE{cond}.datatype {Qd}, Qn, Qm

VCLE{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

#### datatype

must be one of S8, S16, S32, U8, U16, U32, or F32.

The result datatype is:

- I32 for operand datatypes S32, U32, or F32.
- I16 for operand datatypes S16 or U16.
- 18 for operand datatypes S8 or U8.
- Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VCLE takes the value of each element in a vector, and compares it with the value of the corresponding element of a second vector. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

On disassembly, this pseudo-instruction is disassembled to the corresponding VCGE instruction, with the operands reversed.

## **Related references**

# C3.31 VCLT (immediate #0)

Vector Compare Less Than zero.

## Syntax

VCLT{cond}.datatype {Qd}, Qn, #0

VCLT{cond}.datatype {Dd}, Dn, #0

where:

cond

is an optional condition code.

#### datatype

must be one of \$8, \$16, \$32, or \$32.

The result datatype is:

- I32 for operand datatypes S32 or F32.
- I16 for operand datatype S16.
- 18 for operand datatype S8.
- Qd, Qn, Qm

specifies the destination register and the operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register and the operand register, for a doubleword operation.

#0

specifies a comparison with zero.

## Operation

VCLT takes the value of each element in a vector, and compares it with zero. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

## **Related references**

# C3.32 VCLT (register)

Vector Compare Less Than.

## Syntax

VCLT{cond}.datatype {Qd}, Qn, Qm

VCLT{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

#### datatype

must be one of \$8, \$16, \$32, U8, U16, U32, or F32.

The result datatype is:

- I32 for operand datatypes S32, U32, or F32.
- I16 for operand datatypes S16 or U16.
- 18 for operand datatypes S8 or U8.
- Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

## Operation

VCLT takes the value of each element in a vector, and compares it with the value of the corresponding element of a second vector. If the condition is true, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

—— Note —

On disassembly, this pseudo-instruction is disassembled to the corresponding VCGT instruction, with the operands reversed.

*Related references C1.9 Condition code suffixes* on page C1-92

# C3.33 VCLZ

Vector Count Leading Zeros.

## Syntax

VCLZ{cond}.datatype Qd, Qm

VCLZ{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

## datatype

must be one of 18, 116, or 132.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

## Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

# Operation

VCLZ counts the number of consecutive zeros, starting from the top bit, in each element in a vector, and places the results in a second vector.

## **Related references**

# C3.34 VCMLA

Vector Complex Multiply Accumulate.

## Syntax

oymax	
VCMLA{a	g}.dt {Dd,} Dn, Dm, #rotate ; 64-bit SIMD vector FP/SIMD registers
VCMLA{a	g}.dt {Qd,} Qn, Qm, #rotate ; 128-bit SIMD vector FP/SIMD registers
Where:	
Dd	
D	Is the 64-bit name of the SIMD and FP destination register.
ווט	Is the 64-bit name of the first SIMD and FP source register.
Dm	
0d	Is the 64-bit name of the second SIMD and FP source register.
24	Is the 128-bit name of the SIMD and FP destination register.
Qn	Is the 128 bit name of the first SIMD and ED source register
Qm	is the 128-bit name of the first ShviD and FP source register.
-	Is the 128-bit name of the second SIMD and FP source register.
q	Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111
dt	
	Is the data type for the elements of the vectors, and can be either F16 or F32.

#### rotate

Is the rotation to be applied to elements in the second SIMD and FP source register, and can be one of 0, 90, 180 or 270.

## Architectures supported

Supported in the Armv8.3-A architecture and later.

# Usage

Depending on settings in the *CPACR*, *NSACR*, and *HCPTR* registers, and the security state and mode in which the instruction is executed, an attempt to execute the instruction might be UNDEFINED, or trapped to Hyp mode. For more information see *Enabling Advanced SIMD and floating-point support* in the *Arm*<sup>®</sup> *Architecture Reference Manual Arm*<sup>®</sup>v8, for *Arm*<sup>®</sup>v8-A architecture profile.

## **Related references**

C3.1 Summary of Advanced SIMD instructions on page C3-391

# C3.35 VCMLA (by element)

Vector Complex Multiply Accumulate (by element).

#### Syntax

```
VCMLA{q}.F16 Dd, Dn, Dm[index], #rotate ; A1 Double,halfprec FP/SIMD registers (A32)
VCMLA{q}.F32 Dd, Dn, Dm[0], #rotate ; A1 Double,singleprec FP/SIMD registers (A32)
VCMLA{q}.F32 Qd, Qn, Dm[0], #rotate ; A1 Quad,singleprec FP/SIMD registers (A32)
VCMLA{q}.F16 Qd, Qn, Dm[index], #rotate ; A1 Halfprec,quad FP/SIMD registers (A32)
Where:
```

Dd	
	Is the 64-bit name of the SIMD and FP destination register.
Dn	
_	Is the 64-bit name of the first SIMD and FP source register.
Dm	L de CAleitanne Cale anna d'CDAD en dED anna ister
inday	Is the 64-bit name of the second SIMD and FP source register.
LIIUEX	Is the element index in the range 0 to 1
Qd	
-	Is the 128-bit name of the SIMD and FP destination register.
Qn	
	Is the 128-bit name of the first SIMD and FP source register.
q	Is an antional instruction width aposition Soc C2.2 Instruction width apositions on page C2.111
rotate	is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.
, ocuce	Is the rotation to be applied to elements in the second SIMD and FP source register, and can be one of 0, 90, 180 or 270.

#### Architectures supported

Supported in the Armv8.3-A architecture and later.

#### Usage

Depending on settings in the *CPACR*, *NSACR*, and *HCPTR* registers, and the security state and mode in which the instruction is executed, an attempt to execute the instruction might be UNDEFINED, or trapped to Hyp mode. For more information see *Enabling Advanced SIMD and floating-point support* in the *Arm*<sup>®</sup> *Architecture Reference Manual Arm*<sup>®</sup>v8, for *Arm*<sup>®</sup>v8-A architecture profile.

#### **Related references**

C3.1 Summary of Advanced SIMD instructions on page C3-391

# C3.36 VCNT

Vector Count set bits.

## Syntax

VCNT{cond}.datatype Qd, Qm

VCNT{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

## datatype

must be 18.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

## Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

# Operation

VCNT counts the number of bits that are one in each element in a vector, and places the results in a second vector.

## **Related references**

# C3.37 VCVT (between fixed-point or integer, and floating-point)

Vector Convert.

#### Syntax

VCVT{cond}.type Qd, Qm {, #fbits}

VCVT{cond}.type Dd, Dm {, #fbits}

where:

cond

is an optional condition code.

#### type

specifies the data types for the elements of the vectors. It must be one of:

S32.F32

Floating-point to signed integer or fixed-point.

U32.F32

Floating-point to unsigned integer or fixed-point.

F32.S32

Signed integer or fixed-point to floating-point.

F32.U32

Unsigned integer or fixed-point to floating-point.

Qd, Qm

specifies the destination vector and the operand vector, for a quadword operation.

#### Dd, Dm

specifies the destination vector and the operand vector, for a doubleword operation.

fbits

if present, specifies the number of fraction bits in the fixed point number. Otherwise, the conversion is between floating-point and integer. *fbits* must lie in the range 0-32. If *fbits* is omitted, the number of fraction bits is 0.

## Operation

VCVT converts each element in a vector in one of the following ways, and places the results in the destination vector:

- From floating-point to integer.
- From integer to floating-point.
- From floating-point to fixed-point.
- From fixed-point to floating-point.

## Rounding

Integer or fixed-point to floating-point conversions use round to nearest.

Floating-point to integer or fixed-point conversions use round towards zero.

#### **Related references**

# C3.38 VCVT (between half-precision and single-precision floating-point)

Vector Convert.

#### Syntax

VCVT{cond}.F32.F16 Qd, Dm

VCVT{cond}.F16.F32 Dd, Qm

where:

cond

is an optional condition code.

Qd, Dm

specifies the destination vector for the single-precision results and the half-precision operand vector.

Dd, Qm

specifies the destination vector for half-precision results and the single-precision operand vector.

## Operation

VCVT with half-precision extension, converts each element in a vector in one of the following ways, and places the results in the destination vector:

- From half-precision floating-point to single-precision floating-point (F32.F16).
- From single-precision floating-point to half-precision floating-point (F16.F32).

## Architectures

This instruction is available in Armv8. In earlier architectures, it is only available in NEON systems with the half-precision extension.

## **Related references**

# C3.39 VCVT (from floating-point to integer with directed rounding modes)

VCVT (Vector Convert) converts each element in a vector from floating-point to signed or unsigned integer, and places the results in the destination vector.

\_\_\_\_\_ Note \_\_\_\_\_

- This instruction is supported only in Armv8.
- You cannot use VCVT with a directed rounding mode inside an IT block.

#### **Syntax**

VCVTmode.type Qd, Qm

VCVTmode.type Dd, Dm

where:

#### mode

must be one of:

Α

meaning round to nearest, ties away from zero

Ν

D

М

meaning round to nearest, ties to even

meaning round towards plus infinity

meaning round towards minus infinity.

#### type

specifies the data types for the elements of the vectors. It must be one of:

#### S32.F32

floating-point to signed integer

#### U32.F32

floating-point to unsigned integer.

#### Qd, Qm

specifies the destination and operand vectors, for a quadword operation.

#### Dd, Dm

specifies the destination and operand vectors, for a doubleword operation.

# C3.40 VCVTB, VCVTT (between half-precision and double-precision)

These instructions convert between half-precision and double-precision floating-point numbers.

The conversion can be done in either of the following ways:

- From half-precision floating-point to double-precision floating-point (F64.F16).
- From double-precision floating-point to half-precision floating-point (F16.F64).

VCVTB uses the bottom half (bits[15:0]) of the single word register to obtain or store the half-precision value.

VCVTT uses the top half (bits[31:16]) of the single word register to obtain or store the half-precision value.

\_\_\_\_\_ Note \_\_\_\_\_

These instructions are supported only in Armv8.

## Syntax

VCVTB{cond}.F64.F16 Dd, Sm

VCVTB{cond}.F16.F64 Sd, Dm

VCVTT{cond}.F64.F16 Dd, Sm

VCVTT{cond}.F16.F64 Sd, Dm

where:

is an optional condition code.

*Dd* is a double-precision register for the result.

Sm

Sd

is a single word register holding the operand.

is a single word register for the result.

Dm

is a double-precision register holding the operand.

## Usage

These instructions convert the half-precision value in Sm to double-precision and place the result in Dd, or the double-precision value in Dm to half-precision and place the result in Sd.

## **Floating-point exceptions**

These instructions can produce Input Denormal, Invalid Operation, Overflow, Underflow, or Inexact exceptions.
# C3.41 VDUP

Vector Duplicate.

### Syntax

VDUP{cond}.size Qd, Dm[x]

VDUP{cond}.size Dd, Dm[x]

VDUP{cond}.size Qd, Rm

VDUP{cond}.size Dd, Rm

where:

is an optional condition code.

size

must be 8, 16, or 32.

### Qd

specifies the destination register for a quadword operation.

### Dd

specifies the destination register for a doubleword operation.

### Dm[x]

specifies the Advanced SIMD scalar.

### Rm

specifies the general-purpose register. Rm must not be PC.

# Operation

VDUP duplicates a scalar into every element of the destination vector. The source can be an Advanced SIMD scalar or a general-purpose register.

# **Related references**

# C3.42 VEOR

Vector Bitwise Exclusive OR.

### Syntax

VEOR{cond}{.datatype} {Qd}, Qn, Qm

VEOR{cond}{.datatype} {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

is an optional data type. The assembler ignores datatype.

Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VEOR performs a logical exclusive OR between two registers, and places the result in the destination register.

# **Related references**

# C3.43 VEXT

Vector Extract.

### Syntax

VEXT{cond}.8 {Qd}, Qn, Qm, #imm

VEXT{cond}.8 {Dd}, Dn, Dm, #imm

where:

cond

is an optional condition code.

### Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

### Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

imm

is the number of 8-bit elements to extract from the bottom of the second operand vector, in the range 0-7 for doubleword operations, or 0-15 for quadword operations.

### Operation

VEXT extracts 8-bit elements from the bottom end of the second operand vector and the top end of the first, concatenates them, and places the result in the destination vector. See the following figure for an example:



Figure C3-2 Operation of doubleword VEXT for imm = 3

### **VEXT** pseudo-instruction

You can specify a datatype of 16, 32, or 64 instead of 8. In this case, **#imm** refers to halfwords, words, or doublewords instead of referring to bytes, and the permitted ranges are correspondingly reduced.

*Related references C1.9 Condition code suffixes* on page C1-92

# C3.44 VFMA, VFMS

Vector Fused Multiply Accumulate, Vector Fused Multiply Subtract.

### Syntax

Vop{cond}.F32 {Qd}, Qn, Qm
Vop{cond}.F32 {Dd}, Dn, Dm

where:

ор

is one of FMA or FMS.

cond

is an optional condition code.

Dd, Dn, Dm

are the destination and operand vectors for doubleword operation.

Qd, Qn, Qm

are the destination and operand vectors for quadword operation.

### Operation

VFMA multiplies corresponding elements in the two operand vectors, and accumulates the results into the elements of the destination vector. The result of the multiply is not rounded before the accumulation.

VFMS multiplies corresponding elements in the two operand vectors, then subtracts the products from the corresponding elements of the destination vector, and places the final results in the destination vector. The result of the multiply is not rounded before the subtraction.

### **Related references**

C3.77 VMUL on page C3-472 C1.9 Condition code suffixes on page C1-92

# C3.45 VFMAL (by scalar)

Vector Floating-point Multiply-Add Long to accumulator (by scalar).

### Syntax

VFMAL{	]}.F16 Dd, Sn, Sm[index] ; 64-bit SIMD vector				
VFMAL{	].F16 Qd, Dn, Dm[index] ; 128-bit SIMD vector FP/SIMD registers (A32)				
Where:					
Dd					
Sn	Is the 64-bit name of the SIMD and FP destination register.				
<b>.</b>	Is the 32-bit name of the first SIMD and FP source register.				
Sm	Is the 32-bit name of the second SIMD and FP source register.				
index					
	Depends on the instruction variant:				
	64 For the 64-bit SIMD vector variant: is the element index in the range 0 to 1.				
	<b>128</b> For the 128-bit SIMD vector variant: is the element index in the range 0 to 3.				
q Od	Is an optional instruction width specifier. See <i>C2.2 Instruction width specifiers</i> on page C2-111.				
Dn	Is the 128-bit name of the SIMD and FP destination register.				
Dm	Is the 64-bit name of the first SIMD and FP source register.				
	Is the 64-bit name of the second SIMD and FP source register.				

### Architectures supported

Supported in Armv8.2 and later.

### Usage

Vector Floating-point Multiply-Add Long to accumulator (by scalar). This instruction multiplies the vector elements in the first source SIMD and FP register by the specified value in the second source SIMD and FP register, and accumulates the product to the corresponding vector element of the destination SIMD and FP register. The instruction does not round the result of the multiply before the accumulation.

Depending on settings in the CPACR, NSACR, HCPTR, and FPEXC registers, and the Security state and PE mode in which the instruction is executed, an attempt to execute the instruction might be UNDEFINED, or trapped to Hyp mode. For more information see *Enabling Advanced SIMD and floating-point support* in the *Arm*<sup>®</sup> *Architecture Reference Manual Arm*<sup>®</sup>v8, for *Arm*<sup>®</sup>v8-A architecture profile.

In Armv8.2 and Armv8.3, this is an OPTIONAL instruction. From Armv8.4 it is mandatory for all implementations to support it.

----- Note -----

ID\_ISAR6.FHM indicates whether this instruction is supported.

### **Related references**

# C3.46 VFMAL (vector)

Vector Floating-point Multiply-Add Long to accumulator (vector).

### Syntax

VFMAL{a	7}.F16 Dd, Sn, Sm ; 64-bit SIMD vector
VFMAL{a	g}.F16 Qd, Dn, Dm ; 128-bit SIMD vector FP/SIMD registers (A32)
Where:	
Dd	
۶n	Is the 64-bit name of the SIMD and FP destination register.
511	Is the 32-bit name of the first SIMD and FP source register.
Sm	Is the 32-bit name of the second SIMD and FP source register.
q	Is an antional instruction width gradifier Sec C2.2 Instruction width gradifiers on page C2.111
Qd	is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.
<b>D</b>	Is the 128-bit name of the SIMD and FP destination register.
DN	Is the 64-bit name of the first SIMD and FP source register.
Dm	
	Is the 64-bit name of the second SIMD and FP source register.

### Architectures supported

Supported in Armv8.2 and later.

### Usage

Vector Floating-point Multiply-Add Long to accumulator (vector). This instruction multiplies corresponding values in the vectors in the two source SIMD and FP registers, and accumulates the product to the corresponding vector element of the destination SIMD and FP register. The instruction does not round the result of the multiply before the accumulation.

Depending on settings in the CPACR, NSACR, HCPTR, and FPEXC registers, and the Security state and PE mode in which the instruction is executed, an attempt to execute the instruction might be UNDEFINED, or trapped to Hyp mode. For more information see *Enabling Advanced SIMD and floating-point support* in the *Arm*<sup>®</sup> *Architecture Reference Manual Arm*<sup>®</sup>v8, for *Arm*<sup>®</sup>v8-A architecture profile.

In Armv8.2 and Armv8.3, this is an OPTIONAL instruction. From Armv8.4 it is mandatory for all implementations to support it.

— Note —

ID\_ISAR6.FHM indicates whether this instruction is supported.

**Related references** 

# C3.47 VFMSL (by scalar)

Vector Floating-point Multiply-Subtract Long from accumulator (by scalar).

### Syntax

VFMSL{	g}.F16 Dd, Sn, Sm[index] ; 64-bit SIMD vector				
VFMSL{	q}.F16 Qd, Dn, Dm[index] ; 128-bit SIMD vector FP/SIMD registers (A32)				
Where:					
Dd					
Sn	Is the 64-bit name of the SIMD and FP destination register.				
_	Is the 32-bit name of the first SIMD and FP source register.				
Sm	Is the 32-bit name of the second SIMD and FP source register.				
index					
	Depends on the instruction variant:				
	64 For the 64-bit SIMD vector variant: is the element index in the range 0 to 1.				
	<b>128</b> For the 128-bit SIMD vector variant: is the element index in the range 0 to 3.				
q Od	Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.				
Dn	Is the 128-bit name of the SIMD and FP destination register.				
Dm	Is the 64-bit name of the first SIMD and FP source register.				
	Is the 64-bit name of the second SIMD and FP source register.				

### Architectures supported

Supported in Armv8.2 and later.

### Usage

Vector Floating-point Multiply-Subtract Long from accumulator (by scalar). This instruction multiplies the negated vector elements in the first source SIMD and FP register by the specified value in the second source SIMD and FP register, and accumulates the product to the corresponding vector element of the destination SIMD and FP register. The instruction does not round the result of the multiply before the accumulation.

Depending on settings in the CPACR, NSACR, HCPTR, and FPEXC registers, and the Security state and PE mode in which the instruction is executed, an attempt to execute the instruction might be UNDEFINED, or trapped to Hyp mode. For more information see *Enabling Advanced SIMD and floating-point support* in the *Arm*<sup>®</sup> *Architecture Reference Manual Arm*<sup>®</sup>v8, for *Arm*<sup>®</sup>v8-A architecture profile.

In Armv8.2 and Armv8.3, this is an OPTIONAL instruction. From Armv8.4 it is mandatory for all implementations to support it.

------ Note ------

ID\_ISAR6.FHM indicates whether this instruction is supported.

### **Related references**

# C3.48 VFMSL (vector)

Vector Floating-point Multiply-Subtract Long from accumulator (vector).

### Syntax

VFMSL{a	g}.F16 Dd, Sn, Sm ; 64-bit SIMD vector
VFMSL{a	g}.F16 Qd, Dn, Dm ; 128-bit SIMD vector FP/SIMD registers (A32)
Where:	
Dd	
<b>C</b> n	Is the 64-bit name of the SIMD and FP destination register.
511	Is the 32-bit name of the first SIMD and FP source register.
Sm	Is the 22 bit name of the second CD4D on JED source resistor
q	is the 32-bit name of the second SIMD and FP source register.
	Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.
Qđ	Is the 128-bit name of the SIMD and FP destination register.
Dn	
Пm	Is the 64-bit name of the first SIMD and FP source register.
0111	Is the 64-bit name of the second SIMD and FP source register.

### Architectures supported

Supported in Armv8.2 and later.

### Usage

Vector Floating-point Multiply-Subtract Long from accumulator (vector). This instruction negates the values in the vector of one SIMD and FP register, multiplies these with the corresponding values in another vector, and accumulates the product to the corresponding vector element of the destination SIMD and FP register. The instruction does not round the result of the multiply before the accumulation.

Depending on settings in the CPACR, NSACR, HCPTR, and FPEXC registers, and the Security state and PE mode in which the instruction is executed, an attempt to execute the instruction might be UNDEFINED, or trapped to Hyp mode. For more information see *Enabling Advanced SIMD and floating-point support* in the *Arm*<sup>®</sup> *Architecture Reference Manual Arm*<sup>®</sup>v8, for *Arm*<sup>®</sup>v8-A architecture profile.

In Armv8.2 and Armv8.3, this is an OPTIONAL instruction. From Armv8.4 it is mandatory for all implementations to support it.

— Note —

ID\_ISAR6.FHM indicates whether this instruction is supported.

**Related references** 

# C3.49 VHADD

Vector Halving Add.

### Syntax

VHADD{cond}.datatype {Qd}, Qn, Qm

VHADD{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, U8, U16, or U32.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

# Operation

VHADD adds corresponding elements in two vectors, shifts each result right one bit, and places the results in the destination vector. Results are truncated.

# **Related references**

# C3.50 VHSUB

Vector Halving Subtract.

### Syntax

VHSUB{cond}.datatype {Qd}, Qn, Qm

VHSUB{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, U8, U16, or U32.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

# Operation

VHSUB subtracts the elements of one vector from the corresponding elements of another vector, shifts each result right one bit, and places the results in the destination vector. Results are always truncated.

# **Related references**

# C3.51 VLDn (single n-element structure to one lane)

Vector Load single *n*-element structure to one lane.

### Syntax

```
VLDn{cond}.datatype List, [Rn{@align}]{!}
VLDn{cond}.datatype list, [Rn{@align}], Rm
```

where:

n

must be one of 1, 2, 3, or 4.

cond

is an optional condition code.

#### datatype

see the following table.

#### list

is the list of Advanced SIMD registers enclosed in braces, { and }. See the following table for options.

```
Rn
```

is the general-purpose register containing the base address. Rn cannot be PC.

### align

specifies an optional alignment. See the following table for options.

```
!
```

if ! is present, Rn is updated to (Rn + the number of bytes transferred by the instruction). The update occurs after all the loads have taken place.

#### Rm

is a general-purpose register containing an offset from the base address. If Rm is present, the instruction updates Rn to (Rn + Rm) after using the address to access memory. Rm cannot be SP or PC.

### Operation

VLDn loads one *n*-element structure from memory into one or more Advanced SIMD registers. Elements of the register that are not loaded are unaltered.

n	datatype	list <sup>ag</sup>	aLign <sup>ah</sup>	alignment
1	8	{Dd[x]}	-	Standard only
	16	{Dd[x]}	@16	2-byte
	32	{Dd[x]}	@32	4-byte
2	8	{Dd[x], D(d+1)[x]}	@16	2-byte

ag Every register in the list must be in the range D0-D31.

ah *align* can be omitted. In this case, standard alignment rules apply.

n	datatype	list <sup>ag</sup>	align <sup>ah</sup>	alignment
	16	{Dd[x], D(d+1)[x]}	@32	4-byte
		{Dd[x], D(d+2)[x]}	@32	4-byte
	32	{Dd[x], D(d+1)[x]}	@64	8-byte
		{Dd[x], D(d+2)[x]}	@64	8-byte
3	8	{Dd[x], D(d+1)[x], D(d+2)[x]}	-	Standard only
	16 or 32	{Dd[x], D(d+1)[x], D(d+2)[x]}	-	Standard only
		{Dd[x], D(d+2)[x], D(d+4)[x]}	-	Standard only
4	8	{Dd[x], D(d+1)[x], D(d+2)[x], D(d+3)[x]}	@32	4-byte
	16	{Dd[x], D(d+1)[x], D(d+2)[x], D(d+3)[x]}	@64	8-byte
		{Dd[x], D(d+2)[x], D(d+4)[x], D(d+6)[x]}	@64	8-byte
	32	{Dd[x], D(d+1)[x], D(d+2)[x], D(d+3)[x]}	@64 or @128	8-byte or 16-byte
		{Dd[x], D(d+2)[x], D(d+4)[x], D(d+6)[x]}	@64 or @128	8-byte or 16-byte

### Table C3-4 Permitted combinations of parameters for VLDn (single n-element structure to one lane) (continued)

# **Related concepts**

*C3.3 Interleaving provided by load and store element and structure instructions* on page C3-395 *Related references* 

# C3.52 VLDn (single n-element structure to all lanes)

Vector Load single *n*-element structure to all lanes.

### Syntax

```
VLDn{cond}.datatype List, [Rn{@align}]{!}
VLDn{cond}.datatype list, [Rn{@align}], Rm
```

where:

n

must be one of 1, 2, 3, or 4.

cond

is an optional condition code.

#### datatype

see the following table.

#### list

is the list of Advanced SIMD registers enclosed in braces, { and }. See the following table for options.

#### Rn

is the general-purpose register containing the base address. Rn cannot be PC.

#### align

specifies an optional alignment. See the following table for options.

```
!
```

if ! is present, Rn is updated to (Rn + the number of bytes transferred by the instruction). The update occurs after all the loads have taken place.

#### Rm

is a general-purpose register containing an offset from the base address. If Rm is present, the instruction updates Rn to (Rn + Rm) after using the address to access memory. Rm cannot be SP or PC.

### Operation

VLDn loads multiple copies of one *n*-element structure from memory into one or more Advanced SIMD registers.

n	datatype	list <sup>ai</sup>	align <sup>aj</sup>	alignment
1	8	{Dd[]}	-	Standard only
		{Dd[],D(d+1)[]}	-	Standard only
	16	{Dd[]}	@16	2-byte
		{Dd[],D(d+1)[]}	@16	2-byte

### Table C3-5 Permitted combinations of parameters for VLDn (single n-element structure to all lanes)

ai Every register in the list must be in the range D0-D31.

aj align can be omitted. In this case, standard alignment rules apply.

n	datatype	list <sup>ai</sup>	align <sup>aj</sup>	alignment
	32	{Dd[]}	@32	4-byte
		{Dd[],D(d+1)[]}	@32	4-byte
2	8	{Dd[], D(d+1)[]}	@8	byte
		{Dd[], D(d+2)[]}	@8	byte
	16	{Dd[], D(d+1)[]}	@16	2-byte
		{Dd[], D(d+2)[]}	@16	2-byte
	32	{Dd[], D(d+1)[]}	@32	4-byte
		{Dd[], D(d+2)[]}	@32	4-byte
3	8, 16, or 32	{Dd[], D(d+1)[], D(d+2)[]}	-	Standard only
		{Dd[], D(d+2)[], D(d+4)[]}	-	Standard only
4	8	{Dd[], D(d+1)[], D(d+2)[], D(d+3)[]}	@32	4-byte
		{Dd[], D(d+2)[], D(d+4)[], D(d+6)[]}	@32	4-byte
	16	{Dd[], D(d+1)[], D(d+2)[], D(d+3)[]}	@64	8-byte
		{Dd[], D(d+2)[], D(d+4)[], D(d+6)[]}	@64	8-byte
	32	{Dd[], D(d+1)[], D(d+2)[], D(d+3)[]}	@64 or @128	8-byte or 16-byte
		{Dd[], D(d+2)[], D(d+4)[], D(d+6)[]}	@64 or @128	8-byte or 16-byte

### Table C3-5 Permitted combinations of parameters for VLDn (single n-element structure to all lanes) (continued)

### **Related concepts**

*C3.3 Interleaving provided by load and store element and structure instructions* on page C3-395 *Related references* 

# C3.53 VLDn (multiple n-element structures)

Vector Load multiple *n*-element structures.

### Syntax

```
VLDn{cond}.datatype list, [Rn{@align}]{!}
VLDn{cond}.datatype list, [Rn{@align}], Rm
```

where:

```
n
```

must be one of 1, 2, 3, or 4.

cond

is an optional condition code.

#### datatype

see the following table for options.

#### list

is the list of Advanced SIMD registers enclosed in braces, { and }. See the following table for options.

#### Rn

is the general-purpose register containing the base address. Rn cannot be PC.

### align

specifies an optional alignment. See the following table for options.

```
!
```

if ! is present, Rn is updated to (Rn + the number of bytes transferred by the instruction). The update occurs after all the loads have taken place.

#### Rm

is a general-purpose register containing an offset from the base address. If Rm is present, the instruction updates Rn to (Rn + Rm) after using the address to access memory. Rm cannot be SP or PC.

### Operation

VLD*n* loads multiple *n*-element structures from memory into one or more Advanced SIMD registers, with de-interleaving (unless n == 1). Every element of each register is loaded.

n	datatype	list <sup>ak</sup>	align <sup>al</sup>	alignment
1	8, 16, 32, or 64	{Dd}	@64	8-byte
		{Dd, D(d+1)}	@64 or @128	8-byte or 16-byte
		{Dd, D(d+1), D(d+2)}	@64	8-byte
		{Dd, D(d+1), D(d+2), D(d+3)}	@64, @128, or @256	8-byte, 16-byte, or 32-byte

ak Every register in the list must be in the range D0-D31.

al *align* can be omitted. In this case, standard alignment rules apply.

n	datatype	list <sup>ak</sup>	align <sup>al</sup>	alignment
2	8, 16, or 32	{Dd, D(d+1)}	@64, @128	8-byte or 16-byte
		{Dd, D(d+2)}	@64, @128	8-byte or 16-byte
		{Dd, D(d+1), D(d+2), D(d+3)}	@64, @128, or @256	8-byte, 16-byte, or 32-byte
3	8, 16, or 32	{Dd, D(d+1), D(d+2)}	@64	8-byte
		{Dd, D(d+2), D(d+4)}	@64	8-byte
4	8, 16, or 32	{Dd, D(d+1), D(d+2), D(d+3)}	@64, @128, or @256	8-byte, 16-byte, or 32-byte
		{Dd, D(d+2), D(d+4), D(d+6)}	@64, @128, or @256	8-byte, 16-byte, or 32-byte

### Table C3-6 Permitted combinations of parameters for VLDn (multiple n-element structures) (continued)

### **Related concepts**

*C3.3 Interleaving provided by load and store element and structure instructions* on page C3-395 *Related references* 

# C3.54 VLDM

Extension register load multiple.

### Syntax

VLDMmode{cond} Rn{!}, Registers

where:

mode

must be one of:

IA

meaning Increment address After each transfer. IA is the default, and can be omitted.

DB

meaning Decrement address Before each transfer.

EA

meaning Empty Ascending stack operation. This is the same as DB for loads.

FD

meaning Full Descending stack operation. This is the same as IA for loads.

#### cond

is an optional condition code.

#### Rn

is the general-purpose register holding the base address for the transfer.

!

is optional. ! specifies that the updated base address must be written back to *Rn*. If ! is not specified, *mode* must be IA.

Registers

is a list of consecutive extension registers enclosed in braces, { and }. The list can be commaseparated, or in range format. There must be at least one register in the list.

You can specify D or Q registers, but they must not be mixed. The number of registers must not exceed 16 D registers, or 8 Q registers. If Q registers are specified, on disassembly they are shown as D registers.

— Note –

VPOP Registers is equivalent to VLDM sp!, Registers.

You can use either form of this instruction. They both disassemble to VPOP.

### **Related references**

*C1.9 Condition code suffixes* on page C1-92 *C4.14 VLDM (floating-point)* on page C4-561

# C3.55 VLDR

Extension register load.

### Syntax

```
VLDR{cond}{.64} Dd, [Rn{, #offset}]
```

VLDR{cond}{.64} Dd, Label

where:

cond

is an optional condition code.

Dd

is the extension register to be loaded.

### Rn

is the general-purpose register holding the base address for the transfer.

### offset

is an optional numeric expression. It must evaluate to a numeric value at assembly time. The value must be a multiple of 4, and lie in the range -1020 to +1020. The value is added to the base address to form the address used for the transfer.

### Label

is a PC-relative expression.

Label must be aligned on a word boundary within  $\pm 1$ KB of the current instruction.

### Operation

The VLDR instruction loads an extension register from memory.

Two words are transferred.

There is also a VLDR pseudo-instruction.

### **Related references**

C3.57 VLDR pseudo-instruction on page C3-452 C1.9 Condition code suffixes on page C1-92 C4.15 VLDR (floating-point) on page C4-562

# C3.56 VLDR (post-increment and pre-decrement)

Pseudo-instruction that loads extension registers, with post-increment and pre-decrement forms.

\_\_\_\_\_ Note \_\_\_\_\_

There are also VLDR and VSTR instructions without post-increment and pre-decrement.

### Syntax

VLDR{cond}{.64} Dd, [Rn], #offset ; post-increment
VLDR{cond}{.64} Dd, [Rn, #-offset]! ; pre-decrement
where:

cond

is an optional condition code.

#### Dd

is the extension register to load.

#### Rn

is the general-purpose register holding the base address for the transfer.

offset

is a numeric expression that must evaluate to 8 at assembly time.

### Operation

The post-increment instruction increments the base address in the register by the offset value, after the transfer. The pre-decrement instruction decrements the base address in the register by the offset value, and then performs the transfer using the new address in the register. This pseudo-instruction assembles to a VLDM instruction.

### **Related references**

C3.54 VLDM on page C3-449 C3.55 VLDR on page C3-450 C1.9 Condition code suffixes on page C1-92 C4.16 VLDR (post-increment and pre-decrement, floating-point) on page C4-563

# C3.57 VLDR pseudo-instruction

The VLDR pseudo-instruction loads a constant value into every element of a 64-bit Advanced SIMD vector.

\_\_\_\_\_ Note \_\_\_\_

This description is for the VLDR pseudo-instruction only.

### Syntax

VLDR{cond}.datatype Dd,=constant

where:

cond

is an optional condition code.

datatype

must be one of In, Sn, Un, or F32.

n

must be one of 8, 16, 32, or 64.

Dd

is the extension register to be loaded.

constant

is an immediate value of the appropriate type for datatype.

### Usage

If an instruction (for example, VMOV) is available that can generate the constant directly into the register, the assembler uses it. Otherwise, it generates a doubleword literal pool entry containing the constant and loads the constant using a VLDR instruction.

### **Related references**

C3.55 VLDR on page C3-450 C1.9 Condition code suffixes on page C1-92 C3.57 VLDR pseudo-instruction on page C3-452

### C3.58 VMAX and VMIN

Vector Maximum, Vector Minimum.

### Syntax

Vop{cond}.datatype Qd, Qn, Qm
Vop{cond}.datatype Dd, Dn, Dm

where:

ор

must be either MAX or MIN.

cond

is an optional condition code.

#### datatype

must be one of \$8, \$16, \$32, U8, U16, U32, or F32.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

### Operation

VMAX compares corresponding elements in two vectors, and copies the larger of each pair into the corresponding element in the destination vector.

VMIN compares corresponding elements in two vectors, and copies the smaller of each pair into the corresponding element in the destination vector.

### Floating-point maximum and minimum

 $\max(+0.0, -0.0) = +0.0.$ 

 $\min(+0.0, -0.0) = -0.0$ 

If any input is a NaN, the corresponding result element is the default NaN.

### **Related references**

C3.89 VPADD on page C3-484 C1.9 Condition code suffixes on page C1-92

# C3.59 VMAXNM, VMINNM

Vector Minimum, Vector Maximum.

\_\_\_\_\_ Note \_\_\_\_

- These instructions are supported only in Armv8.
- You cannot use VMAXNM or VMINNM inside an IT block.

#### Syntax

Vop.F32 Qd, Qn, Qm

Vop.F32 Dd, Dn, Dm

where:

ор

must be either MAXNM or MINNM.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

### Operation

VMAXNM compares corresponding elements in two vectors, and copies the larger of each pair into the corresponding element in the destination vector.

VMINNM compares corresponding elements in two vectors, and copies the smaller of each pair into the corresponding element in the destination vector.

If one of the elements in a pair is a number and the other element is NaN, the corresponding result element is the number. This is consistent with the IEEE 754-2008 standard.

# C3.60 VMLA

Vector Multiply Accumulate.

### Syntax

VMLA{cond}.datatype {Qd}, Qn, Qm

VMLA{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

must be one of 18, 116, 132, or F32.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

# Operation

VMLA multiplies corresponding elements in two vectors, and accumulates the results into the elements of the destination vector.

# **Related references**

# C3.61 VMLA (by scalar)

Vector Multiply by scalar and Accumulate.

### Syntax

```
VMLA{cond}.datatype {Qd}, Qn, Dm[x]
```

```
VMLA{cond}.datatype {Dd}, Dn, Dm[x]
```

where:

cond

is an optional condition code.

### datatype

must be one of I16, I32, or F32.

### Qd, Qn

are the destination vector and the first operand vector, for a quadword operation.

Dd, Dn

are the destination vector and the first operand vector, for a doubleword operation.

Dm[x]

is the scalar holding the second operand.

# Operation

VMLA multiplies each element in a vector by a scalar, and accumulates the results into the corresponding elements of the destination vector.

# **Related references**

# C3.62 VMLAL (by scalar)

Vector Multiply by scalar and Accumulate Long.

### Syntax

VMLAL{cond}.datatype Qd, Dn, Dm[x]

where:

cond

is an optional condition code.

datatype

must be one of \$16, \$32, U16, or U32

Qd, Dn

are the destination vector and the first operand vector, for a long operation.

Dm[x]

is the scalar holding the second operand.

### Operation

VMLAL multiplies each element in a vector by a scalar, and accumulates the results into the corresponding elements of the destination vector.

### **Related references**

# C3.63 VMLAL

Vector Multiply Accumulate Long.

### Syntax

VMLAL{cond}.datatype Qd, Dn, Dm

where:

cond

is an optional condition code.

datatype

must be one of S8, S16, S32, U8, U16, or U32.

Qd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a long operation.

# Operation

VMLAL multiplies corresponding elements in two vectors, and accumulates the results into the elements of the destination vector.

### **Related concepts**

B1.8 Polynomial arithmetic over  $\{0,1\}$  on page B1-54

# C3.64 VMLS (by scalar)

Vector Multiply by scalar and Subtract.

### Syntax

```
VMLS{cond}.datatype {Qd}, Qn, Dm[x]
```

```
VMLS\{cond\}.datatype \ \{Dd\}, \ Dn, \ Dm[x]
```

where:

cond

is an optional condition code.

### datatype

must be one of **I16**, **I32**, or **F32**.

### Qd, Qn

are the destination vector and the first operand vector, for a quadword operation.

Dd, Dn

are the destination vector and the first operand vector, for a doubleword operation.

Dm[x]

is the scalar holding the second operand.

### Operation

VMLS multiplies each element in a vector by a scalar, subtracts the results from the corresponding elements of the destination vector, and places the final results in the destination vector.

# **Related references**

# C3.65 VMLS

Vector Multiply Subtract.

### Syntax

VMLS{cond}.datatype {Qd}, Qn, Qm

VMLS{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

must be one of 18, 116, 132, F32.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

# Operation

VMLS multiplies corresponding elements in two vectors, subtracts the results from corresponding elements of the destination vector, and places the final results in the destination vector.

# **Related references**

# C3.66 VMLSL

Vector Multiply Subtract Long.

### Syntax

VMLSL{cond}.datatype Qd, Dn, Dm

where:

cond

is an optional condition code.

datatype

must be one of \$8, \$16, \$32, U8, U16, or U32.

Qd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a long operation.

# Operation

VMLSL multiplies corresponding elements in two vectors, subtracts the results from corresponding elements of the destination vector, and places the final results in the destination vector.

### **Related references**

# C3.67 VMLSL (by scalar)

Vector Multiply by scalar and Subtract Long.

### Syntax

VMLSL{cond}.datatype Qd, Dn, Dm[x]

where:

cond

is an optional condition code.

datatype

must be one of \$16, \$32, U16, or U32.

Qd, Dn

are the destination vector and the first operand vector, for a long operation.

Dm[x]

is the scalar holding the second operand.

### Operation

VMLSL multiplies each element in a vector by a scalar, subtracts the results from the corresponding elements of the destination vector, and places the final results in the destination vector.

### **Related references**

# C3.68 VMOV (immediate)

Vector Move.

### Syntax

VMOV{cond}.datatype Qd, #imm

VMOV{cond}.datatype Dd, #imm

where:

cond

is an optional condition code.

### datatype

must be one of 18, 116, 132, 164, or F32.

### Qd or Dd

is the Advanced SIMD register for the result.

#### imm

is an immediate value of the type specified by *datatype*. This is replicated to fill the destination register.

### Operation

VMOV replicates an immediate value in every element of the destination register.

Table C3-7	Available	immediate values	in	VMOV	(immediate)
------------	-----------	------------------	----	------	-------------

datatype	imm
18	ØxXY
I16	0x00XY, 0xXY00
132	0x000000XY, 0x0000XY00, 0x00XY0000, 0xXY000000
	0x0000XYFF, 0x00XYFFFF
164	byte masks, ØxGGHHJJKKLLMMNNPP am
F32	floating-point numbers an

# **Related references**

C1.9 Condition code suffixes on page C1-92

an Any number that can be expressed as  $+/-n * 2^{-r}$ , where *n* and *r* are integers,  $16 \le n \le 31$ ,  $0 \le r \le 7$ .

am Each of 0xGG, 0xHH, 0xJJ, 0xKK, 0xLL, 0xMM, 0xNN, and 0xPP must be either 0x00 or 0xFF.

# C3.69 VMOV (register)

Vector Move.

### Syntax

VMOV{cond}{.datatype} Qd, Qm

VMOV{cond}{.datatype} Dd, Dm

where:

cond

is an optional condition code.

### datatype

is an optional datatype. The assembler ignores datatype.

### Qd, Qm

specifies the destination vector and the source vector, for a quadword operation.

### Dd, Dm

specifies the destination vector and the source vector, for a doubleword operation.

### Operation

VMOV copies the contents of the source register into the destination register.

### **Related references**

# C3.70 VMOV (between two general-purpose registers and a 64-bit extension register)

Transfer contents between two general-purpose registers and a 64-bit extension register.

### Syntax

VMOV{cond} Dm, Rd, Rn

VMOV{cond} Rd, Rn, Dm

where:

cond

is an optional condition code.

Dm

is a 64-bit extension register.

Rd, Rn

are the general-purpose registers. Rd and Rn must not be PC.

### Operation

VMOV Dm, Rd, Rn transfers the contents of Rd into the low half of Dm, and the contents of Rn into the high half of Dm.

VMOV Rd, Rn, Dm transfers the contents of the low half of Dm into Rd, and the contents of the high half of Dm into Rn.

### **Related references**

# C3.71 VMOV (between a general-purpose register and an Advanced SIMD scalar)

Transfer contents between a general-purpose register and an Advanced SIMD scalar.

#### Syntax

```
VMOV{cond}{.size} Dn[x], Rd
```

```
VMOV{cond}{.datatype} Rd, Dn[x]
```

where:

cond

is an optional condition code.

size

the data size. Can be 8, 16, or 32. If omitted, *size* is 32.

#### datatype

the data type. Can be U8, S8, U16, S16, or 32. If omitted, datatype is 32.

#### Dn[x]

is the Advanced SIMD scalar.

Rd

is the general-purpose register. Rd must not be PC.

### Operation

VMOV Dn[x], Rd transfers the contents of the least significant byte, halfword, or word of Rd into Dn[x].

VMOV Rd, Dn[x] transfers the contents of Dn[x] into the least significant byte, halfword, or word of Rd. The remaining bits of Rd are either zero or sign extended.

### **Related references**

# C3.72 VMOVL

Vector Move Long.

### Syntax

VMOVL{cond}.datatype Qd, Dm

where:

cond

is an optional condition code.

datatype

must be one of \$8, \$16, \$32, U8, U16, or U32.

Qd, Dm

specifies the destination vector and the operand vector.

# Operation

VMOVL takes each element in a doubleword vector, sign or zero extends them to twice their original length, and places the results in a quadword vector.

### **Related references**

# C3.73 VMOVN

Vector Move and Narrow.

### Syntax

VMOVN{cond}.datatype Dd, Qm

where:

cond

is an optional condition code.

datatype

must be one of 116, 132, or 164.

Dd, Qm

specifies the destination vector and the operand vector.

### Operation

VMOVN copies the least significant half of each element of a quadword vector into the corresponding elements of a doubleword vector.

### **Related references**
# C3.74 VMOV2

Pseudo-instruction that generates an immediate value and places it in every element of an Advanced SIMD vector, without loading a value from a literal pool.

### Syntax

VMOV2{cond}.datatype Qd, #constant

VMOV2{cond}.datatype Dd, #constant

where:

datatype

must be one of:

- 18, 116, 132, or 164.
- S8, S16, S32, or S64.
- U8, U16, U32, or U64.
- F32.

cond

is an optional condition code.

### Qd or Dd

is the extension register to be loaded.

constant

is an immediate value of the appropriate type for datatype.

### Operation

VMOV2 can generate any 16-bit immediate value, and a restricted range of 32-bit and 64-bit immediate values.

VMOV2 is a pseudo-instruction that always assembles to exactly two instructions. It typically assembles to a VMOV or VMVN instruction, followed by a VBIC or VORR instruction.

### **Related references**

C3.68 VMOV (immediate) on page C3-463 C3.16 VBIC (immediate) on page C3-408 C1.9 Condition code suffixes on page C1-92

# C3.75 VMRS

Transfer contents from an Advanced SIMD system register to a general-purpose register.

### Syntax

VMRS{cond} Rd, extsysreg

where:

cond

extsysreg

is an optional condition code.

Rd

is the general-purpose register. Rd must not be PC.

It can be APSR\_nzcv, if *extsysreg* is FPSCR. In this case, the floating-point status flags are transferred into the corresponding flags in the special-purpose APSR.

is the Advanced SIMD and floating-point system register, usually FPSCR, FPSID, or FPEXC.

### Usage

The VMRS instruction transfers the contents of *extsysreg* into *Rd*.

\_\_\_\_\_ Note \_\_\_\_\_

The instruction stalls the processor until all current Advanced SIMD or floating-point operations complete.

## Example

VMRS r2,FPCID VMRS APSR\_nzcv, FPSCR ; transfer FI

; transfer FP status register to the ; special-purpose APSR

### **Related references**

*B1.14 Advanced SIMD system registers in AArch32 state* on page B1-60 *C1.9 Condition code suffixes* on page C1-92 *C4.26 VMRS (floating-point)* on page C4-573

# C3.76 VMSR

Transfer contents of a general-purpose register to an Advanced SIMD system register.

### Syntax

VMSR{cond} extsysreg, Rd

where:

cond

extsysreg

is an optional condition code.

Rd

is the general-purpose register. Rd must not be PC.

It can be APSR\_nzcv, if *extsysreg* is FPSCR. In this case, the floating-point status flags are transferred into the corresponding flags in the special-purpose APSR.

is the Advanced SIMD and floating-point system register, usually FPSCR, FPSID, or FPEXC.

### Usage

The VMSR instruction transfers the contents of *Rd* into *extsysreg*.

\_\_\_\_\_ Note \_\_\_\_\_

The instruction stalls the processor until all current Advanced SIMD operations complete.

### Example

VMSR FPSCR, r4

### **Related references**

*B1.14 Advanced SIMD system registers in AArch32 state* on page B1-60 *C1.9 Condition code suffixes* on page C1-92 *C4.27 VMSR (floating-point)* on page C4-574

# C3.77 VMUL

Vector Multiply.

## Syntax

VMUL{cond}.datatype {Qd}, Qn, Qm

VMUL{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## datatype

must be one of 18, 116, 132, F32, or P8.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

# Operation

VMUL multiplies corresponding elements in two vectors, and places the results in the destination vector.

### **Related references**

# C3.78 VMUL (by scalar)

Vector Multiply by scalar.

## Syntax

```
VMUL{cond}.datatype {Qd}, Qn, Dm[x]
```

```
VMUL{cond}.datatype {Dd}, Dn, Dm[x]
```

where:

cond

is an optional condition code.

### datatype

must be one of I16, I32, or F32.

## Qd, Qn

are the destination vector and the first operand vector, for a quadword operation.

Dd, Dn

are the destination vector and the first operand vector, for a doubleword operation.

Dm[x]

is the scalar holding the second operand.

# Operation

VMUL multiplies each element in a vector by a scalar, and places the results in the destination vector.

### **Related references**

# C3.79 VMULL

Vector Multiply Long

### Syntax

VMULL{cond}.datatype Qd, Dn, Dm

where:

cond

is an optional condition code.

datatype

must be one of U8, U16, U32, S8, S16, S32, or P8.

Qd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a long operation.

## Operation

VMULL multiplies corresponding elements in two vectors, and places the results in the destination vector.

### **Related references**

# C3.80 VMULL (by scalar)

Vector Multiply Long by scalar

### Syntax

VMULL{cond}.datatype Qd, Dn, Dm[x]

where:

cond

is an optional condition code.

datatype

must be one of \$16, \$32, U16, or U32.

Qd, Dn

are the destination vector and the first operand vector, for a long operation.

### Dm[x]

is the scalar holding the second operand.

## Operation

VMULL multiplies each element in a vector by a scalar, and places the results in the destination vector.

### **Related references**

# C3.81 VMVN (register)

Vector Move NOT (register).

## Syntax

VMVN{cond}{.datatype} Qd, Qm

VMVN{cond}{.datatype} Dd, Dm

where:

cond

is an optional condition code.

### datatype

is an optional datatype. The assembler ignores *datatype*.

## Qd, Qm

specifies the destination vector and the source vector, for a quadword operation.

## Dd, Dm

specifies the destination vector and the source vector, for a doubleword operation.

# Operation

VMVN inverts the value of each bit from the source register and places the results into the destination register.

### **Related references**

# C3.82 VMVN (immediate)

Vector Move NOT (immediate).

### Syntax

VMVN{cond}.datatype Qd, #imm

VMVN{cond}.datatype Dd, #imm

where:

cond

is an optional condition code.

### datatype

must be one of 18, 116, 132, 164, or F32.

### Qd or Dd

is the Advanced SIMD register for the result.

#### imm

is an immediate value of the type specified by *datatype*. This is replicated to fill the destination register.

## Operation

VMVN inverts the value of each bit from an immediate value and places the results into each element in the destination register.

datatype	imm
18	-
I16	ØxFFXY, ØxXYFF
132	0xFFFFFFXY, 0xFFFFXYFF, 0xFFXYFFFF, 0xXYFFFFFF
	0xFFFFXY00, 0xFFXY0000
164	-
F32	-

### Table C3-8 Available immediate values in VMVN (immediate)

### **Related references**

# C3.83 VNEG

Vector Negate.

### Syntax

VNEG{cond}.datatype Qd, Qm

VNEG{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, or \$32.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

## Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

# Operation

VNEG negates each element in a vector, and places the results in a second vector. (The floating-point version only inverts the sign bit.)

## **Related references**

*C4.29 VNEG (floating-point)* on page C4-576 *C1.9 Condition code suffixes* on page C1-92

# C3.84 VORN (register)

Vector bitwise OR NOT (register).

## Syntax

VORN{cond}{.datatype} {Qd}, Qn, Qm

VORN{cond}{.datatype} {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

is an optional data type. The assembler ignores datatype.

Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VORN performs a bitwise logical OR complement between two registers, and places the results in the destination register.

## **Related references**

# C3.85 VORN (immediate)

Vector bitwise OR NOT (immediate) pseudo-instruction.

### Syntax

VORN{cond}.datatype Qd, #imm

VORN{cond}.datatype Dd, #imm

where:

cond

is an optional condition code.

#### datatype

must be either 18, 116, 132, or 164.

#### Qd or Dd

is the Advanced SIMD register for the result.

#### imm

is the immediate value.

### Operation

VORN takes each element of the destination vector, performs a bitwise OR complement with an immediate value, and returns the results in the destination vector.

—— Note —

On disassembly, this pseudo-instruction is disassembled to a corresponding VORR instruction, with a complementary immediate value.

### Immediate values

If *datatype* is **I16**, the immediate value must have one of the following forms:

- ØxFFXY.
- ØxXYFF.

If *datatype* is I32, the immediate value must have one of the following forms:

- 0xFFFFFFXY.
- 0xFFFFXYFF.
- 0xFFXYFFFF.
- ØxXYFFFFFF.

### **Related references**

*C3.87 VORR (immediate)* on page C3-482 *C1.9 Condition code suffixes* on page C1-92

# C3.86 VORR (register)

Vector bitwise OR (register).

### Syntax

```
VORR{cond}{.datatype} {Qd}, Qn, Qm
```

VORR{cond}{.datatype} {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

is an optional data type. The assembler ignores datatype.

Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

— Note —

VORR with the same register for both operands is a VMOV instruction. You can use VORR in this way, but disassembly of the resulting code produces the VMOV syntax.

### Operation

VORR performs a bitwise logical OR between two registers, and places the result in the destination register.

### **Related references**

*C3.69 VMOV (register)* on page C3-464 *C1.9 Condition code suffixes* on page C1-92

# C3.87 VORR (immediate)

Vector bitwise OR immediate.

### Syntax

VORR{cond}.datatype Qd, #imm

VORR{cond}.datatype Dd, #imm

where:

cond

is an optional condition code.

### datatype

must be either 18, 116, 132, or 164.

#### Qd or Dd

is the Advanced SIMD register for the source and result.

imm

is the immediate value.

## Operation

VORR takes each element of the destination vector, performs a bitwise logical OR with an immediate value, and places the results in the destination vector.

### Immediate values

You can either specify *imm* as a pattern which the assembler repeats to fill the destination register, or you can directly specify the immediate value (that conforms to the pattern) in full. The pattern for *imm* depends on the datatype, as shown in the following table:

### Table C3-9 Patterns for immediate value in VORR (immediate)

116	132
0x00XY	0x000000XY
0xXY00	0×0000XY00
-	0×00XY0000
-	0×XY000000

If you use the **I8** or **I64** datatypes, the assembler converts it to either the **I16** or **I32** instruction to match the pattern of *imm*. If the immediate value does not match any of the patterns in the preceding table, the assembler generates an error.

Related references

# C3.88 VPADAL

Vector Pairwise Add and Accumulate Long.

### Syntax

VPADAL{cond}.datatype Qd, Qm

VPADAL{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, U8, U16, or U32.

Qd, Qm

are the destination vector and the operand vector, for a quadword instruction.

Dd, Dm

are the destination vector and the operand vector, for a doubleword instruction.

### Operation

VPADAL adds adjacent pairs of elements of a vector, and accumulates the absolute values of the results into the elements of the destination vector.



Figure C3-3 Example of operation of VPADAL (in this case for data type S16)

**Related references** 

# C3.89 VPADD

Vector Pairwise Add.

### Syntax

VPADD{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

must be one of 18, 116, 132, or F32.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector.

## Operation

VPADD adds adjacent pairs of elements of two vectors, and places the results in the destination vector.



Figure C3-4 Example of operation of VPADD (in this case, for data type I16)

**Related references** C1.9 Condition code suffixes on page C1-92

# C3.90 VPADDL

Vector Pairwise Add Long.

### Syntax

VPADDL{cond}.datatype Qd, Qm

VPADDL{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, U8, U16, or U32.

### Qd, Qm

are the destination vector and the operand vector, for a quadword instruction.

### Dd, Dm

are the destination vector and the operand vector, for a doubleword instruction.

## Operation

VPADDL adds adjacent pairs of elements of a vector, sign or zero extends the results to twice their original width, and places the final results in the destination vector.



### Figure C3-5 Example of operation of doubleword VPADDL (in this case, for data type S16)

**Related references** C1.9 Condition code suffixes on page C1-92

## C3.91 VPMAX and VPMIN

Vector Pairwise Maximum, Vector Pairwise Minimum.

### Syntax

VPop{cond}.datatype Dd, Dn, Dm

where:

ор

must be either MAX or MIN.

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, U8, U16, U32, or F32.

Dd, Dn, Dm

are the destination doubleword vector, the first operand doubleword vector, and the second operand doubleword vector.

### Operation

VPMAX compares adjacent pairs of elements in two vectors, and copies the larger of each pair into the corresponding element in the destination vector. Operands and results must be doubleword vectors.

VPMIN compares adjacent pairs of elements in two vectors, and copies the smaller of each pair into the corresponding element in the destination vector. Operands and results must be doubleword vectors.

### Floating-point maximum and minimum

 $\max(+0.0, -0.0) = +0.0.$ 

 $\min(+0.0, -0.0) = -0.0$ 

If any input is a NaN, the corresponding result element is the default NaN.

### **Related references**

# C3.92 VPOP

Pop extension registers from the stack.

### Syntax

VPOP{cond} Registers

where: cond

is an optional condition code.

### Registers

is a list of consecutive extension registers enclosed in braces, { and }. The list can be commaseparated, or in range format. There must be at least one register in the list.

You can specify D or Q registers, but they must not be mixed. The number of registers must not exceed 16 D registers, or 8 Q registers. If Q registers are specified, on disassembly they are shown as D registers.

----- Note ------

VPOP Registers is equivalent to VLDM sp!, Registers.

You can use either form of this instruction. They both disassemble to VPOP.

### **Related references**

C1.9 Condition code suffixes on page C1-92 C3.93 VPUSH on page C3-488 C4.33 VPOP (floating-point) on page C4-580

# C3.93 VPUSH

Push extension registers onto the stack.

### Syntax

VPUSH{cond} Registers

where: cond

is an optional condition code.

### Registers

is a list of consecutive extension registers enclosed in braces, { and }. The list can be commaseparated, or in range format. There must be at least one register in the list.

You can specify D or Q registers, but they must not be mixed. The number of registers must not exceed 16 D registers, or 8 Q registers. If Q registers are specified, on disassembly they are shown as D registers.

----- Note ------

VPUSH Registers is equivalent to VSTMDB sp!, Registers.

You can use either form of this instruction. They both disassemble to VPUSH.

### **Related references**

*C1.9 Condition code suffixes* on page C1-92 *C3.92 VPOP* on page C3-487 *C4.34 VPUSH (floating-point)* on page C4-581

# C3.94 VQABS

Vector Saturating Absolute.

## Syntax

VQABS{cond}.datatype Qd, Qm

VQABS{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, or \$32.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

## Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

# Operation

VQABS takes the absolute value of each element in a vector, and places the results in a second vector.

The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

## **Related references**

# C3.95 VQADD

Vector Saturating Add.

## Syntax

VQADD{cond}.datatype {Qd}, Qn, Qm

VQADD{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, \$64, U8, U16, U32, or U64.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

# Operation

VQADD adds corresponding elements in two vectors, and places the results in the destination vector.

The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

## **Related references**

# C3.96 VQDMLAL and VQDMLSL (by vector or by scalar)

Vector Saturating Doubling Multiply Accumulate Long, Vector Saturating Doubling Multiply Subtract Long.

#### Syntax

VQDopL{cond}.datatype Qd, Dn, Dm

VQDopL{cond}.datatype Qd, Dn, Dm[x]

where:

ор

must be one of:

MLA

Multiply Accumulate.

MLS

Multiply Subtract.

#### cond

is an optional condition code.

#### datatype

must be either S16 or S32.

### Qd, Dn

are the destination vector and the first operand vector.

### Dm

is the vector holding the second operand, for a by vector operation.

#### Dm[x]

is the scalar holding the second operand, for a by scalar operation.

### Operation

These instructions multiply their operands and double the results. VQDMLAL adds the results to the values in the destination register. VQDMLSL subtracts the results from the values in the destination register.

If any of the results overflow, they are saturated. The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

### **Related references**

# C3.97 VQDMULH (by vector or by scalar)

Vector Saturating Doubling Multiply Returning High Half.

### Syntax

```
VQDMULH{cond}.datatype {Qd}, Qn, Qm
VQDMULH{cond}.datatype {Dd}, Dn, Dm
VQDMULH{cond}.datatype {Qd}, Qn, Dm[x]
VQDMULH{cond}.datatype {Dd}, Dn, Dm[x]
where:
```

cond

is an optional condition code.

#### datatype

must be either S16 or S32.

#### Qd, Qn

are the destination vector and the first operand vector, for a quadword operation.

Dd, Dn

are the destination vector and the first operand vector, for a doubleword operation.

#### Qm or Dm

is the vector holding the second operand, for a by vector operation.

Dm[x]

is the scalar holding the second operand, for a by scalar operation.

### Operation

VQDMULH multiplies corresponding elements in two vectors, doubles the results, and places the most significant half of the final results in the destination vector.

The second operand can be a scalar instead of a vector.

If any of the results overflow, they are saturated. The sticky QC flag (FPSCR bit[27]) is set if saturation occurs. Each result is truncated.

### **Related references**

# C3.98 VQDMULL (by vector or by scalar)

Vector Saturating Doubling Multiply Long.

### Syntax

```
VQDMULL{cond}.datatype Qd, Dn, Dm
```

```
VQDMULL{cond}.datatype Qd, Dn, Dm[x]
```

where:

cond

is an optional condition code.

### datatype

must be either S16 or S32.

### Qd, Dn

are the destination vector and the first operand vector.

### Dm

is the vector holding the second operand, for a by vector operation.

Dm[x]

is the scalar holding the second operand, for a by scalar operation.

## Operation

VQDMULL multiplies corresponding elements in two vectors, doubles the results and places the results in the destination register.

The second operand can be a scalar instead of a vector.

If any of the results overflow, they are saturated. The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

# **Related references**

# C3.99 VQMOVN and VQMOVUN

Vector Saturating Move and Narrow.

### Syntax

VQMOVN{cond}.datatype Dd, Qm

VQMOVUN{cond}.datatype Dd, Qm

where:

cond

is an optional condition code.

### datatype

must be one of:

```
S16, S32, S64
```

for VQMOVN or VQMOVUN.

U16, U32, U64

for VQMOVN.

Dd, Qm

specifies the destination vector and the operand vector.

### Operation

VQMOVN copies each element of the operand vector to the corresponding element of the destination vector. The result element is half the width of the operand element, and values are saturated to the result width. The results are the same type as the operands.

VQMOVUN copies each element of the operand vector to the corresponding element of the destination vector. The result element is half the width of the operand element, and values are saturated to the result width. The elements in the operand are signed and the elements in the result are unsigned.

### **Related references**

# C3.100 VQNEG

Vector Saturating Negate.

## Syntax

VQNEG{cond}.datatype Qd, Qm

VQNEG{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, or \$32.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

## Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

# Operation

VQNEG negates each element in a vector, and places the results in a second vector.

The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

# **Related references**

# C3.101 VQRDMULH (by vector or by scalar)

Vector Saturating Rounding Doubling Multiply Returning High Half.

### Syntax

```
VQRDMULH{cond}.datatype {Qd}, Qn, Qm
VQRDMULH{cond}.datatype {Dd}, Dn, Dm
VQRDMULH{cond}.datatype {Qd}, Qn, Dm[x]
VQRDMULH{cond}.datatype {Dd}, Dn, Dm[x]
where:
```

cond

is an optional condition code.

#### datatype

must be either S16 or S32.

#### Qd, Qn

are the destination vector and the first operand vector, for a quadword operation.

Dd, Dn

are the destination vector and the first operand vector, for a doubleword operation.

#### Qm or Dm

is the vector holding the second operand, for a by vector operation.

Dm[x]

is the scalar holding the second operand, for a by scalar operation.

### Operation

VQRDMULH multiplies corresponding elements in two vectors, doubles the results, and places the most significant half of the final results in the destination vector.

The second operand can be a scalar instead of a vector.

If any of the results overflow, they are saturated. The sticky QC flag (FPSCR bit[27]) is set if saturation occurs. Each result is rounded.

### **Related references**

# C3.102 VQRSHL (by signed variable)

Vector Saturating Rounding Shift Left by signed variable.

### Syntax

VQRSHL{cond}.datatype {Qd}, Qm, Qn

VQRSHL{cond}.datatype {Dd}, Dm, Dn

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, \$64, U8, U16, U32, or U64.

Qd, Qm, Qn

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dm, Dn

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

## Operation

VQRSHL takes each element in a vector, shifts them by a value from the least significant byte of the corresponding element of a second vector, and places the results in the destination vector. If the shift value is positive, the operation is a left shift. Otherwise, it is a rounding right shift.

The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

### **Related references**

# C3.103 VQRSHRN and VQRSHRUN (by immediate)

Vector Saturating Shift Right, Narrow, by immediate value, with Rounding.

### Syntax

VQRSHR{U}N{cond}.datatype Dd, Qm, #imm

where:

U

if present, indicates that the results are unsigned, although the operands are signed. Otherwise, the results are the same type as the operands.

#### cond

is an optional condition code.

#### datatype

must be one of:

#### I16, I32, I64

for VQRSHRN or VQRSHRUN. Only a #0 immediate is permitted with these datatypes.

S16, S32, S64

for VQRSHRN or VQRSHRUN.

U16, U32, U64

for VQRSHRN only.

#### Dd, Qm

are the destination vector and the operand vector.

#### imm

is the immediate value specifying the size of the shift. The ranges are shown in the following table:

### Table C3-10 Available immediate ranges in VQRSHRN and VQRSHRUN (by immediate)

datatype	imm range	
S16 or U16	0 to 8	
S32 or U32	0 to 16	
S64 or U64	0 to 32	

### Operation

VQRSHR{U}N takes each element in a quadword vector of integers, right shifts them by an immediate value, and places the results in a doubleword vector.

The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

Results are rounded.

### **Related references**

# C3.104 VQSHL (by signed variable)

Vector Saturating Shift Left by signed variable.

### Syntax

VQSHL{cond}.datatype {Qd}, Qm, Qn

VQSHL{cond}.datatype {Dd}, Dm, Dn

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, \$64, U8, U16, U32, or U64.

Qd, Qm, Qn

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dm, Dn

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

## Operation

VQSHL takes each element in a vector, shifts them by a value from the least significant byte of the corresponding element of a second vector, and places the results in the destination vector. If the shift value is positive, the operation is a left shift. Otherwise, it is a truncating right shift.

The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

### **Related references**

## C3.105 VQSHL and VQSHLU (by immediate)

Vector Saturating Shift Left.

### Syntax

```
VQSHL{U}{cond}.datatype {Qd}, Qm, #imm
VQSHL{U}{cond}.datatype {Dd}, Dm, #imm
```

where:

### U

only permitted if Q is also present. Indicates that the results are unsigned even though the operands are signed.

#### cond

is an optional condition code.

#### datatype

must be one of :

### S8, S16, S32, S64

for VQSHL or VQSHLU.

### U8, U16, U32, U64

for VQSHL only.

#### Qd, Qm

are the destination and operand vectors, for a quadword operation.

### Dd, Dm

are the destination and operand vectors, for a doubleword operation.

#### imm

is the immediate value specifying the size of the shift, in the range 0 to (size(datatype) - 1). The ranges are shown in the following table:

### Table C3-11 Available immediate ranges in VQSHL and VQSHLU (by immediate)

datatype	imm range
S8 or U8	0 to 7
S16 or U16	0 to 15
S32 or U32	0 to 31
S64 or U64	0 to 63

### Operation

VQSHL and VQSHLU instructions take each element in a vector of integers, left shift them by an immediate value, and place the results in the destination vector.

The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

# **Related references**

## C3.106 VQSHRN and VQSHRUN (by immediate)

Vector Saturating Shift Right, Narrow, by immediate value.

### Syntax

VQSHR{U}N{cond}.datatype Dd, Qm, #imm

where:

U

if present, indicates that the results are unsigned, although the operands are signed. Otherwise, the results are the same type as the operands.

#### cond

is an optional condition code.

#### datatype

must be one of:

#### I16, I32, I64

for VQSHRN or VQSHRUN. Only a #0 immediate is permitted with these datatypes.

S16, S32, S64

for VQSHRN or VQSHRUN.

U16, U32, U64

for VQSHRN only.

#### Dd, Qm

are the destination vector and the operand vector.

#### imm

is the immediate value specifying the size of the shift. The ranges are shown in the following table:

### Table C3-12 Available immediate ranges in VQSHRN and VQSHRUN (by immediate)

datatype	imm range	
S16 or U16	0 to 8	
S32 or U32	0 to 16	
S64 or U64	0 to 32	

#### Operation

VQSHR{U}N takes each element in a quadword vector of integers, right shifts them by an immediate value, and places the results in a doubleword vector.

The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

Results are truncated.

### **Related references**

# C3.107 VQSUB

Vector Saturating Subtract.

### Syntax

VQSUB{cond}.datatype {Qd}, Qn, Qm

VQSUB{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, \$64, U8, U16, U32, or U64.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

## Operation

VQSUB subtracts the elements of one vector from the corresponding elements of another vector, and places the results in the destination vector.

The sticky QC flag (FPSCR bit[27]) is set if saturation occurs.

### **Related references**

## C3.108 VRADDHN

Vector Rounding Add and Narrow, selecting High half.

### Syntax

VRADDHN{cond}.datatype Dd, Qn, Qm

where:

cond

is an optional condition code.

datatype

must be one of 116, 132, or 164.

Dd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector.

## Operation

VRADDHN adds corresponding elements in two quadword vectors, selects the most significant halves of the results, and places the final results in the destination doubleword vector. Results are rounded.

### **Related references**

## C3.109 VRECPE

Vector Reciprocal Estimate.

### Syntax

VRECPE{cond}.datatype Qd, Qm

VRECPE{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

### datatype

must be either U32 or F32.

### Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

#### Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

### Operation

VRECPE finds an approximate reciprocal of each element in a vector, and places the results in a second vector.

### Results for out-of-range inputs

The following table shows the results where input values are out of range:

Table C3-13	Results fo	r out-of-range	inputs i	in VRECPE
-------------	------------	----------------	----------	-----------

	Operand element	Result element
Integer	<= 0x7FFFFFF	ØxFFFFFFF
Floating-point	NaN	Default NaN
	Negative 0, Negative Denormal	Negative Infinity ao
	Positive 0, Positive Denormal	Positive Infinity <sup>ao</sup>
	Positive infinity	Positive 0
	Negative infinity	Negative 0

### **Related references**

ao The Division by Zero exception bit in the FPSCR (FPSCR[1]) is set
# C3.110 VRECPS

Vector Reciprocal Step.

## Syntax

VRECPS{cond}.F32 {Qd}, Qn, Qm

VRECPS{cond}.F32 {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

## Operation

VRECPS multiplies the elements of one vector by the corresponding elements of another vector, subtracts each of the results from 2, and places the final results into the elements of the destination vector.

The Newton-Raphson iteration:

 $x_{n+1} = x_n (2 - dx_n)$ 

converges to (1/d) if  $x_0$  is the result of VRECPE applied to d.

## Results for out-of-range inputs

The following table shows the results where input values are out of range:

1st operand element	2nd operand element	Result element
NaN	-	Default NaN
-	NaN	Default NaN
$\pm 0.0$ or denormal	± infinity	2.0
± infinity	$\pm 0.0$ or denormal	2.0

Table C3-14 Results for out-of-range inputs in VRECPS

## **Related references**

# C3.111 VREV16, VREV32, and VREV64

Vector Reverse within halfwords, words, or doublewords.

## Syntax

```
VREVn{cond}.size Qd, Qm
VREVn{cond}.size Dd, Dm
```

where:

n

must be one of 16, 32, or 64.

cond

is an optional condition code.

size

must be one of 8, 16, or 32, and must be less than n.

Qd, Qm

specifies the destination vector and the operand vector, for a quadword operation.

Dd, Dm

specifies the destination vector and the operand vector, for a doubleword operation.

## Operation

VREV16 reverses the order of 8-bit elements within each halfword of the vector, and places the result in the corresponding destination vector.

VREV32 reverses the order of 8-bit or 16-bit elements within each word of the vector, and places the result in the corresponding destination vector.

VREV64 reverses the order of 8-bit, 16-bit, or 32-bit elements within each doubleword of the vector, and places the result in the corresponding destination vector.

### **Related references**

# C3.112 VRHADD

Vector Rounding Halving Add.

## Syntax

VRHADD{cond}.datatype {Qd}, Qn, Qm

VRHADD{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## datatype

must be one of \$8, \$16, \$32, U8, U16, or U32.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

# Operation

VRHADD adds corresponding elements in two vectors, shifts each result right one bit, and places the results in the destination vector. Results are rounded.

# **Related references**

# C3.113 VRSHL (by signed variable)

Vector Rounding Shift Left by signed variable.

## Syntax

```
VRSHL{cond}.datatype {Qd}, Qm, Qn
```

VRSHL{cond}.datatype {Dd}, Dm, Dn

where:

cond

is an optional condition code.

## datatype

must be one of \$8, \$16, \$32, \$64, U8, U16, U32, or U64.

Qd, Qm, Qn

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dm, Dn

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

## Operation

VRSHL takes each element in a vector, shifts them by a value from the least significant byte of the corresponding element of a second vector, and places the results in the destination vector. If the shift value is positive, the operation is a left shift. Otherwise, it is a rounding right shift.

## **Related references**

# C3.114 VRSHR (by immediate)

Vector Rounding Shift Right by immediate value.

## Syntax

```
VRSHR{cond}.datatype {Qd}, Qm, #imm
```

```
VRSHR{cond}.datatype {Dd}, Dm, #imm
```

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, \$64, U8, U16, U32, or U64.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

## Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

imm

is the immediate value specifying the size of the shift, in the range 0 to (size(*datatype*)). The ranges are shown in the following table:

## Table C3-15 Available immediate ranges in VRSHR (by immediate)

datatype	imm range
S8 or U8	0 to 8
S16 or U16	0 to 16
S32 or U32	0 to 32
S64 or U64	0 to 64

VRSHR with an immediate value of zero is a pseudo-instruction for VORR.

## Operation

VRSHR takes each element in a vector, right shifts them by an immediate value, and places the results in the destination vector. The results are rounded.

## **Related references**

*C3.86 VORR (register)* on page C3-481 *C1.9 Condition code suffixes* on page C1-92

# C3.115 VRSHRN (by immediate)

Vector Rounding Shift Right, Narrow, by immediate value.

## Syntax

VRSHRN{cond}.datatype Dd, Qm, #imm

where:

cond

is an optional condition code.

datatype

must be one of 116, 132, or 164.

### Dd, Qm

are the destination vector and the operand vector.

#### imm

is the immediate value specifying the size of the shift, in the range 0 to (size(*datatype*)/2). The ranges are shown in the following table:

## Table C3-16 Available immediate ranges in VRSHRN (by immediate)

datatype	imm range
I16	0 to 8
I32	0 to 16
164	0 to 32

VRSHRN with an immediate value of zero is a pseudo-instruction for VMOVN.

## Operation

VRSHRN takes each element in a quadword vector, right shifts them by an immediate value, and places the results in a doubleword vector. The results are rounded.

## **Related references**

*C3.73 VMOVN* on page C3-468 *C1.9 Condition code suffixes* on page C1-92

# C3.116 VRINT

VRINT (Vector Round to Integer) rounds each floating-point element in a vector to integer, and places the results in the destination vector.

The resulting integers are represented in floating-point format.

------ Note -

This instruction is supported only in Armv8.

### Syntax

VRINTmode.F32.F32 Qd, Qm

VRINTmode.F32.F32 Dd, Dm

where:

## mode

must be one of:

Α

meaning round to nearest, ties away from zero. This cannot generate an Inexact exception, even if the result is not exact.

Ν

meaning round to nearest, ties to even. This cannot generate an Inexact exception, even if the result is not exact.

Х

Ρ

м

meaning round to nearest, ties to even, generating an Inexact exception if the result is not exact.

meaning round towards plus infinity. This cannot generate an Inexact exception, even if the result is not exact.

meaning round towards minus infinity. This cannot generate an Inexact exception, even if the result is not exact.

Z

meaning round towards zero. This cannot generate an Inexact exception, even if the result is not exact.

### Qd, Qm

specifies the destination vector and the operand vector, for a quadword operation.

Dd, Dm

specifies the destination and operand vectors, for a doubleword operation.

### Notes

You cannot use VRINT inside an IT block.

# C3.117 VRSQRTE

Vector Reciprocal Square Root Estimate.

## Syntax

VRSQRTE{cond}.datatype Qd, Qm

VRSQRTE{cond}.datatype Dd, Dm

where:

cond

is an optional condition code.

### datatype

must be either U32 or F32.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

### Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

## Operation

VRSQRTE finds an approximate reciprocal square root of each element in a vector, and places the results in a second vector.

## **Results for out-of-range inputs**

The following table shows the results where input values are out of range:

	Operand element	Result element
Integer	<= 0x3FFFFFF	ØxFFFFFFF
Floating-point	NaN, Negative Normal, Negative Infinity	Default NaN
	Negative 0, Negative Denormal	Negative Infinity ap
	Positive 0, Positive Denormal	Positive Infinity ap
	Positive infinity	Positive 0
		Negative 0

## Table C3-17 Results for out-of-range inputs in VRSQRTE

## **Related references**

ap The Division by Zero exception bit in the FPSCR (FPSCR[1]) is set

# C3.118 VRSQRTS

Vector Reciprocal Square Root Step.

## Syntax

VRSQRTS{cond}.F32 {Qd}, Qn, Qm

VRSQRTS{cond}.F32 {Dd}, Dn, Dm

where:

cond

is an optional condition code.

## Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

## Operation

VRSQRTS multiplies the elements of one vector by the corresponding elements of another vector, subtracts each of the results from three, divides these results by two, and places the final results into the elements of the destination vector.

The Newton-Raphson iteration:

 $x_{n+1} = x_n (3 - dx_n^2)/2$ 

converges to  $(1/\sqrt{d})$  if  $x_0$  is the result of VRSQRTE applied to d.

## **Results for out-of-range inputs**

The following table shows the results where input values are out of range:

1st operand element	2nd operand element	Result element
NaN	-	Default NaN
-	NaN	Default NaN
$\pm 0.0$ or denormal	± infinity	1.5
± infinity	$\pm 0.0$ or denormal	1.5

Table C3-18 Results for out-of-range inputs in VRSQRTS

## **Related references**

# C3.119 VRSRA (by immediate)

Vector Rounding Shift Right by immediate value and Accumulate.

## Syntax

```
VRSRA{cond}.datatype {Qd}, Qm, #imm
```

```
VRSRA{cond}.datatype {Dd}, Dm, #imm
```

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, \$64, U8, U16, U32, or U64.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

## Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

imm

is the immediate value specifying the size of the shift, in the range 1 to (size(*datatype*)). The ranges are shown in the following table:

## Table C3-19 Available immediate ranges in VRSRA (by immediate)

datatype	imm range
S8 or U8	1 to 8
S16 or U16	1 to 16
S32 or U32	1 to 32
S64 or U64	1 to 64

# Operation

VRSRA takes each element in a vector, right shifts them by an immediate value, and accumulates the results into the destination vector. The results are rounded.

## **Related references**

# C3.120 VRSUBHN

Vector Rounding Subtract and Narrow, selecting High half.

## Syntax

VRSUBHN{cond}.datatype Dd, Qn, Qm

where:

cond

is an optional condition code.

datatype

must be one of 116, 132, or 164.

Dd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector.

## Operation

VRSUBHN subtracts the elements of one quadword vector from the corresponding elements of another quadword vector, selects the most significant halves of the results, and places the final results in the destination doubleword vector. Results are rounded.

## **Related references**

# C3.121 VSDOT (vector)

Dot Product vector form with signed integers.

## Syntax

```
VSDOT{g}.S8 Dd, Dn, Dm ; 64-bit SIMD vector
VSDOT{q}.S8 Qd, Qn, Qm; A1 128-bit SIMD vector FP/SIMD registers (A32)
Where:
q
        Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.
Dd
        Is the 64-bit name of the SIMD and FP destination register.
Dn
        Is the 64-bit name of the first SIMD and FP source register.
Dm
        Is the 64-bit name of the second SIMD and FP source register.
0d
        Is the 128-bit name of the SIMD and FP destination register.
On
        Is the 128-bit name of the first SIMD and FP source register.
Om
        Is the 128-bit name of the second SIMD and FP source register.
```

## Architectures supported

Supported in Armv8.2 and later.

For Armv8.2 and Armv8.3, this is an OPTIONAL instruction.

## Usage

Dot Product vector form with signed integers. This instruction performs the dot product of the four 8-bit elements in each 32-bit element of the first source register with the four 8-bit elements of the corresponding 32-bit element in the second source register, accumulating the result into the corresponding 32-bit element of the destination register.

\_\_\_\_\_ Note \_\_\_\_\_

ID\_ISAR6.DP indicates whether this instruction is supported in the T32 and A32 instruction sets.

## **Related references**

C3.1 Summary of Advanced SIMD instructions on page C3-391

# C3.122 VSDOT (by element)

Dot Product index form with signed integers.

## Syntax

VSDOT{۵	].S8 Dd, Dn, Dm[index] ; 64-bit SIMD vector		
VSDOT{a	g}.S8 Qd, Qn, Dm[index] ; A1 128-bit SIMD vector FP/SIMD registers (A32)		
Where:			
9	Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111		
Dd Dn	Is the 64-bit name of the SIMD and FP destination register.		
Dm	Is the 64-bit name of the first SIMD and FP source register.		
index	Is the 64-bit name of the second SIMD and FP source register.		
Qd	Is the 128-bit name of the SIMD and FP destination register.		
Qn	Is the 128-bit name of the first SIMD and FP source register.		

## Architectures supported

Supported in Armv8.2 and later.

For Armv8.2 and Armv8.3, this is an OPTIONAL instruction.

# Usage

Dot Product index form with signed integers. This instruction performs the dot product of the four 8-bit elements in each 32-bit element of the first source register with the four 8-bit elements of an indexed 32-bit element in the second source register, accumulating the result into the corresponding 32-bit element of the destination register.

\_\_\_\_\_ Note \_\_\_\_\_

ID\_ISAR6.DP indicates whether this instruction is supported in the T32 and A32 instruction sets.

**Related references** 

C3.1 Summary of Advanced SIMD instructions on page C3-391

# C3.123 VSHL (by immediate)

Vector Shift Left by immediate.

## Syntax

```
VSHL{cond}.datatype {Qd}, Qm, #imm
```

```
VSHL{cond}.datatype {Dd}, Dm, #imm
```

where:

cond

is an optional condition code.

### datatype

must be one of 18, 116, 132, or 164.

## Qd, Qm

are the destination and operand vectors, for a quadword operation.

### Dd, Dm

are the destination and operand vectors, for a doubleword operation.

imm

is the immediate value specifying the size of the shift. The ranges are shown in the following table:

## Table C3-20 Available immediate ranges in VSHL (by immediate)

datatype	imm range
18	0 to 7
I16	0 to 15
I32	0 to 31
164	0 to 63

# Operation

VSHL takes each element in a vector of integers, left shifts them by an immediate value, and places the results in the destination vector.

Bits shifted out of the left of each element are lost.

The following figure shows the operation of VSHL with two elements and a shift value of one. The least significant bit in each element in the destination vector is set to zero.



Figure C3-6 Operation of quadword VSHL.I64 Qd, Qm, #1

**Related references** C1.9 Condition code suffixes on page C1-92

# C3.124 VSHL (by signed variable)

Vector Shift Left by signed variable.

## Syntax

```
VSHL{cond}.datatype {Qd}, Qm, Qn
```

VSHL{cond}.datatype {Dd}, Dm, Dn

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, \$64, U8, U16, U32, or U64.

Qd, Qm, Qn

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

Dd, Dm, Dn

are the destination vector, the first operand vector, and the second operand vector, for a doubleword operation.

## Operation

VSHL takes each element in a vector, shifts them by the value from the least significant byte of the corresponding element of a second vector, and places the results in the destination vector. If the shift value is positive, the operation is a left shift. Otherwise, it is a truncating right shift.

## **Related references**

# C3.125 VSHLL (by immediate)

Vector Shift Left Long.

### Syntax

VSHLL{cond}.datatype Qd, Dm, #imm

where:

cond

is an optional condition code.

datatype

must be one of \$8, \$16, \$32, U8, U16, or U32.

### Qd, Dm

are the destination and operand vectors, for a long operation.

#### imm

is the immediate value specifying the size of the shift. The ranges are shown in the following table:

## Table C3-21 Available immediate ranges in VSHLL (by immediate)

datatype	imm range
S8 or U8	1 to 8
S16 or U16	1 to 16
S32 or U32	1 to 32

0 is permitted, but the resulting code disassembles to VMOVL.

## Operation

VSHLL takes each element in a vector of integers, left shifts them by an immediate value, and places the results in the destination vector. Values are sign or zero extended.

### **Related references**

## C3.126 VSHR (by immediate)

Vector Shift Right by immediate value.

## Syntax

```
VSHR{cond}.datatype {Qd}, Qm, #imm
```

```
VSHR{cond}.datatype {Dd}, Dm, #imm
```

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, \$64, U8, U16, U32, or U64.

### Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

### Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

imm

is the immediate value specifying the size of the shift. The ranges are shown in the following table:

## Table C3-22 Available immediate ranges in VSHR (by immediate)

datatype	imm range
S8 or U8	0 to 8
S16 or U16	0 to 16
S32 or U32	0 to 32
S64 or U64	0 to 64

VSHR with an immediate value of zero is a pseudo-instruction for VORR.

## Operation

VSHR takes each element in a vector, right shifts them by an immediate value, and places the results in the destination vector. The results are truncated.

## **Related references**

*C3.86 VORR (register)* on page C3-481 *C1.9 Condition code suffixes* on page C1-92

# C3.127 VSHRN (by immediate)

Vector Shift Right, Narrow, by immediate value.

## Syntax

VSHRN{cond}.datatype Dd, Qm, #imm

where:

cond

is an optional condition code.

datatype

must be one of 116, 132, or 164.

### Dd, Qm

are the destination vector and the operand vector.

#### imm

is the immediate value specifying the size of the shift. The ranges are shown in the following table:

## Table C3-23 Available immediate ranges in VSHRN (by immediate)

datatype	imm range
I16	0 to 8
132	0 to 16
164	0 to 32

VSHRN with an immediate value of zero is a pseudo-instruction for VMOVN.

## Operation

VSHRN takes each element in a quadword vector, right shifts them by an immediate value, and places the results in a doubleword vector. The results are truncated.

## **Related references**

*C3.73 VMOVN* on page C3-468 *C1.9 Condition code suffixes* on page C1-92

# C3.128 VSLI

Vector Shift Left and Insert.

## Syntax

VSLI{cond}.size {Qd}, Qm, #imm
VSLI{cond}.size {Dd}, Dm, #imm
where:

cond

is an optional condition code.

size

must be one of 8, 16, 32, or 64.

#### Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

#### Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

imm

is the immediate value specifying the size of the shift, in the range 0 to (size - 1).

## Operation

VSLI takes each element in a vector, left shifts them by an immediate value, and inserts the results in the destination vector. Bits shifted out of the left of each element are lost. The following figure shows the operation of VSLI with two elements and a shift value of one. The least significant bit in each element in the destination vector is unchanged.



Figure C3-7 Operation of quadword VSLI.64 Qd, Qm, #1

## *Related references C1.9 Condition code suffixes* on page C1-92

# C3.129 VSRA (by immediate)

Vector Shift Right by immediate value and Accumulate.

## Syntax

```
VSRA{cond}.datatype {Qd}, Qm, #imm
```

```
VSRA{cond}.datatype {Dd}, Dm, #imm
```

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, \$64, U8, U16, U32, or U64.

## Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

## Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

imm

is the immediate value specifying the size of the shift. The ranges are shown in the following table:

## Table C3-24 Available immediate ranges in VSRA (by immediate)

datatype	imm range
S8 or U8	1 to 8
S16 or U16	1 to 16
S32 or U32	1 to 32
S64 or U64	1 to 64

# Operation

VSRA takes each element in a vector, right shifts them by an immediate value, and accumulates the results into the destination vector. The results are truncated.

## **Related references**

# C3.130 VSRI

Vector Shift Right and Insert.

## Syntax

VSRI{cond}.size {Qd}, Qm, #imm
VSRI{cond}.size {Dd}, Dm, #imm
where:

cond

is an optional condition code.

size

must be one of 8, 16, 32, or 64.

### Qd, Qm

are the destination vector and the operand vector, for a quadword operation.

### Dd, Dm

are the destination vector and the operand vector, for a doubleword operation.

imm

is the immediate value specifying the size of the shift, in the range 1 to size.

## Operation

VSRI takes each element in a vector, right shifts them by an immediate value, and inserts the results in the destination vector. Bits shifted out of the right of each element are lost. The following figure shows the operation of VSRI with a single element and a shift value of two. The two most significant bits in the destination vector are unchanged.





# *Related references C1.9 Condition code suffixes* on page C1-92

# C3.131 VSTM

Extension register store multiple.

### Syntax

VSTMmode{cond} Rn{!}, Registers

where:

mode

must be one of:

IA

meaning Increment address After each transfer. IA is the default, and can be omitted.

DB

meaning Decrement address Before each transfer.

EA

meaning Empty Ascending stack operation. This is the same as IA for stores.

meaning Full Descending stack operation. This is the same as DB for stores.

FD

cond

is an optional condition code.

Rn

is the general-purpose register holding the base address for the transfer.

!

is optional. ! specifies that the updated base address must be written back to Rn. If ! is not specified, mode must be IA.

Registers

is a list of consecutive extension registers enclosed in braces, { and }. The list can be commaseparated, or in range format. There must be at least one register in the list.

You can specify D or Q registers, but they must not be mixed. The number of registers must not exceed 16 D registers, or 8 Q registers. If Q registers are specified, on disassembly they are shown as D registers.

— Note –

VPUSH Registers is equivalent to VSTMDB sp!, Registers.

You can use either form of this instruction. They both disassemble to VPUSH.

## **Related references**

*C1.9 Condition code suffixes* on page C1-92 *C4.38 VSTM (floating-point)* on page C4-585

# C3.132 VSTn (multiple n-element structures)

Vector Store multiple *n*-element structures.

## Syntax

```
VSTn{cond}.datatype list, [Rn{@align}]{!}
VSTn{cond}.datatype list, [Rn{@align}], Rm
```

where:

n

must be one of 1, 2, 3, or 4.

cond

is an optional condition code.

#### datatype

see the following table for options.

#### list

is the list of Advanced SIMD registers enclosed in braces, { and }. See the following table for options.

#### Rn

is the general-purpose register containing the base address. Rn cannot be PC.

### align

specifies an optional alignment. See the following table for options.

```
!
```

if ! is present, Rn is updated to (Rn + the number of bytes transferred by the instruction). The update occurs after all the stores have taken place.

#### Rm

is a general-purpose register containing an offset from the base address. If Rm is present, the instruction updates Rn to (Rn + Rm) after using the address to access memory. Rm cannot be SP or PC.

### Operation

VST*n* stores multiple *n*-element structures to memory from one or more Advanced SIMD registers, with interleaving (unless n == 1). Every element of each register is stored.

Table C3-25	Permitted	combinations o	f parameters f	or VSTn	(multiple	n-element	structures)
-------------	-----------	----------------	----------------	---------	-----------	-----------	-------------

n	datatype	list <sup>aq</sup>	align <sup>ar</sup>	alignment
1	8, 16, 32, or 64	{Dd}	@64	8-byte
		{Dd, D(d+1)}	<b>@64</b> or <b>@128</b>	8-byte or 16-byte
		{Dd, D(d+1), D(d+2)}	@64	8-byte
		{Dd, D(d+1), D(d+2), D(d+3)}	@64, @128, or @256	8-byte, 16-byte, or 32-byte

aq Every register in the list must be in the range D0-D31.

ar align can be omitted. In this case, standard alignment rules apply.

n	datatype	list <sup>aq</sup>	align <sup>ar</sup>	alignment
2	8, 16, or 32	{Dd, D(d+1)}	@64, @128	8-byte or 16-byte
		{Dd, D(d+2)}	@64, @128	8-byte or 16-byte
		{Dd, D(d+1), D(d+2), D(d+3)}	@64, @128, or @256	8-byte, 16-byte, or 32-byte
3	8, 16, or 32	{Dd, D(d+1), D(d+2)}	@64	8-byte
		{Dd, D(d+2), D(d+4)}	@64	8-byte
4	8, 16, or 32	{Dd, D(d+1), D(d+2), D(d+3)}	@64, @128, or @256	8-byte, 16-byte, or 32-byte
		{Dd, D(d+2), D(d+4), D(d+6)}	@64, @128, or @256	8-byte, 16-byte, or 32-byte

## Table C3-25 Permitted combinations of parameters for VSTn (multiple n-element structures) (continued)

## **Related concepts**

*C3.3 Interleaving provided by load and store element and structure instructions* on page C3-395 *C3.4 Alignment restrictions in load and store element and structure instructions* on page C3-396 *Related references* 

# C3.133 VSTn (single n-element structure to one lane)

Vector Store single *n*-element structure to one lane.

## Syntax

```
VSTn{cond}.datatype List, [Rn{@align}]{!}
VSTn{cond}.datatype list, [Rn{@align}], Rm
```

where:

n

must be one of 1, 2, 3, or 4.

cond

is an optional condition code.

#### datatype

see the following table.

#### list

is the list of Advanced SIMD registers enclosed in braces, { and }. See the following table for options.

#### Rn

is the general-purpose register containing the base address. Rn cannot be PC.

### align

specifies an optional alignment. See the following table for options.

```
!
```

if ! is present, Rn is updated to (Rn + the number of bytes transferred by the instruction). The update occurs after all the stores have taken place.

#### Rm

is a general-purpose register containing an offset from the base address. If Rm is present, the instruction updates Rn to (Rn + Rm) after using the address to access memory. Rm cannot be SP or PC.

## Operation

VSTn stores one n-element structure into memory from one or more Advanced SIMD registers.

Table	C3-26	Permitted	combinations	of r	parameters	for VSTn	(sinc	ı əlc	n-element	structure	to o	ne l	ane
IUDIO	00 20	1 0111111100	oomonationo	~ r	paramotoro		101115	<u>, , , , , , , , , , , , , , , , , , , </u>		onaotaio			4110

n	datatype	list <sup>as</sup>	aLign <sup>at</sup>	alignment
1	8	{Dd[x]}	-	Standard only
	16	{Dd[x]}	@16	2-byte
	32	{Dd[x]}	@32	4-byte
2	8	{Dd[x], D(d+1)[x]}	@16	2-byte
	16	{Dd[x], D(d+1)[x]}	@32	4-byte

as Every register in the list must be in the range D0-D31.

at align can be omitted. In this case, standard alignment rules apply.

n	datatype	list <sup>as</sup>	aLign <sup>at</sup>	alignment
		{Dd[x], D(d+2)[x]}	@32	4-byte
	32	{Dd[x], D(d+1)[x]}	@64	8-byte
		{Dd[x], D(d+2)[x]}	@64	8-byte
3	8	{Dd[x], D(d+1)[x], D(d+2)[x]}	-	Standard only
	16 or 32	{Dd[x], D(d+1)[x], D(d+2)[x]}	-	Standard only
		{Dd[x], D(d+2)[x], D(d+4)[x]}	-	Standard only
4	8	{Dd[x], D(d+1)[x], D(d+2)[x], D(d+3)[x]}	@32	4-byte
	16	{Dd[x], D(d+1)[x], D(d+2)[x], D(d+3)[x]}	@64	8-byte
		{Dd[x], D(d+2)[x], D(d+4)[x], D(d+6)[x]}	@64	8-byte
	32	{Dd[x], D(d+1)[x], D(d+2)[x], D(d+3)[x]}	@64 or @128	8-byte or 16-byte
		{Dd[x], D(d+2)[x], D(d+4)[x], D(d+6)[x]}	@64 or @128	8-byte or 16-byte

## Table C3-26 Permitted combinations of parameters for VSTn (single n-element structure to one lane) (continued)

## **Related concepts**

*C3.3 Interleaving provided by load and store element and structure instructions* on page C3-395 *C3.4 Alignment restrictions in load and store element and structure instructions* on page C3-396 *Related references* 

# C3.134 VSTR

Extension register store.

## Syntax

```
VSTR{cond}{.64} Dd, [Rn{, #offset}]
```

where:

cond

is an optional condition code.

Dd

is the extension register to be saved.

Rn

is the general-purpose register holding the base address for the transfer.

## offset

is an optional numeric expression. It must evaluate to a numeric value at assembly time. The value must be a multiple of 4, and lie in the range -1020 to +1020. The value is added to the base address to form the address used for the transfer.

# Operation

The VSTR instruction saves the contents of an extension register to memory.

Two words are transferred.

# **Related references**

*C1.9 Condition code suffixes* on page C1-92 *C4.39 VSTR (floating-point)* on page C4-586

# C3.135 VSTR (post-increment and pre-decrement)

Pseudo-instruction that stores extension registers with post-increment and pre-decrement forms.

\_\_\_\_\_ Note \_\_\_\_\_

There are also VLDR and VSTR instructions without post-increment and pre-decrement.

### Syntax

VSTR{cond}{.64} Dd, [Rn], #offset ; post-increment
VSTR{cond}{.64} Dd, [Rn, #-offset]! ; pre-decrement
where:

cond

is an optional condition code.

#### Dd

is the extension register to be saved.

#### Rn

is the general-purpose register holding the base address for the transfer.

offset

is a numeric expression that must evaluate to 8 at assembly time.

## Operation

The post-increment instruction increments the base address in the register by the offset value, after the transfer. The pre-decrement instruction decrements the base address in the register by the offset value, and then performs the transfer using the new address in the register. This pseudo-instruction assembles to a VSTM instruction.

## **Related references**

C3.134 VSTR on page C3-531 C3.131 VSTM on page C3-526 C1.9 Condition code suffixes on page C1-92 C4.40 VSTR (post-increment and pre-decrement, floating-point) on page C4-587

# C3.136 VSUB

Vector Subtract.

## Syntax

VSUB{cond}.datatype {Qd}, Qn, Qm

VSUB{cond}.datatype {Dd}, Dn, Dm

where:

cond

is an optional condition code.

### datatype

must be one of 18, 116, 132, 164, or F32.

Qd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector, for a quadword operation.

## Operation

VSUB subtracts the elements of one vector from the corresponding elements of another vector, and places the results in the destination vector.

## **Related references**

# C3.137 VSUBHN

Vector Subtract and Narrow, selecting High half.

## Syntax

VSUBHN{cond}.datatype Dd, Qn, Qm

where:

cond

is an optional condition code.

datatype

must be one of 116, 132, or 164.

Dd, Qn, Qm

are the destination vector, the first operand vector, and the second operand vector.

## Operation

VSUBHN subtracts the elements of one quadword vector from the corresponding elements of another quadword vector, selects the most significant halves of the results, and places the final results in the destination doubleword vector. Results are truncated.

## **Related references**

# C3.138 VSUBL and VSUBW

Vector Subtract Long, Vector Subtract Wide.

## Syntax

VSUBL{cond}.datatype Qd, Dn, Dm ; Long operation

VSUBW{cond}.datatype {Qd}, Qn, Dm ; Wide operation

where:

cond

is an optional condition code.

### datatype

must be one of \$8, \$16, \$32, U8, U16, or U32.

Qd, Dn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a long operation.

Qd, Qn, Dm

are the destination vector, the first operand vector, and the second operand vector, for a wide operation.

## Operation

VSUBL subtracts the elements of one doubleword vector from the corresponding elements of another doubleword vector, and places the results in the destination quadword vector.

VSUBW subtracts the elements of a doubleword vector from the corresponding elements of a quadword vector, and places the results in the destination quadword vector.

## **Related references**

# C3.139 VSWP

Vector Swap.

## Syntax

VSWP{cond}{.datatype} Qd, Qm

VSWP{cond}{.datatype} Dd, Dm

where:

cond

is an optional condition code.

## datatype

is an optional datatype. The assembler ignores datatype.

## Qd, Qm

specifies the vectors for a quadword operation.

## Dd, Dm

specifies the vectors for a doubleword operation.

## Operation

VSWP exchanges the contents of two vectors. The vectors can be either doubleword or quadword. There is no distinction between data types.

## **Related references**

# C3.140 VTBL and VTBX

Vector Table Lookup, Vector Table Extension.

## Syntax

Vop{cond}.8 Dd, List, Dm

where:

ор

must be either TBL or TBX.

cond

is an optional condition code.

Dd

specifies the destination vector.

### list

Specifies the vectors containing the table. It must be one of:

- {Dn}.
- {Dn,D(n+1)}.
- {Dn,D(n+1),D(n+2)}.
- {Dn,D(n+1),D(n+2),D(n+3)}.
- {Qn,Q(n+1)}.

All the registers in *List* must be in the range D0-D31 or Q0-Q15 and must not wrap around the end of the register bank. For example {D31,D0,D1} is not permitted. If *List* contains Q registers, they disassemble to the equivalent D registers.

Dm

specifies the index vector.

### Operation

VTBL uses byte indexes in a control vector to look up byte values in a table and generate a new vector. Indexes out of range return zero.

VTBX works in the same way, except that indexes out of range leave the destination element unchanged.

### **Related references**

# C3.141 VTRN

Vector Transpose.

### Syntax

VTRN{cond}.size Qd, Qm

VTRN{cond}.size Dd, Dm

where:

cond

is an optional condition code.

## size

must be one of 8, 16, or 32.

## Qd, Qm

specifies the vectors, for a quadword operation.

## Dd, Dm

specifies the vectors, for a doubleword operation.

## Operation

VTRN treats the elements of its operand vectors as elements of 2 x 2 matrices, and transposes the matrices. The following figures show examples of the operation of VTRN:



## Figure C3-9 Operation of doubleword VTRN.8



Figure C3-10 Operation of doubleword VTRN.32

## **Related references**

# C3.142 VTST

Vector Test bits.

## Syntax

VTST{cond}.size {Qd}, Qn, Qm

VTST{cond}.size {Dd}, Dn, Dm

where:

cond

is an optional condition code.

size

must be one of 8, 16, or 32.

Qd, Qn, Qm

specifies the destination register, the first operand register, and the second operand register, for a quadword operation.

Dd, Dn, Dm

specifies the destination register, the first operand register, and the second operand register, for a doubleword operation.

# Operation

VTST takes each element in a vector, and bitwise logical ANDs them with the corresponding element of a second vector. If the result is not zero, the corresponding element in the destination vector is set to all ones. Otherwise, it is set to all zeros.

# **Related references**

# C3.143 VUDOT (vector)

Dot Product vector form with unsigned integers.

## Syntax

VUDOT{a	7}.U8 Dd, Dn, Dm ; 64-bit SIMD vector
VUDOT{a	].U8 Qd, Qn, Qm ; A1 128-bit SIMD vector FP/SIMD registers (A32)
Where:	
q	Is an optional instruction width specifier. See <i>C2.2 Instruction width specifiers</i> on page C2-111.
Dd	Is the 64-bit name of the SIMD and FP destination register.
Dn Dm	Is the 64-bit name of the first SIMD and FP source register.
Qd	Is the 64-bit name of the second SIMD and FP source register.
Qn	Is the 128-bit name of the SIMD and FP destination register.
Qm	Is the 128-bit name of the first SIMD and FP source register.
	Is the 128-bit name of the second SIMD and FP source register.

## Architectures supported

Supported in Armv8.2 and later.

For Armv8.2 and Armv8.3, this is an OPTIONAL instruction.

# Usage

Dot Product vector form with unsigned integers. This instruction performs the dot product of the four 8bit elements in each 32-bit element of the first source register with the four 8-bit elements of the corresponding 32-bit element in the second source register, accumulating the result into the corresponding 32-bit element of the destination register.

\_\_\_\_\_ Note \_\_\_\_\_

ID\_ISAR6.DP indicates whether this instruction is supported in the T32 and A32 instruction sets.

## **Related references**

C3.1 Summary of Advanced SIMD instructions on page C3-391
# C3.144 VUDOT (by element)

Dot Product index form with unsigned integers.

# Syntax

VUDOT{a	].U8 Dd, Dn, Dm[index] ; 64-bit SIMD vector
VUDOT{a	g}.U8 Qd, Qn, Dm[index] ; A1 128-bit SIMD vector FP/SIMD registers (A32)
Where:	
9	Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111
Dd Dn	Is the 64-bit name of the SIMD and FP destination register.
Dm	Is the 64-bit name of the first SIMD and FP source register.
index	Is the 64-bit name of the second SIMD and FP source register.
Qd	Is the element index in the range 0 to 1. Is the 128-bit name of the SIMD and FP destination register
Qn	Is the 128-bit name of the first SIMD and FP source register.

### Architectures supported

Supported in Armv8.2 and later.

For Armv8.2 and Armv8.3, this is an OPTIONAL instruction.

# Usage

Dot Product index form with unsigned integers. This instruction performs the dot product of the four 8bit elements in each 32-bit element of the first source register with the four 8-bit elements of an indexed 32-bit element in the second source register, accumulating the result into the corresponding 32-bit element of the destination register.

\_\_\_\_\_ Note \_\_\_\_\_

ID\_ISAR6.DP indicates whether this instruction is supported in the T32 and A32 instruction sets.

**Related references** 

C3.1 Summary of Advanced SIMD instructions on page C3-391

# C3.145 VUZP

Vector Unzip.

#### Syntax

- VUZP.32 Dd, Dm.
- VTRN.32 Dd, Dm.

The instruction is disassembled as VTRN.32 Dd, Dm.

#### Operation

VUZP de-interleaves the elements of two vectors.

De-interleaving is the inverse process of interleaving.

#### Table C3-27 Operation of doubleword VUZP.8

	Reg	giste	er sta	ate b	efor	re op	perat	tion	Re	gist	er si	tate	afte	r op	erat	ion
Dd	A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>	B <sub>6</sub>	B <sub>4</sub>	B <sub>2</sub>	B <sub>0</sub>	A <sub>6</sub>	A <sub>4</sub>	A <sub>2</sub>	A <sub>0</sub>
Dm	B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>	<b>B</b> <sub>7</sub>	B <sub>5</sub>	B <sub>3</sub>	<b>B</b> <sub>1</sub>	A <sub>7</sub>	$A_5$	A <sub>3</sub>	$A_1$

#### Table C3-28 Operation of quadword VUZP.32

	Registe	er state b	efore op	peration	Register state after operation					
Qd	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>	B <sub>2</sub>	B <sub>0</sub>	A <sub>2</sub>	A <sub>0</sub>		
Qm	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>	B <sub>3</sub>	B <sub>1</sub>	A <sub>3</sub>	A <sub>1</sub>		

#### **Related concepts**

*C3.3 Interleaving provided by load and store element and structure instructions* on page C3-395 *Related references* 

*C3.141 VTRN* on page C3-538

# C3.146 VZIP

Vector Zip.

#### Syntax

VZIP{cond}.size Qd, Qm

VZIP{cond}.size Dd, Dm

where:

cond

is an optional condition code.

#### size

must be one of 8, 16, or 32.

# Qd, Qm

specifies the vectors, for a quadword operation.

# Dd, Dm

specifies the vectors, for a doubleword operation.

----- Note --

The following are all the same instruction:

- VZIP.32 Dd, Dm.
- VUZP.32 Dd, Dm.
- VTRN.32 Dd, Dm.

The instruction is disassembled as VTRN.32 Dd, Dm.

# Operation

VZIP interleaves the elements of two vectors.

# Table C3-29 Operation of doubleword VZIP.8

	Reg	giste	er sta	ate b	efor	e op	perat	tion	Re	gist	er st	ate	afte	r op	erat	ion
Dd	A <sub>7</sub>	A <sub>6</sub>	A <sub>5</sub>	A <sub>4</sub>	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>	B <sub>3</sub>	A <sub>3</sub>	B <sub>2</sub>	A <sub>2</sub>	$B_1$	A <sub>1</sub>	B <sub>0</sub>	A <sub>0</sub>
Dm	B <sub>7</sub>	B <sub>6</sub>	B <sub>5</sub>	B <sub>4</sub>	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>	<b>B</b> <sub>7</sub>	A <sub>7</sub>	B <sub>6</sub>	A <sub>6</sub>	B <sub>5</sub>	A <sub>5</sub>	B <sub>4</sub>	$A_4$

#### Table C3-30 Operation of quadword VZIP.32

	Registe	er state b	Register state after operation					
Qd	A <sub>3</sub>	A <sub>2</sub>	A <sub>1</sub>	A <sub>0</sub>	B <sub>1</sub>	A <sub>1</sub>	B <sub>0</sub>	A <sub>0</sub>
Qm	B <sub>3</sub>	B <sub>2</sub>	B <sub>1</sub>	B <sub>0</sub>	B <sub>3</sub>	A <sub>3</sub>	B <sub>2</sub>	A <sub>2</sub>

# **Related concepts**

*C3.3 Interleaving provided by load and store element and structure instructions* on page C3-395 *Related references* 

C3.141 VTRN on page C3-538

C3 Advanced SIMD Instructions (32-bit) C3.146 VZIP

# Chapter C4 Floating-point Instructions (32-bit)

Describes floating-point assembly language instructions.

It contains the following sections:

- C4.1 Summary of floating-point instructions on page C4-547.
- C4.2 VABS (floating-point) on page C4-549.
- C4.3 VADD (floating-point) on page C4-550.
- C4.4 VCMP, VCMPE on page C4-551.
- C4.5 VCVT (between single-precision and double-precision) on page C4-552.
- C4.6 VCVT (between floating-point and integer) on page C4-553.
- C4.7 VCVT (from floating-point to integer with directed rounding modes) on page C4-554.
- C4.8 VCVT (between floating-point and fixed-point) on page C4-555.
- C4.9 VCVTB, VCVTT (half-precision extension) on page C4-556.
- C4.10 VCVTB, VCVTT (between half-precision and double-precision) on page C4-557.
- C4.11 VDIV on page C4-558.
- C4.12 VFMA, VFMS, VFNMA, VFNMS (floating-point) on page C4-559.
- *C4.13 VJCVT* on page C4-560.
- C4.14 VLDM (floating-point) on page C4-561.
- *C4.15 VLDR (floating-point)* on page C4-562.
- C4.16 VLDR (post-increment and pre-decrement, floating-point) on page C4-563.
- *C4.17 VLLDM* on page C4-564.
- C4.18 VLSTM on page C4-565.
- C4.19 VMAXNM, VMINNM (floating-point) on page C4-566.
- *C4.20 VMLA (floating-point)* on page C4-567.
- C4.21 VMLS (floating-point) on page C4-568.
- C4.22 VMOV (floating-point) on page C4-569.

- *C4.23 VMOV (between one general-purpose register and single precision floating-point register)* on page C4-570.
- *C4.24 VMOV* (between two general-purpose registers and one or two extension registers) on page C4-571.
- *C4.25 VMOV (between a general-purpose register and half a double precision floating-point register)* on page C4-572.
- C4.26 VMRS (floating-point) on page C4-573.
- *C4.27 VMSR (floating-point)* on page C4-574.
- C4.28 VMUL (floating-point) on page C4-575.
- C4.29 VNEG (floating-point) on page C4-576.
- *C4.30 VNMLA (floating-point)* on page C4-577.
- C4.31 VNMLS (floating-point) on page C4-578.
- C4.32 VNMUL (floating-point) on page C4-579.
- *C4.33 VPOP (floating-point)* on page C4-580.
- *C4.34 VPUSH (floating-point)* on page C4-581.
- *C4.35 VRINT (floating-point)* on page C4-582.
- *C4.36 VSEL* on page C4-583.
- *C4.37 VSQRT* on page C4-584.
- C4.38 VSTM (floating-point) on page C4-585.
- C4.39 VSTR (floating-point) on page C4-586.
- C4.40 VSTR (post-increment and pre-decrement, floating-point) on page C4-587.
- C4.41 VSUB (floating-point) on page C4-588.

# C4.1 Summary of floating-point instructions

A summary of the floating-point instructions. Not all of these instructions are available in all floating-point versions.

The following table shows a summary of floating-point instructions that are not available in Advanced SIMD.

\_\_\_\_\_ Note \_\_\_\_\_

Floating-point vector mode is not supported in Armv8. Use Advanced SIMD instructions for vector floating-point.

#### Table C4-1 Summary of floating-point instructions

Mnemonic	Brief description
VABS	Absolute value
VADD	Add
VCMP, VCMPE	Compare
VCVT	Convert between single-precision and double-precision
	Convert between floating-point and integer
	Convert between floating-point and fixed-point
	Convert floating-point to integer with directed rounding modes
VCVTB, VCVTT	Convert between half-precision and single-precision floating-point
	Convert between half-precision and double-precision
VDIV	Divide
VFMA, VFMS	Fused multiply accumulate, Fused multiply subtract
VFNMA, VFNMS	Fused multiply accumulate with negation, Fused multiply subtract with negation
VJCVT	Javascript Convert to signed fixed-point, rounding toward Zero
VLDM	Extension register load multiple
VLDR	Extension register load
VLLDM	Floating-point Lazy Load Multiple
VLSTM	Floating-point Lazy Store Multiple
VMAXNM, VMINNM	Maximum, Minimum, consistent with IEEE 754-2008
VMLA	Multiply accumulate
VMLS	Multiply subtract
VMOV	Insert floating-point immediate in single-precision or double-precision register, or copy one FP register into another FP register of the same width
VMRS	Transfer contents from a floating-point system register to a general-purpose register
VMSR	Transfer contents from a general-purpose register to a floating-point system register
VMUL	Multiply
VNEG	Negate

### Table C4-1 Summary of floating-point instructions (continued)

Mnemonic	Brief description
VNMLA	Negated multiply accumulate
VNMLS	Negated multiply subtract
VNMUL	Negated multiply
VPOP	Extension register load multiple
VPUSH	Extension register store multiple
VRINT	Round to integer
VSEL	Select
VSQRT	Square Root
VSTM	Extension register store multiple
VSTR	Extension register store
VSUB	Subtract

# C4.2 VABS (floating-point)

Floating-point absolute value.

# Syntax

VABS{cond}.F32 Sd, Sm

VABS{cond}.F64 Dd, Dm

where:

cond

is an optional condition code.

Sd, Sm

are the single-precision registers for the result and operand.

Dd, Dm

are the double-precision registers for the result and operand.

# Operation

The VABS instruction takes the contents of Sm or Dm, clears the sign bit, and places the result in Sd or Dd. This gives the absolute value.

If the operand is a NaN, the sign bit is cleared, but no exception is produced.

# **Floating-point exceptions**

VABS instructions do not produce any exceptions.

# **Related references**

# C4.3 VADD (floating-point)

Floating-point add.

# Syntax

VADD{cond}.F32 {Sd}, Sn, Sm

VADD{cond}.F64 {Dd}, Dn, Dm

where:

cond

is an optional condition code.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

# Operation

The VADD instruction adds the values in the operand registers and places the result in the destination register.

# **Floating-point exceptions**

The VADD instruction can produce Invalid Operation, Overflow, or Inexact exceptions.

# **Related references**

# C4.4 VCMP, VCMPE

Floating-point compare.

# Syntax

```
VCMP{E}{cond}.F32 Sd, Sm
VCMP{E}{cond}.F32 Sd, #0
VCMP{E}{cond}.F64 Dd, Dm
VCMP{E}{cond}.F64 Dd, #0
where:
```

Е

if present, indicates that the instruction raises an Invalid Operation exception if either operand is a quiet or signaling NaN. Otherwise, it raises the exception only if either operand is a signaling NaN.

cond

is an optional condition code.

```
Sd, Sm
```

are the single-precision registers holding the operands.

Dd, Dm

are the double-precision registers holding the operands.

# Operation

The VCMP{E} instruction subtracts the value in the second operand register (or 0 if the second operand is #0) from the value in the first operand register, and sets the VFP condition flags based on the result.

# **Floating-point exceptions**

VCMP{E} instructions can produce Invalid Operation exceptions.

**Related references** 

# C4.5 VCVT (between single-precision and double-precision)

Convert between single-precision and double-precision numbers.

## Syntax

VCVT{cond}.	F64.	F32	Dd,	Sm
• •				

```
VCVT{cond}.F32.F64 Sd, Dm
```

where:

cond

is an optional condition code.

Dd

is a double-precision register for the result.

Sm

is a single-precision register holding the operand.

Sd

is a single-precision register for the result.

Dm

is a double-precision register holding the operand.

# Operation

These instructions convert the single-precision value in Sm to double-precision, placing the result in Dd, or the double-precision value in Dm to single-precision, placing the result in Sd.

# **Floating-point exceptions**

These instructions can produce Invalid Operation, Input Denormal, Overflow, Underflow, or Inexact exceptions.

# **Related references**

# C4.6 VCVT (between floating-point and integer)

Convert between floating-point numbers and integers.

## Syntax

```
VCVT{R}{cond}.type.F64 Sd, Dm
VCVT{R}{cond}.type.F32 Sd, Sm
VCVT{cond}.F64.type Dd, Sm
VCVT{cond}.F32.type Sd, Sm
where:
R
```

makes the operation use the rounding mode specified by the FPSCR. Otherwise, the operation rounds towards zero.

#### cond

is an optional condition code.

#### type

can be either U32 (unsigned 32-bit integer) or S32 (signed 32-bit integer).

## Sd

Dd

is a single-precision register for the result.

is a double-precision register for the result.

Sm

#### Dm

is a double-precision register holding the operand.

is a single-precision register holding the operand.

# Operation

The first two forms of this instruction convert from floating-point to integer.

The third and fourth forms convert from integer to floating-point.

# **Floating-point exceptions**

These instructions can produce Input Denormal, Invalid Operation, or Inexact exceptions.

# **Related references** C1.9 Condition code suffixes on page C1-92

# C4.7 VCVT (from floating-point to integer with directed rounding modes)

Convert from floating-point to signed or unsigned integer with directed rounding modes.

# Syntax

VCVTmode.S32.F64 Sd, Dm VCVTmode.S32.F32 Sd, Sm VCVTmode.U32.F64 Sd, Dm VCVTmode.U32.F32 Sd, Sm where:

#### mode

must be one of:

Α

meaning round to nearest, ties away from zero

N D

м

meaning round to nearest, ties to even

- meaning round towards plus infinity
- meaning round towards minus infinity.

#### Sd, Sm

specifies the single-precision registers for the operand and result.

Sd, Dm

specifies a single-precision register for the result and double-precision register holding the operand.

#### Notes

You cannot use VCVT with a directed rounding mode inside an IT block.

#### **Floating-point exceptions**

These instructions can produce Input Denormal, Invalid Operation, or Inexact exceptions.

#### C4.8 VCVT (between floating-point and fixed-point)

Convert between floating-point and fixed-point numbers.

### **Syntax**

-
VCVT{cond}.type.F64 Dd, Dd, #fbits
VCVT{cond}.type.F32 Sd, Sd, #fbits
VCVT{cond}.F64.type Dd, Dd, #fbits
VCVT{cond}.F32.type Sd, Sd, #fbits
where:
cond
is an optional condition code.
type
can be any one of:
S16
16-bit signed fixed-point number.
U16
16-bit unsigned fixed-point number.
S32
32-bit signed fixed-point number.
U32
32-bit unsigned fixed-point number.
Sd
is a single-precision register for the operand and result.
Dd
is a double-precision register for the operand and result.
fbits
is the number of fraction bits in the fixed-point number, in the range 0-16 if <i>type</i> is S16 or U16, or in the range 1-32 if <i>type</i> is S32 or U32.
Operation
The first two forms of this instruction convert from floating-point to fixed-point.

The third and fourth forms convert from fixed-point to floating-point.

In all cases the fixed-point number is contained in the least significant 16 or 32 bits of the register.

#### **Floating-point exceptions**

These instructions can produce Input Denormal, Invalid Operation, or Inexact exceptions.

### **Related references**

# C4.9 VCVTB, VCVTT (half-precision extension)

Convert between half-precision and single-precision floating-point numbers.

## Syntax

VCVTB{cond}.type Sd, Sm

VCVTT{cond}.type Sd, Sm

where:

cond

is an optional condition code.

type

can be any one of:

# F32.F16

Convert from half-precision to single-precision.

#### F16.F32

Convert from single-precision to half-precision.

#### Sd

is a single word register for the result.

Sm

is a single word register for the operand.

# Operation

VCVTB uses the bottom half (bits[15:0]) of the single word register to obtain or store the half-precision value

VCVTT uses the top half (bits[31:16]) of the single word register to obtain or store the half-precision value.

# Architectures

The instructions are only available in VFPv3 systems with the half-precision extension, and VFPv4.

# **Floating-point exceptions**

These instructions can produce Input Denormal, Invalid Operation, Overflow, Underflow, or Inexact exceptions.

**Related references** C1.9 Condition code suffixes on page C1-92

# C4.10 VCVTB, VCVTT (between half-precision and double-precision)

These instructions convert between half-precision and double-precision floating-point numbers.

The conversion can be done in either of the following ways:

- From half-precision floating-point to double-precision floating-point (F64.F16).
- From double-precision floating-point to half-precision floating-point (F16.F64).

VCVTB uses the bottom half (bits[15:0]) of the single word register to obtain or store the half-precision value.

VCVTT uses the top half (bits[31:16]) of the single word register to obtain or store the half-precision value.

\_\_\_\_\_ Note \_\_\_\_\_

These instructions are supported only in Armv8.

# Syntax

VCVTB{cond}.F64.F16 Dd, Sm

VCVTB{cond}.F16.F64 Sd, Dm

VCVTT{cond}.F64.F16 Dd, Sm

VCVTT{cond}.F16.F64 Sd, Dm

where:

is an optional condition code.

is a double-precision register for the result.

Sm

Sd

Dd

is a single word register holding the operand.

is a single word register for the result.

Dm

is a double-precision register holding the operand.

# Usage

These instructions convert the half-precision value in Sm to double-precision and place the result in Dd, or the double-precision value in Dm to half-precision and place the result in Sd.

# **Floating-point exceptions**

These instructions can produce Input Denormal, Invalid Operation, Overflow, Underflow, or Inexact exceptions.

# C4.11 VDIV

Floating-point divide.

# Syntax

VDIV{cond}.F32 {Sd}, Sn, Sm

VDIV{cond}.F64 {Dd}, Dn, Dm

where:

cond

is an optional condition code.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

# Operation

The VDIV instruction divides the value in the first operand register by the value in the second operand register, and places the result in the destination register.

# **Floating-point exceptions**

VDIV operations can produce Division by Zero, Invalid Operation, Overflow, Underflow, or Inexact exceptions.

# **Related references**

# C4.12 VFMA, VFMS, VFNMA, VFNMS (floating-point)

Fused floating-point multiply accumulate and fused floating-point multiply subtract, with optional negation.

#### Syntax

VF{N}op{cond}.F64 {Dd}, Dn, Dm

VF{N}op{cond}.F32 {Sd}, Sn, Sm

where:

ор

is one of MA or MS.

Ν

negates the final result.

cond

is an optional condition code.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

### Operation

VFMA multiplies the values in the operand registers, adds the value in the destination register, and places the final result in the destination register. The result of the multiply is not rounded before the accumulation.

VFMS multiplies the values in the operand registers, subtracts the product from the value in the destination register, and places the final result in the destination register. The result of the multiply is not rounded before the subtraction.

In each case, the final result is negated if the N option is used.

#### **Floating-point exceptions**

These instructions can produce Input Denormal, Invalid Operation, Overflow, Underflow, or Inexact exceptions.

**Related references** 

*C4.28 VMUL (floating-point)* on page C4-575 *C1.9 Condition code suffixes* on page C1-92

# C4.13 VJCVT

Javascript Convert to signed fixed-point, rounding toward Zero.

# Syntax

VJCVT{q}.S32.F64 Sd, Dm ; A1 FP/SIMD registers (A32)
VJCVT{q}.S32.F64 Sd, Dm ; T1 FP/SIMD registers (T32)
Where:
q
Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.
Sd

Is the 32-bit name of the SIMD and FP destination register.

Is the 64-bit name of the SIMD and FP source register.

# Architectures supported

Supported in the Armv8.3-A architecture and later.

# Usage

Dm

Javascript Convert to signed fixed-point, rounding toward Zero. This instruction converts the doubleprecision floating-point value in the SIMD and FP source register to a 32-bit signed integer using the Round towards Zero rounding mode, and write the result to the general-purpose destination register. If the result is too large to be held as a 32-bit signed integer, then the result is the integer modulo  $2^{32}$ , as held in a 32-bit signed integer.

Depending on settings in the *CPACR*, *NSACR*, *HCPTR*, and *FPEXC* registers, and the security state and mode in which the instruction is executed, an attempt to execute the instruction might be UNDEFINED, or trapped to Hyp mode. For more information see *Enabling Advanced SIMD and floating-point support* in the *Arm*<sup>®</sup> *Architecture Reference Manual Arm*<sup>®</sup> v8, for *Arm*<sup>®</sup> v8-A architecture profile.

# **Related references**

C4.1 Summary of floating-point instructions on page C4-547

# C4.14 VLDM (floating-point)

Extension register load multiple.

## Syntax

VLDMmode{cond} Rn{!}, Registers

where:

mode

must be one of:

IA

meaning Increment address After each transfer. IA is the default, and can be omitted.

DB

meaning Decrement address Before each transfer.

EA

meaning Empty Ascending stack operation. This is the same as DB for loads.

FD

meaning Full Descending stack operation. This is the same as IA for loads.

#### cond

is an optional condition code.

Rn

is the general-purpose register holding the base address for the transfer.

!

is optional. ! specifies that the updated base address must be written back to *Rn*. If ! is not specified, *mode* must be IA.

Registers

is a list of consecutive extension registers enclosed in braces, { and }. The list can be commaseparated, or in range format. There must be at least one register in the list.

You can specify S or D registers, but they must not be mixed. The number of registers must not exceed 16 D registers.

—— Note —

VPOP Registers is equivalent to VLDM sp!, Registers.

You can use either form of this instruction. They both disassemble to VPOP.

**Related references** 

# C4.15 VLDR (floating-point)

Extension register load.

# Syntax

VLDR{cond}{.size} Fd, [Rn{, #offset}]

VLDR{cond}{.size} Fd, label

where:

cond

is an optional condition code.

size

is an optional data size specifier. Must be 32 if *Fd* is an S register, or 64 otherwise.

#### Fd

is the extension register to be loaded, and can be either a D or S register.

#### Rn

is the general-purpose register holding the base address for the transfer.

offset

is an optional numeric expression. It must evaluate to a numeric value at assembly time. The value must be a multiple of 4, and lie in the range -1020 to +1020. The value is added to the base address to form the address used for the transfer.

#### Label

is a PC-relative expression.

*LabeL* must be aligned on a word boundary within  $\pm 1$ KB of the current instruction.

# Operation

The VLDR instruction loads an extension register from memory.

One word is transferred if *Fd* is an S register. Two words are transferred otherwise.

There is also a VLDR pseudo-instruction.

# **Related references**

# C4.16 VLDR (post-increment and pre-decrement, floating-point)

Pseudo-instruction that loads extension registers, with post-increment and pre-decrement forms.

#### Syntax

VLDR{cond}{.size} Fd, [Rn], #offset ; post-increment
VLDR{cond}{.size} Fd, [Rn, #-offset]! ; pre-decrement

where:

cond

is an optional condition code.

#### size

is an optional data size specifier. Must be 32 if Fd is an S register, or 64 if Fd is a D register.

#### Fd

is the extension register to load. It can be either a double precision (Dd) or a single precision (Sd) register.

#### Rn

is the general-purpose register holding the base address for the transfer.

offset

is a numeric expression that must evaluate to a numeric value at assembly time. The value must be 4 if *Fd* is an S register, or 8 if *Fd* is a D register.

# Operation

The post-increment instruction increments the base address in the register by the offset value, after the transfer. The pre-decrement instruction decrements the base address in the register by the offset value, and then performs the transfer using the new address in the register. This pseudo-instruction assembles to a VLDM instruction.

# **Related references**

*C4.14 VLDM (floating-point)* on page C4-561 *C4.15 VLDR (floating-point)* on page C4-562 *C1.9 Condition code suffixes* on page C1-92

# C4.17 VLLDM

Floating-point Lazy Load Multiple.

# Syntax

 $VLLDM{c}{q} Rn$ 

Where:

с

Is an optional condition code. See *Chapter C1 Condition Codes* on page C1-83.

q Rn

Is the general-purpose base register.

# Architectures supported

Supported in Armv8-M Main extension only.

# Usage

Floating-point Lazy Load Multiple restores the contents of the Secure floating-point registers that were protected by a VLSTM instruction, and marks the floating-point context as active.

Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.

If the lazy state preservation set up by a previous VLSTM instruction is active (FPCCR.LSPACT == 1), this instruction deactivates lazy state preservation and enables access to the Secure floating-point registers.

If lazy state preservation is inactive (FPCCR.LSPACT == 0), either because lazy state preservation was not enabled (FPCCR.LSPEN == 0) or because a floating-point instruction caused the Secure floating-point register contents to be stored to memory, this instruction loads the stored Secure floating-point register contents back into the floating-point registers.

If Secure floating-point is not in use (CONTROL\_S.SFPA == 0), this instruction behaves as a NOP.

This instruction is only available in Secure state, and is UNDEFINED in Non-secure state.

If the Floating-point Extension is not implemented, this instruction is available in Secure state, but behaves as a NOP.

# **Related references**

C4.1 Summary of floating-point instructions on page C4-547

# C4.18 VLSTM

Floating-point Lazy Store Multiple.

# Syntax

 $VLSTM{c}{q} Rn$ 

Where:

с

Is an optional condition code. See Chapter C1 Condition Codes on page C1-83.

Is an optional instruction width specifier. See C2.2 Instruction width specifiers on page C2-111.

q Rn

Is the general-purpose base register.

# Architectures supported

Supported in Armv8-M Main extension only.

# Usage

Floating-point Lazy Store Multiple stores the contents of Secure floating-point registers to a prepared stack frame, and clears the Secure floating-point registers.

If floating-point lazy preservation is enabled (FPCCR.LSPEN == 1), then the next time a floating-point instruction other than VLSTM or VLLDM is executed:

- The contents of Secure floating-point registers are stored to memory.
- The Secure floating-point registers are cleared.

If Secure floating-point is not in use (CONTROL\_S.SFPA == 0), this instruction behaves as a NOP.

This instruction is only available in Secure state, and is UNDEFINED in Non-secure state.

If the Floating-point extension is not implemented, this instruction is available in Secure state, but behaves as a NOP.

# **Related references**

C4.1 Summary of floating-point instructions on page C4-547

# C4.19 VMAXNM, VMINNM (floating-point)

Vector Minimum, Vector Maximum.

\_\_\_\_\_ Note \_\_\_\_

These instructions are supported only in Armv8.

#### Syntax

Vop.F32 Sd, Sn, Sm Vop.F64 Dd, Dn, Dm

where:

ор

must be either MAXNM or MINNM.

Sd, Sn, Sm

are the single-precision destination register, first operand register, and second operand register. *Dd*, *Dn*, *Dm* 

are the double-precision destination register, first operand register, and second operand register.

# Operation

VMAXNM compares the values in the operand registers, and copies the larger value into the destination operand register.

VMINNM compares the values in the operand registers, and copies the smaller value into the destination operand register.

If one of the values being compared is a number and the other value is NaN, the number is copied into the destination operand register. This is consistent with the IEEE 754-2008 standard.

# Notes

You cannot use VMAXNM or VMINNM inside an IT block.

#### **Floating-point exceptions**

These instructions can produce Input Denormal, Invalid Operation, Overflow, Underflow, or Inexact exceptions.

# C4.20 VMLA (floating-point)

Floating-point multiply accumulate.

## Syntax

VMLA{cond}.F32 Sd, Sn, Sm

VMLA{cond}.F64 Dd, Dn, Dm

where:

cond

is an optional condition code.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

### Operation

The VMLA instruction multiplies the values in the operand registers, adds the value in the destination register, and places the final result in the destination register.

# **Floating-point exceptions**

This instruction can produce Invalid Operation, Overflow, Underflow, Inexact, or Input Denormal exceptions.

### **Related references**

# C4.21 VMLS (floating-point)

Floating-point multiply subtract.

# Syntax

VMLS{cond}.F32 Sd, Sn, Sm

VMLS{cond}.F64 Dd, Dn, Dm

where:

cond

is an optional condition code.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

# Operation

The VMLS instruction multiplies the values in the operand registers, subtracts the result from the value in the destination register, and places the final result in the destination register.

# **Floating-point exceptions**

This instruction can produce Invalid Operation, Overflow, Underflow, Inexact, or Input Denormal exceptions.

# **Related references**

# C4.22 VMOV (floating-point)

Insert a floating-point immediate value into a single-precision or double-precision register, or copy one register into another register. This instruction is always scalar.

## Syntax

VMOV{cond}.F32 Sd, #imm

VMOV{cond}.F64 Dd, #imm
VMOV{cond}.F32 Sd, Sm

VMOV{cond}.F64 Dd, Dm

where:

cond

is an optional condition code.

Sd

is the single-precision destination register.

Dd

is the double-precision destination register.

imm

is the floating-point immediate value.

Sm

is the single-precision source register.

Dm

is the double-precision source register.

#### Immediate values

Any number that can be expressed as  $\pm n * 2^{-r}$ , where *n* and *r* are integers,  $16 \le n \le 31$ ,  $0 \le r \le 7$ .

# Architectures

The instructions that copy immediate constants are available in VFPv3 and above.

The instructions that copy from registers are available in all VFP systems.

#### **Related references**

# C4.23 VMOV (between one general-purpose register and single precision floatingpoint register)

Transfer contents between a single-precision floating-point register and a general-purpose register.

#### Syntax

VMOV{cond} Rd, Sn

VMOV{cond} Sn, Rd

where:

cond

is an optional condition code.

Sn

is the floating-point single-precision register.

Rd

is the general-purpose register. Rd must not be PC.

# Operation

VMOV Rd, Sn transfers the contents of Sn into Rd.

VMOV Sn, Rd transfers the contents of Rd into Sn.

# **Related references**

# C4.24 VMOV (between two general-purpose registers and one or two extension registers)

Transfer contents between two general-purpose registers and either one 64-bit register or two consecutive 32-bit registers.

#### Syntax

VMOV{cond} Dm, Rd, Rn
VMOV{cond} Rd, Rn, Dm
VMOV{cond} Sm, Sm1, Rd, Rn
VMOV{cond} Rd, Rn, Sm, Sm1
where:

cond

is an optional condition code.

#### Dm

is a 64-bit extension register.

#### Sm

is a VFP 32-bit register.

#### Sm1

is the next consecutive VFP 32-bit register after Sm.

Rd, Rn

are the general-purpose registers. Rd and Rn must not be PC.

# Operation

VMOV Dm, Rd, Rn transfers the contents of Rd into the low half of Dm, and the contents of Rn into the high half of Dm.

VMOV Rd, Rn, Dm transfers the contents of the low half of Dm into Rd, and the contents of the high half of Dm into Rn.

VMOV Rd, Rn, Sm, Sm1 transfers the contents of Sm into Rd, and the contents of Sm1 into Rn.

VMOV Sm, Sm1, Rd, Rn transfers the contents of Rd into Sm, and the contents of Rn into Sm1.

#### Architectures

The instructions are available in VFPv2 and above.

*Related references C1.9 Condition code suffixes* on page C1-92

# C4.25 VMOV (between a general-purpose register and half a double precision floating-point register)

Transfer contents between a general-purpose register and half a double precision floating-point register.

### Syntax

```
VMOV{cond}{.size} Dn[x], Rd
```

```
VMOV{cond}{.size} Rd, Dn[x]
```

where:

cond

is an optional condition code.

size

the data size. Must be either 32 or omitted. If omitted, *size* is 32.

Dn[x]

is the upper or lower half of a double precision floating-point register.

Rd

is the general-purpose register. Rd must not be PC.

# Operation

VMOV Dn[x], Rd transfers the contents of Rd into Dn[x].

VMOV Rd, Dn[x] transfers the contents of Dn[x] into Rd.

# **Related references**

# C4.26 VMRS (floating-point)

Transfer contents from an floating-point system register to a general-purpose register.

#### Syntax

VMRS{cond} Rd, extsysreg

where:

cond

extsysreg

is an optional condition code.

Rd

is the floating-point system register, usually FPSCR, FPSID, or FPEXC.

is the general-purpose register. Rd must not be PC.

It can be APSR\_nzcv, if *extsysreg* is FPSCR. In this case, the floating-point status flags are transferred into the corresponding flags in the special-purpose APSR.

### Usage

The VMRS instruction transfers the contents of *extsysreg* into *Rd*.

\_\_\_\_\_ Note \_\_\_\_\_

The instruction stalls the processor until all current floating-point operations complete.

# Examples

VMRS r2,FPCID VMRS APSR\_nzcv, FPSCR ;

; transfer FP status register to the ; special-purpose APSR

# **Related references**

# C4.27 VMSR (floating-point)

Transfer contents of a general-purpose register to a floating-point system register.

### Syntax

VMSR{cond} extsysreg, Rd

where:

cond

extsysreg

is an optional condition code.

.

is the floating-point system register, usually FPSCR, FPSID, or FPEXC.

Rd

is the general-purpose register. Rd must not be PC.

It can be APSR\_nzcv, if *extsysreg* is FPSCR. In this case, the floating-point status flags are transferred into the corresponding flags in the special-purpose APSR.

### Usage

The VMSR instruction transfers the contents of *Rd* into *extsysreg*.

\_\_\_\_\_ Note \_\_\_\_\_

The instruction stalls the processor until all current floating-point operations complete.

# Example

VMSR FPSCR, r4

**Related references** 

# C4.28 VMUL (floating-point)

Floating-point multiply.

# Syntax

VMUL{cond}.F32 {Sd,} Sn, Sm

VMUL{cond}.F64 {Dd,} Dn, Dm

where:

cond

is an optional condition code.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

# Operation

The VMUL operation multiplies the values in the operand registers and places the result in the destination register.

# **Floating-point exceptions**

This instruction can produce Invalid Operation, Overflow, Underflow, Inexact, or Input Denormal exceptions.

# **Related references**

# C4.29 VNEG (floating-point)

Floating-point negate.

# Syntax

VNEG{cond}.F32 Sd, Sm

VNEG{cond}.F64 Dd, Dm

where:

cond

is an optional condition code.

Sd, Sm

are the single-precision registers for the result and operand.

Dd, Dm

are the double-precision registers for the result and operand.

# Operation

The VNEG instruction takes the contents of Sm or Dm, changes the sign bit, and places the result in Sd or Dd. This gives the negation of the value.

If the operand is a NaN, the sign bit is changed, but no exception is produced.

# **Floating-point exceptions**

VNEG instructions do not produce any exceptions.

# **Related references**
# C4.30 VNMLA (floating-point)

Floating-point multiply accumulate with negation.

#### Syntax

VNMLA{cond}.F32 Sd, Sn, Sm

VNMLA{cond}.F64 Dd, Dn, Dm

where:

cond

is an optional condition code.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

#### Operation

The VNMLA instruction multiplies the values in the operand registers, adds the value to the destination register, and places the negated final result in the destination register.

#### **Floating-point exceptions**

This instruction can produce Invalid Operation, Overflow, Underflow, Inexact, or Input Denormal exceptions.

#### **Related references**

# C4.31 VNMLS (floating-point)

Floating-point multiply subtract with negation.

#### Syntax

VNMLS{cond}.F32 Sd, Sn, Sm

VNMLS{cond}.F64 Dd, Dn, Dm

where:

cond

is an optional condition code.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

#### Operation

The VNMLS instruction multiplies the values in the operand registers, subtracts the result from the value in the destination register, and places the negated final result in the destination register.

### **Floating-point exceptions**

This instruction can produce Invalid Operation, Overflow, Underflow, Inexact, or Input Denormal exceptions.

#### **Related references**

# C4.32 VNMUL (floating-point)

Floating-point multiply with negation.

#### Syntax

VNMUL{cond}.F32 {Sd,} Sn, Sm

VNMUL{cond}.F64 {Dd,} Dn, Dm

where:

cond

is an optional condition code.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

#### Operation

The VNMUL instruction multiplies the values in the operand registers and places the negated result in the destination register.

#### **Floating-point exceptions**

This instruction can produce Invalid Operation, Overflow, Underflow, Inexact, or Input Denormal exceptions.

#### **Related references**

# C4.33 VPOP (floating-point)

Pop extension registers from the stack.

#### Syntax

VPOP{cond} Registers

where:

cond

is an optional condition code.

#### Registers

is a list of consecutive extension registers enclosed in braces, { and }. The list can be commaseparated, or in range format. There must be at least one register in the list.

You can specify S or D registers, but they must not be mixed. The number of registers must not exceed 16 D registers.

\_\_\_\_\_ Note \_\_\_\_\_

VPOP Registers is equivalent to VLDM sp!, Registers.

You can use either form of this instruction. They both disassemble to VPOP.

#### **Related references**

*C1.9 Condition code suffixes* on page C1-92 *C4.34 VPUSH (floating-point)* on page C4-581

# C4.34 VPUSH (floating-point)

Push extension registers onto the stack.

#### Syntax

VPUSH{cond} Registers

where:

cond

is an optional condition code.

#### Registers

is a list of consecutive extension registers enclosed in braces, { and }. The list can be commaseparated, or in range format. There must be at least one register in the list.

You can specify S or D registers, but they must not be mixed. The number of registers must not exceed 16 D registers.

\_\_\_\_\_ Note \_\_\_\_\_

VPUSH Registers is equivalent to VSTMDB sp!, Registers.

You can use either form of this instruction. They both disassemble to VPUSH.

#### **Related references**

*C1.9 Condition code suffixes* on page C1-92 *C4.33 VPOP (floating-point)* on page C4-580

#### **VRINT** (floating-point) C4.35

Rounds a floating-point number to integer and places the result in the destination register. The resulting integer is represented in floating-point format.

- Note -

This instruction is supported only in Armv8.

#### **Syntax**

VRINTmode{cond}.F64.F64 Dd, Dm		
VRINTmode{cond}.F32.F32 Sd, Sm		
where:		
mode		
	must be one of:	
	z	
	meaning round towards zero.	
	R	
	meaning use the rounding mode specified in the FPSCR.	
	<b>x</b> meaning use the rounding mode specified in the FPSCR, generating an Inexact exception if the result is not exact.	
	Α	
	meaning round to nearest, ties away from zero.	
	meaning round to nearest, ties to even.	
	P meaning round towards plus infinity	
	M	
	meaning round towards minus infinity.	
cond	is an optional condition code. This can only be used when <i>mode</i> is Z, R or X.	
Sd, Sm Dd. Dm	specifies the destination and operand registers, for a word operation.	

specifies the destination and operand registers, for a doubleword operation.

#### Notes

You cannot use VRINT with a rounding mode of A, N, P or M inside an IT block.

#### **Floating-point exceptions**

These instructions cannot produce any exceptions, except VRINTX which can generate an Inexact exception.

#### **Related references**

# C4.36 VSEL

Floating-point select.

—— Note —

This instruction is supported only in Armv8.

#### Syntax

VSELcond.F32 Sd, Sn, Sm VSELcond.F64 Dd, Dn, Dm where: cond

must be one of GE, GT, EQ, VS.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

#### Usage

The VSEL instruction compares the values in the operand registers. If the condition is true, it copies the value in the first operand register into the destination operand register. Otherwise, it copies the value in the second operand register.

You cannot use VSEL inside an IT block.

#### **Floating-point exceptions**

VSEL instructions cannot produce any exceptions.

#### **Related references**

*C1.11 Comparison of condition code meanings in integer and floating-point code* on page C1-94 *C1.9 Condition code suffixes* on page C1-92

# C4.37 VSQRT

Floating-point square root.

#### Syntax

VSQRT{cond}.F32 Sd, Sm

VSQRT{cond}.F64 Dd, Dm

where:

cond

is an optional condition code.

Sd, Sm

are the single-precision registers for the result and operand.

Dd, Dm

are the double-precision registers for the result and operand.

### Operation

The VSQRT instruction takes the square root of the contents of Sm or Dm, and places the result in Sd or Dd.

### **Floating-point exceptions**

VSQRT instructions can produce Invalid Operation or Inexact exceptions.

**Related references** 

## C4.38 VSTM (floating-point)

Extension register store multiple.

#### Syntax

VSTMmode{cond} Rn{!}, Registers

where:

mode

must be one of:

IA

meaning Increment address After each transfer. IA is the default, and can be omitted.

DB

meaning Decrement address Before each transfer.

EA

meaning Empty Ascending stack operation. This is the same as IA for stores.

FD

meaning Full Descending stack operation. This is the same as DB for stores.

#### cond

is an optional condition code.

Rn

is the general-purpose register holding the base address for the transfer.

!

is optional. ! specifies that the updated base address must be written back to Rn. If ! is not specified, mode must be IA.

Registers

is a list of consecutive extension registers enclosed in braces, { and }. The list can be commaseparated, or in range format. There must be at least one register in the list.

You can specify S or D registers, but they must not be mixed. The number of registers must not exceed 16 D registers.

——Note —

VPUSH Registers is equivalent to VSTMDB sp!, Registers.

You can use either form of this instruction. They both disassemble to VPUSH.

Related references

# C4.39 VSTR (floating-point)

Extension register store.

#### Syntax

VSTR{cond}{.size} Fd, [Rn{, #offset}]

where:

cond

is an optional condition code.

#### size

is an optional data size specifier. Must be 32 if Fd is an S register, or 64 otherwise.

Fd

is the extension register to be saved. It can be either a D or S register.

#### Rn

is the general-purpose register holding the base address for the transfer.

#### offset

is an optional numeric expression. It must evaluate to a numeric value at assembly time. The value must be a multiple of 4, and lie in the range -1020 to +1020. The value is added to the base address to form the address used for the transfer.

#### Operation

The VSTR instruction saves the contents of an extension register to memory.

One word is transferred if *Fd* is an S register. Two words are transferred otherwise.

#### **Related references**

# C4.40 VSTR (post-increment and pre-decrement, floating-point)

Pseudo-instruction that stores extension registers with post-increment and pre-decrement forms.

\_\_\_\_\_ Note \_\_\_\_\_

There are also VLDR and VSTR instructions without post-increment and pre-decrement.

#### Syntax

VSTR{cond}{.size} Fd, [Rn], #offset ; post-increment
VSTR{cond}{.size} Fd, [Rn, #-offset]! ; pre-decrement

where:

cond

is an optional condition code.

#### size

is an optional data size specifier. Must be 32 if Fd is an S register, or 64 if Fd is a D register.

#### Fd

is the extension register to be saved. It can be either a double precision (Dd) or a single precision (Sd) register.

#### Rn

is the general-purpose register holding the base address for the transfer.

offset

is a numeric expression that must evaluate to a numeric value at assembly time. The value must be 4 if *Fd* is an S register, or 8 if *Fd* is a D register.

#### Operation

The post-increment instruction increments the base address in the register by the offset value, after the transfer. The pre-decrement instruction decrements the base address in the register by the offset value, and then performs the transfer using the new address in the register. This pseudo-instruction assembles to a VSTM instruction.

#### **Related references**

*C4.39 VSTR (floating-point)* on page C4-586 *C4.38 VSTM (floating-point)* on page C4-585 *C1.9 Condition code suffixes* on page C1-92

# C4.41 VSUB (floating-point)

Floating-point subtract.

#### Syntax

VSUB{cond}.F32 {Sd}, Sn, Sm

VSUB{cond}.F64 {Dd}, Dn, Dm

where:

cond

is an optional condition code.

Sd, Sn, Sm

are the single-precision registers for the result and operands.

Dd, Dn, Dm

are the double-precision registers for the result and operands.

#### Operation

The VSUB instruction subtracts the value in the second operand register from the value in the first operand register, and places the result in the destination register.

#### **Floating-point exceptions**

The VSUB instruction can produce Invalid Operation, Overflow, or Inexact exceptions.

#### **Related references**

# Chapter C5 A32/T32 Cryptographic Algorithms

Lists the cryptographic algorithms that A32 and T32 SIMD instructions support.

It contains the following section:

• C5.1 A32/T32 Cryptographic instructions on page C5-590.

# C5.1 A32/T32 Cryptographic instructions

A set of A32 and T32 cryptographic instructions is available in the Armv8 architecture.

These instructions use the 128-bit Advanced SIMD registers and support the acceleration of the following cryptographic and hash algorithms:

- AES.
- SHA1.
- SHA256.

#### Summary of A32/T32 cryptographic instructions

The following table lists the A32/T32 cryptographic instructions that are supported:

#### Table C5-1 Summary of A32/T32 cryptographic instructions

Mnemonic	Brief description
AESD	AES single round decryption
AESE	AES single round encryption
AESIMC	AES inverse mix columns
AESMC	AES mix columns
SHA1C	SHA1 hash update (choose)
SHA1H	SHA1 fixed rotate
SHA1M	SHA1 hash update (majority)
SHA1P	SHA1 hash update (parity)
SHA1SU0	SHA1 schedule update 0
SHA1SU1	SHA1 schedule update 1
SHA256H2	SHA256 hash update part 2
SHA256H	SHA256 hash update part 1
SHA256SU0	SHA256 schedule update 0
SHA256SU1	SHA256 schedule update 1